

Euclidean Distance Degrees of Secant Varieties to the Rational Normal Curve

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MAX PLANCK INSTITUTE
FOR MATHEMATICS
IN THE SCIENCES

A mathematician and an engineer walk into a bar

| Engineer | Mathematician |
|--------------------------------------------------|-------------------------------------------------------------------|
| Uses calculus | Teaches calculus |
| Can build a bridge but doesn't know why it holds | Will count the number of possible bridges |
| Likes two columns | Hates two columns |
| Has funding from industry | |
| Likes the smell of whiteboard markers | Crazy for specific chalk from Japan |
| Cares about real solutions | Invents imaginary numbers and points at ∞ just to be right |
| Wants solutions quickly | Wants correct solutions |

Realization of linear time-invariant difference equations

$$a_0 \hat{y}_i + a_1 \hat{y}_{i+1} + \cdots + a_r \hat{y}_{i+r} = 0, \quad i = 0, \dots, d-r$$

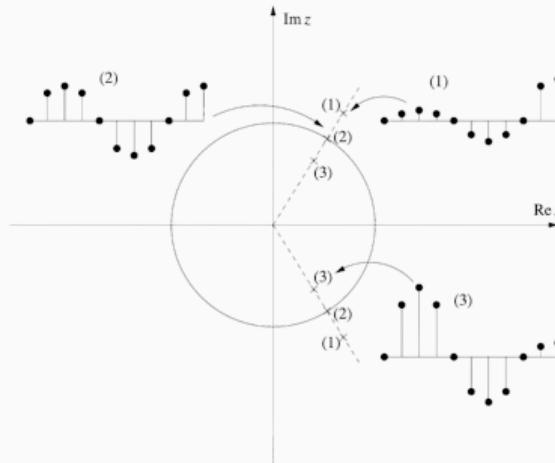
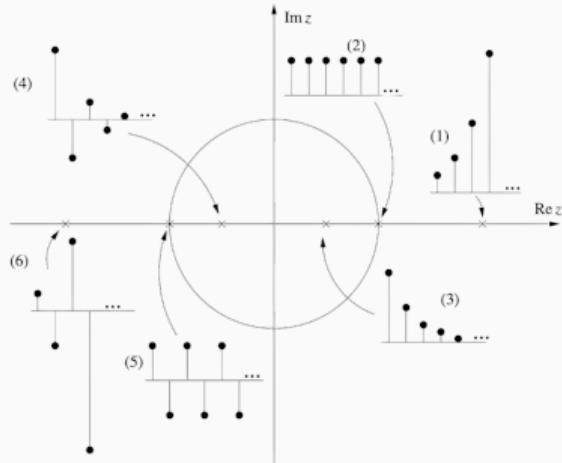
- ▷ Discrete-time (physical) system generating signals $\hat{y} = (\hat{y}_0, \hat{y}_1, \dots, \hat{y}_d)^T \in \mathbb{R}^{d+1}$
- ▷ Explain observed data with a mathematical model
- ▷ Impose a model class: *autonomous LTI models of finite order*
 - **autonomous** = no input signals, no influence from outside world
 - **linear** = linear relation between past outputs
 - **time-invariant** = coefficients $a = (a_0, \dots, a_r)^T$ are independent of time
 - **finite order** r = the relation involves at most r past outputs
- ▷ \hat{y} “model compliant” data

Roots of $a(z) = \sum_{i=0}^r a_i z^i$ determine dynamics of model

- ▷ Simple roots: Each root λ generates mode $\text{vand}(\lambda) = (1, \lambda, \lambda^2, \dots, \lambda^d)^T$

$$\hat{y} = \sum_{\lambda} c_{\lambda} \cdot \text{vand}(\lambda) = \left[\sum_{\lambda} c_{\lambda} \cdot \lambda^k \right]_{k=0}^d$$

- ▷ Multiple roots introduce *confluent Vandermonde vectors* $\frac{\partial^j}{\partial \lambda^j} \text{vand}(\lambda)$
- ▷ Magnitude of λ 's determines growth or decay, argument determines phase



Exact realization = Linear Algebra

- ▷ Model population of rabbits $\hat{y} = (2, 3, 5, 8, 13)^\top$
- ▷ $T_d(a)\hat{y} = 0$ is equivalent to $H_r(\hat{y})a = 0$
- ▷ \hat{y} satisfies LTI difference equation iff $\text{rank } H_r(\hat{y}) \leq r$, all such \hat{y} form a variety

$$\mathcal{X}_{d,r} := \left\{ \hat{y} \in \mathbb{C}^{d+1} \mid \text{rank } H_r(\hat{y}) \leq r \right\} = \widehat{\sigma_r \nu_d \mathbb{P}^1}$$

- ▷ Identify model a via kernel of Hankel matrix, $\text{Ker} \begin{bmatrix} 2 & 3 & 5 \\ 3 & 5 & 8 \\ 5 & 8 & 13 \end{bmatrix} = \mathbb{R} \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}$

$$\underbrace{\begin{bmatrix} a_0 & a_1 & \cdots & a_r \\ a_0 & a_1 & \cdots & a_r \\ \ddots & \ddots & \ddots & \ddots \\ & a_0 & a_1 & \cdots & a_r \end{bmatrix}}_{=: T_d(a) \text{ Toeplitz matrix } (d-r+1) \times (d+1)} \begin{pmatrix} \hat{y}_0 \\ \vdots \\ \hat{y}_d \end{pmatrix} = \underbrace{\begin{bmatrix} \hat{y}_0 & \hat{y}_1 & \cdots & \hat{y}_r \\ \hat{y}_1 & \hat{y}_2 & \cdots & \hat{y}_{r+1} \\ \vdots & \vdots & \ddots & \vdots \\ \hat{y}_{d-r} & \hat{y}_{d-r+1} & \cdots & y_d \end{bmatrix}}_{=: H_r(\hat{y}) \text{ Hankel matrix } (d-r+1) \times (r+1)} \begin{pmatrix} a_0 \\ \vdots \\ a_r \end{pmatrix} = 0$$

Least squares realization

- ▷ Fix a 2-norm on \mathbb{R}^{d+1} , $Q(\mathbf{y}) = \frac{1}{2}\|\mathbf{y}\|^2 = \frac{1}{2}\mathbf{y}^\top \Lambda \mathbf{y}$
- ▷ Real world scenario: Don't have access to $\hat{\mathbf{y}}$, measure noisy $y = \hat{y} + \varepsilon$
- ↝ \mathbf{y} never satisfies a difference equation exactly, rank $H_r(y) = r + 1$ almost surely
- ▷ If ε is Gaussian white noise, then closest $\hat{\mathbf{y}}$ is maximum likelihood estimator

$$\hat{\mathbf{y}} = \underset{\hat{\mathbf{y}} \in \mathcal{X}_{d,r}(\mathbb{R})}{\operatorname{argmin}} \|\mathbf{y} - \hat{\mathbf{y}}\|^2 = \underset{\hat{\mathbf{y}} \in \mathcal{X}_{d,r}(\mathbb{R})}{\operatorname{argmin}} \mathcal{L}(\hat{\mathbf{y}} \mid y = \hat{\mathbf{y}} + \varepsilon)$$

- ▷ Constraint optimization problem: Impose rank condition on $\hat{\mathbf{y}}$

$$\underset{\hat{\mathbf{y}} \in \mathbb{R}^{d+1}}{\operatorname{minimize}} \quad Q(\mathbf{y} - \hat{\mathbf{y}}) \quad \text{subject to} \quad \operatorname{rank} H_r(\hat{\mathbf{y}}) \leq r$$

$$\iff \underset{\hat{\mathbf{y}} \in \mathbb{R}^{d+1}, \mathbf{a} \in \mathbb{R}^r \setminus \{0\}}{\operatorname{minimize}} \quad Q(\mathbf{y} - \hat{\mathbf{y}}) \quad \text{subject to} \quad H_r(\hat{\mathbf{y}}) \cdot \mathbf{a} = 0$$

Heuristic approaches

- ▷ First idea goes back to Prony [PGDB95]
- ▷ Cadzow's method [Cad88] (assume standard norm on \mathbb{R}^{d+1})
 1. Compute SVD of $H_r(y) = U\Sigma V^T$, singular values $\sigma_1 \geq \dots \geq \sigma_{r+1} > 0$
 2. Setting $\sigma_{r+1} \rightsquigarrow 0$ yields rank-deficient matrix H' , but lose Hankel structure
 3. Approximate H' by Hankel matrix $H_r(y')$, lose rank-deficiency
 4. Iterate 1.-3. until convergence to rank-deficient Hankel matrix
- ▷ Eckart–Young theorem: SVD gives optimal low rank approximation of a matrix
- ▷ Other heuristic approaches: iterative quadratic maximum likelihood (IQML), Steiglitz–McBride, for a comparison see [LVVHDM01]
- ▷ What if we care about *global* minima?

Euclidean Distance Degree

- Given a variety $X \subseteq \mathbb{C}^N$ and a point $y \in \mathbb{R}^N$, find closest point on $X(\mathbb{R})$
- Distance measured using non-degenerate quadric $Q(x) = x^\top \Lambda x$

Definition (Euclidean distance degree, $\text{EDD}_Q(X)$)

The number of complex critical points of $\hat{y} \mapsto Q(\hat{y} - y)$ on X_{reg} for general $y \in \mathbb{R}^N$ is the **Euclidean Distance degree** of X (with respect to Q).

- For generic quadric obtain **generic EDD**; upper bound on specific $\text{EDD}_Q(X)$
- Here X is the r -th secant variety of the rational normal curve $\mathcal{X}_{d,1} = \nu_d(\mathbb{P}^1)$

$$X = \mathcal{X}_{d,r} = \widehat{\sigma_r \nu_d(\mathbb{P}^1)} = \{ T \in \text{Sym}^d \mathbb{C}^2 \mid \underline{\text{rk}} T \leq r \} \subseteq \mathbb{C}^{d+1}$$

- $\text{EDD}_Q(\mathcal{X}_{d,r})$ is algebraic degree of approximate rank- r decomposition

Let's get FONCy!

- ▷ $\mathbb{P}(\mathcal{X}_{d,r})$ is not smooth, $\{ (\mathbf{y}, \mathbf{a}) \in \mathbb{P}^d \times \mathbb{P}^r \mid H_r^{\mathbf{y}} \cdot \mathbf{a} = 0 \}$ is desingularization
- ↝ Prefer this formulation of the optimization problem

$$\underset{\hat{\mathbf{y}} \in \mathbb{R}^{d+1}, \mathbf{a} \in \mathbb{R}^r \setminus 0}{\text{minimize}} \quad Q(\mathbf{y} - \hat{\mathbf{y}}) \quad \text{subject to} \quad H_r(\hat{\mathbf{y}}) \cdot \mathbf{a} = 0 = T_d(\mathbf{a}) \cdot \hat{\mathbf{y}}$$

- ▷ Introduce Lagrange multipliers $\boldsymbol{\ell} \in \mathbb{R}^{d-r+1}$ to make unconstrained problem

$$\mathcal{L}_{\mathbf{y}}(\hat{\mathbf{y}}, \mathbf{a}, \boldsymbol{\ell}) = Q(\hat{\mathbf{y}} - \mathbf{y}) + \boldsymbol{\ell}^T \cdot H_r(\hat{\mathbf{y}}) \cdot \mathbf{a}$$

- ▷ First order necessary conditions for optimality:

$$0 \stackrel{!}{=} \frac{\partial \mathcal{L}_{\mathbf{y}}}{\partial \hat{\mathbf{y}}} = \Lambda(\hat{\mathbf{y}} - \mathbf{y}) + (T_d(\mathbf{a}))^T \boldsymbol{\ell}$$

$$0 \stackrel{!}{=} \frac{\partial \mathcal{L}_{\mathbf{y}}}{\partial \mathbf{a}} = (H_r(\hat{\mathbf{y}}))^T \boldsymbol{\ell} = T_{d-r}(\boldsymbol{\ell}) \hat{\mathbf{y}}, \quad 0 \stackrel{!}{=} \frac{\partial \mathcal{L}_{\mathbf{y}}}{\partial \boldsymbol{\ell}} = H_r(\hat{\mathbf{y}}) \mathbf{a} = T_d(\mathbf{a}) \hat{\mathbf{y}}$$

Lower-rank solutions are never optimal

Lemma

If (\hat{y}, a, ℓ) is a solution to the FONC with $\text{rank } H_r(\hat{y}) \leq r - 1$, then \hat{y} is **not** a local minimum of $Q(\hat{y} - y)$ on $\mathcal{X}_{d,r}$.

Idea: Can use additional degrees of freedom $\hat{y} + c \cdot \text{vand}(\lambda)$ to decrease norm

Theorem (Characterization of rank r solutions)

Consider a solution (\hat{y}, a, ℓ) , interpret $a \in S_{\leq r} := \mathbb{C}[z]_{\leq r}$, $\ell \in \mathbb{R}^{d-r+1} = S_{\leq d-r}$.

1. If $\text{rank } H_r(\hat{y}) = r$, then $\ell = g \cdot a$ (as polynomials) for some $g \in S_{\leq d-2r}$
2. If y is sufficiently random, then $\ell = g \cdot a$ also implies $\text{rank } H_r(\hat{y}) = r$.

Idea: 1. Linear algebra (apolarity) 2. Dimension argument

Putting it all together

$$0 \stackrel{!}{=} \frac{\partial \mathcal{L}_{\hat{y}}}{\partial \hat{y}} = \Lambda(\hat{y} - y) + (T_d(a))^{\top} \ell \quad \ell \stackrel{!}{=} g \cdot a$$

$$0 \stackrel{!}{=} \frac{\partial \mathcal{L}_{\hat{y}}}{\partial a} = T_{d-r}(\ell) \hat{y} \quad 0 \stackrel{!}{=} \frac{\partial \mathcal{L}_{\hat{y}}}{\partial \ell} = T_d(a) \hat{y}$$

- ▷ First equation allows to eliminate \hat{y} : $\hat{y} := y - \Lambda^{-1}(a \cdot \ell)$
- ▷ Assuming y is general, we can substitute $\ell := g \cdot a$ and simplify

Theorem

For general y , the FONC solutions (\hat{y}, a, ℓ) correspond to solutions (a, g) to

$$T_d(a)y = T_d(a)\Lambda^{-1}(T_d(a))^{\top}(T_{d-r}(a))^{\top}g = T_d(a)\Lambda^{-1}(a^2 \cdot g).$$

The isomorphism is given by $\ell = a \cdot g$, $\hat{y} = y - \Lambda^{-1}(a^2 \cdot g)$.

The bad locus

- ▷ Reduced to system of $d - r + 1$ equations in $(\textcolor{teal}{a}, \textcolor{violet}{g}) \in (\mathbb{C}^{r+1} \setminus 0) \times \mathbb{C}^{d-2r+1}$

$$T_d(a)\textcolor{teal}{y} = B_\Lambda(a)\textcolor{violet}{g}, \quad B_\Lambda(a) := T_d(a)\Lambda^{-1}(\textcolor{teal}{T}_d(a))^\top (\textcolor{teal}{T}_{d-r}(a))^\top$$

- ▷ Almost linear in $\textcolor{violet}{g}$, homogenize by $\textcolor{violet}{g}_{-1}$

$$YAG := \{ (\textcolor{teal}{y}, \textcolor{teal}{a}, (\textcolor{violet}{g}_{-1} : g)) \mid T_d(a)y \cdot \textcolor{violet}{g}_{-1} = B_\Lambda(a)\textcolor{violet}{g} \} \subseteq \mathbb{C}^{d+1} \times \mathcal{G} \times \mathbb{P}^{d-2r+1}$$

- ▷ $\textcolor{violet}{g}_{-1}$ can vanish if and only if $B_\Lambda(a)$ becomes rank-deficient for some $\textcolor{teal}{a} \neq 0$
- ▷ Good locus $\mathcal{G} := \{ \textcolor{teal}{a} \mid \text{rank } B_\Lambda(a) = d - 2r + 1 \}$, bad locus $\mathcal{B} := \mathbb{C}^{r+1} \setminus \mathcal{G}$

Lemma

YAG is a smooth irreducible global complete intersection of dimension $d + 2$ and codimension $d - r + 1$ in $\mathbb{C}^{d+1} \times \mathcal{G} \times \mathbb{P}^{d-2r+1}$

Assumption: The set $\mathbb{P}(\mathcal{B})$ should be finite. General Λ : $\mathbb{P}(\mathcal{B}) = \emptyset$

The multi-parameter eigenvalue problem

- ▷ Rearrange polynomial system to reveal MEP structure

$$T_d(a)\mathbf{y} \cdot \mathbf{g}_{-1} = B_\Lambda(a) \cdot \mathbf{g} \iff \underbrace{[T_d(a)\mathbf{y} \mid B_\Lambda(a)]}_{=: M(\mathbf{a}, \mathbf{y})} \cdot \begin{pmatrix} -\mathbf{g}_{-1} \\ \mathbf{g} \end{pmatrix} = 0$$

- ▷ This is almost homogeneous in \mathbf{y} , after projecting onto (\mathbf{a}, \mathbf{y}) we have

$$AY := \{ (\mathbf{a}, \mathbf{y}) \mid \text{rank } M(\mathbf{a}, \mathbf{y}) \leq d - 2r + 1 \} \subseteq \mathbb{P}(\mathcal{G}) \times \mathbb{P}^d$$

- ▷ AY has the structure of a projective subbundle $\mathbb{P}(\mathcal{F}) \subseteq \mathbb{P}(\mathcal{O}_{\mathbb{P}(\mathcal{G})}^{d+1})$

Theorem

AY is a smooth irreducible variety of dimension d and codimension r in $\mathbb{P}^d \times \mathbb{P}\mathcal{G}$.

- ▷ Restricting to a (general) $\mathbf{y} \in \mathbb{P}^d$, we obtain a finite reduced set of solutions!

AY is a reduced determinantal variety

Lemma

Let M be a “tall” $m \times (n + 1)$ -matrix with polynomial entries over a variety X and

$$\mathcal{K} = \{ (x, [v]) \mid M(x) \cdot v = 0 \} \subseteq X \times \mathbb{P}^n.$$

Let Z be the projection of \mathcal{K} onto X . If \mathcal{K} is reduced and for all $x \in X$ one has $\text{rank } M(x) \in \{n, n + 1\}$, then the ideal of Z is given by the $(n + 1)$ -minors of M .

$$AY := \{ (\underline{a}, \underline{y}) \mid \text{rank } M(\underline{a}, \underline{y}) \leq d - 2r + 1 \} \subseteq \mathbb{P}(\mathcal{G}) \times \mathbb{P}^d$$

Corollary

1. The prime ideal of AY is locally given by the $(d - 2r + 2)$ -minors of $M(\underline{a}, \underline{y})$.
2. Restricting to a general $\underline{y} \in \mathbb{P}^d$, the system of minors of $M(\underline{a}, \underline{y})$ defines a finite set of reduced points in $\mathbb{P}(\mathcal{G})$.

Intersection theory saves the day

$$AY := \{ (\textcolor{teal}{a}, \textcolor{teal}{y}) \mid \text{rank } M(\textcolor{teal}{a}, \textcolor{teal}{y}) \leq k \} \subseteq \mathbb{P}^r \times \mathbb{P}^d, \quad k := d - 2r + 1$$

- ▷ Assume $\mathcal{B} = \emptyset$, satisfies for general Λ
- ▷ AY has the *expected dimension* 0, hence Porteous formula applies
- ▷ $M(\textcolor{teal}{a}, \textcolor{teal}{y}) = [\textcolor{teal}{T}_d(a)\textcolor{teal}{y} \mid B_\Lambda(a)]$ has entries of degree (1, 1) and (3, 0) (k columns)

Theorem (A formula for $\text{EDD}_{\text{gen}}(\mathcal{X}_{d,r})$)

In the Chow ring $A^\bullet(\mathbb{P}^r \times \mathbb{P}^d) = \mathbb{Z}[\alpha, \beta]/\langle \alpha^{r+1}, \beta^{d+1} \rangle$ we have

$$[AY] = \left\{ \frac{1}{(1 - (\alpha + \beta))(1 - 3\alpha)^k} \right\}^r = \sum_{j=0}^r \sum_{i=0}^j \binom{k+r}{j-i} \binom{k-1+i}{i} 2^i \alpha^j \beta^{r-j}.$$

For general $\textcolor{teal}{y}$, the number of solutions is $\sum_{i=0}^r \binom{k+r}{r-i} \binom{k-1+i}{i} 2^i = \sum_{j=0}^r \binom{k-1+j}{j} 3^j$.

What if the bad locus is non-empty?

- ▷ $\mathbb{P}(\mathcal{B}) = \emptyset$ iff $B_\Lambda(a) = T_d(a)\Lambda^{-1}(T_d(a^2))^\top$ has full rank for all $a \neq 0$
- ▷ Recovers formula for $\text{EDD}_{\text{gen}}(\mathcal{X}_{d,r})$ from [OSS14, Theorem 3.7]
- ▷ If $\mathbb{P}(\mathcal{B})$ is non-empty but finite, then the determinantal formula still applies:

$$\text{EDD}_\Lambda(\mathcal{X}_{d,r}) = \sum_{j=0}^r \binom{k-1+j}{j} 3^j - (\text{multiplicity of } \mathcal{B} \text{ in ideal of minors of } M(a, \mathbf{y}))$$

Theorem

Assume that $\mathbb{P}(\mathcal{B})$ is finite. One has

$$\text{EDD}_{\text{gen}}(\mathcal{X}_{d,r}) - \deg \mathcal{B}^{\text{red}} \geq \text{EDD}_\Lambda(\mathcal{X}_{d,r}) \geq \text{EDD}_{\text{gen}}(\mathcal{X}_{d,r}) - \deg(\text{minors of } B_\Lambda(a)).$$

The latter inequality is strict if and only if the multiplicity structure of \mathcal{B} in the ideal of minors of $M(a, \mathbf{y})$ does depend on \mathbf{y} . This can be verified explicitly.

$\text{EDD}_\Lambda(\mathcal{X}_{d,r})$ for special weights

| | | $\Lambda = \mathbf{1}$ Unit | | | | $\Lambda = F$ Frobenius | | | | $\Lambda = \Theta$ Bombieri | | | |
|-----------------|----|-----------------------------|-----|-----|---|-------------------------|-----|-----|-----|-----------------------------|--------|----------|-----|
| $d \setminus r$ | | 1 | 2 | 3 | 4 | 1 | 2 | 3 | 4 | 1 | 2 | 3 | 4 |
| 1 | 1 | | | | | 1 | | | | 1 | | | |
| 2 | 4 | | | | | 2 | | | | 2 | | | |
| 3 | 7 | 1 | | | | 7 | 1 | | | 3 | 1 | | |
| 4 | 10 | 13 | | | | 6 | 9 | | | 4 | 7 | | |
| 5 | 13 | 34 | 1 | | | 13 | 34 | 1 | | 5 | 16 | 1 | |
| 6 | 16 | 64 | 40 | | | 10 | 38 | 34 | | 6 | 28 | 20 | |
| 7 | 19 | 103 | 142 | 1 | | 19 | 103 | 142 | 1 | 7 | 43..45 | 62..64 | 1 |
| 8 | 22 | 151 | 334 | 121 | | 14 | 103 | 246 | 113 | 8 | 61..65 | 134..142 | 53 |
| 9 | 25 | 208 | 643 | 547 | | 25 | 208 | 643 | 543 | 9 | 82..88 | 243..263 | 229 |

- ▶ Bombieri weights for $\mathcal{X}_{d,r}$ gives the first case where previous inequality is strict
- ▶ Efficient implementation in Macaulay2 for extensive experimentation

Thank you! Questions?

The ED discriminant

- ▶ Fixing Λ , our computation still relied on genericity of y
- ▶ The ED discriminant consists of $y \in \mathbb{C}^{d+1}$ such that the system has a multiple solution a .

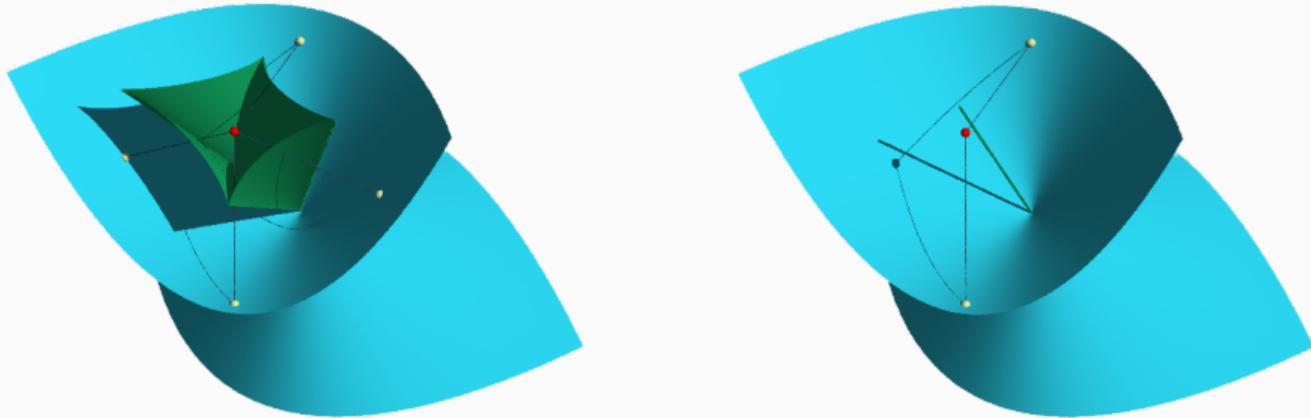


Figure 1: General (unit) and special (Bombieri) weights

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Image credit

- ▷ Slide 3: “With permission” from Sibren’s lecture on systems theory
- ▷ Slide 17: Thanks to Luca Sodomaco for letting me use his graphics!