

LEONARDO SANTOS

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[Google Scholar](#) ◊ [Github](#) ◊ [LinkedIn](#)

EDUCATION

Federal University of Minas Gerais (UFMG)

July 2025 (expected), Brazil

B.Sc. in Electrical Engineering, Emphasis in Robotics

GPA: 86.6/100 (top 11%)

Relevant coursework: Mobile Robotics, Control of Linear Systems, Robot Motion Planning (Master's course).

KTH Royal Institute of Technology

Aug 2023 - Jan 2024, Sweden

Study abroad semester

GPA: 4.2/5.0

Relevant graduate coursework: Introduction to Robotics, Machine Learning, Safe Robot Planning and Control, Reinforcement Learning.

SKILLS

Programming

Python, C++, MATLAB

Technologies

ROS, RViz, Git, L^AT_EX

Languages

English (fluent) and Portuguese (native)

RESEARCH EXPERIENCE

Robotics Institute Summer Scholar (RISS)

June 2024 - Present

Carnegie Mellon University | [Prof. Andrea Bajcsy](#) | [Intent Lab](#)

Pittsburgh, USA

- Developed a framework to update safety specifications online from human language feedback using a Vision Language Model.
- Applied the safety specifications in a downstream reachability controller for safe navigation and demonstrated the system in both hardware and simulation experiments. Co-first author [paper](#) under review to ICRA 2025 [1].
- More information and demos on the [project website](#).
- **Technical skills:** Python, ROS.

Research Assistant

Sep 2023 - Jan 2024

KTH Royal Institute of Technology | [Prof. Jana Tumova](#) | [RPL](#)

Stockholm, Sweden

- Studied risk-aware trajectory optimization for safe navigation among humans.
- Implemented an MPPI-based trajectory optimizer to minimize a CVaR risk measure in belief space for trajectory planning under uncertainty.
- **Technical skills:** Python, PyTorch.

Robotics Institute Summer Scholar (RISS)

June 2023 - Aug 2023

Carnegie Mellon University | [Prof. Sebastian Scherer](#) | [AirLab](#)

Pittsburgh, USA

- Developed a framework based on Random Finite Sets that mathematically unifies search and track objectives for informative path planning.
- Contributed to both theoretical and implementation developments.
- Co-first author [paper](#) published at 2025 AIAA SciTech Forum [2].
- **Technical skills:** C++, MATLAB, ROS.

Research Assistant

Feb 2021 - May 2023

Federal University of Minas Gerais | [Prof. Douglas Macharet](#) | [VeRLab](#) Belo Horizonte, Brazil

- Developed a planning pipeline for communication-constrained multi-robot systems. The pipeline is based on virtual structures and guarantees that communication between robots is preserved by construction. Demonstrated in simulation and in a simple hardware experiment. First author [paper](#) under review at IEEE Latin America Transactions [3].
- Ran and evaluated experiments in a project that uses a heterogeneous multi-robot system for warehouse management. Second author [paper](#) published at LARS 2022 [4].
- **Technical skills:** Python, ROS.

PUBLICATIONS

- [1] L. Santos*, Z. Li*, L. Peters, S. Bansal', and A. Bajcsy', "Updating robot safety representations online from natural language feedback," *To appear in IEEE ICRA 2025*, 2025.
- [2] L. Santos, B. Moon, S. Scherer, and H. Van Nguyen, "Unisat: Unified-objective belief model and planner to search for and track multiple objects," in *AIAA SCITECH 2025 Forum*, 2025, p. 2114.
- [3] L. Santos, C. C. G. Ribeiro, and D. G. Macharet, "Communication backbone reconfiguration with connectivity maintenance," *IEEE Latin America Transactions (under review)*, 2024.
- [4] C. C. G. Ribeiro, L. H. M. C. dos Santos, and D. G. Macharet, "Collaborative ugv/uav path planning for inventory management in warehouses," in *2022 Latin American Robotics Symposium (LARS)*, 2022, pp. 121–126.

SERVICE AND OUTREACH

Member of Admissions Committee

Jan 2025

[CMU RISS](#)

- Helped reviewing applications for the Robotics Institute Summer Scholars (RISS) program at CMU.

Co-Lead Organizer

Jun 2023 - Aug 2024

[RoboLaunch](#)

Pittsburgh, USA

- Helped organize a robotics seminar series aimed at introducing undergraduate students to robotics through a series of accessible talks from speakers from academia and industry.
- Led logistics involving speaker invitations, advertisement, and general team coordination.
- During the time I was involved, we hosted speakers from CMU, MIT, University of Washington, University of Adelaide, ETH Zurich, among others.

Co-Founder and Webmaster

Sep 2024 - Present

[UFMG IEEE Student Branch](#)

Belo Horizonte, Brazil

- Organized events to promote and advertise research at UFMG, including seminars on microelectronics, AI, robotics, and biomedical engineering; research partnerships between Brazilian and French universities.
- Currently responsible for everything related to branding, external communications, and social media presence.

AWARDS AND SCHOLARSHIPS

Google Undergraduate Research Scholarship , 1 of 3 scholars at CMU	<i>Summer 2024</i>
Minas Mundi Study Abroad , selected UFMG student	<i>Fall 2023</i>
Mobility21 Undergraduate Research Scholarship , 1 of 3 scholars at CMU	<i>Summer 2023</i>
National Finalist , top 3 Overall, 2nd SARC-BARINet Aerospace Competition	<i>Fall 2022</i>
Top 15 Papers Award out of 80 submissions, LARS 2022	<i>Fall 2022</i>
Minas Gerais Research Support Foundation Scholarship	Fall 2022, Spring 2023
Brazilian National Council for R&D Scholarship	Fall 2021, Spring 2022

SOCIETY MEMBERSHIPS

IEEE RAS Student Member	<i>2025</i>
IEEE Student Member	<i>2024</i>