

Camera Calibration

Leopold Gaube - 34948, IN

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1 Task Overview

- 3D scene projected onto 2D image (loss of information) - distortions - intrinsic and extrinsic camera parameters - can be used to undistort images/frames

[Ope22] The code and all frames used for this camera calibration task are available in this GitLab repository [Gau22].

List of Acronyms

References

[Gau22] Gaube. Camera calibration. <https://gitlab.com/gaubeleo/camera-calibration>, 07.06.2022.

[Ope22] OpenCV. Opencv - about. <https://opencv.org/about/>, 21.04.2022.