



Technical University of Munich

DEPARTMENT OF MATHEMATICS

[Thesis Title]

Master's Thesis

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Submission Date: [Day. Month. Year]

I hereby declare that this thesis is my own work and that no other sources have been used except those clearly indicated and referenced.

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Acknowledgements

[text of acknowledgements]

German Abstract

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English Abstract

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1. Introduction

2. Continuous problem

2.1. Gateaux differentiability

Assumption 2.1.1 (Geometry assumptions for the shape optimization problem)

Let $D \subseteq \mathbb{R}^n$ be a bounded Lipschitz domain, and $\Omega_r \subset\subset D$ also bounded Lipschitz. Call $U_r := D \setminus \Omega_r$, another bounded Lipschitz domain.

Definition 2.1.2 (Admissible transformations)

Given D , we consider the set \mathcal{T} as defined in definition C.1.6, based on the perturbations Θ , also defined in definition C.1.6.

We consider $\mathcal{T}_a := \mathcal{T} \cap \{\tau \in W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n), \|\tau - \text{Id}\|_{W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n)} < C(U_r)\}$, where $C(U_r)$ is given by theorem C.1.9. This ensures that $T(U_r) \subset\subset D$ is also bounded Lipschitz, T the unique Lipschitz continuous representative of any $\tau \in \mathcal{T}_a$ (see corollary A.1.4).

Thanks to proposition C.1.8, a small Θ perturbation of $\tau \in \mathcal{T}_a$ done in the $W^{1,\infty}(D; \mathbb{R}^n)$ topology leaves us inside \mathcal{T}_a .

Note, we need T to have a Lipschitz inverse to conclude $T(U_r) \subset\subset D$: for $x \in D$, we have $0 < \delta = \inf_{d \in \partial D} |x - d| \leq \|T^{-1}\|_{W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n)} \inf_{d \in \partial D} |T(x) - d|$.

We are interested in solving the following problem.

Problem 2.1.3 (Shape optimization problem)

Suppose assumption 2.1.1, assumption B.2.1.1, assumption B.2.2.1 hold. Using the notation $T = U(\tau)$ for "unique continuous representative" of τ , we want to solve:

$$\inf_{\tau \in \mathcal{T}_a} \frac{1}{2} \|v_\tau - w_\tau\|_{L^2(I, H_T)}^2 =: J(\tau)$$

Here $v^\tau = v_0^\tau + \bar{u}$, and v_0^τ, w_τ are given in problem C.4.3 and \bar{u} is given in problem B.2.1.12. The notation for the spaces also comes from problem C.4.3, where \cdot_T means a space defined on the moving domain, $H = L^2, W = H_0^1, V = H_c^1$ (and the last space is defined in appendix B.2.1).

Observation 2.1.4 (Well posedness of J). We know from theorem B.2.1.11 that $v_0^T + \bar{u}$ doesn't depend on the particular choice of \bar{u} , therefore, for different τ 's yielding the same domain, $J(\tau)$ doesn't change.

Moreover, assumption 2.1.1 ensures in particular assumption C.4.1, which enables the applicability of theorem C.4.2.

Now, let $U := T(U_r)$, for $T \in \mathcal{T}_a$ (we write $T \in \mathcal{T}_a$ for $\tau \in \mathcal{T}_a, U(\tau) = T$) and let $\delta\theta \in \Theta$.

We are interested in finding $J'(\tau) \in \Theta^*$ such that, for all $\delta\theta_k \rightarrow 0$ in Θ , we have:

$$\lim_k \frac{|J(\tau + \delta\theta_k) - J(\tau) - J'(\tau)(\delta\theta_k)|}{\|\delta\theta_k\|_\Theta}$$

For simplicity we have put $\|\theta\|_\Theta = \|\theta\|_{W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)} = \|\theta\|_{W^{1,\infty}(D; \mathbb{R}^n)}$.

Note, $\tau + \delta\theta_k \in \mathcal{T}_a$ for large enough k . In fact, $\tau + \delta\theta_k \in \mathcal{T}$ for large k as in proposition C.1.8, and the condition on $C(U_r)$ is satisfied too, because $\theta := \tau - \text{Id}$ was already in the $W^{1,\infty}$ open ball of radius $C(U_r)$ centered at the origin, and so will be $\theta + \delta_k\theta$, always for large k .

Now, $\tau + \delta\theta_k = (\text{Id} + \delta\theta_k \circ \tau^{-1}) \circ \tau$, and $\text{Id} + \delta\theta_k \circ \tau^{-1}$ is in \mathcal{T}_a (it is in \mathcal{T} by proposition C.1.8 and the reasoning above shows it is also in \mathcal{T}_a).

We are then equivalently interested in:

$$\lim_k \frac{|J((\text{Id} + \delta\theta_k \circ \tau^{-1}) \circ \tau) - J(\tau) - J'(\tau)(\delta\theta_k)|}{\|\delta\theta_k\|_{\Theta}}$$

This amounts to setting the reference domain to $T(U_r)$ instead of U_r and perturbing the former, at least for the sake of computing derivatives.

We now introduce a Lagrangian.

For $k \geq K(T)$ we define $T_k := \text{Id} + \delta\theta_k \circ \tau^{-1} \in \mathcal{T}_a$, as seen above.

With the help and the notation of theorem C.4.2 we can set:

$$\begin{aligned} L_T(k, w, v_0, q, p) = & \frac{1}{2} \int_I \int_{T(U_r)} |v_0 + \bar{u}_T \circ T_k - w|^2 |\det(DT_k)| + \\ & \int_I (w_t, q |\det(DT_k)|)_{H_T} + (A_{T_k} \nabla w, \nabla q)_{H_T} - \int_I (g, \text{tr}_U q)_{L^2(\Gamma_f)} + \\ & \int_I (v_{0t}, p |\det(DT_k)|)_{H_T} + (A_{T_k} \nabla v_0, \nabla p)_{H_T} + \\ & \int_I ((\bar{u} \circ T_k)', p |\det(DT_k)|)_{H_T} + (A_{T_k} \nabla(\bar{u} \circ T_k), \nabla p)_{H_T} \end{aligned}$$

for $w \in Q_0(I, V_T)$, $v_0 \in Q_0(I, W_T)$, $q \in Q^0(I, V_T)$, $p \in Q^0(I, W_T)$. Remember, $A_T := (DT)^{-1}(DT)^{-t} |\det(DT)|$.

Note that to be precise, \bar{u} is an extension (any extension in fact, satisfying the conditions of problem B.2.1.12) of the Dirichlet datum f , on the moving domain $T_k(T(U_r))$. Because of this, let's fix \bar{u}_T with this property on $T(U_r)$. We show that $\bar{u}_T \circ T_k^{-1}$ satisfies the conditions stated in problem B.2.1.12.

In particular:

- composition with T preserves the smoothness of the extension, as seen in proposition A.2.2, given that $\circ T_k^{-1}$ is a linear bounded operator between V_T and $V_{T_k \circ T}$ (see C.2.1)
- the initial value is preserved, as seen in the proof of proposition C.3.1
- the trace on Σ_f is preserved, because the trace on $\Gamma_f = \partial D$ is preserved, see theorem C.2.1

Therefore we can state the following definition.

Definition 2.1.5 (Lagrangian)

For a fixed $T \in \mathcal{T}_a$ and $k \geq K(T)$, for $T_k := \text{Id} + \delta\theta_k \circ \tau^{-1} \in \mathcal{T}_a$, we define:

$$\begin{aligned} L_T(k, w, v_0, q, p) = & \frac{1}{2} \int_I \int_{T(U_r)} |v_0 + \bar{u}_T - w|^2 |\det(DT_k)| + \\ & \int_I (w_t, q |\det(DT_k)|)_{H_T} + (A_{T_k} \nabla w, \nabla q)_{H_T} - \int_I (g, \text{tr}_U q)_{L^2(\Gamma_f)} + \\ & \int_I (v_{0t}, p |\det(DT_k)|)_{H_T} + (A_{T_k} \nabla v_0, \nabla p)_{H_T} + \\ & \int_I (\bar{u}'_T, p |\det(DT_k)|)_{H_T} + (A_{T_k} \nabla \bar{u}_T, \nabla p)_{H_T} \end{aligned}$$

L_T is defined as a map $\{k \geq K(T)\} \times Q_0(I, V_T) \times Q_0(I, W_T) \times Q^0(I, V_T) \times Q^0(I, W_T) \rightarrow \mathbb{R}$.

We call $u = (w, v_0)$, $\pi = (q, p)$, $G(k, u, \pi) = L_T(k, w, v_0, q, p)$ to ease the notation.

We also call $b(k, u) = \frac{1}{2} \int_I \int_{T(U_r)} |v_0 + \bar{u}_T - w|^2 |\det(DT_k)|$ and $a(k, u, \pi) = G(k, u, \pi) - b(k, u)$, $E = Q_0(I, V_T) \times Q_0(I, W_T)$, $F = Q^0(I, V_T) \times Q^0(I, W_T)$.

Proposition 2.1.6 (Properties of the Lagrangian)

L_T satisfies the following properties:

1. $\psi \mapsto a(k, \phi, \psi)$ is linear, no matter what ϕ, k
2. G is Frechet differentiable with respect to ψ at $(k, \phi, 0)$ for all k, ϕ
3. $d_\psi G(k, \phi, 0)[\delta\psi] = 0$ for all $\delta\psi \in F$ admits a unique solution $\phi = u^k$
4. $[0, 1] \ni s \mapsto G(k, su^k + (1-s)u^0, \psi)$ is $AC[0, 1]$, no matter what k, ψ
5. G is Frechet differentiable with respect to ϕ at (k, ψ, ϕ) for all k, ψ, ϕ
6. $[0, 1] \ni s \mapsto d_\phi G(k, su^k + (1-s)u^0, \psi)[\delta\phi]$ is $L^1(0, 1)$, no matter what $k, \psi, \delta\phi$
7. there exists a unique solution $\psi = \pi^k$ to $\int_0^1 d_\phi G(k, su^k + (1-s)u^0, \psi)[\delta\phi] ds = 0$ for all $\delta\psi$

In particular $\pi^k = (Q^k \circ \tau^k, P^k \circ \tau^k)$, where we introduced the averaged adjoint problems on the moving domain:

Problem 2.1.7 (Averaged adjoint equations)

$$\begin{aligned} -Q_t^k - \Delta Q^k &= \frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1} \\ Q^k(T) &= 0 \\ \partial_\nu Q^k &= 0 \text{ on } \Sigma_f \\ Q^k &= 0 \text{ on } \Sigma_m^{T_k \circ T} \end{aligned}$$

and

$$\begin{aligned} -P_t^k - \Delta P^k &= -\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} - \bar{u}_T \circ T_k^{-1} \\ P^k(T) &= 0 \\ P^k &= 0 \text{ on } \Sigma_m^{T_k \circ T} \sqcup \Sigma_f \end{aligned}$$

Proof.

The first point is immediate.

Proof of 2

All the pieces are linear in ψ . We only check the boundedness of the various differentials. For simplicity, call $|\det(DT_k)| = d$, and note that $\|qd\|_{H_T} \leq C(d) \|q\|_{H_T}$.

And now, for instance:

$$\begin{aligned} \int_I (w_t, \delta q |\det(DT_k)|)_{H_T} &= \int_I (w_t, \delta q d)_{H_T} \leq \\ C(d) \int_I \|w_t\|_{H_T} \|\delta q\|_{H_T} &\leq C(d) \|w_t\|_{L^2(I, H_T)} \|\delta q\|_{L^2(I, H_T)} \leq \\ C(d) \|w\|_{Q(I, V_T)} \|\delta q\|_{Q(I, V_T)} &\leq C(d) \|w\|_{Q(I, V_T)} (\|\delta q\|_{Q(I, V_T)} + \|\delta p\|_{Q(I, V_T)}) = \\ &C(d) \|w\|_{Q(I, V_T)} \|\delta\psi\|_F \end{aligned}$$

Or also:

$$\int_I (g, \text{tr}_U \delta q)_{L^2(\Gamma_f)} \leq \int_I \|g\|_{L^2(\Gamma_f)} \|\delta q\|_{V_T} \leq \|g\|_{H^1(I, L^2(\Gamma_f))} \|\delta\psi\|_F$$

and:

$$\begin{aligned} \int_I (A_{T_k} \nabla \bar{u}_T, \nabla \delta p)_{H_T} &\leq C \|A_{T_k}\|_{L^\infty(D; \mathbb{R}^{n \times n})} \int_I \|\nabla \bar{u}_T\|_{L^2(I, H_T)} \|\nabla \delta p\|_{L^2(I, H_T)} \leq \\ &C(T) \|\delta \psi\|_F \|\bar{u}\|_{H^1(I, V_T)} \end{aligned}$$

Proof of 3

We get back the state equations, thanks to linearity, and by testing separately with $\delta \psi = (\delta q, 0)$ and $\delta \psi = (0, \delta p)$, so that a unique solution exists by theorem C.4.2.

Proof of 4

Every piece but b is linear or constant in the state ϕ . We only need to prove that $[0, 1] \ni s \mapsto b(k, su^k + (1-s)u^0)$ is $AC[0, 1]$. But by the structure of the cost function J , transported on $T(U_r)$, we see that the latter is a quadratic polynomial in s , hence, absolutely continuous.

Proof of 5

For the pieces with the gradients, it follows as above, by in case employing the simmetry of A_{T_k} .

Now, for instance the linear form $\delta v_0 \mapsto \int_I (\delta v_{0t}, p | \det(DT_k))_{H_T}$ is also bounded by $C(d) \|\delta v_0\|_{Q(I, W_T)} \|\delta q\|_{Q(I, V_T)}$ just like before.

What remains to check is the Frechet differentiability of b .

To do so, perturb ϕ by $\delta \phi$ and expanding the square:

$$\begin{aligned} \frac{1}{2} \int_I \int_{T(U_r)} |v_0 + \delta v_0 + \bar{u}_T - w - \delta w|^2 | \det(DT_k) | &= \\ \frac{1}{2} \int_I \int_{T(U_r)} |v_0 + \bar{u}_T - w|^2 | \det(DT_k) | &+ \\ \frac{1}{2} \int_I \int_{T(U_r)} |\delta v_0 - \delta w|^2 | \det(DT_k) | &+ \\ \int_I \int_{T(U_r)} (v_0 + \bar{u}_T - w)(\delta v_0 - \delta w) | \det(DT_k) | & \end{aligned}$$

Now, $\int_I \int_{T(U_r)} |\delta v_0 - \delta w|^2 | \det(DT_k) | \leq C(T_k) \|\delta v_0 - \delta w\|_{L^2(I, H_T)}^2 \leq C(T_k) \|\phi\|_E^2$, so that this term is of higher term.

And $\int_I \int_{T(U_r)} (v_0 + \bar{u}_T - w)(\delta v_0 - \delta w) | \det(DT_k) |$ is linear and bounded by reasonings similar to the former ones.

Proof of 6

By the last point:

$$\begin{aligned} d_\phi G(k, \phi, \psi)[\delta \phi] &= \\ \int_I ((v_0 + \bar{u}_T - w) | \det(DT_k) |, \delta v_0 - \delta w)_{H_T} &+ \\ \int_I (\delta w_t, q | \det(DT_k) |)_{H_T} + (A_{T_k} \nabla \delta w, \nabla q)_{H_T} &+ \\ \int_I (\delta v_{0t}, p | \det(DT_k) |)_{H_T} + (A_{T_k} \nabla \delta v_0, \nabla p)_{H_T} & \end{aligned}$$

so that:

$$\begin{aligned}
& d_\phi G(k, su^k + (1-s)u^0, \psi)[\delta\phi] = \\
& \int_I ((s(v_0^k + \bar{u}_T - w^k) + (1-s)(v_0^0 + \bar{u}_T - w^0)) | \det(DT_k)|, \delta v_0 - \delta w)_{H_T} + \\
& \int_I (\delta w_t, q | \det(DT_k)|)_{H_T} + (A_{T_k} \nabla \delta w, \nabla q)_{H_T} + \\
& \int_I (\delta v_{0t}, p | \det(DT_k)|)_{H_T} + (A_{T_k} \nabla \delta v_0, \nabla p)_{H_T}
\end{aligned}$$

which is a degree 1 polynomial in s , hence, $L^1(0, 1)$.

Proof of 7

Rewriting the formula above and integrating in s , we come to:

$$\begin{aligned}
& \int_0^1 d_\phi G(k, su^k + (1-s)u^0, \psi)[\delta\phi] ds = \\
& \int_I (((v_0^k + \bar{u}_T - w^k) + (v_0^0 + \bar{u}_T - w^0))/2 | \det(DT_k)|, \delta v_0 - \delta w)_{H_T} + \\
& \int_I (\delta w_t, q | \det(DT_k)|)_{H_T} + (A_{T_k} \nabla \delta w, \nabla q)_{H_T} + \\
& \int_I (\delta v_{0t}, p | \det(DT_k)|)_{H_T} + (A_{T_k} \nabla \delta v_0, \nabla p)_{H_T}
\end{aligned}$$

As in proposition C.3.1, $\delta w_t = (\delta w \circ T_k^{-1})_t \circ T_k$, where $\delta w \circ T_k^{-1} \in Q_0(I, V_{T_k \circ T})$ by proposition C.3.1 (that can be applied thanks to the smallness of T_k).

Applying a change of variables we are left with:

$$\begin{aligned}
& \int_0^1 d_\phi G(k, su^k + (1-s)u^0, \psi)[\delta\phi] ds = \\
& \int_I \left(\frac{v_0^k - w^k}{2} \circ T_k^{-1} + \frac{v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta v_0 \circ T_k^{-1} - \delta w \circ T_k^{-1} \right)_{H_{T_k \circ T}} + \\
& \int_I ((\delta w \circ T_k^{-1})_t, q \circ T_k^{-1})_{H_{T_k \circ T}} + (\nabla(\delta w \circ T_k^{-1}), \nabla(q \circ T_k^{-1}))_{H_{T_k \circ T}} + \\
& \int_I ((\delta v_0 \circ T_k^{-1})_t, p \circ T_k^{-1})_{H_{T_k \circ T}} + (\nabla(\delta v_0 \circ T_k^{-1}), \nabla(p \circ T_k^{-1}))_{H_{T_k \circ T}}
\end{aligned}$$

Here, as we saw in proposition C.3.1, we have $\delta w \circ T_k^{-1}, w \circ T_k^{-1} \in Q_0(I, V_{T_k \circ T})$, $\delta v_0 \circ T_k^{-1}, v_0 \circ T_k^{-1} \in Q_0(I, W_{T_k \circ T})$, $q \circ T_k^{-1} \in Q^0(I, V_{T_k \circ T})$ and $p \circ T_k^{-1} \in Q^0(I, W_{T_k \circ T})$.

Because $\circ T_k^{-1}$ is a bijection of $Q_0(I, W_{T_k \circ T})$ and $Q_0(I, W_{T_k})$ as we saw in C.3.1 (and analogously of V), we have that $\int_0^1 d_\phi G(k, su^k + (1-s)u^0, \psi)[\delta\phi] ds = 0$ for all $\delta\phi \in E$ if and only if:

$$\begin{aligned}
& \int_I \left(\frac{v_0^k + w^k}{2} \circ T_k^{-1} - \frac{v_0^0 + w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta V_0 - \delta W \right)_{H_{T_k \circ T}} + \\
& \int_I (\delta W_t, q \circ T_k^{-1})_{H_{T_k \circ T}} + (\nabla \delta W, \nabla(q \circ T_k^{-1}))_{H_{T_k \circ T}} + \\
& \int_I (\delta V_{0t}, p \circ T_k^{-1})_{H_{T_k \circ T}} + (\nabla \delta V_0, \nabla(p \circ T_k^{-1}))_{H_{T_k \circ T}} = 0
\end{aligned}$$

for all $\delta W, \delta V_0 \in Q_0(I, V_{T_k \circ T}), \delta V_0 \in Q_0(I, W_{T_k \circ T})$.

We wish to find a (unique) solution $(q^k, p^k) \in Q^0(I, V_T) \times Q^0(I, W_T)$ of this problem. We can equivalently (by proposition C.3.1) find $(Q^k, P^k) \in Q^0(I, V_{T_k \circ T}) \times Q^0(I, W_{T_k \circ T})$ satisfying:

$$\begin{aligned}
 & \int_I \left(\frac{v_0^k - w^k}{2} \circ T_k^{-1} + \frac{v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta V_0 - \delta W \right)_{H_{T_k \circ T}} + \\
 & \int_I (\delta W_t, Q^k)_{H_{T_k \circ T}} + (\nabla \delta W, \nabla Q^k)_{H_{T_k \circ T}} + \\
 & \int_I (\delta V_{0t}, P^k)_{H_{T_k \circ T}} + (\nabla \delta V_0, \nabla P^k)_{H_{T_k \circ T}} = 0
 \end{aligned}$$

for all $\delta W, \in Q_0(I, V_{T_k \circ T})$, $\delta V_0 \in Q_0(I, W_{T_k \circ T})$.

By testing first with $\delta W = 0$ and then with $\delta V_0 = 0$ we can equivalently look for:

$$\begin{aligned}
 & (Q^k, P^k) \in Q^0(I, V_{T_k \circ T}) \times Q^0(I, W_{T_k \circ T}) \text{ with} \\
 & \int_I (\delta W_t, Q^k)_{H_{T_k \circ T}} + (\nabla \delta W, \nabla Q^k)_{H_{T_k \circ T}} = \\
 & \int_I \left(\frac{v_0^k + w^k - v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta W \right)_{H_{T_k \circ T}} \\
 & \int_I (\delta V_{0t}, P^k)_{H_{T_k \circ T}} + (\nabla \delta V_0, \nabla P^k)_{H_{T_k \circ T}} = \\
 & - \int_I \left(\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta V_0 \right)_{H_{T_k \circ T}}
 \end{aligned}$$

An application of integration by parts in time (see proposition B.3.3) yields the problem:

$$\begin{aligned}
 & (Q^k, P^k) \in W^0(I, V_{T_k \circ T}) \times W^0(I, W_{T_k \circ T}) \text{ with} \\
 & - \int_I (Q_t^k, \delta W)_{H_{T_k \circ T}} + (\nabla \delta W, \nabla Q^k)_{H_{T_k \circ T}} = \\
 & \int_I \left(\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta W \right)_{H_{T_k \circ T}} \\
 & - \int_I (P_t^k, \delta V_0)_{H_{T_k \circ T}} + (\nabla \delta V_0, \nabla P^k)_{H_{T_k \circ T}} = \\
 & - \int_I \left(\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1}, \delta V_0 \right)_{H_{T_k \circ T}}
 \end{aligned}$$

But this is the weak formulation (cfr. theorem C.4.2, problem B.2.1.12, problem B.2.2.2) of the problems:

$$\begin{aligned}
 -Q_t^k - \Delta Q^k &= \frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1} \\
 Q^k(T) &= 0 \\
 \partial_\nu Q^k &= 0 \text{ on } \Sigma_f \\
 Q^k &= 0 \text{ on } \Sigma_m
 \end{aligned}$$

and

$$\begin{aligned}
 -P_t^k - \Delta P^k &= -\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} - \bar{u}_T \circ T_k^{-1} \\
 P^k(T) &= 0 \\
 P^k &= 0 \text{ on } \Sigma_m \sqcup \Sigma_f
 \end{aligned}$$

Applying the time reversal $t \mapsto T - t$ (where $I = [0, T]$), these are a couple of standard heat equations for which we have available existence, uniqueness and stability results (see appendix B, and proposition B.3.5).

By calling then $\pi^k = (Q^k \circ T^k, P^k \circ T^k)$ we conclude the proof. □

We now turn to the verification of Gateaux differentiability of J , applying the techniques proposed in [30].

Proposition 2.1.8 (Averaged adjoint method for Gateaux derivatives)

If $J'(\tau) \in \Theta^*$ satisfies:

$$\lim_k \frac{G(k, u^0, \pi^k) - G(0, u^0, \pi^k)}{t_k} = J'(\tau)[\delta\theta]$$

where $\delta\theta_k = t_k \delta\theta$ for $t_k \rightarrow 0$, then $J'(\tau)$ is the Gateaux derivative of J at τ .

Proof.

We have $G(k, u^k, \pi^k) - G(k, u^0, \pi^k) = \int_0^1 d_\phi G(k, su^k + (1-s)u^0, \pi^k)[u^k - u^0]ds = 0$ because $u^k - u^0 \in E$, and by absolute continuity and integrability of derivative as seen in proposition 2.1.6.

Moreover, calling $g_k = G(k, u^k, 0) - G(0, u^0, 0)$, we have:

- $g_0 = 0$
- $g_k = J((\text{Id} + \delta\theta_k \circ \tau^{-1}) \circ \tau) - J(\tau)$, thanks again to a change of variables
- $g_k = G(k, u^k, \pi^k) - G(0, u^0, \pi^k)$ thanks to $\pi^k \in F$ and the state equations (note, this is possible because k, u^k appear, and $0, u^0$ appear, so that the indices don't mix)

And now, $J(\tau + \delta\theta_k) - J(\tau) = J((\text{Id} + \delta\theta_k \circ \tau^{-1}) \circ \tau) - J(\tau) = g_k = G(k, u^k, \pi^k) - G(0, u^0, \pi^k) = G(k, u^k, \pi^k) - G(k, u^0, \pi^k) + G(k, u^0, \pi^k) - G(0, u^0, \pi^k) = G(k, u^0, \pi^k) - G(0, u^0, \pi^k)$. □

Proposition 2.1.9 (Gateaux differentiability of J)

Given $\tau \in \mathcal{T}_a$, J is Gateaux differentiable at τ with respect to the $W^{1,\infty}$ topology. The Gateaux differential is:

$$\begin{aligned} J'(\tau)[\delta\theta] = & \int_I (w_t^\tau \text{div}(\delta\theta \circ \tau^{-1}), q^\tau) + \int_I (A'(\delta\theta \circ \tau^{-1}) \nabla v^\tau, \nabla p^\tau) + \\ & \int_I (v_t^\tau \text{div}(\delta\theta \circ \tau^{-1}), p^\tau) + \int_I (A'(\delta\theta \circ \tau^{-1}) \nabla w^\tau, \nabla q^\tau) + \\ & \frac{1}{2} \int_I \int_{T(U_r)} |v^\tau - w^\tau|^2 \text{div}(\delta\theta \circ \tau^{-1}) \end{aligned}$$

where p^τ, q^τ solve:

$$\begin{aligned} -q_t^\tau - \Delta q^\tau &= v^\tau - w^\tau \\ q^\tau(T) &= 0 \\ \partial_\nu q^\tau &= 0 \text{ on } \Sigma_f \\ q^\tau &= 0 \text{ on } \Sigma_m^{T_k \circ T} \end{aligned}$$

and

$$\begin{aligned} -p_t^\tau - \Delta p^\tau &= -v^\tau + w^\tau \\ p^\tau(T) &= 0 \\ p^\tau &= 0 \text{ on } \Sigma_m^{T_k \circ T} \sqcup \Sigma_f \end{aligned}$$

and where $A'(\delta\theta) = -D\delta\theta - (D\delta\theta)^t + \text{div}(\delta\theta)$.

Proof.

The shape derivative is linear and bounded

Linearity is immediate. For the boundedness:

$$|J'(\tau)[\delta\theta]| \leq \|\operatorname{div}(\delta\theta \circ \tau^{-1})\|_{L^\infty(T(U_r))} \left(\int_I (\|q_t^\tau\|_{H^T} \|q^\tau\|_{H_T} + \|v_t^\tau\|_{H_T} \|p^\tau\|_{H_T}) + \frac{1}{2} \|v^\tau - w^\tau\|_{L^2(I, H_T)}^2 \right) + \left(\sum_{ij} \|(A'(\delta\theta \circ \tau^{-1}))_{ij}\|_{L^\infty(T(U_r))} \right) \left(\int_I \|\nabla v^\tau\|_{H_T} \|\nabla p^\tau\|_{H_T} + \int_I \|\nabla w^\tau\|_{H_T} \|\nabla q^\tau\|_{H_T} \right)$$

and then, for C independent of $\delta\theta$:

$$|J'(\tau)[\delta\theta]| \leq C \left(\|\operatorname{div}(\delta\theta \circ \tau^{-1})\|_{L^\infty(T(U_r))} + \left(\sum_{ij} \|(A'(\delta\theta \circ \tau^{-1}))_{ij}\|_{L^\infty(T(U_r))} \right) \right) \leq \|\delta\theta \circ \tau^{-1}\|_{W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)} \leq C \|\delta\theta\|_{W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)}$$

where in the last step we applied point i) of lemme 2.2, [29]. This shows the boundedness.

Conclusion

Assume $p^k \rightharpoonup p^0$ in $Q(I, W_T)$ and $q^k \rightharpoonup q^0$ in $Q(I, V_T)$.

Now, using that $u^0 = (w^\tau, v_0^\tau)$:

$$\begin{aligned} G(k, u^0, \pi^k) - G(0, u^0, \pi^k) &= \frac{1}{2} \int_I \int_{T(U_r)} |v^\tau - w^\tau|^2 |\det(DT_k)| + \\ &\int_I (w_t^\tau |\det(DT_k)|, q^k)_{H_T} + (A_{T_k} \nabla w^\tau, \nabla q^k)_{H_T} - \int_I (g, \operatorname{tr}_U q^k)_{L^2(\Gamma_f)} + \\ &\int_I (v_t^\tau |\det(DT_k)|, p^k)_{H_T} + (A_{T_k} \nabla v^\tau, \nabla p^k)_{H_T} - \\ &\frac{1}{2} \int_I \int_{T(U_r)} |v^\tau - w^\tau|^2 - \\ &\int_I (w_t^\tau, q^k)_{H_T} + (\nabla w^\tau, \nabla q^k)_{H_T} + \int_I (g, \operatorname{tr}_U q^k)_{L^2(\Gamma_f)} - \\ &\int_I (v_t^\tau, p^k)_{H_T} + (\nabla v^\tau, \nabla p^k)_{H_T} \end{aligned}$$

Grouping some terms and cancelling the boundary integral:

$$\begin{aligned} G(k, u^0, \pi^k) - G(0, u^0, \pi^k) &= \frac{1}{2} \int_I \int_{T(U_r)} |v^\tau - w^\tau|^2 (|\det(DT_k)| - 1) + \\ &\int_I (w_t^\tau (|\det(DT_k)| - 1), q^k)_{H_T} + ((A_{T_k} - I) \nabla w^\tau, \nabla q^k)_{H_T} + \\ &\int_I (v_t^\tau (|\det(DT_k)| - 1), p^k)_{H_T} + ((A_{T_k} - I) \nabla v^\tau, \nabla p^k)_{H_T} \end{aligned}$$

Now, the application $\delta\theta \mapsto \text{Id} + \delta\theta \circ \tau^{-1}$ is Frechet differentiable at $\delta\theta = 0$, as a map of Θ into \mathcal{V}^1 , with Frechet derivative $\delta\theta \circ \tau^{-1}$, which is linear and bounded by point i) of lemme 2.2, [29]. Note, we needed here $\tau \in \mathcal{T}^1$.

Also, the maps $\delta\eta \mapsto |\det(D\eta)|$ and $\eta \mapsto (D\eta)^{-1}(D\eta)^{-t}|\det D\eta|$ are Frechet differentiable at Id , from \mathcal{V}^1 into $L^\infty(\mathbb{R}^n; \mathbb{R})$ and $L^\infty(\mathbb{R}^n; \mathbb{R}^{n \times n})$, as stated in lemma 4.16, page 80 of [24]. Their Frechet derivatives are $\text{div}(\beta)$ and $I - D\beta - (D\beta)^t$, respectively.

Therefore, composition with $\delta\theta \mapsto \text{Id} + \delta\theta \circ \tau^{-1}$ yields two Frechet differentiable maps, whose derivatives at 0, in direction $\delta\theta \in \Theta$ are exactly:

- $\text{div}(\delta\theta \circ \tau^{-1})$
- $A'(\delta\theta \circ \tau^{-1})$

These maps are:

- $\delta\theta_k \mapsto |\det(DT_k)|$
- $\delta\theta_k \mapsto A_{T_k}$

Therefore:

- $|\det(DT_k)| - 1 = |\det(DT_k)| - 1 - t_k \text{div}(\delta\theta \circ \tau^{-1}) + t_k \text{div}(\delta\theta \circ \tau^{-1}) = o_k^1 + t_k \text{div}(\delta\theta \circ \tau^{-1})$
- $A_{T_k} - I = A_{T_k} - I - t_k A'(\delta\theta \circ \tau^{-1}) + t_k A'(\delta\theta \circ \tau^{-1}) = o_k^2 + t_k A'(\delta\theta \circ \tau^{-1})$

where $o_k^1 \in L^\infty(\mathbb{R}^n; \mathbb{R})$ and $o_k^2 \in L^\infty(\mathbb{R}^n; \mathbb{R}^{n \times n})$ being higher order terms, in L^∞ and with respect to t_k .

We can then write $(G(k, u^0, \pi^k) - G(0, u^0, \pi^k))/t_k = a_k + o_k$.

Here:

$$\begin{aligned} a_k := & \frac{1}{2} \int_I \int_{T(U_r)} |v^\tau - w^\tau|^2 \text{div}(\delta\theta \circ \tau^{-1}) + \\ & \int_I (w_t^\tau \text{div}(\delta\theta \circ \tau^{-1}), q^k)_{H_T} + (A'(\delta\theta \circ \tau^{-1}) \nabla w^\tau, \nabla q^k)_{H_T} + \\ & \int_I (v_t^\tau \text{div}(\delta\theta \circ \tau^{-1}), p^k)_{H_T} + (A'(\delta\theta \circ \tau^{-1}) \nabla v^\tau, \nabla p^k)_{H_T} \end{aligned}$$

Thanks to the assumed weak convergence, $a_k \rightarrow J'(\tau)[\delta\theta]$.

So, we still have to show that:

$$\begin{aligned} o_k := & \frac{1}{2} \int_I \int_{T(U_r)} |v^\tau - w^\tau|^2 o_k^1 t_k^{-1} + \\ & \int_I (w_t^\tau o_k^1 t_k^{-1}, q^k)_{H_T} + (t_k^{-1} o_k^2 \nabla w^\tau, \nabla q^k)_{H_T} + \\ & \int_I (v_t^\tau o_k^1 t_k^{-1}, p^k)_{H_T} + (t_k^{-1} o_k^2 \nabla v^\tau, \nabla p^k)_{H_T} \end{aligned}$$

goes to zero. This is true because again we can write:

$$|o_k| \leq \left\| o_k^1 t_k^{-1} \right\|_{L^\infty(T(U_r))} \left(\int_I (\|v_t^\tau\|_{H^T} \|p^k\|_{H_T} + \|v_t^\tau\|_{H_T} \|p^k\|_{H_T}) + \frac{1}{2} \|v^\tau - w^\tau\|_{L^2(I, H_T)}^2 \right) + \left(\sum_{ij} \|((t_k^{-1} o_k^2)_{ij})\|_{L^\infty(T(U_r))} \right) \left(\int_I \|\nabla v^\tau\|_{H_T} \|\nabla p^k\|_{H_T} + \int_I \|\nabla w^\tau\|_{H_T} \|\nabla q^k\|_{H_T} \right)$$

which goes to 0, thanks to the boundedness of the averaged adjoint states, which stems from their weak convergence.

We assumed $p^k \rightharpoonup p^0$ in $Q(I, W_T)$ and $q^k \rightharpoonup q^0$ in $Q(I, V_T)$. We now prove these claims.

Weak convergence of states

We show at first $v_0^k \rightharpoonup v_0^0$ in $Q(I, W_T)$ and $w^k \rightharpoonup w^0$ in $Q(I, V_T)$.

We do this by showing a bound, uniform in k .

To do this, recall that $V_0^k := v_0^k \circ T_k^{-1}$ and $W^k := w^k \circ T_k^{-1}$ satisfy, as seen in C.4.2:

$$\begin{aligned} W^k &\in Q_0(I, V_{T_k \circ T}), V_0^k \in Q_0(I, W_{T_k \circ T}) \\ \int_I (W_t^k, Q)_{H_{T_k \circ T}} + (\nabla W^k, \nabla Q)_{H_{T_k \circ T}} &= \int_I (g, \text{tr}_{T_k \circ T(U)} Q)_{L^2(\Gamma_f)}, \quad \forall Q \in Q^0(I, V_{T_k \circ T}) \\ \int_I (V_{0t}^k, P)_{H_{T_k \circ T}} + (\nabla V_0^k, \nabla P)_{H_{T_k \circ T}} &= - \int_I (U_k', P)_{H_{T_k \circ T}} + (U^k, \nabla P)_{H_{T_k \circ T}}, \quad \forall P \in Q^0(I, W_{T_k \circ T}) \end{aligned}$$

where $U^k := \bar{u} \circ T_k^{-1}$, where we used that pullbacks and time derivatives commute, see proposition C.3.1.

Thanks to theorem B.2.1.11 and theorem B.2.2.10 we obtain the stability estimates:

$$\begin{aligned} &\|V^k\|_{C([0;T], H_{T_k \circ T})}^2 + \|V^k\|_{L^2(I, H_{T_k \circ T})}^2 + \\ &\|\nabla V^k\|_{L^2(I, H_{T_k \circ T})}^2 + \|(V^k)_t\|_{L^2(I, H_{T_k \circ T})}^2 \leq \\ &\quad C \|U^k\|_{H^1(I, V_{T_k \circ T})}^2 \\ &\|W^k\|_{C([0;T], H_{T_k \circ T})}^2 + \|W^k\|_{L^2(I, H_{T_k \circ T})}^2 + \|\nabla W^k\|_{L^2(I, H_{T_k \circ T})}^2 + \\ &\quad \|W_t^k\|_{L^2(I, H_{T_k \circ T})}^2 \leq \\ &\quad C \|g\|_{H^1(I, L^2(\Gamma_f))}^2 \end{aligned}$$

where C is independent of k .

Now, consider C.2.1. It says that for almost every time:

$$\|U^k\|_{V_{T_k \circ T}} \leq \left(1 + \|\det DT_k\|_{L^\infty(\mathbb{R}^n)}\right)^{1/2} \|(DT_k)^{-1}\|_{L^\infty(\mathbb{R}^n; \mathbb{R}^{n \times n})} \|\bar{u}\|_{H^1(T(U_r); \mathbb{R}^n)}$$

and the same goes for the first derivative.

This bound is uniform on k because of the continuity of the bound, with respect to k , as seen in 4.12, page IV.6, [29].

We conclude that $\|U^k\|_{H^1(I, V_{T_k \circ T})}^2$ is bounded and we thus have that $W^k \in Q_0(I, V_{T_k \circ T})$, $V_0^k \in Q_0(I, W_{T_k \circ T})$ are bounded.

Now, for almost all times, using 4.11, page IV.6 of [29], we obtain that, for instance:

$$\|v_0^k\|_{V_T} \leq \left(1 + \|\det(DT_k)^{-1}\|_{L^\infty(\mathbb{R}^n)}\right)^{1/2} \|DT_k\|_{L^\infty(\mathbb{R}^n; \mathbb{R}^{n \times n})} \|V_0^k\|_{H^1(T_K(T(U_T)))}$$

where we remember that H_0^1 was chosen to be normed with the full H^1 norm.

The same goes for w^k and the first derivatives in time, yielding that $w^k \in Q_0(I, V_T)$, $v_0^k \in Q_0(I, W_T)$ are bounded.

We thus have $w^k \rightharpoonup w^? \in Q_0(I, V_T)$, $v_0^k \rightharpoonup v_0^? \in Q_0(I, W_T)$, in the weak topologies of, respectively, $Q(I, V_T)$, $Q(I, W_T)$, and modulo subsequences. The initial values are preserved because Q_0 is closed and convex in the Hilbert space Q (see B.3.3). The closedness follows from the fact that the embedding into continuous function is linear bounded, and evaluation at 0 is linear bounded from continuous functions.

We now prove that $w^? = w^0$, $v^? = v^0$, and this will yield the weak convergence of the whole sequence.

To prove e.g. that $v^? = v^0$, let us look at the weak formulations of v_0^k :

$$\int_I (v_{0t}^k, p | \det(DT_k)|)_{H_T} + (A_{T_k} \nabla v_0^k, \nabla p)_{H_T} + (\bar{u}', p | \det(DT_k)|)_{H_T} + (A_{T_k} \nabla \bar{u}, \nabla p)_{H_T} = 0$$

for all $p \in Q_0(I, W_T)$.

Let's analyze the first term, which is $\int_I (v_{0t}^k, p | \det(DT_k)|)_{H_T} = (v_{0t}^k, p | \det(DT_k)|)_{L^2(I, H_T)}$.

We can write:

$$\begin{aligned} (v_{0t}^k, p | \det(DT_k)|)_{L^2(I, H_T)} &= \\ (v_{0t}^k, p)_{L^2(I, H_T)} - (v_{0t}^k, p)_{L^2(I, H_T)} + (v_{0t}^k, p | \det(DT_k)|)_{L^2(I, H_T)} &= \\ (v_{0t}^k, p)_{L^2(I, H_T)} + (v_{0t}^k, p(| \det(DT_k)| - 1))_{L^2(I, H_T)} \end{aligned}$$

Because $p \in Q(I, W_T)$, the first term converges to $(v_{0t}^?, p)_{L^2(I, H_T)}$, see proposition B.3.3 for details on why we can write the time derivative of the limit. The other term can be estimated as follows:

$$\begin{aligned} |(v_{0t}^k, p(| \det(DT_k)| - 1))_{L^2(I, H_T)}| &\leq \\ \|v_{0t}^k\|_{L^2(I, H_T)} \|p(| \det(DT_k)| - 1)\|_{L^2(I, H_T)} &\leq \|v_{0t}^k\|_{L^2(I, H_T)} \|p\|_{L^2(I, H_T)} \| | \det(DT_k)| - 1 \|_{L^\infty} \end{aligned}$$

Where the first term in the product is bounded by the weak convergence property, and the last one goes to 0 by continuity, see again 4.12, page IV.6 of [29].

In a similar fashion for the other pieces, and by passing to the limit:

$$\int_I (v_{0t}^?, p)_{H_T} + (\nabla v_0^?, \nabla p)_{H_T} + (\bar{u}', p)_{H_T} + (\nabla \bar{u}, \nabla p)_{H_T} = 0$$

By uniqueness, $v^? = v^0$.

Weak convergence of averages adjoint states

So, $v_0^k \rightharpoonup v_0^0$, $w^k \rightharpoonup w^0$ in the sense of the $Q(I, W_T)$ and $Q(I, V_T)$ weak convergence.

We now claim that $p^k \rightharpoonup p^0$, $q^k \rightharpoonup q^0$, in a similar style as before. To do so, remember that $P^k := p^k \circ T_k^{-1}$ and $Q^k := q^k \circ T_k^{-1}$ solve:

$$\begin{aligned} -Q_t^k - \Delta Q^k &= \frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} + \bar{u}_T \circ T_k^{-1} \\ Q^k(T) &= 0 \\ \partial_\nu Q^k &= 0 \text{ on } \Sigma_f \\ Q^k &= 0 \text{ on } \Sigma_m \end{aligned}$$

and

$$\begin{aligned} -P_t^k - \Delta P^k &= -\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1} - \bar{u}_T \circ T_k^{-1} \\ P^k(T) &= 0 \\ P^k &= 0 \text{ on } \Sigma_m \sqcup \Sigma_f \end{aligned}$$

By proposition B.1.14, we will obtain a bound in Q of the transported averaged adjoints as soon as we have a bound on $\frac{v_0^k - w^k + v_0^0 - w^0}{2} \circ T_k^{-1}$ in the $L^2(I, H)$ norm, and of $U^k := \bar{u}_T \circ T_k^{-1}$. The latter was proven above.

So, by theorem C.2.1 and 4.12 of [29] at page IV.6, it suffices to have an $L^2(I, H)$ bound on $\frac{v_0^k + w^k + v_0^0 + w^0}{2} \circ T_k^{-1} \circ T_k = \frac{v_0^k + w^k + v_0^0 + w^0}{2}$ which we have, since we just proved that v_0^k, w^k are weakly convergent in e.g. $L^2(I, H)$.

We conclude that Q^k, P^k are bounded in the $Q(I, V_{T_k \circ T})$ and $Q(I, W_{T_k \circ T})$ sense.

But what we want is a bound on q^k, p^k in the $Q(I, V_T)$ and $Q(I, W_T)$ sense. This can be accomplished in exactly the same way as before.

We conclude that there exist $q^?, p^?$ in $Q^0(I, V_T), Q^0(I, W_T)$, that are, modulo subsequences, the weak limits of q^k, p^k .

To show e.g. $q^? = q^0$ and conclude the convergence of the full sequence, we analyze the weak formulation of q^k , which reads, after going to the moving domain and applying integration by parts in time (see B.3.3):

$$\begin{aligned} - \int_I \left(\frac{((v_0^k + \bar{u}_T - w^k) + (v_0^0 + \bar{u}_T - w^0))}{2} \right) | \det(DT_k) |, \delta w)_{H_T} + \\ - \int_I (q_t^k, \delta w | \det(DT_k) |)_{H_T} + (A_{T_k} \nabla \delta w, \nabla q^k)_{H_T} \end{aligned}$$

for all $\delta w \in Q_0(I, V_T)$.

We show the convergence of e.g. the member: $\int_I (v_0^k | \det(DT_k) |, \delta w)_{H_T}$. By splitting the scalar product as we saw above, we are left with checking that $\int_I (v_0^k, \delta w)_{H_T} \rightarrow \int_I (v_0^0, \delta w)_{H_T}$, which is true, since we proved that $v_0^k \rightharpoonup v_0^0$ in $Q(I, W_T)$.

We conclude upon convergence that:

$$\begin{aligned} - \int_I \left(\frac{((v_0^0 + \bar{u}_T - w^0) + (v_0^0 + \bar{u}_T - w^0))}{2} \right), \delta w)_{H_T} + \\ - \int_I (q_t^?, \delta w)_{H_T} + (\nabla \delta w, \nabla q^?)_{H_T} \end{aligned}$$

which is satisfied also by q^0 , therefore $q^? = q^0$ and we have weak convergence of the entire sequence.

□

2.2. Star shaped reparametrization

Here we reparametrize the problem assuming the optimization domain to be star-shaped with respect to the origin. We do this to justify the computer implementation of the solution algorithm.

Proposition 2.2.1 (Star shaped boundary)

Let $f \in C(\mathbb{S}^{n-1})$, $f > 0$. Define $\Omega_f := \{x, |x| < f(\hat{x})\} \cup \{0\}$, where $\hat{x} = x/|x|$. Then:

- Ω_f is open
- Ω_f has boundary $\{x, |x| = f(\hat{x})\}$
- Ω_f is a bounded Lipschitz domain

Proof.

For $x \in \partial\Omega_f$ (so, $x \neq 0$) we find $x_n, y_n \rightarrow x$ with $|x_n| < f(\hat{x}_n)$ and $|y_n| \geq f(\hat{y}_n)$. For large n and by continuity, $|x| = f(\hat{x})$ and we have shown one inclusion.

For the reverse, and $x, |x| = f(\hat{x})$ (so, $x \neq 0$), we define $x_n = \frac{n}{n+1}x$ which satisfies $|x_n| < |x| = f(\hat{x}) = f(\hat{x}_n)$, that is, $x_n \in \Omega_f$, and also $x_n \rightarrow x$. This shows that $x \in \partial\Omega_f$.

It is a bounded Lipschitz domain by lemma 2 at page 96 of [7], and lemma 5 at page 151 also of [7], a fact that was not discussed in [10]. Note that the definition of Lipschitz domain of [7] is completely equivalent to that of [5] (and at least implies that of [26], [20], [23], [1], a fact which is needed in the sequel), by an application of the Lebesgue number lemma, whose statement can be found at e.g. page 179 of [27].

□

We now create functions taking a radial function into a star-shaped domain. We choose $0 < \epsilon < f_D \in W^{1,\infty}(\mathbb{S}^{n-1})$, to parametrize the non moving part of the optimization domain. The reference domain is taken to be $\Omega_{f_D} \setminus \overline{B}_\epsilon$, and we call $D := \Omega_{f_D}$

Proposition 2.2.2 (H_f, A_f)

Let $\epsilon < f_D \in W^{1,\infty}(\mathbb{S}^{n-1})$ and $0 < f \in W^{1,\infty}(\mathbb{S}^{n-1})$, $f < f_D$, and define:

- $H_f(x) := \begin{cases} \frac{x}{\epsilon} f(\hat{x}) & x \neq 0 \\ 0 & x = 0 \end{cases}$, as a function $\mathbb{R}^n \rightarrow \mathbb{R}^n$
- $A_f(x) := \left(f(\hat{x}) + \frac{f_D(\hat{x}) - f(\hat{x})}{f_D(\hat{x}) - \epsilon} (|x| - \epsilon) \right) \hat{x}$, as a function $\mathbb{R}^n \setminus \{0\} \rightarrow \mathbb{R}^n$

They enjoy the following properties:

1. $H_f(B_\epsilon) = \Omega_f$, $H_f(\epsilon\mathbb{S}^{n-1}) = \partial\Omega_f$
2. $A_f(D \setminus \overline{B}_\epsilon) = D \setminus \overline{\Omega_f}$, $A_f(\partial D) = \text{Id}$, $A_f(\epsilon\mathbb{S}^{n-1}) = \partial\Omega_f$
3. $A_f = H_f$ on $\epsilon\mathbb{S}^{n-1}$
4. $H_f^{-1}(y) := \begin{cases} \epsilon \frac{y}{f(\hat{y})} & y \neq 0 \\ 0 & y = 0 \end{cases}$, as a function $\mathbb{R}^n \rightarrow \mathbb{R}^n$
5. $A_f^{-1}(y) := \left(\epsilon + \frac{f_D(\hat{y}) - \epsilon}{f_D(\hat{y}) - f(\hat{y})} (|y| - f(\hat{y})) \right) \hat{y}$, as a function $\overline{D} \setminus \Omega_f \rightarrow \overline{D} \setminus B_\epsilon$

Proof.

All the properties are straightforward from the definitions. It helps to recognize that A_f is just the linear map from the radial segment $[\epsilon, f_D(\hat{x})]$ to $[f(\hat{x}), f_D(\hat{x})]$ and that $\overline{\Omega_{f_D}} \setminus \Omega_f = \{f(\hat{x}) \leq |x| \leq f_D(\hat{x})\}$ □

They also satisfy a bi-Lipschitz condition.

Proposition 2.2.3 (Bi-Lipschitz condition)

We have that $A_f : \overline{D} \setminus B_\epsilon \rightarrow \overline{D} \setminus \Omega_f$ is Lipschitz with Lipschitz inverse (bi-Lipschitz), and so is $H_f : \mathbb{R}^n \rightarrow \mathbb{R}^n$.

Proof.

The second part of the proposition is contained in [10] in a weaker form, we therefore proceed to prove all the statements.

H_f

We can assume both $x, y \neq 0$. Then $|f(\hat{x})x - f(\hat{y})y| \leq |x||f(\hat{x}) - f(\hat{y})| + f(\hat{y})|x - y|$. Employing direct and reverse triangle inequalities we get $|\hat{x} - \hat{y}| \leq \frac{2}{|x|}|x - y|$.

As f is Lipschitz (see [10]) we obtain: $|f(\hat{x})x - f(\hat{y})y| \leq |x|C(f)\frac{2}{|x|}|x - y| + C(f)|x - y|$.

Now, $1/f$ is also Lipschitz and bounded, because $f > 0$ and is continuous on a compact set. Thus the same proof shows the Lipschitz property also for H_f^{-1} .

 A_f

Call $A_f(x) = \left(f(\hat{x}) + \frac{f_D(\hat{x}) - f(\hat{x})}{f_D(\hat{x}) - \epsilon}(|x| - \epsilon)\right)\hat{x} =: Q(x)\hat{x}$. Because $|x| \geq \epsilon$, as before, we obtain $|A_f(x) - A_f(y)| \leq 2/\epsilon Q(x)|x - y| + |Q(x) - Q(y)|$, so that we need to show that Q is bounded Lipschitz.

By continuity and compactness, $f_D(\hat{x}) - \epsilon \geq \delta > 0$ and boundedness follows. The Lipschitz property follows because Q is sums of products of bounded Lipschitz functions. For instance, $f_D(\hat{x})$ is bounded and Lipschitz because $|x| \geq \epsilon$, as before, and so is $f_D(\hat{x}) - \epsilon$. Is is a bounded Lipschitz function that is uniformly above δ , so that its reciprocal is also a bounded Lipschitz function.

Analogous reasonings let us prove also the Lipschitz property of A_f^{-1} .

□

We now try to glue H_f, A_f together and still obtain a bi-Lipschitz function. Even the Lipschitz property need not to hold in general, see page 7 of [34] for a counterexample. We therefore proceed to the proof of this fact.

Proposition 2.2.4 (Gluing H_f^{-1}, A_f^{-1})

H_f^{-1}, A_f^{-1} , or also A_f, H_f can be glued into a Lipschitz function $\overline{D} \rightarrow \overline{D}$.

Proof.

Call τ_f^{-1} the gluing. It is Lipschitz $\overline{D} \rightarrow \overline{D}$ if and only if $\tau_f^{-1} \circ H_f$ is Lipschitz $H_f^{-1}(\overline{D}) \rightarrow \mathbb{R}^n$, because we proved that H_f is bi-Lipschitz $\mathbb{R}^n \rightarrow \mathbb{R}^n$.

We are therefore left to prove that gluing Lipschitz function on \mathbb{S}^{n-1} produces a Lipschitz function, which would also yield the claim for τ_f , the gluing of A_f, H_f . Note that by the preceding proposition, all the functions to be glued are Lipschitz and agree on their overlaps.

Gluing lemma for Lipschitz functions on \mathbb{S}^{n-1}

Let $A \supseteq \overline{B_\epsilon}$. Suppose $g : A \rightarrow \mathbb{R}^n$ and $h : \overline{B_\epsilon} \rightarrow \mathbb{R}^n$ are Lipschitz and agree on $\epsilon\mathbb{S}^{n-1}$. Call f their gluing.

For the proof we can assume that $x \in B_\epsilon, y \in A \setminus \overline{B_\epsilon}$.

Then, $|f(x) - f(y)| \leq |h(x) - h(\epsilon\hat{y})| + |g(\epsilon\hat{y}) - g(y)|$.

We claim at first that $|y - \epsilon\hat{y}| \leq |x - y|$. To see this, choose $n := \hat{y}$. Then $|y - x|^2 \geq |(y - x) \cdot nn|^2$ by Pythagoras' theorem, so that $|y - x| \geq |(y - x) \cdot n| = |(y - \epsilon\hat{y}) \cdot n + (\epsilon\hat{y} - x) \cdot n|$. But $(y - \epsilon\hat{y}) \cdot n = |y| - \epsilon \geq 0$, and $(\epsilon\hat{y} - x) \cdot n = \epsilon - x \cdot n \geq 0$ as $x \cdot n \leq |x| \leq \epsilon$.

Thus $|y - x| \geq |(y - \epsilon\hat{y}) \cdot n| + |(\epsilon\hat{y} - x) \cdot n| \geq |(y - \epsilon\hat{y}) \cdot n| = |y - \epsilon\hat{y}|$.

We also claim that $|x - \epsilon\hat{y}| \leq |x - y|$. To do so, pick $n := \frac{\epsilon\hat{y} - x}{|\epsilon\hat{y} - x|}$. By Pythagoras' theorem we obtain $|y - x| \geq |(y - x) \cdot n| = |(y - \epsilon\hat{y}) \cdot n + (\epsilon\hat{y} - x) \cdot n|$. The second summand is non-negative and for the first one, it is directly proportional to $(y - \epsilon\hat{y}) \cdot (\epsilon\hat{y} - x) = (|y| - \epsilon)(\epsilon - \hat{y} \cdot x) \geq 0$. So, $|x - y| \geq |(\epsilon\hat{y} - x) \cdot n| = |\epsilon\hat{y} - x|$.

Thus $|f(x) - f(y)| \leq C|x - y|$ as desired.

□

Corollary 2.2.5 (Radial to volumetric transformation)

Let again $\epsilon < f_D \in W^{1,\infty}(\mathbb{S}^{n-1})$ and $0 < f \in W^{1,\infty}(\mathbb{S}^{n-1})$, $f < f_D$. Define:

$$\bullet \tau_f(x) := \begin{cases} x & |x| \geq f_D(\hat{x}) \\ \left(f(\hat{x}) + \frac{f_D(\hat{x}) - f(\hat{x})}{f_D(\hat{x}) - \epsilon} (|x| - \epsilon) \right) \hat{x} & \epsilon \leq |x| \leq f_D(\hat{x}) \\ \frac{x}{\epsilon} f(\hat{x}) & 0 < |x| \leq \epsilon \\ 0 & |x| = 0 \end{cases}$$

$$\bullet \tau_f^{-1}(y) := \begin{cases} y & |y| \geq f_D(\hat{y}) \\ \left(\epsilon + \frac{f_D(\hat{y}) - \epsilon}{f_D(\hat{y}) - f(\hat{y})} (|y| - f(\hat{y})) \right) \hat{y} & f(\hat{y}) \leq |y| \leq f_D(\hat{y}) \\ \epsilon \frac{y}{f(\hat{y})} & 0 < |y| \leq f(\hat{y}) \\ 0 & |y| = 0 \end{cases}$$

Then $\tau_f \in \mathcal{T}$.

Proof.

The final gluing on the border of D yields a Lipschitz function: we can see this by taking $\text{Id} - \tau_f^{\pm 1}$, which is Lipschitz and 0 on ∂D , so that we are considering the zero extension outside D of a Lipschitz function, null on ∂D . This extension is Lipschitz. □

Note that, as long as $f < f_D$, $\tau_f(B_\epsilon)$ will always be bounded Lipschitz.

We finally have a look at shape derivatives in this radial framework. The cost functional will be $j(q) := J(\tau_{\epsilon+q})$, where $0 < q + \epsilon < f_D$. We are interested, for $h \in W^{1,\infty}(\mathbb{S}^{n-1})$, in the limits

$$\lim_{t \rightarrow 0} \frac{j(q + th) - j(q)}{t}$$

But this is:

$$\lim_{t \rightarrow 0} \frac{J(\tau_{\epsilon+q+th}) - J(\tau_{\epsilon+q})}{t}$$

Now, we derive the expression of a displacement field V_h , to connect this difference quotient to the already computed shape derivative, see also [10]. The ansatz $\tau_{q+th} = (\text{Id} + tV_h \circ \tau_q^{-1}) \circ \tau_q$ brings us to $V_h = \frac{\tau_q + th - \tau_q}{t}$, and by some computations, we obtain:

$$V_h(x) = \tau_f(x) := \begin{cases} 0 & |x| \geq f_D(\hat{x}) \\ h(\hat{x}) \frac{f_D(\hat{x}) - |x|}{f_D(\hat{x}) - \epsilon} \hat{x} & \epsilon \leq |x| \leq f_D(\hat{x}) \\ \frac{x}{\epsilon} h(\hat{x}) & 0 < |x| \leq \epsilon \\ 0 & |x| = 0 \end{cases}$$

This expression only depends on h and is the gluing of Lipschitz functions, that are either 0 at the gluing points, or such that the gluing points lie in $\epsilon \mathbb{S}^{n-1}$. Note, this vector field is just moving $\epsilon \mathbb{S}^{n-1}$ by h and radially damping this movement to 0 close to ∂D . We can therefore conclude:

Proposition 2.2.6 (Shape derivative, star shaped case)

We have the following facts, for $h \in W^{1,\infty}(\mathbb{S}^{n-1})$:

- $\tau_{q+th} = (\text{Id} + tV_h \circ \tau_q^{-1}) \circ \tau_q$
- $V_h \in \Theta$
- j is Gateaux differentiable at every $0 < q < f_D$, $q \in W^{1,\infty}(\mathbb{S}^{n-1})$, with $j'(q)[h] = J'(\tau_{\epsilon+q})[V_h]$

Proof.

We only need to show that $h \mapsto V_j$ is linear bounded $W^{1,\infty}(\mathbb{S}^{n-1}) \rightarrow \Theta$. Linearity is immediate and for the boundedness: $\sup_x |V_h(x)| = \|h\|_\infty$, and we only therefore need to bound the Lipschitz constant of V_h .

We only need to restrict ourselves to \overline{D} , as extending to zero a Lipschitz function doesn't increase its Lipschitz constant.

The gluing lemma proposition 2.2.4 shows that it is sufficient to bound the Lipschitz constants of the two branches, separately.

These bounds are respectively: $C(\epsilon)(\|h\|_\infty + 2\|D_T h\|_\infty)$ and $[2\epsilon^{-1}(\|D_T h\|_\infty + \|h\|_\infty)]C(f_D, \epsilon) + C(f_D, \epsilon)\|h\|_\infty$, which concludes the proof. □

2.2.1. Smoother star shaped domains

We want to increase the regularity of f and see an increase in the regularity of $\partial\Omega_f$.

Proposition 2.2.1.1 (Smooth radial function yields smooth star shaped domain)

Let $f > 0$ which is either $C^{1,1}(\mathbb{S}^{n-1})$ (that is, C^1 with all the components of $D_T f$ Lipschitz) or $C^2(\mathbb{S}^{n-1})$. We say $f \in C^o(\mathbb{S}^{n-1})$.

Then, Ω_f has boundary of class C^o .

Proof.

A punctured diffeomorphism of class C^o

We consider H_f , neglecting the ϵ factor. It has gradient (see [10]) $DH_f(x) = f(\hat{x})I + \hat{x} \otimes D_T f(\hat{x})$, and $DH_f^{-1}(y) = 1/f(\hat{y})I - 1/f(\hat{y})^2 \hat{y} \otimes D_T f(\hat{y})$. They are C^o away from the origin. In particular H_f is C^o outside of $B_\delta(0)$, $\delta < 1$. $H_f(B_\delta)$ also contains a ball around the origin, and the complement contains Ω_f .

We conclude that $H_f : \overline{B_\delta(0)}^c \rightarrow \overline{H_f(B_\delta(0))}^c$ is a C^o diffeomorphism, where the right set is open by H_f being a homeomorphism of \mathbb{R}^n . The Lipschitz regularity of the gradients follows from the Lipschitz and boundedness of every factor, and the fact that we are setting ourselves away from the origin. In particular, $D_T f$ is Lipschitz, therefore continuous, on the sphere, and so bounded too.

We have therefore obtained a homeomorphism $\mathbb{R}^n \rightarrow \mathbb{R}^n$, which is C^o as $\overline{B_\delta(0)}^c \rightarrow \overline{H_f(B_\delta(0))}^c$, so, in a neighbourhood of $\partial\Omega_f$.

For simplicity let's refer to such maps as C^o punctured diffeomorphisms for Ω_f .

Punctured diffeomorphism and C^o domains

Let Ω be of class C^o (always locally) and bounded. Assume we have F , a punctured diffeomorphism for Ω , so, $F : \mathbb{R}^n \rightarrow \mathbb{R}^n$ is a homeomorphism, and $F : U \rightarrow F(U)$ is C^o , $\partial\Omega \subset\subset U$. Then, by analyzing the composition of F with (small enough) charts of Ω we see that $F(\Omega)$ is another C^o domain (local sense).

From diffeomorphisms to graphs

Let Ω be any C^o domain, $x \in \partial\Omega$. We obtain $A \ni x$, B open, and $\phi : A \rightarrow B$ a C^o diffeomorphism, with $\phi^{-1}(B \cap \mathbb{R}_+^n) = A \cap \Omega$, and $\phi(x) = 0$.

ϕ is a C^1 diffeomorphism, so $D\phi_n(x) \neq 0$, and we can assume $D\phi_n(x)$ to be proportional to $-e_n$ by a rotation of the axis.

Thus $\partial_n \phi_n(z) < 0$ in some $B(x) \subseteq A$. $B(x)$ is chosen small that ϕ is Lipschitz on $B(x)$.

Apply the implicit function theorem to obtain V', I open with $x \in V' \times I \subseteq B(x)$ and a function $\eta : V' \rightarrow I$ that is C^o and Lipschitz, with $\phi_n(z', z_n) = 0 \iff z_n = \eta(z')$, for $z \in V' \times I$.

V' is open around x' , so let's restrict it to a square centered at x' . Relabel η as the restriction to this new V' and restrict I to be the connected component of G hosting $\eta(V')$, which is now an interval, as continuous image of a connected set. Because $x_n \in I$, and by continuity, V' can be shrunk such that $\eta(V') \subset\subset J \subset\subset I$ for some open interval J .

All these shrinkings don't change the character of being the implicit function, i.e. η still satisfies $\phi_n(z', z_n) = 0 \iff z_n = \eta(z')$, for $z \in V' \times I$, and also, $x \in V' \times I \subseteq B(x)$ and $\eta : V' \rightarrow I$ is still C^o and Lipschitz.

Now, the choice of $B(x)$ makes $z_n \mapsto \phi(z', z_n)$ strictly decreasing, for $(z', z_n) \in B(x)$. So, for $z \in V' \times I$, we have $\phi_n(z', z_n) = \phi_n(z) > 0 = \phi_n(z', \eta(z')) \iff z_n < \eta(z')$ (by basic properties of strictly decreasing functions).

But also, $\phi_n(z) > 0 \iff \phi(z) \in B \cap \mathbb{R}_+^n \iff z \in \phi^{-1}(\mathbb{R}_+^n \cap B) = A \cap \Omega$.

Therefore, $z \in V' \times I, z_n < \eta_n(z) \iff z \in V' \times I, \phi_n(z) > 0 \iff z \in A \cap \Omega \cap (V' \times I) = (V' \times I) \cap \Omega$.

Summing up we have the following:

- a square and an interval V', I with $V' \times I \ni x$
- $\eta : V' \rightarrow I$, Lipschitz, of class C^o
- $\phi(V') \subset\subset J \subset\subset I$
- $z \in V' \times I, z_n < \eta_n(z) \iff z \in (V' \times I) \cap \Omega$
- (and consequently, $z \in V' \times I, z_n = \eta_n(z) \iff z \in (V' \times I) \cap \partial\Omega$)

Conclusion

Let a radial function $f > 0$ be of class C^o . Thanks to H_f , a punctured diffeomorphism of class C^o , we have that $\partial\Omega_f$ is the image of $\epsilon\mathbb{S}^{n-1}$, a domain of class C^o as well, locally. So Ω_f is of class C^o locally, in the sense of diffeomorphisms, and by what we showed, also in the sense of graphs.

So, for $x \in \partial\Omega_f$ we can find a change of coordinates and a parallelepiped $V = V' \times I$ with $\phi : V' \rightarrow I$, ϕ of class C^o and also Lipschitz, and $V \cap \Omega_f = V \cap \{x_n < \phi(x')\}$. We have moreover that $\phi \in J \subset\subset I$ for some open interval J . By a compactness argument, finitely many $V_j = V'_j \times (a_n^j, b_n^j)$ are necessary to cover $\partial\Omega_f$.

So, we have $V_j \cap \Omega_f = V_j \cap \{x_n < \phi_j(x')\} = V \cap \{a_n^j < x_n < \phi_j(x'), x' \in V'_j\}$. Choose $d > 0$ to be the minimum gap between ϕ_j and I_j . $d > 0$ by the existence of $J_j \subset\subset I_j$. We call L the maximum Lipschitz constant of ϕ_j .

We have therefore a Lipschitz and C^o domain in the style of [7], which yields, modulo an application of the Lebesgue number lemma, a C^o and Lipschitz domain in the style of [20].

Remarks about the usage of the implicit function theorem

Examining the proofs of the inverse and implicit function theorems as given e.g. at pages 310, 311 of [18], we see that solving $f = 0$ for f Lipschitz and C^o , yields a Lipschitz and C^o implicit function.

□

A. Functional spaces

A.1. Sobolev spaces

Theorem A.1.1 (Integration by parts)

Let Ω be a bounded Lipschitz domain. Let $1 < p < \infty$ and $f, g \in W^{1,p}(\Omega), W^{1,q}(\Omega)$, $q = p'$. Then:

$$\int_{\Omega} f \partial_i g = - \int_{\Omega} g \partial_i f + \int_{\partial\Omega} f \nu_i d\mathcal{H}^{n-1}$$

Proof.

This follows from [23], theorem 18.1 at page 592, where g needs to be $C_c^1(\mathbb{R}^n)$. But [1], theorem 3.18 at page 54, says that (thanks to the smoothness of the boundary) the set of the restriction of such functions is dense in $W^{1,q}(\Omega)$, so that we can conclude by a density argument [developed here](#).

□

Lemma A.1.2

$f \in L^\infty(\Omega; \mathbb{R}^N) \iff f_i \in L^\infty$, and two equivalent norms are $\|f\|_a := \|f\|_\infty$, $\|f\|_b := \max_i \|f_i\|_\infty$, for $|\cdot|$ any finite dimensional norm.

Proof.

We choose $|\cdot| = |\cdot|_1$.

Consider $f_n \in X_a = \{[f], f : \Omega \rightarrow \mathbb{R}^n \text{ measurable}, \|f\|_a\}$, Cauchy. Then every component is Cauchy in the scalar L^∞ , so that $f_n^i \rightarrow f^i$ in L^∞ . The limit f is in X_a because the functions $|f_i|$ are essentially bounded, and so is $|f|$.

Then $\|f_n - f\|_a \leq \|f_n - f_m\|_a + \sum_i \|f_m^i - f^i\|_\infty$ for all n, m . Choose $m \geq n$ with $\|f_m^i - f^i\|_\infty \leq 1/(Nn)$ and conclude X_a is Banach.

We know from [23], theorem B.88 at page 671, and page 669, we know that $X_b = \{[f], f : \Omega \rightarrow \mathbb{R}^n \text{ measurable}, \|f\|_b\}$ is Banach.

Moreover $X_a = X_b$ as sets, so that the thesis follows.

□

Proposition A.1.3 (Characterization of $W^{1,\infty}$)

Let Ω be a bounded Lipschitz domain, or \mathbb{R}^n . Then $W^{1,\infty}(\Omega) = C^{0,1} \cap L^\infty(\Omega)$.

This means that $u \in W^{1,\infty}(\Omega)$ if and only if u has a (unique) representative that is bounded, Lipschitz continuous. Weak and classical derivatives coincide a.e.

Proof.

Extension

In the case Ω is bounded Lipschitz, then Ω is an extension domain for $W^{1,\infty}(\Omega)$, meaning that there is $E : W^{1,\infty}(\Omega) \rightarrow W^{1,\infty}(\mathbb{R}^n)$ linear bounded with $Eu = u$ a.e. on Ω (see [23], theorem 13.17 at page 425, 13.13 at page 424, and definition 9.57 at page 273).

The proof

Let $u \in W^{1,\infty}(\Omega)$. By [23], 11.50 at page 339, because Ω is an extension domain, we obtain that u has a representative \bar{u} that is bounded Lipschitz. Let $\phi \in C_c^\infty(\Omega)$. By The Kirszbraun theorem (see e.g. [2]), we can extend \bar{u} to a Lipschitz function e on \mathbb{R}^n . Then, for a large enough cube Q containing Ω , $\int_\Omega \bar{u} \partial_i \phi = \int_Q e \partial_i \phi = - \int_Q \partial_i e \phi$, by Fubini's theorem and integration by parts for AC functions.

Because $e = \bar{u}$ on Ω , we conclude $\int_\Omega \bar{u} \partial_i \phi = - \int_\Omega \partial_i \bar{u} \phi$, so that $\nabla \bar{u} = \nabla u$ almost everywhere.

Conversely, let u be bounded Lipschitz. The above reasoning shows that u has essentially bounded weak derivatives equal to the a.e. classical derivatives.

□

Corollary A.1.4 ($W^{k,\infty} = C_B^{k,1}$)

For a bounded Lipschitz domain Ω , or for $\Omega = \mathbb{R}^n$, then $W^{k,\infty} = C_B^{k,1}$ ($C^{k,1}$ bounded functions with bounded classical derivatives up to order $k+1$).

Proof.

We have already proved the case $k=1$. We prove, for instance, the case $k=2$. Then, $u \in W^{k,2} \implies u, \partial_i u \in W^{k,1}$ ([23], 11.7 at page 321), so that by proposition A.1.3, we find bounded Lipschitz h, g_i with $u = h$ a.e., $\partial_i u = \partial_i h$ a.e., $g_i = \partial_i u$ a.e..

Therefore h is continuous, with continuous weak derivatives g_i , which implies that $h \in C^1(\Omega)$ (see [here](#) and [here](#)).

Now, $\partial_i h = g_i$ a.e., so everywhere, so that:

- h is bounded Lipschitz and C^1
- $\partial_i h$ are bounded Lipschitz

□

A.2. Bochner spaces

Here are some useful results about Bochner spaces.

Proposition A.2.1 (Bochner integral and bounded operators)

Let X, Y be separable Banach, let $T \in L(X, Y)$ be a linear bounded operator. For $f \in L^1(I, X)$ define $Tf(t) := T(f(t))$. Then $Tf \in L^1(I, Y)$ with $T \int_I f = \int_I Tf$.

Proof.

First of all, a clarification on the definition. What is really happening is that from the time equivalence class f , we select a g , and then $Tf(t) := T(g(t))$. Tf is then the equivalence class of $t \mapsto Tg(t)$. The definition is well posed, because $g_1(t) = g_2(t) \implies T(g_1(t)) = T(g_2(t))$.

Let f_n be simple, $f_n \rightarrow f$ a.e., with $\lim_n \int_I f_n = \int_I f$ and $\|f_n\|_X \leq C \|f\|_X$ (see page 6, and corollary 2.7 at page 8 of [22]).

Measurability

For almost all t , $T(f_n(t)) \rightarrow T(f(t)) = Tf(t)$ in Y , so that Tf is measurable (strongly).

Integrability

By the assumptions, $\|Tf_n\| \leq \|T\| \|f_n\| \leq C \|f\| \in L^1(I)$, so that by dominated convergence (corollary 2.6 of [22]) Tf is integrable too. Thus $\int_T Tf = \lim_n \int_I Tf_n = \lim_n T \int_I f_n$, because f_n is simple. And now, by the choice of f_n , $\int_T Tf = \lim_n T \int_I f_n = T \lim_n \int_I f_n = T \int_I f$.

□

Proposition A.2.2 (Derivations and bounded operators)

As before, let X, Y be separable Banach, let $T \in L(X, Y)$ be a linear bounded operator.

For $k \geq 0$, $f \in H^k(I, X) \implies Tf \in H^k(I, Y)$, with weak derivatives $\partial_{t^i} Tf = T\partial_{t^i} f$, $0 \leq i \leq k$.

The map $f \mapsto Tf$, $H^k(I, X) \rightarrow H^k(I, Y)$ is linear, and bounded by $\|T\|$.

Proof.

The case $k = 0$ is proved above.

We prove now that $\partial_{t^i} Tf = T\partial_{t^i} f$ for $i = 1$. Note that $T\partial_{t^i} f \in L^2(I, Y)$, which qualifies as weak derivative.

In fact, for $\phi \in C_c^\infty(I)$, we have $\int_I \phi T\partial_{t^i} f = \int_I T(\phi\partial_{t^i} f) = T \int_I \phi\partial_{t^i} f = -T \int_I \phi' f = - \int_I \phi' Tf$.

Higher weak derivatives are treated analogously and the rest of the claims follow from the time stationarity of T and by $\|\partial_{t^i} Tf\| = \|T\partial_{t^i} f\| \leq \|T\| \|\partial_{t^i} f\|$.

□

Proposition A.2.3 (Continuous representatives)

Let X be separable Banach. $f \in L^1(I, X)$ has at most a continuous representative on $[0, T]$.

Proof.

Assume there exists two such continuous representatives, so that we get a function $\delta : [0, T] \rightarrow X$ that is zero almost everywhere and continuous. Hence, $[0, T] \ni t \mapsto \|\delta(t)\|$ is continuous in \mathbb{R} and zero a.e., so that it must be zero everywhere. □

We now check that a vector valued test function has weak derivatives of all orders.

Proposition A.2.4 (Weak derivatives of test functions)

Let $\phi \in C^1([0, T], X)$, for X separable Banach. It means that the limit of the difference quotients exists for all points of I , that $t \mapsto \phi(t), \phi'(t)$ are continuous, and that they can be continuously extended to $[0, T]$.

Then these classical derivatives coincide a.e. with the weak derivatives of u .

Proof.

We rely on proposition 3.8 of [22] at page 26.

Absolute continuity

Consider $\epsilon > 0$. Divide $[a, b] \subset\subset (0, T)$ into a uniform partition t_i . By theorem 6 at page 146 of [17], we get that $\|\phi(t_i) - \phi(t_{i-1})\|_X \leq (t_i - t_{i-1}) \|\phi(\xi_i)\|_X \leq (b-a) \|\phi'\|_\infty / n$, and by choosing n small enough, we conclude that ϕ is (locally) absolutely continuous.

Weak derivative

Therefore, ϕ is locally AC, differentiable everywhere and ϕ' is bounded, so that $\phi \in H^1(I, X)$ and weak and classical derivatives coincide.

□

And now, introduce a time dependent version of the trace operator which is useful for our computations.

Definition A.2.5 (Time dependent trace)

Let Ω be a bounded Lipschitz domain. For $k \geq 0$ we define $\text{tr} : H^k(I, H^1(\Omega)) \rightarrow H^k(I, H^{1/2}(\partial\Omega))$ by $\text{tr}(u)(t) := \text{tr}(u(t))$

Below are some properties of this operator.

Proposition A.2.6 (Properties of trace operator)

The trace operator just defined:

1. is well posed
2. is linear bounded
3. admits a linear bounded right inverse, for instance, $E(g)(t) := E(g(t))$ (for E a right inverse of the static trace)
4. tr and E , in the case of $k \in \mathbb{N}_0$, coincide (in the time a.e. sense) for the case $l \geq k$
5. for $k \geq 1$, $\text{tru}(0) = 0 \iff u(0) = 0$ (in the sense of continuous representatives)
6. it coincides with the trace treated for instance in [25]

Proof.

Proof of the proposition

We recall that the trace operator is bounded surjective onto $H^{1/2}(\partial\Omega)$, with a right inverse E (see theorem 3.37 at page 102 of [26]).

The first three points are consequences of this fact and of proposition A.2.1.

The fourth property follows by the definition of tr , E and the fact that $H^l \subseteq H^k$, for $k \leq l$.

Let now $k \geq 1$. We know that $H^1, H^{1/2}$ are separable and Banach (the latter is separable because the continuous image of H^1 separable, and Banach (see [20], page 20). Therefore, by [15], theorem 2 of page 286, we obtain the embeddings $H^k(I, H^1) \hookrightarrow C([0, T], H^1)$ and the same goes for $H^k(I, H^{1/2})$. The embedding is U , the unique continuous representative of a certain time equivalence class (proposition A.2.3). We also introduce brackets to indicate equivalence classes in time, so, $u = [Uu]$.

We want to prove $(Uu)(0) = 0 \iff U(\text{tru})(0) = 0$. But we have $[t \mapsto U(\text{tru})(t)] = \text{tru} := [t \mapsto \text{tr}((Uu)(t))]$. So, $U(\text{tru})(t) = \text{tr}((Uu)(t))$ for all $t \in [0, T]$ by continuity.

For the last point, let $k = 0$. We have:

1. $H^1(\Omega) \cap C^1(\overline{\Omega})$ is dense in $H^1(\Omega)$ (see [1], theorem 3.18 at page 54, where being Ω bounded Lipschitz is important)
2. functions $\sum_{i \leq m} \phi_i(t) f_i$ for $\phi_i \in C_c^\infty(I)$, $f_i \in H^1(\Omega) \cap C^1(\overline{\Omega})$ are dense in $L^2(I, H^1)$ (see [21], page 39, lemma 1.9)

It follows by the third point that $C^1(\overline{\Omega \times I})$ is dense in $L^2(I, H^1)$, so that $u \mapsto u|_{I \times \partial\Omega}$ admits a unique extension by continuity to $L^2(I, H^1)$, so that this definition of trace coincides with the one from the literature in the case of the space $H^{1,0} := L^2(I, H^1)$ (see [25], theorem 4.1), we expand this argument below.

Proof of leftover facts

We call $C^k(\overline{\Omega}) := \{u \in C^k(\Omega) \text{ with } \partial_\alpha f \text{ extendable by continuity to } \overline{\Omega}\}$.

Consider $u(x, t) := \phi(t)v(x)$, for $\phi \in C^1([0, T])$, $v \in C^1(\overline{\Omega})$. Then, it has partial derivatives $u_t = \phi_t v$, $u_i = \phi u_i$. u and all its partial derivatives are continuous on $I \times \Omega$, meaning that $u \in C^1(\Omega \times I)$.

Moreover, $u, u_i, u_t \in C([0, T], C(\overline{\Omega}))$. We claim $C([0, T], C(\overline{\Omega})) = C(\overline{\Omega \times I})$. In fact, one direction is trivial, and so, let $f \in C([0, T], C(\overline{\Omega})) = C(\overline{\Omega})$. Fix $(t, x) \in \overline{\Omega \times I}$. Then, $|f(s, y) - f(t, x)| \leq |f(t, y) - f(t, x)| + |f(t, y) - f(s, y)| \leq |f(t, y) - f(t, x)| + \|f(t, \cdot) - f(s, \cdot)\|_\infty$. If now s is close to t , and y is close to x , then $|f(s, y) - f(t, x)|$ is small.

This shows $u, u_i, u_t \in C([0, T], C(\overline{\Omega})) \in C(\overline{\Omega \times I})$, i.e. $u \in C^1(\overline{\Omega \times I})$.

To conclude, let $u \in L^2(I, H^1)$. Approximate u by $u_k := \sum_{i \leq m_k} \phi_i^k(t) f_i^k$ as in point 2, and approximate f_i^k by suitable $g_i^k \in H^1(\Omega) \cap C^1(\overline{\Omega})$, to obtain $u_k := \sum_{i \leq m_k} \phi_i^k(t) g_i^k$

Then $\|u - u_k\|_{L^2(I, H^1)} \leq \|u_k - w_k\|_{L^2(I, H^1)} + \|u_k - u\|_{L^2(I, H^1)}$. We only need to estimate $\|u_k - w_k\|_{L^2(I, H^1)} \leq T \sum_{i \leq m_k} \|\phi_i^k\|_\infty \|f_i^k - g_i^k\|_{H^1}$.

By the first point, $\|f_i^k - g_i^k\|_{H^1}$ can be made as small as it is necessary to conclude.

Last remarks

Again with reference to [25], consider the anisotropic spaces $H^{r,s} := L^2(I, H^r) \cap H^s(I, L^2)$. We restrict to the case $r = 1$,

$s \geq 0$. Denote the traces tr_s defined in theorem 4.1, mapping $H^{1,s}(\Omega \times I) \rightarrow H^{1/2,s/2}(\partial\Omega \times I)$. For $\partial\Omega$ Lipschitz this theorem is still valid, as $1/2 \leq 1$, see the discussion above lemma 2.4 in [9]. As stated in [25], tr_s is an extension of $u \mapsto u|_{I \times \partial\Omega}$, defined on the dense suspace $C^\infty(\bar{Q} \times \bar{I})$ of $H^{1,s}$ (that this space is dense can be proved as in lemma 2.22 of [9]). So, let $C^\infty(\bar{Q} \times \bar{I}) \ni u_n \rightarrow_{H^{r,s}} u \in H^{1,s}$.

We have $\text{tr}_s u_n = \text{tr}_0 u_n$. Then, $u_n \rightarrow_{H^{1,s}} u$, $u_n \rightarrow_{H^{1,0}} u$, so that $\text{tr}_s u_n \rightarrow_{H^{1/2,s/2}} \text{tr}_s u$ (hence $\text{tr}_0 u_n \rightarrow_{H^{1/2,0}} \text{tr}_s u$) and $\text{tr}_0 u_n \rightarrow_{H^{1/2,0}} \text{tr}_\sigma u$.

Thus $\text{tr}_0 u = \text{tr}_s u$.

Using what we derived before, we can conclude the characterization of the traces in the anisotropic settign define

□

And now some sanity checks in the case of Gelfand triples.

Proposition A.2.7 (Sanity checks for Gelfand triples)

Consider the following Gelfand triples (the diagram commutes):

$$\begin{array}{ccccc} V & & & & V^* \\ & \searrow a & & \nearrow a^* & \\ & & H & \xrightarrow{r} & H^* \\ & \nearrow b & & \searrow b^* & \\ W & & & & W^* \end{array}$$

Here $W \subseteq V \subseteq H$ are all separable Hilbert spaces, a, b, c the trivial injections, r the Riesz isomorphism of H . We denote by i_V the Gelfand triple embedding $V \hookrightarrow V^*$, so, $i_V = a^* r a$.

Then:

1. $H^1(I, V) \subseteq W(I, V)$ with continuous embedding. The $W(I, V)$ derivative of $u \in H^1(I, V)$ is $i_V u_t$.
2. for $u \in W(I, W)$ with $(i_W u)' \in L^2(I, H)$ (i.e. $(i_W u)_t = b^* r h$ for h in $L^2(I, H)$) we obtain $u \in W(I, V)$ (i.e. $cu \in W(I, V)$), with derivative $(i_V cu)' = a^* r h$, so that also $(i_V cu)' \in L^2(I, H)$. It also holds $(i_V cu)'|_W = (i_W u)'$. h is also the weak derivative $L^2(I, H)$ of bu .
3. let $u, v \in W(I, V)$ with $u - v \in W$. Then $u - v \in W(I, W)$ with derivative $(i_W(u - v))' = (i_V u)'|_W - (i_V v)'|_W$.

Proof.

We use several times that time integrals and bounded linear static operators commute, see proposition A.2.1. ϕ denotes $\phi \in C_c^\infty(I)$.

First point

We need to check that $a^* r a u \in H^1(I, V^*)$. This follows from proposition A.2.2, so that $(a^* r a u)_t = a^* r a u_t$.

Second point

At first we claim that h is a weak derivative of $bu \in L^2(I, H)$. In fact, $b^* r \int_I bu \phi' = \int_I (i_W u) \phi' = \{ u \in W(I, W) \} = - \int_I (i_W u)' \phi = - \int_I b^* r h \phi = b^* r (- \int_I h \phi)$. By density (definition of Gelfand triple), b^* is injective, r is too, and thus $\int_I bu \phi' = - \int_I h \phi$, which shows that bu has weak derivative h , in the $H^1(I, H)$ sense.

And now $\int_I i_V cu \phi' = \int_I a^* r a cu \phi' = a^* r \int_I bu \phi' = \{ \text{by what we just proved} \} = -a^* r \int_I h \phi$, proving that $(i_V cu)' = a^* r h$.

Morevoer $(i_V cu)'|_W = c^* a^* r h = b^* r h = \{ \text{assumption} \} = (i_W u)'$.

Third point

We check the derivative. We have $\int_i i_W(u - v) \phi' = \{ u - v \in W \subseteq V \} = \int_I b^* r a(u - v) = c^* \int_I (i_V u - i_V v) \phi' = - \int c^* ((i_V u)' - (i_V v)') \phi$.

□

B. Parabolic equations

B.1. Abstract theory

Assumption B.1.1 (Basic assumption for parabolic problems)

Let $V \subseteq H$ be real separable Hilbert spaces, V dense in H . Then $H \hookrightarrow V^*$ is also dense, as stated in [33] at page 147. This embedding is $H \ni f \mapsto (f, \cdot)_H$. We thus obtain a Gelfand triple, and we have $W(I, V) \subseteq C(I, H)$.

Let $A : V \rightarrow V^*$ be linear bounded, $u \in W(I; V)$, $f \in L^2(I, V^*)$ and $u_0 \in H$.

We also assume that $\langle Av, v \rangle_{V^*, V} + \lambda \|v\|_H^2 \geq \alpha \|v\|_V^2$ for $\lambda \geq 0, \alpha > 0$.

We are interested in the following problem:

Problem B.1.2 (Abstract parabolic equation)

$$u_t + Au = f \text{ in } V^* \text{ and for a.e. } t \in (0, T) \quad (\text{B.1.3})$$

$$u(0) = u_0 \quad (\text{B.1.4})$$

Theorem B.1.5 (Basic well posedness of problem B.1.2)

Under assumption B.1.1, problem B.1.2 has a unique solution u . Moreover u satisfies the energy estimate:

$$\|u\|_{W(I, V)} + \|u\|_{C([0, T], H)} \leq c(\lambda, \alpha, \|A\|_{V^*}, T)(\|u_0\|_H + \|f\|_{L^2(I, V^*)}) \quad (\text{B.1.6})$$

Proof.

See [19] at page 19, theorem 26. □

We can also obtain additional regularity. Here are further assumptions to make this possible.

Assumption B.1.7 (Assumptions for additional regularity)

We assume $u_0 \in V$, $f = f_1 + f_2 \in L^2(I, H) + H^1(I, V^*)$. We also need A to be symmetric (i.e. $\langle Au, v \rangle_{V^*, V} = \langle Av, u \rangle_{V^*, V}$).

Theorem B.1.8 (Regularity of time derivative)

Suppose assumption B.1.1 and assumption B.1.7. Then $u_t \in L^2(I, H)$ with the estimate:

$$\|u\|_{W(I, V)} + \|u\|_{C(I, H)} + \|u_t\|_{L^2(I, H)} \leq \quad (\text{B.1.9})$$

$$c(\lambda, \alpha, \|A\|_{V^*}, T)(\|u_0\|_V + \|f_1\|_{L^2(I, H)} + \|f_2\|_{H^1(I, V^*)}) \quad (\text{B.1.10})$$

That $u_t \in L^2(I, H)$ means precisely that there is $h \in L^2(I, H)$ with $a^* r h = (i_V u)'$, with the notation introduced in proposition A.2.7.

Proof.

We refer to page 26 of [19], theorem 28, and only prove the necessary modifications.

Product rule for A

We have

$$\begin{aligned} \int_0^t \langle Au_n, u'_n \rangle_{V^*, V} &= \sum_{k, l \leq n} \langle Aw_k^n, w_l^n \rangle_{V^*, V} \int_0^t g_k^n g_l^{n'} = \\ &= \sum_{k, l \leq n} \langle Aw_k^n, w_l^n \rangle_{V^*, V} \left(- \int_0^t g_k^{n'} g_l^n + g_k^n(t) g_l^n(t) - g_k^n(0) g_l^n(0) \right) \end{aligned}$$

By linearity at first and then symmetry we get:

$$\begin{aligned} &= \langle Au_n, u_n \rangle_{V^*, V}(t) - \langle Au_n, u_n \rangle_{V^*, V}(0) - \int_0^t \langle Au'_n, u_n \rangle_{V^*, V} = \\ &= \langle Au_n, u_n \rangle_{V^*, V}(t) - \langle Au_n, u_n \rangle_{V^*, V}(0) - \int_0^t \langle Au_n, u'_n \rangle_{V^*, V} \end{aligned}$$

so that:

$$\int_0^t \langle Au_n, u'_n \rangle_{V^*, V} = \frac{1}{2} (\langle Au_n, u_n \rangle_{V^*, V}(t) - \langle Au_n, u'_n \rangle_{V^*, V}(0))$$

Estimate for right hand side

We have:

$$\int_0^t \langle f_2, u'_n \rangle_{V^*, V} = \sum_{k \leq n} \int_0^t g_k^{n'} \langle f_2, w_k^n \rangle_{V^*, V}$$

By the smoothness of f_2 we have that $t \mapsto \langle f_2(t), w_k^n \rangle_{V^*, V}$ is $H^1(0, T)$, in particular $AC[0, t]$, so that we can integrate by parts:

$$\begin{aligned} &= - \sum_{k \leq n} \int_0^t g_k^n \langle f'_2, w_k^n \rangle_{V^*, V} + \sum_{k \leq n} g_k^n(t) \langle f_2(t), w_k^n \rangle_{V^*, V} - \sum_{k \leq n} g_k^n(0) \langle f_2(0), w_k^n \rangle_{V^*, V} = \\ &\quad - \int_0^t \langle f'_2, u_n \rangle_{V^*, V} + \langle f_2, u_n \rangle_{V^*, V}(t) - \langle f_2, u_n \rangle_{V^*, V}(0) \end{aligned}$$

Here we have used proposition A.2.2 to take the derivative inside the bracket.

Note that by the smoothness of f_2 , we can write, for instance, $\langle f_2, u_n \rangle_{V^*, V}(0) = \langle f_2(0), u_n \rangle_{V^*, V}$.

NB: here I need $f_2(0) \in V$ probably, but I'm not yet using the compatibility condition!

Going to the absolute values:

$$\begin{aligned} \left| \int_0^t \langle f_2, u'_n \rangle_{V^*, V} \right| &\leq \int_0^T |\langle f'_2, u_n \rangle_{V^*, V}| + \|f_2(t)\|_{V^*} \|u_n(t)\|_V + \|f_2(0)\|_{V^*} \|u_n(0)\|_V \leq \\ &\quad \frac{1}{2} \|f'_2\|_{L^2(I, V^*)}^2 + \frac{1}{2} \|u_n\|_{L^2(I, V)}^2 + \frac{\alpha}{4} \|u_n(t)\|_V^2 + \\ &\quad + \frac{4}{\alpha} \|f_2\|_{L^\infty(I, V^*)}^2 + \frac{1}{2} \|f_2\|_{L^\infty(I, V^*)}^2 + \frac{1}{2} \|u_{n0}\|_V^2 \end{aligned}$$

Now, u_n converges weakly in $L^2(I, V)$ by estimate (59) of [19] and thus $\frac{1}{2} \|u_n\|_{L^2(I, V)}$ is bounded. The term $\frac{\alpha}{4} \|u_n(t)\|_V$ can be pulled to the left hand side, u_{0n} is V convergent hence bounded. Therefore as in [19] we are able to conclude that u'_n is bounded in $L^2(I, H)$. We want to conclude $u_t \in L^2(I, H)$. We know for sure that $\langle u'_m, w_j \rangle_{V^*, V} = \langle f - Au_m, w_j \rangle_{V^*, V}$, so

that muliplication by a test function and integration yields $\int_I \langle u'_m, w_j \phi \rangle_{V^*, V} = \int_I \langle f - Au_m, w_j \phi \rangle_{V^*, V}$. Because $u_m \rightharpoonup u$ in $L^2(I, V)$ we observe that, by proposition A.2.1 applied on $A \in L(V, V^*)$, it holds $\int_I \langle u'_m, w_j \phi \rangle_{V^*, V} \rightarrow \int_I \langle u', w_j \phi \rangle_{V^*, V}$.

What's more, is that $u'_m \rightharpoonup h$ in $L^2(I, H)$, so that $\int_I \langle h, w_j \rangle_{V^*, V} \phi = \int_I \langle u', w_j \rangle_{V^*, V} \phi$. It means that for almost all t , $\langle h, w_j \rangle_{V^*, V} = \langle u', w_j \rangle_{V^*, V}$. And now we can really say that $u' \in L^2(I, H)$, which even more precisely means $(i_V u)' = a^* r h$ almost everywhere.

We also obtain that u_t is bounded by $c(\alpha)(\|f_2\|_{L^\infty(I, V^*)} + \|f_2\|_{L^2(I, V^*)} + \|u_0\|_V + \|u\|_{L^2(I, V)})$.

Note that, by [15], theorem 2 of page 286, we can estimate $\|f_2\|_{L^\infty(I, V^*)}$ by $c(T) \|f_2\|_{H^1(I, V^*)}$, so that the claim for the time derivative u_t is proven. □

For the case where $H = L^2$, $H^1 \supseteq V \supseteq H_0^1$, $f_2|_{H_0^1} = 0$ we have even more regularity available.

Theorem B.1.11 (Additional regularity)

Suppose assumption B.1.1 and assumption B.1.7.

Let additionally $H = L^2$, $H^1 \supseteq V \supseteq H_0^1$, $f_2|_{H_0^1} = 0$. Then $Au|_{H_0^1}$ extends to $\overline{Au|_{H_0^1}} \in L^2(I, H)$ with:

$$\|u\|_{W(I, V)} + \|u\|_{C([0, T], H)} + \|u_t\|_{L^2(I, H)} + \left\| \overline{Au|_{H_0^1}} \right\|_{L^2(I, H)} \leq \quad (\text{B.1.12})$$

$$c(\lambda, \alpha, \|A\|_{V^*}, T)(\|u_0\|_V + \|f_1\|_{L^2(I, H)} + \|f_2\|_{H^1(I, V^*)}) \quad (\text{B.1.13})$$

Moreover $u_t + \overline{Au|_{H_0^1}} = f_1$ in $L^2(0, T, L^2) \cong L^2(Q)$ and $\overline{Au|_{H_0^1}} = Au$ on H_0^1 .

Proof.

For $v \in H_0^1$ we get $\langle Au, v \rangle_{V^*, V} = \langle f_1 - u_t, v \rangle_{V^*, V} = (f_1 - u_t, v)_H$, for almost all $t \in (0, T)$. From here we conclude that $Au(t)$ extends for a.a. t to an element of H with $(\overline{Au} - f_1 + u_t, v)_{L^2} = 0$ for all $v \in H_0^1$, almost all t . By density, $\overline{Au} - f_1 + u_t = 0$ in H for almost all t , so that $\overline{Au} = f_1 - u_t$ in $L^2(0, T, L^2) \cong L^2(Q)$.

This isometric isomorphism is stated in [33], page 144. □

For our applications we also need to track the constants more precisely, which is accomplished in the next proposition.

Proposition B.1.14 (Tracking the costants)

With assumption B.1.1 there holds:

$$\|u\|_{C([0, T], H)}^2 + \alpha \|u\|_{L^2(I, V)}^2 \leq \exp(2\lambda T)(\|u_0\|_H^2 + \alpha^{-1} \|f\|_{L^2(I, V^*)}^2) \quad (\text{B.1.15})$$

$$\|u'\|_{L^2(I, V^*)} \leq \|A\|_{L(V, V^*)} \alpha^{-1/2} \sqrt{\exp(2\lambda T)} \|u_0\|_H + \quad (\text{B.1.16})$$

$$\left(\|A\|_{L(V, V^*)} \alpha^{-1} \sqrt{\exp(2\lambda T)} + 1 \right) \|f\|_{L^2(I, V^*)} \quad (\text{B.1.17})$$

With additionally assumption B.1.7 we obtain:

$$C \|u'\|_{L^2(I, H)}^2 \leq (1 + (1 + C_0)\alpha^{-1}) \|f_2\|_{H^1(I, V^*)}^2 + \quad (\text{B.1.18})$$

$$(1 + \|A\|_{L(V, V^*)}) \|u_0\|_V^2 + C_0 \|u_0\|_H^2 + \quad (\text{B.1.19})$$

$$\|f_1\|_{L^2(I, H)}^2 + C_0 \alpha^{-1} \|f_1\|_{L^2(I, V^*)}^2 \quad (\text{B.1.20})$$

with $C > 0$ a number independent of the problem.

Here $C_0 = 2^{-1} \max(1, \lambda) \max(1, \alpha^{-1}) \exp(2\lambda T)$.

Proof.

No regularity

From page 21 of [19] we obtain that $\|u\|_{C([0, T], H)}^2 + \alpha \|u\|_{L^2(I, V)}^2 \leq \exp(2\lambda T)(\|u_0\|_H^2 + \alpha^{-1} \|f\|_{L^2(I, V^*)}^2)$. **NOTA BENE, this is slightly wrong, i.e. a 2 is missing from the left hand side.**

In particular, $\sqrt{\alpha} \|u\|_{L^2(I,V)} \leq \sqrt{\exp(2\lambda T)}(\|u_0\|_H + \alpha^{-1/2} \|f\|_{L^2(I,V^*)})$, or $\|u\|_{L^2(I,V)} \leq \alpha^{-1/2} \sqrt{\exp(2\lambda T)}(\|u_0\|_H + \alpha^{-1/2} \|f\|_{L^2(I,V^*)})$.

Moreover $\|u'\|_{L^2(I,V^*)} \leq \|Au\|_{L^2(I,V^*)} + \|f\|_{L^2(I,V^*)} \leq \|A\| \|u\|_{L^2(I,V)} + \|f\|_{L^2(I,V^*)}$.

All in all, we obtain:

$$\|u\|_{C([0,T],H)}^2 + \alpha \|u\|_{L^2(I,V)}^2 \leq \exp(2\lambda T)(\|u_0\|_H^2 + \alpha^{-1} \|f\|_{L^2(I,V^*)}^2)$$

and:

$$\|u'\|_{L^2(I,V^*)} \leq \|A\|_{L(V,V^*)} \alpha^{-1/2} \sqrt{\exp(2\lambda T)}(\|u_0\|_H + \alpha^{-1/2} \|f\|_{L^2(I,V^*)}) + \|f\|_{L^2(I,V^*)}$$

More regularity

We tie back to page 25 of [19]. In particular:

$$\int_0^t \|u'_n\|_H^2 + \int_0^t \langle Au_n, u'_n \rangle_{V^*,V} = \int_0^t (f_1, u'_n)_H + \int_0^t \langle f_2, u'_n \rangle_{V^*,V}$$

Then:

$$\int_0^t \langle Au_n, u'_n \rangle_{V^*,V} \geq \frac{\alpha}{2} \|u_n(t)\|_V^2 - \frac{\lambda}{2} \|u_n(t)\|_H^2 - \frac{\|A\|}{2} \|u_{n0}\|_V$$

whereas, as in the proof of theorem B.1.8:

$$\begin{aligned} \left| \int_0^t \langle f_2, u'_n \rangle_{V^*,V} \right| &\leq \frac{1}{2} \|f'_2\|_{L^2(I,V^*)}^2 + \frac{1}{2} \|u_n\|_{L^2(I,V)}^2 + \frac{\alpha}{4} \|u_n(t)\|_V^2 + \\ &\quad + \frac{4}{\alpha} \|f_2\|_{L^\infty(I,V^*)}^2 + \frac{1}{2} \|f_2\|_{L^\infty(I,V^*)}^2 + \frac{1}{2} \|u_{n0}\|_V^2 \end{aligned}$$

Also:

$$\int_0^t (f_1, u'_n)_H \leq \frac{1}{2} \|f_1\|_{L^2(I,H)}^2 + \frac{1}{2} \int_0^t \|u'_n\|_H^2$$

Putting all together:

$$\begin{aligned} \int_0^t \|u'_n\|_H^2 + \frac{\alpha}{2} \|u_n(t)\|_V^2 - \frac{\lambda}{2} \|u_n(t)\|_H^2 - \frac{\|A\|}{2} \|u_{n0}\|_V \\ \frac{1}{2} \|f'_2\|_{L^2(I,V^*)}^2 + \frac{1}{2} \|u_n\|_{L^2(I,V)}^2 + \frac{\alpha}{4} \|u_n(t)\|_V^2 + \\ + \frac{4}{\alpha} \|f_2\|_{L^\infty(I,V^*)}^2 + \frac{1}{2} \|f_2\|_{L^\infty(I,V^*)}^2 + \frac{1}{2} \|u_{n0}\|_V^2 + \\ + \frac{1}{2} \|f_1\|_{L^2(I,H)}^2 + \frac{1}{2} \int_0^t \|u'_n\|_H^2 \end{aligned}$$

which brings us to:

$$\frac{1}{2} \int_0^t \|u'_n\|_H^2 + \frac{\alpha}{4} \|u_n(t)\|_V^2 - \frac{\lambda}{2} \|u_n(t)\|_H^2 \leq \quad (\text{B.1.21})$$

$$\frac{1}{2} \|f'_2\|_{L^2(I,V^*)}^2 + \frac{1}{2} \|u_n\|_{L^2(I,V)}^2 + \quad (\text{B.1.22})$$

$$+ \frac{8+\alpha}{2\alpha} \|f_2\|_{L^\infty(I,V^*)}^2 + \frac{1+\|A\|}{2} \|u_{n0}\|_V^2 + \quad (\text{B.1.23})$$

$$+ \frac{1}{2} \|f_1\|_{L^2(I,H)}^2 \quad (\text{B.1.24})$$

and thus, because norms are lower semicontinuous and because we have weak convergence of the time derivative, and V -strong convergence of the initial data:

$$\begin{aligned} \frac{1}{2} \int_0^T \|u'\|_H^2 &\leq \frac{1}{2} \|f_2'\|_{L^2(I, V^*)}^2 + \frac{8+\alpha}{2\alpha} \|f_2\|_{L^\infty(I, V^*)}^2 + \frac{1+\|A\|}{2} \|u_0\|_V^2 + \frac{1}{2} \|f_1\|_{L^2(I, H)}^2 + \\ &\quad \limsup_n \left(\frac{\lambda}{2} \|u_n\|_{C([0, T], H)}^2 + \frac{1}{2} \|u_n\|_{L^2(I, V)}^2 \right) \end{aligned}$$

Using a purely numeric constant C without dependences on the problem we can write:

$$\begin{aligned} \int_0^T \|u'\|_H^2 &\leq \|f_2'\|_{L^2(I, V^*)}^2 + C(1+\alpha^{-1}) \|f_2\|_{L^\infty(I, V^*)}^2 + C(1+\|A\|) \|u_0\|_V^2 + \|f_1\|_{L^2(I, H)}^2 + \\ &\quad C \limsup_n \left(\frac{\lambda}{2} \|u_n\|_{C([0, T], H)}^2 + \frac{1}{2} \|u_n\|_{L^2(I, V)}^2 \right) \end{aligned}$$

For the last term, employing the exact argument as in the first part of the proof:

$$\limsup_n \left(\frac{\lambda}{2} \|u_n\|_{C([0, T], H)}^2 + \frac{1}{2} \|u_n\|_{L^2(I, V)}^2 \right) \leq \quad (\text{B.1.25})$$

$$2^{-1} \max(1, \lambda) \max(1, \alpha^{-1}) \limsup_n \left(\|u_n\|_{C([0, T], H)}^2 + \alpha \|u_n\|_{L^2(I, V)}^2 \right) \leq \quad (\text{B.1.26})$$

$$2^{-1} \max(1, \lambda) \max(1, \alpha^{-1}) \exp(2\lambda T) (\|u_0\|_H^2 + \alpha^{-1} \|f_1 + f_2\|_{L^2(I, V^*)}^2) \leq \quad (\text{B.1.27})$$

$$2^{-1} \max(1, \lambda) \max(1, \alpha^{-1}) \exp(2\lambda T) (\|u_0\|_H^2 + 2\alpha^{-1} \|f_1\|_{L^2(I, V^*)}^2 + 2\alpha^{-1} \|f_2\|_{L^2(I, V^*)}^2) \leq \quad (\text{B.1.28})$$

$$CC_0(\|u_0\|_H^2 + \alpha^{-1} \|f_1\|_{L^2(I, V^*)}^2 + \alpha^{-1} \|f_2\|_{L^2(I, V^*)}^2) \quad (\text{B.1.29})$$

where $C_0 = 2^{-1} \max(1, \lambda) \max(1, \alpha^{-1}) \exp(2\lambda T)$ and C is a purely numeric constant without dependences on the problem.

Therefore:

$$\begin{aligned} C \int_0^T \|u'\|_H^2 &\leq \|f_2'\|_{L^2(I, V^*)}^2 + (1+\alpha^{-1}) \|f_2\|_{L^\infty(I, V^*)}^2 + (1+\|A\|) \|u_0\|_V^2 + \|f_1\|_{L^2(I, H)}^2 + \\ &\quad C_0(\|u_0\|_H^2 + \alpha^{-1} \|f_1\|_{L^2(I, V^*)}^2 + \alpha^{-1} \|f_2\|_{L^2(I, V^*)}^2) \end{aligned}$$

The embedding $H^1(I, V^*) \hookrightarrow C([0, T], V^*)$ has norm that only depends on T , which follows from the equality $f_2(t) = f_2(s) + \int_s^t f_2'$, for $0 \leq s \leq t \leq T$, a bound being $1 + T$.

Thus:

$$\begin{aligned} C \int_0^T \|u'\|_H^2 &\leq (1 + (1 + C_0)\alpha^{-1}) \|f_2\|_{H^1(I, V^*)}^2 + \\ &\quad (1 + \|A\|) \|u_0\|_V^2 + C_0 \|u_0\|_H^2 + \\ &\quad \|f_1\|_{L^2(I, H)}^2 + C_0 \alpha^{-1} \|f_1\|_{L^2(I, V^*)}^2 \end{aligned}$$

□

Proving higher time regularity under additional compatibility assumptions and smoothness of the data can alternatively be done as follows.

Proposition B.1.30 (Higher time regularity)

Let $k \geq 1$. Suppose $f \in H^k(I, V^*)$, together with:

- $g_j := f^{(j-1)}(0) - Ag_{j-1} \in H$, for $j = k$
- $g_{j-1} \in V$ for $1 \leq j \leq k$

where $g_0 = u_0$.

Then, there holds, for $1 \leq j \leq k$:

$$\begin{cases} u^{(j+1)} + Au^{(j)} = f^{(j)} \\ u^{(j)}(0) = f^{(j-1)}(0) - Ag_{j-1} \end{cases}$$

In particular $u \in H^k(I, V)$, and $u^{(k+1)} \in L^2(I, V^*)$. One can prove, with the help of theorem B.1.5, a-priori estimates on these successive derivatives.

Proof.

See [35], theorem 27.2, page 406. The proof is a simplification of his argument, since our operator A is for simplicity, independent in time. We also prove the proposition for the lowest order of differentiation, being the extension to higher derivatives tractable with equal arguments.

Consider the problem:

$$\begin{aligned} v_t + Av &= f' \\ v(0) &= f(0) - Au(0) \end{aligned}$$

By assumption, $f(0) - Au(0) \in H$, and $f' \in L^2(I, V^*)$, so that, by theorem B.1.5 we obtain $v \in W(I; V)$.

Define $w(t) := u(0) + \int_0^t v(s)ds$, an absolutely continuous V -valued function, being $u(0) \in V$ by assumption. We have $w_t = v$, so that $w \in H^1(I, V)$. We show that $w = u$.

Integrating the equation of v we obtain, with equalities holding in V^* , that:

$$\begin{aligned} w_t(t) &= v(t) = \int_0^t f' - \int_0^t Av + v(0) = \\ &= f(t) - f(0) + f(0) - Au(0) - \int_0^t A(w_t) = \\ &= f(t) - f(0) + f(0) - Au(0) - Aw(t) + Au(0) = f(t) - Aw(t) \end{aligned}$$

Therefore, w solves the same equation as u and thus, $w = u$. From here we obtain both $u \in H^1(I, V)$, together with $u_{tt} = w_{tt} = v_t \in L^2(I, V^*)$, and the equation:

$$\begin{aligned} u_{tt} + Au_t &= f' \\ u_t(0) &= f(0) - Au(0) \end{aligned}$$

□

B.2. Application to inhomogeneous parabolic problems

B.2.1. Inhomogeneous Dirichlet problem

We make the following assumption.

Assumption B.2.1.1 (Assumptions for problem B.2.1.2)

We assume $\Omega \subset\subset D$ to be bounded Lipschitz domains, so that $U := D \setminus \Omega$ is bounded Lipschitz too and the trace operator is bounded surjective onto $H^{1/2}(\partial U)$, with a right inverse E (see theorem 3.37 at page 102 of [26]). For such a choice we also have $H_0^1 = H^1 \cap \ker \text{tr}$, see [23], page 595, theorem 18.7.

Moreover, we select $f \in H^1(I, H^{1/2}(\Gamma_f))$, $f(0) = 0$.

Note that, given a bounded extension operator $E : H^{1/2}(\partial U) \rightarrow H^1(U)$, we obtain by proposition A.2.2 that $Ef \in H^1(I, H^1(U))$. We have defined $\text{tru}(t) := \text{tr}(u(t))$ and analogously $Eu(t) := E(u(t))$ (see proposition A.2.6).

Call $H = L^2(U)$, $V = \{v \in H^1(U), \text{tru} = 0 \text{ on } \Gamma_m\} =: H_c^1$. V is a closed subspace of H^1 , which is Hilbert separable, hence also Hilbert separable. We norm it with the full H^1 norm. Because $H_0^1(U)$ is dense in H , so is V and we obtain a Gelfand triple. That V is a closed subspace of H^1 follows from the observation that if $u_n \rightarrow u$ in the V norm, then $\text{tru}_n \rightarrow \text{tru}$ in $L^2(\partial U)$. We can take an almost everywhere pointwise convergent sequence, so that $\text{tru}_n \rightarrow \text{tru}$ a.e., and by the fact that Γ_m has positive Hausdorff measure, we conclude $\text{tru} = 0$ on Γ_m .

We define $A : H^1 \rightarrow H^{1*}$ by $(Au)v := \int_u \nabla u \nabla v$. This operator can be recast to $V \rightarrow H^{-1}$ and $V \rightarrow V^*$.

The problem under consideration is the following. For $U = D \setminus \Omega$ we have:

Problem B.2.1.2 (Inhomogeneous heat equation, Dirichlet conditions)

$$u_t - \Delta u = 0 \text{ in } (0, T) \times U \quad (\text{B.2.1.3})$$

$$u(\Sigma_f) = f \quad (\text{B.2.1.4})$$

$$u(\Sigma_m) = 0 \quad (\text{B.2.1.5})$$

$$u(0) = 0 \quad (\text{B.2.1.6})$$

By this we mean:

$$u \in W(I, H_c^1) \quad (\text{B.2.1.7})$$

$$u_t|_{H^{-1}} + Au = 0 \text{ in } H^{-1} \text{ and for a.e. } t \in (0, T) \quad (\text{B.2.1.8})$$

$$\text{tru} = f \text{ on } \Sigma_f \quad (\text{B.2.1.9})$$

$$u(0) = 0 \quad (\text{B.2.1.10})$$

Theorem B.2.1.11 (Well posedness and regularity for problem B.2.1.2)

Given assumption B.2.1.1, the solution u to problem B.2.1.2 is unique with $u_t \in L^2(I, H)$.

The problem is equivalent to:

Problem B.2.1.12 (Equivalent formulation with extension)

$$u_0 \in W(I, H_0^1) \quad (\text{B.2.1.13})$$

$$u_0' + Au_0 = -((\bar{u}', \cdot)_H + A\bar{u}) \text{ in } H^{-1} \text{ and for a.e. } t \in (0, T) \quad (\text{B.2.1.14})$$

$$u_0(0) = 0 \quad (\text{B.2.1.15})$$

with \bar{u} any given $\bar{u} \in H^1(I, H_c^1(U))$ such that $\text{tr}\bar{u} = f$ on Σ_f , and with $\bar{u}(0) = 0$. This means that u solves problem B.2.1.2 $\implies u - \bar{u}$ solves problem B.2.1.12, and if $u_0(\bar{u})$ solves problem B.2.1.12, then $\bar{u} + u_0(\bar{u})$ solves problem B.2.1.2.

Furthermore:

$$\|u\|_{C([0,T],H)}^2 + \|u\|_{L^2(I,H)}^2 + \|\nabla u\|_{L^2(I,H)}^2 + \|u'\|_{L^2(I,H)}^2 \leq C(T) \|\bar{u}\|_{H^1(I,V)}^2 \quad (\text{B.2.1.16})$$

with $C > 1$, only dependent on T , smoothly, exploding for large T .

Proof.

Extension of the boundary data

Let $\bar{u} \in H^1(I, H_c^1(U))$ be such that $\text{tr}\bar{u} = f$ on Σ_f , and with $\bar{u}(0) = 0$. We can choose for instance $E\tilde{f}$, see proposition A.2.6,

where $\tilde{f} = 0$ on Σ_m , $\tilde{f} = f$ on Σ_f . $\tilde{f} \in H^1(I, H^{1/2}(\partial U))$, because Γ_f and Γ_m have positive distance (see the definition of the norm in [20], page 20).

Reformulation (first part)

Consider the following commutative diagram, where $V = H_c^1$, $W = H_0^1$:

$$\begin{array}{ccccc}
 H_c^1 & & & & (H_c^1)^* \\
 & \searrow a & & \nearrow a^* & \\
 & & H & \xrightarrow{r} & H^* \\
 & \nearrow b & & \searrow b^* & \\
 H_0^1 & & & & H^{-1} \\
 & \downarrow c & & \downarrow c^* &
 \end{array}$$

Here, a, b, c are the trivial injections, r the Riesz isomorphism $h \mapsto (h, \cdot)_H$.

Now $(i_W(u - \bar{u}))' + A(u - \bar{u}) = (i_V u)'|_{H^{-1}} - (i_V \bar{u})'|_{H^{-1}} + Au - A\bar{u} = \{ \text{proposition A.2.7} \} = (i_V u)'|_{H^{-1}} - (i_V \bar{u}_t)'|_{H^{-1}} + Au - A\bar{u} = -(i_V \bar{u}_t)'|_{H^{-1}} - A\bar{u}$ if u solves problem B.2.1.2, where \bar{u}_t is the weak derivative of \bar{u} in the $H^1(I, V)$ sense. Call $u_0 = u - \bar{u}$. By again proposition A.2.7, $u_0 \in W(I, H_0^1)$.

This motivates us to consider the problem:

$$u_0 \in W(I, H_0^1) \quad (\text{B.2.1.17})$$

$$u_0' + Au_0 = -(f_1 + f_2) \text{ in } H^{-1} \text{ and for a.e. } t \in (0, T) \quad (\text{B.2.1.18})$$

$$u_0(0) = 0 \quad (\text{B.2.1.19})$$

Here, $f_1 := (i_V \bar{u}_t)'|_{H^{-1}} = c^* a^* r a \bar{u}_t = b^* r(a \bar{u}_t) \in L^2(I, H)$.

Moreover, $A \in L(V, H^{-1})$, so, by proposition A.2.2, $f_2 := A\bar{u} \in H^1(I, H^{-1})$.

Existence

By theorem B.1.11 we get a solution of the above problem with $u_0' \in L^2(I, H)$.

And now, let $u := \bar{u} + cu_0 = \bar{u} + u_0$. We claim it is a solution. The initial and boundary conditions are surely satisfied. We check it is in $W(I, V)$ and is satisfies the partial differential equation.

By proposition A.2.7, we have both $\bar{u}, cu_0 \in W(I, V)$. The derivative of \bar{u} becomes $i_V \bar{u}_t$, see proposition A.2.7. Therefore $(i_V(\bar{u} + cu_0))'|_{H_0^1} = c^*(i_V(\bar{u} + cu_0))' = c^* i_V \bar{u}_t + c^* i_V(cu_0)' = b^* r(a \bar{u}_t) + i_W(u_0)'$ by proposition A.2.7.

Using the pde of u_0 , ... $= b^* r(a \bar{u}_t) - Au_0 - f_1 - f_2 = -A(u_0 + \bar{u})$.

Uniqueness

For two solutions u_1, u_2 of B.2.1.2 we can form $d := u_1 - u_2 \in W(I, H_0^1)$ by proposition A.2.7. Clearly, $d(0) = 0$. Moreover, $(i_{H_0^1} d)' = \{ \text{proposition A.2.7} \} = (i_V u_1)'|_{H_0^1} - (i_V u_2)'|_{H_0^1} = A(u_1 - u_2)$.

By uniqueness stated in theorem B.1.5 we obtain $d = 0$ in $L^2(I, H)$, so that the solution is unique and doesn't depend on the choice of the extension of the Dirichlet datum.

Reformulation (part 2)

Therefore $u = \bar{u} + u_0$ above is the unique solution of problem B.2.1.2. So, given any $\bar{u} \in H^1(I, H_c^1(U))$ such that $\text{tr} \bar{u} = f$ on Σ_f , and with $\bar{u}(0) = 0$, we can construct u_0 as above and get $u = \bar{u} + u_0$ solving problem B.2.1.2.

Viceversa, let u solve problem B.2.1.2. Call $u_0 = u - \bar{u}$. Then, as seen above, $u_0 \in W(I, H_0^1)$ and $(i_V(u - \bar{u}))'|_{H^{-1}} + A(u - \bar{u}) = (i_V u)'|_{H^{-1}} - (i_V \bar{u})'|_{H^{-1}} + Au - A\bar{u} = \{ \text{proposition A.2.7} \} = (i_V u)'|_{H^{-1}} - (i_V \bar{u}_t)'|_{H^{-1}} + Au - A\bar{u} = -(i_V \bar{u}_t)'|_{H^{-1}} - A\bar{u}$ if u solves problem B.2.1.2, where \bar{u}_t is the weak derivative of \bar{u} in the $H^1(I, V)$ sense. Call $u_0 = u - \bar{u}$. By again proposition A.2.7, $(i_W(u - \bar{u}))' + A(u - \bar{u}) = (i_V u)'|_{H^{-1}} - (i_V \bar{u})'|_{H^{-1}} + Au - A\bar{u} = (i_V u)'|_{H^{-1}} - (i_V \bar{u}_t)'|_{H^{-1}} + Au - A\bar{u} = -(i_V \bar{u}_t)'|_{H^{-1}} - A\bar{u} = -b^* r(a \bar{u}_t) - A\bar{u}$. Moreover, $u_0(0) = 0$, so that u_0 solves problem B.2.1.2.

Regularity

Let $u = \bar{u} + u_0$ be the unique solution, as before, of problem B.2.1.2. From proposition A.2.7 we know $(i_V(\bar{u}))' = i_V(\bar{u}_t) =$

$a^*r(a\bar{u}_t)$, and $i_V(cu_0)' = a^*r(u_0')$, for $u_0' \in L^2(I, H)$ the representative of $(i_W(u_0))'$, equivalently, the weak derivative of u_0 in the $H^1(I, H)$ sense. It follows that $(i_V u)' = a^*r(a\bar{u}_t + u_0')$, proving the additional time smoothness claim.

Stability

Let $\bar{u} \in H^1(I, H_c^1(U))$ such that $\text{tr} \bar{u} = f$ on Σ_f , and with $\bar{u}(0) = 0$. Consider u_0 . Then, by B.1.14:

$$\|u_0\|_{C([0;T], H)}^2 + \alpha \|u_0\|_{L^2(I, H_0^1)}^2 \leq \exp(2\lambda T) \alpha^{-1} \|(\bar{u}', \cdot)_H + A\bar{u}\|_{L^2(I, H^{-1})}^2$$

$$\begin{aligned} C \|u_0'\|_{L^2(I, H)}^2 &\leq (1 + (1 + C_0)\alpha^{-1}) \|A\bar{u}\|_{H^1(I, H^{-1})}^2 + \\ &\|(\bar{u}', \cdot)_H\|_{L^2(I, H)}^2 + C_0\alpha^{-1} \|(\bar{u}', \cdot)_H\|_{L^2(I, H^{-1})}^2 \end{aligned}$$

$$C_0 = 2^{-1} \max(1, \lambda) \max(1, \alpha^{-1}) \exp(2\lambda T).$$

We norm H_0^1 with the full H^1 norm too. Then:

$$\begin{aligned} &\|(\bar{u}', \cdot)_H + A\bar{u}\|_{L^2(I, H^{-1})} \leq \\ &\sup_{\|v\|_{L^2(I, H_0^1)}=1} \|\bar{u}'\|_{L^2(I, H)} \|v\|_{L^2(I, H)} + \|\nabla \bar{u}\|_{L^2(I, H)} \|\nabla v\|_{L^2(I, H)} \leq \\ &C(\|\bar{u}'\|_{L^2(I, H)} + \|\nabla \bar{u}\|_{L^2(I, H)}) \end{aligned}$$

By proposition A.2.2, $\|A\bar{u}\|_{H^1(I, H^{-1})} \leq \|A\|_{L(V, H^{-1})} \|\bar{u}\|_{H^1(I, V)}$ (we could apply it since H^{-1} is separable, as a dual of a reflexive Banach space).

$$\text{Finally, } \|(\bar{u}', \cdot)_H\|_{L^2(I, H^{-1})}^2 \leq \|\bar{u}'\|_{L^2(I, H)}^2.$$

We can then say:

$$\begin{aligned} &\|u_0\|_{C([0;T], H)}^2 + C\alpha \|u_0\|_{L^2(I, H_0^1)}^2 \leq \exp(2\lambda T) \alpha^{-1} \|\bar{u}\|_{H^1(I, V)}^2 \\ &C \|u_0'\|_{L^2(I, H)}^2 \leq ((1 + (1 + C_0)\alpha^{-1}) \|A\|_{L(V, H^{-1})}^2 + 1 + C_0\alpha^{-1}) \|\bar{u}\|_{H^1(I, V)}^2 \end{aligned}$$

Now, $\langle Av, v \rangle_{H^{-1}, H_0^1} + 1 \cdot \|v\|_H^2 = 1 \cdot \|v\|_{H_0^1}^2$, so that $\alpha = \lambda = 1$. Moreover, $\langle Au, v \rangle_{H^{-1}, H_0^1} \leq \|u\|_V \|v\|_{H_0^1}$, i.e. $\|A\|_{L(V, H^{-1})} \leq 1$.

Therefore $\|u_0\|_{C([0;T], H)}^2 + \|u_0\|_{L^2(I, H_0^1)}^2 + \|u_0'\|_{L^2(I, H)}^2 \leq C(T) \|\bar{u}\|_{H^1(I, V)}^2$ with $C > 1$, only dependent on T , smoothly, exploding for large T .

Now, let's analyse the norms of \bar{u} . Because $\bar{u} \in H^1(I, V)$, then, $\bar{u} \in C([0, T], V) \hookrightarrow C([0, T], H)$, where the embedding is non-expansive by the choice of the norm of V . Therefore $\|\bar{u}\|_{C([0;T], H)} \leq \|\bar{u}\|_{C([0;T], V)} \leq (1 + T) \|\bar{u}\|_{H^1(I, V)}$. We can therefore conclude that $\|u\|_{C([0;T], H)}^2 + \|u\|_{L^2(I, H_0^1)}^2 + \|u'\|_{L^2(I, H)}^2 \leq C(T) \|\bar{u}\|_{H^1(I, V)}^2$ with $C > 1$, only dependent on T , smoothly, exploding for large T .

□

B.2.2. Inhomogeneous Neumann-Dirichlet problem

We make the following assumption.

Assumption B.2.2.1 (Assumptions for problem B.2.1.2)

We keep assumption B.2.1.1 (apart from the Dirichlet datum). We consired $g \in H^1(I, L^2(\Gamma_f))$, $g(0) = 0$.

Again, call $H = L^2(U)$, $V = \{v \in H^1(U), \text{tr} u = 0 \text{ on } \Gamma_m\} =: H_c^1$. H, V induce a Gelfand triple as seen before.

The problem under consideration is:

Problem B.2.2.2 (Inhomogeneous heat equation, Neumann conditions)

$$u_t - \Delta u = 0 \text{ in } (0, T) \times U \quad (\text{B.2.2.3})$$

$$\partial_\nu u(\Sigma_f) = g \quad (\text{B.2.2.4})$$

$$u(\Sigma_m) = 0 \quad (\text{B.2.2.5})$$

$$u(0) = 0 \quad (\text{B.2.2.6})$$

By this we mean:

$$u \in W(I, H_c^1) \quad (\text{B.2.2.7})$$

$$u_t + Au = G \text{ in } V^* \text{ and for a.e. } t \in (0, T) \quad (\text{B.2.2.8})$$

$$u(0) = 0 \quad (\text{B.2.2.9})$$

where $\langle G(t), v \rangle_{V^*, V} := \int_{\Gamma_f} g(t) \text{tr} v d\sigma$, σ the 1-codimensional Hausdorff measure, and A was introduced before in $L(V, H^{-1})$.

By proposition A.2.2, $G \in H^1(I, V^*)$. In fact, define $T : L^2(\Sigma_f) \rightarrow V^*$ by $\langle Tg, v \rangle_{V^*, V} := \int_{\Gamma_f} g \text{tr} v d\sigma$. Then, $\langle Tg, v \rangle_{V^*, V} \leq \|g\|_{L^2(\Gamma_f)} \|v\|_V$ by trace theory. Now, $G(t) = Tg(t)$.

Moreover, $\langle Av, v \rangle_{V^*, V} + 1 \cdot \|v\|_H = 1 \cdot \|V\|$, so that we can immediately conclude:

Theorem B.2.2.10 (Well posedness and regularity for problem B.2.2.2)

Given assumption B.2.2.1, the solution u to problem B.2.2.2 is unique with $u_t \in L^2(I, H)$.

Furthermore:

$$\|u\|_{C([0, T], H)}^2 + \|u\|_{L^2(I, H)}^2 + \|\nabla u\|_{L^2(I, H)}^2 + \|u'\|_{L^2(I, H)}^2 \leq C(T) \|g\|_{H^1(I, L^2(\Gamma_f))}^2 \quad (\text{B.2.2.11})$$

with $C > 1$, only dependent on T , smoothly, exploding for large T .

Proof.

It is an application of theorem B.1.5, theorem B.1.8 and proposition B.1.14. □

B.2.3. Space-time regularity for a more general problem

Here, we build on the results of the last subsections, and prove higher spatial and time regularity, under suitable smoothness assumptions.

The overall problem, comprehending problem B.2.1.2, problem B.2.2.2, is:

Problem B.2.3.1 (Inhomogeneous heat equation, general case)

$$\begin{aligned} u_t - \Delta u &= f \text{ in } (0, T) \times U \\ \partial_\nu u(\Sigma_N) &= g_N \\ u(\Sigma_D) &= g_D \\ u(0) &= u_0 \end{aligned}$$

Calling $V := H_c^1(U)$ (see assumption B.2.2.1), and $H = L^2(U)$, we mean:

$$\begin{aligned} u &\in W(I, H^1) \\ u_t + Au &= f + G \text{ in the sense of } V^* \text{ and for a.e. } t \in (0, T) \\ \text{tr} u &= g_D \text{ on } \Sigma_D \\ u(0) &= u_0 \end{aligned}$$

where $\langle G(t), v \rangle_{V^*, V} := \int_{\Gamma_N} g(t) \text{tr} v d\sigma$, σ the 1-codimensional Hausdorff measure.

Note, for the regular case, we will be discussing only a homogeneous initial condition. This will suffice for our purposes. A generalization will entail handling more complicated compatibility conditions, see [25], Chapter 2. Also note that the requirements imposed on the data below, are only sufficient, to ensure the desired regularity.

Assumption B.2.3.2 (Basic assumption for problem B.2.3.1)

1. $u_0 \in H^1(U)$
2. $\Omega \subset\subset D$ are bounded Lipschitz domains
3. $A : H^1 \rightarrow (H^1)^*$, $(Au)v = \int_U \nabla u \nabla v$
4. $g_D \in H^1(I, H^{1/2}(\Gamma_D))$. Here $\Gamma_D \neq \emptyset$ is either $\partial U, \partial D$ or $\partial \Omega$, with $g_D(0) = u_0$ on Γ_D
5. $g_N \in H^1(I, L^2(\Gamma_N))$, where $\Gamma_N = \partial U \setminus \Gamma_D$
6. $f \in L^2(I, H)$

Assumption B.2.3.3 (Time regularity assumption for problem B.2.3.1)

Let $k \geq 1$.

Consider $G_D \in H^1(U)$ solving:

$$\begin{cases} -\Delta G_D(t) = 0 & \text{in } U \\ G_D(t) = g_D(t) & \text{on } \Gamma_D \\ G_D(t) = 0 & \text{on } \Gamma_N \end{cases}$$

We ask, aside from assumption B.2.3.2:

1. $u_0 = 0$
2. $g_D \in H^{k+1}(I, H^{1/2}(\Gamma_D))$
3. $g_N \in H^k(I, L^2(\Gamma_N))$
4. $f \in H^k(I, H)$
5. $g_N^{(j)}(0) = 0$, for $j = 0, \dots, k-1$
6. $f^{(j-1)}(0) - G_D^{(j)}(0) + \sum_{l=1}^{j-1} (-1)^l A^l f^{(j-l-1)}(0) \in V$, for $j = 0, \dots, k-1$ (for $j = 0$ it is read $g_D(0) = 0$, which we already assumed)
7. $\sum_{j=1}^{k-1} (-1)^j A^j (f^{(k-j-1)}(0)) \in H$ (remember that $A : V \rightarrow V^*$, so that $Af \neq -\Delta f$, in general)

Assumption B.2.3.4 (Additional time regularity assumptions)

Apart from assumption B.2.3.2 and assumption B.2.3.3, suppose that, for $k \geq 1$, there holds:

- $g_N \in H^{k+1}(I, L^2(\Gamma_N))$
- $f^{(k-1)}(0) - G_D^{(k)}(0) + \sum_{l=1}^{k-1} (-1)^l A^l f^{(k-l-1)}(0) \in V$

Assumption B.2.3.5 (Spatial regularity assumptions)

Let assumption B.2.3.2 for $k = 0$, and also assumption B.2.3.3 and assumption B.2.3.4 hold for $k \geq 1$. Further assume:

- $\partial U \in C^{1,1}$
- $g_D \in H^k(I, H^{3/2}(\Gamma_D))$
- $g_N \in H^k(I, H^{1/2}(\Gamma_N))$

Theorem B.2.3.6 (Regularity results for problem B.2.3.1)

Under assumption B.2.3.2:

- there exists a unique $u \in W(I, H^1(U))$ solution to problem B.2.3.1
- for such u there holds $u' \in L^2(I, L^2(U))$ with:

$$\|u\|_{L^2(I, H)}^2 + \|\nabla u\|_{L^2(I, H)}^2 + \|u'\|_{L^2(I, H)}^2 \leq C(T) \left(\|f\|_{L^2(I, H)}^2 + \|g_N\|_{H^1(I, L^2(\Gamma_N))}^2 + C(U) \|g_D\|_{H^1(I, H^{1/2}(\Gamma_D))}^2 + \|u_0\|_{H^1(U)}^2 \right)$$

Under assumption B.2.3.3 have that $u \in H^k(I, V) \cap (H^{k+1}(I, V) + H^{k+1}(I, V^*))$.

Under assumption B.2.3.4, $u^{k+1} \in H^1(I, H)$, or $u \in H^{(k+1)}(I, H)$, and, for $1 \leq j \leq k$:

$$\begin{cases} (u^{(j+1)}, v)_H + (\nabla u^{(j)}, \nabla v)_H = (f^{(j)}, v)_H + (g_N^{(j)}, v)_{L^2(\Gamma_N)} \\ u^{(j)}(0) = f^{(j-1)}(0) - G_D^{(j)}(0) + \sum_{l=1}^{j-1} (-1)^l A^l f^{(j-l-1)}(0) \in V \\ \text{tru}^{(j)}(\Sigma_D) = g_D^{(j)} \end{cases}$$

Finally, if assumption B.2.3.5 holds, then $u \in H^k(I, H^2(U)) \cap H^{k+1}(I, H)$.

Proof.

Well-posedness, stability

Existence and uniqueness follow with similar arguments as in the previous subsections.

In particular, $u = G_D + \delta$, where G_D is (for a.e. t), a e.g. harmonic extension of g_D :

$$\begin{cases} -\Delta G_D(t) = 0 & \text{in } U \\ G_D(t) = g_D(t) & \text{on } \Gamma_D \\ G_D(t) = 0 & \text{on } \Gamma_N \end{cases}$$

Using the results of trace theory we know, in particular, that $G_D \in H^1(U)$ with $\|G_D\|_{H^1} \leq C(U) \|g_D\|_{H^{1/2}(U)}$.

$\delta \in W(I, V) \cap H^1(I, H)$ is the solution to:

$$\begin{cases} (\delta_t, v)_H + (\nabla \delta, \nabla v)_H = (f - \partial_t G_D, v)_H + (g_N, v)_{L^2(\Gamma_N)} \text{ for all } v \in V \\ \delta(0) = u_0 - G_D(0) \in V \end{cases}$$

Note that $G_D(0)$ makes sense, being $g_D \in C([0, T], H^{1/2}(\Gamma_D))$ and $g_D \mapsto G_D$ is linear bounded, so that we can apply proposition A.2.2.

We can therefore deduce the estimate:

$$\begin{aligned} & \|u\|_{L^2(I,H)}^2 + \|\nabla u\|_{L^2(I,H)}^2 + \|u'\|_{L^2(I,H)}^2 \leq \\ & C(T) \left(\|f\|_{L^2(I,H)}^2 + \|g_N\|_{H^1(I,L^2(\Gamma_N))}^2 + \|G_D\|_{H^1(I,H^1(U))}^2 \right) \leq \\ & C(T) \left(\|f\|_{L^2(I,H)}^2 + \|g_N\|_{H^1(I,L^2(\Gamma_N))}^2 + C(U) \|g_D\|_{H^1(I,H^{1/2}(\Gamma_D))}^2 + \|u_0\|_{H^1(U)}^2 \right) \end{aligned}$$

Regularity: compatibility relations

$F := (f - \partial_t G_D, \cdot)_H + (g_N, \text{tr}(\cdot))_{L^2(\Gamma_N)}$ is, thanks to the smoothness assumptions, in $H^k(I, V^*)$. We apply proposition B.1.30, to the problem:

$$\begin{cases} (\delta_t, v)_H + (\nabla \delta, \nabla v)_H = (F, v)_H \\ \delta(0) = \delta_0 \in V \end{cases}$$

for $\delta_0 = -G_D(0)$.

We check its hypothesis, for $k \geq 1$.

In particular $F^{(k-1)} = (f^{(k-1)} - G_D^{(k)}, \cdot)_H + (g_N^{(k-1)}, \text{tr}(\cdot))_{L^2(\Gamma_N)}$.

Because $f \in H^k(I, H)$, and $g_N, G_D \in H^{k+1}(I, H^{1/2}(\Gamma_D)), H^{k+1}(I, H^1(U))$, we can define $F^{(k-1)}(0)$, which is $F^{(k-1)}(0) = (f^{(k-1)}(0) - G_D^{(k)}(0), \cdot)_H + (g_N^{(k-1)}(0), \text{tr}(\cdot))_{L^2(\Gamma_N)}$. As $g_N^{(k-1)}(0) = 0$, we get:

$$F^{(k-1)}(0) = (f^{(k-1)}(0) - G_D^{(k)}(0), \cdot)_H$$

We now compute the terms g_k .

We have $g_k = \sum_{j=0}^{k-1} (-1)^j A^j F^{(k-j-1)}(0) + (-1)^k A^k (-G_D(0))$, $g_0 = -G_D(0)$.

Note, $AG_D(v) = (\nabla G_D, \nabla v) = 0$ for $v \in V$. Therefore, $A^j G_D(0) = 0$ and we get to $g_k = \sum_{j=0}^{k-1} (-1)^j A^j F^{(k-j-1)}(0)$, $k \geq 1$.

Let's start to check that $g_k \in H$. To do so, note that for $j = 0, \dots, k-1$ we have that $A^j F^{(k-j-1)}(0) = A^j f^{(k-j-1)}(0) - A^j G_D^{(k-j)}(0)$.

So, for $j = 0$: $A^j F^{(k-j-1)}(0) = f^{(k-1)}(0) - G_D^{(k)}(0)$, whereas for $j \geq 1$: $A^j F^{(k-j-1)}(0) = A^j f^{(k-j-1)}(0) - A^{j-1} AG_D^{(k-j)}(0)$.

Because $f \in H^k(I, H)$, $G_D \in H^{k+1}(I, H^1(U))$, the term for $j = 0$ is in H .

For $j \geq 1$. Note that, by calling $h : H^{1/2}(\Gamma_D) \rightarrow H^1(U)$ the operator $g_D \mapsto G_D$, thanks to the assumption $g_D \in H^{k+1}(I, H^{1/2}(\Gamma_D))$ and to proposition A.2.2, we have $\partial_{t^k} h g_D = h \partial_{t^k} g_D$, so that $AG_D^{(j)} = 0$, for all t and all $j \leq k$. Therefore $A^{j-1} AG_D^{(k-j)}(0) = 0$ for $j \geq 1$ without other assumptions, and we have to ask for $\sum_{j=1}^{k-1} (-1)^j A^j F^{(k-j-1)}(0) = \sum_{j=1}^{k-1} (-1)^j A^j (f^{(k-j-1)}(0)) \in H$.

It now remains to ask that $g_j \in V$ for $j = 1, \dots, k-1$.

We have $g_j = \sum_{l=0}^{j-1} (-1)^l A^l F^{(j-l-1)}(0)$, for $j = 1, \dots, k-1$, and, as seen before, $AG_D^{(j-l)} = 0$, so that we must ensure:

$$f^{(j-1)}(0) - G_D^{(j)}(0) + \sum_{l=1}^{j-1} (-1)^l A^l f^{(j-l-1)}(0) \in V$$

Regularity: time smoothness

So, proposition B.1.30 ensures then that $\delta \in H^k(I, V)$, $\delta^{(k+1)} \in L^2(I, V^*)$. Because we $G_D \in H^{k+1}(I, H^1(U))$ we obtain that $u = G_D + \delta$ is in $H^{k+1}(I, H^1(U)) + H^{k+1}(I, V^*)$ and in $H^k(I, H^1(U))$.

Regularity: time smoothness again

By proposition B.1.30 we also have:

$$\begin{cases} \langle \partial_t \delta^{(k)}, v \rangle_{V^*, V} + (\nabla \delta^{(k)}, \nabla v)_H = \langle F^{(k)}, v \rangle_{V^*, V} \\ \delta^{(k)}(0) = g_k \in H \end{cases}$$

We ask for $g_k \in V$.

The right hand side $F^{(k)} = (f^{(k)} - G_D^{(k+1)}, \cdot)_H + (g_N^{(k)}, \text{tr}(\cdot))_{L^2(\Gamma_N)}$ is now an element of $L^2(I, H) + H^1(I, V^*)$, meaning that we can apply B.1.8 to obtain $\delta \in H^{k+1}(I, H)$.

With analogous reasoning to theorem B.2.1.11 we conclude that $u \in H^{(k+1)}(I, H)$, and, for $1 \leq j \leq k$:

$$\begin{cases} (u^{(j+1)}, v)_H + (\nabla u^{(j)}, \nabla v)_H = (f^{(j)}, v)_H + (g_N^{(j)}, v)_{L^2(\Gamma_N)} \\ u^{(j)}(0) = g_k + G_D^{(j)}(0) \in V \\ \text{tr} u^{(j)}(\Sigma_D) = g_D^{(j)} \end{cases}$$

Spatial regularity

This last equation reads, for a.e. $t \in (0, T)$:

$$\begin{cases} (\nabla u^{(j)}, \nabla v)_H = (f^{(j)} - u^{(j+1)}, v)_H + (g_N^{(j)}, v)_{L^2(\Gamma_N)} \\ \text{tr} u^{(j)}(\Sigma_D) = g_D^{(j)} \end{cases}$$

which is the variational counterpart to:

$$\begin{cases} -\Delta u^{(j)} = f^{(j)} - u^{(j+1)} \\ u^{(j)}(\Gamma_D) = g_D^{(j)} \\ \partial_\nu u^{(j)}(\Gamma_N) = g_N^{(j)} \end{cases}$$

This holds for $0 \leq j \leq k$.

H^2 regularity results that can be found in Chapter 2 of [20] let us conclude the proof.

□

An application of this, please

B.3. Reformulation of parabolic equations

We just saw that the two parabolic equations of interest can be recasted into the problem of finding $u \in W(I, V)$, $u(0) = 0$, $u_t + Au = f$ for a.e. t in V^* , with notation from preceding sections.

In particular, $f \in L^2(I, V^*)$ and so is Au (because $A \in L(V, V^*)$, and by A.2.2).

Call then $E(u) := u_t + Au - f \in L^2(I, V^*)$ and $W_0(I, V)$ the $W(I, V)$ functions with zero initial value. Then, the differential equation reads $\langle E(u)(t), v \rangle_{V^*, V} = 0$ for all $v \in V$, for a.a. t , equivalently, $E(u) = 0$ for a.a. t . Thus, we are interested in the abstract problem:

Problem B.3.1 (Even more abstract parabolic equation)

Given a function $E : W(I, V) \rightarrow L^2(I, V^*)$, find $u \in W_0(I, V)$, such that $E(u) = 0$ for a.a. t .

We can view $L^2(I, V^*) \cong L^2(I, V)^*$.

Hence $\langle E(u), v \rangle_{L^2(I, V)^*, L^2(I, V)} = \int_I \langle E(u)(t), v(t) \rangle_{V^*, V} dt$ (see [21], theorem 1.31 at page 39).

We are now ready to restric both state and adjoint space.

Definition B.3.2 ($Q(I, V)$)

We define $Q(I, V) = H^{1,1} = L^2(I, V) \cap H^1(I, H)$, with the norm $\|v\|_Q^2 = \|v\|_{L^2(I, V)}^2 + \|v_t\|_{L^2(I, H)}^2$.

Proposition B.3.3 (Properties of Q)

There holds:

- $Q = Q(I, V)$ is Hilbert with $(v, w)_{L^2(I, V)} + (v_t, w_t)_{L^2(I, H)}$
- $Q(I, V)$ is dense in $L^2(I, V)$
- $Q(I, V) \hookrightarrow C([0, T], H)$
- $Q_0(I, V)$ is dense in $L^2(I, V)$, $Q_0(I, V)$ the space of $Q(I, V)$ function with zero initial value
- $Q(I, V) = W(I, V) \cap H^1(I, H)$, $Q_0(I, V) = W_0(I, V) \cap H^1(I, H)$ as sets. There holds that the $W(I, V)$ derivative is represented by the $H^1(I, H)$ derivative and $\langle u', v \rangle_{V^*, V} = (u', v)_H$, with the suitable interpretations of u' (on the left, we have $i_V(u)'$, i_V the Gelfand triple embedding; on the right we have u , seen in H , and then weakly differentiated in the $H^1(I, H)$ sense)
- integration by parts in time holds: $\int_I (v_t, w)_H = -\int_I (w_t, v)_H + (v(T), w(T))_H - (v(0), w(0))_H$
- if q_n is bounded in $Q(I, V)$, then there exists a weakly convergent subsequence q_k such that $q_k \rightharpoonup q$ in $L^2(I, H)$, $\partial_i q_k \rightharpoonup \partial_i q$ in $L^2(I, H)$ and $q'_k \rightharpoonup q'$ in $L^2(I, H)$

Proof.

Completeness

We have the inclusions $L^2(I, H) \subseteq L^2(I, V) \cap H^1(I, H) \subseteq H^1(I, V)$.

If q_n is Cauchy in Q , then it is Cauchy in the individual norms of $L^2(I, V)$, $H^1(I, H)$, so that q_n converges to two limits, one in $L^2(I, V)$ and one in $H^1(I, H)$. The convergence is common in $L^2(I, H)$, which implies that the two limits coincide at $q \in Q(I, V)$. The convergence in $Q(I, V)$ of q_n to Q follows from the individual convergences of $q_n, \nabla q_n, q_{nt}$ in $L^2(I, H), L^2(I, H), L^2(I, H)$.

Density

We have $C_c^\infty(I, V) \subseteq Q(I, V) \subseteq L^2(I, V)$. The first inclusion holds because of proposition A.2.4, so that $C_c^\infty(I, V) \subseteq H^1(I, V)$. Moreover $H^1(I, V) \subseteq Q(I, V)$ trivially, where the $H^1(I, H)$ derivative is the $H^1(I, V)$ derivative. $C_c^\infty(I, V)$ is dense in $L^2(I, V)$ by [21], page 39, lemma 1.9.

Continuity

Follows from the embedding $H^1(I, H) \hookrightarrow C([0, T], H)$, as seen in [15], theorem 2 of page 286.

More density

We can therefore speak of initial values. In particular, $C_c^\infty(I, V) \subseteq Q_0(I, V) \subseteq L^2(I, V)$, and as before, the density result follows.

Relationship with $W(I, V)$

Consider the chain:

$$V \xhookrightarrow{a} H \xrightarrow{r} H^* \xhookrightarrow{a^*} V^*$$

where a is the trivial embedding and r the Riesz isomorphism.

We claim that for $v \in Q(I, V)$, then $(a^* r a v)' = a^* r (a v)'$, where $av \in H^1(I, H)$. In fact, for $\phi \in C_c^\infty(I)$, we get $\int_I a^* r a v \phi' = \{ \text{A.2.1} \} = a^* r \int_I a v \phi' = -a^* r \int_I (a v)' \phi = -\int_I a^* r (a v)' \phi$.

Now, let $u \in W(I, V)$, with $(a^* r a u)' = a^* r h$, $h \in L^2(I, H)$. Then $a^* r \int_I h \phi = \{ \text{A.2.1} \} = \int_I a^* r h \phi = \int_I (a^* r a u)' \phi = a^* r (-\int_I a u \phi')$.

We know that a^* is injective and so is r , so that $\int_I h \phi = -\int_I a u \phi'$ as we wanted.

Integration by parts

We note that for $v, w \in Q(I, V) \subseteq W(I, V)$, we have $\int_I \langle (a^* r a v)', w \rangle_{V^*, V} = \int_I \langle a^* r (a v)', w \rangle_{V^*, V} = \int_I ((a v)', a w)_H$. We can now apply theorem 3.11 at page 148 of [33] to conclude that $\int_I (v_t, w)_H = - \int_I ((a w)_t, a v)_H + ((a v)(T), (a w)(T))_H - ((a v)(0), (a w)(0))_H$

Weak convergence

At first we note that ∂_i, ∂_t are linear bounded operators from $Q(I, V)$ to $L^2(I, H)$.

Remember that in any case, V is a closed subspace of H^1 . Then, $\partial_i : V \rightarrow H$ is linear and bounded, because V is bounded by the full H^1 norm, as we declared already.

Therefore, by proposition A.2.2, ∂_i extends to a linear bounded map from $L^2(I, V)$ to $L^2(I, H)$, therefore, to a linear bounded map on $Q(I, V)$, in the sense of:

$$Q(I, V) \xhookrightarrow{i} L^2(I, V) \xrightarrow{\partial_i} L^2(I, H)$$

Because q_n is bounded in the Hilbert space $Q(I, V)$, it has a weakly convergent subsequence $q_k \rightharpoonup q \in Q(I, V)$. Therefore, $\partial_i(i(q_k)) \rightharpoonup \partial_i(i(q))$ in $L^2(I, H)$. By the Hilbert space property of $L^2(I, H)$ we conclude that $(\partial_i q_k, p)_{L^2(I, H)} \rightarrow (\partial_i q, p)_{L^2(I, H)}$ for all $p \in L^2(I, H)$.

For the time derivative we can draw a similar diagram:

$$Q(I, V) \xhookrightarrow{j} H^1(I, H) \xrightarrow{\partial_t} L^2(I, H)$$

We therefore obtain $(\partial_t q_k, p)_{L^2(I, H)} \rightarrow (\partial_t q, p)_{L^2(I, H)}$ for all $p \in L^2(I, H)$.

The convergence $(q_k, p)_{L^2(I, H)} \rightarrow (q, p)_{L^2(I, H)}$ for all $p \in L^2(I, H)$ follows analogously.

□

We can therefore restrict the testing space.

Proposition B.3.4 (Equivalent testing)

Let $E : W(I, V) \rightarrow L^2(I, V^*)$, and $u \in W_0(I, V)$.

Then:

$$\begin{aligned} E(u) &= 0 \\ &\iff \\ \langle E(u), v \rangle_{L^2(I, V)^*, L^2(I, V)} &= 0 \quad \forall v \in L^2(I, V) \\ &\iff \\ \langle E(u), v \rangle_{L^2(I, V)^*, L^2(I, V)} &= 0 \quad \forall v \in W^0(I, V) \\ &\iff \\ \langle E(u), v \rangle_{L^2(I, V)^*, L^2(I, V)} &= 0 \quad \forall v \in Q^0(I, V) \end{aligned}$$

We have also seen that with smoothness assumption on data (assumption B.2.1.1 and assumption B.2.2.1) we obtain that the solutions of problem B.2.1.2, problem B.2.2.2 have $Q_0(I, V)$ smoothness.

We can therefore formulate the two partial differential equations directly on $Q_0(I, V)$ as follows.

$$\begin{aligned} w &\in W_0(I, H_c^1), \bar{u} + v_0 \in W_0(I, H_c^1), v_0 \in W_0(I, H_0^1) \\ w' + A w &= (g, \cdot)_{L^2(\Gamma_f)} \text{ in } H_c^{1*} \text{ and for a.e. } t \in (0, T) \\ v_0' + A v_0 &= -((\bar{u}', \cdot)_H + A \bar{u}) \text{ in } H^{-1} \text{ and for a.e. } t \in (0, T) \end{aligned}$$

with \bar{u} any given $\bar{u} \in H^1(I, H_c^1)$ such that $\text{tr} \bar{u} = f$ on Σ_f , and with $\bar{u}(0) = 0$.

We are working under B.2.1.1, B.2.2.1.

Thanks to proposition B.3.5, this is equivalent to:

$$\begin{aligned} w &\in W_0(I, H_c^1), \bar{u} + v_0 \in W_0(I, H_c^1), v_0 \in W_0(I, H_0^1) \\ \int_I \langle w', q \rangle_{H_c^{1*}, H_c^1} + (\nabla w, \nabla q)_H &= \int_I (g, \text{tr} q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, H_c^1) \\ \int_I \langle v_0', p \rangle_{H^{-1}, H_0^1} + (\nabla v_0, \nabla p)_H &= - \int_I (\bar{u}', p)_H + (\nabla \bar{u}, \nabla p)_H, \quad \forall p \in Q^0(I, H_0^1) \end{aligned}$$

By regularity, see theorem B.2.1.11, theorem B.2.2.10, and thanks to proposition B.3.3 this implies:

$$\begin{aligned} w &\in Q_0(I, H_c^1), \bar{u} + v_0 \in Q_0(I, H_c^1), v_0 \in Q_0(I, H_0^1) \\ \int_I (w', q)_H + (\nabla w, \nabla q)_H &= \int_I (g, \text{tr} q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, H_c^1) \\ \int_I (v_0', p)_H + (\nabla v_0, \nabla p)_H &= - \int_I (\bar{u}', p)_H + (\nabla \bar{u}, \nabla p)_H, \quad \forall p \in Q^0(I, H_0^1) \end{aligned}$$

where now the derivatives are in the $H^1(I, H)$ sense. Indeed we have proved in proposition B.3.3 that $u \in W(I, V)$ with $L^2(I, H)$ derivative, is actually $Q(I, V)$, with weak derivative in the $H^1(I, H)$ sense equal to the $L^2(I, H)$ representative of u' in the $W(I, V)$ sense. There, we also proved the representation of the duality bracket.

Conversely, a solution $w \in Q_0(I, H_c^1), \bar{u} + v_0 \in Q_0(I, H_c^1), v_0 \in Q_0(I, H_0^1)$ to the above problem satisfies $w \in W_0(I, H_c^1), \bar{u} + v_0 \in W_0(I, H_c^1), v_0 \in W_0(I, H_0^1)$, see proposition B.3.3, and the proof of theorem B.2.1.11. And by proposition B.3.3 we can get to:

$$\begin{aligned} w &\in W_0(I, H_c^1), \bar{u} + v_0 \in W_0(I, H_c^1), v_0 \in W_0(I, H_0^1) \\ \int_I \langle w', q \rangle_{H_c^{1*}, H_c^1} + (\nabla w, \nabla q)_H &= \int_I (g, \text{tr} q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, H_c^1) \\ \int_I \langle v_0', p \rangle_{H^{-1}, H_0^1} + (\nabla v_0, \nabla p)_H &= - \int_I (\bar{u}', p)_H + (\nabla \bar{u}, \nabla p)_H, \quad \forall p \in Q^0(I, H_0^1) \end{aligned}$$

By proposition B.3.4 we obtain back:

$$\begin{aligned} w &\in W_0(I, H_c^1), \bar{u} + v_0 \in W_0(I, H_c^1), v_0 \in W_0(I, H_0^1) \\ w' + Aw &= (g, \cdot)_{L^2(\Gamma_f)} \text{ in } H_c^{1*} \text{ and for a.e. } t \in (0, T) \\ v_0' + Av_0 &= -((\bar{u}', \cdot)_H + A\bar{u}) \text{ in } H^{-1} \text{ and for a.e. } t \in (0, T) \end{aligned}$$

Therefore:

Proposition B.3.5 (Equivalent formulation)

Under assumption B.2.1.1, assumption B.2.2.1, problem B.2.1.2, problem B.2.2.2 can be equivalently formulated as:

$$\begin{aligned} w &\in Q_0(I, H_c^1), \bar{u} + v_0 \in Q_0(I, H_c^1), v_0 \in Q_0(I, H_0^1) \\ \int_I (w', q)_H + (\nabla w, \nabla q)_H &= \int_I (g, \text{tr} q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, H_c^1) \\ \int_I (v_0', p)_H + (\nabla v_0, \nabla p)_H &= - \int_I (\bar{u}', p)_H + (\nabla \bar{u}, \nabla p)_H, \quad \forall p \in Q^0(I, H_0^1) \end{aligned}$$

Existence, uniqueness and stability proved already in theorem B.2.1.11, theorem B.2.2.10 carry over to this new formulation.

C. Domains transformations

C.1. Transforming domains

Proposition C.1.1 (Measurability of composition)

Define $\mathcal{M} := \{\tau : \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ Lebesgue measurable}\} / \sim$, the quotient being the almost everywhere equal relation (according to the Lebesgue measure).

Consider also U from $\mathcal{M}_c := \{\tau : \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ continuous}\} / \sim$, the application "unique continuous representative", and $\mathcal{M}_{BL} := \{\tau : \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ Lipschitz homeomorphism}\} / \sim \subseteq \mathcal{M}_c$.

We can then define $\circ : \mathcal{M} \times \mathcal{M}_{BL}, \mathcal{M}_c \times \mathcal{M} \rightarrow \mathcal{M}$ by, respectively, $[f] \circ g := [f \circ U(g)], f \circ [g] := [U(f) \circ g]$. These definitions are well posed.

Proof.

\mathcal{M}_c

$U(f)$ is Borel measurable, so the preimage of a Borel set is Borel measurable, and g is Lebesgue measurable, so his preimage of such Borel set is Lebesgue measurable ([see here for the different notions of measurability](#)).

This shows that $U(f) \circ g$ is measurable.

To complete the well posedness, if $h = g$ a.e., then clearly $U(f) \circ g = U(f) \circ h$ a.e..

\mathcal{M}_{BL}

Consider $f \circ U(g)$. We need to prove it is measurable and that only depends on $[f]$.

For the measurability: the preimage of a Borel set, by f , is Lebesgue measurable L . $U(g)$ has a Lipschitz inverse, which will map this set to a Lebesgue set. Indeed, $L = B \cup N$, with B Borel and N Lebesgue measurable and null ([see here](#)). Image and unions commute, so, $U(g)^{-1}(L) = U(g)^{-1}(B) \cup U(g)^{-1}(N)$. The first set is Lebesgue measurable by measurability of $U(g)$, the second one is null, because Lipschitz maps map null sets into null sets, see 9.54 at page 271 of [23].

□

Throughout, D is a bounded Lipschitz domain. We define as in [29] the following spaces of transformations:

Definition C.1.2 (Spaces of transformations)

We define:

- $\mathcal{V}^k = \{\tau \in \mathcal{M}, \tau - \text{Id} \in W^{k,\infty}(\mathbb{R}^n, \mathbb{R}^n)\}, k \geq 1$
- $\mathcal{T}^k = \{\tau \in \mathcal{V}^k \text{ with an } \eta \in \mathcal{V}^k, \tau \circ \eta = \eta \circ \tau = \text{Id}\}$. Any such η is unique, we denote it by τ^{-1} and we have that $U(\tau)$ is a Lipschitz homeomorphism with $U(\tau^{-1}) = U(\tau)^{-1}$

Observation C.1.3 (A technicality). Technically, in the original definition of [29], τ need not to be a continuous function, although this is suggested e.g. in remarque 2.1 at page II-4.

Going to equivalence classes of τ makes the identification with continuous functions more precise, as we now show.

One implication

Let $\tau : \mathbb{R}^n \rightarrow \mathbb{R}^n$ with $[\tau - \text{Id}] \in W^{k,\infty}$. Then τ is equal a.e. to a (Lebesgue) measurable function, hence also (Lebesgue) measurable, and thus $[\tau] \in \mathcal{V}^k$ as we have defined it (**this is proved here; note that $\{g \neq f\}$ is measurable as the Lebesgue measure is complete**).

Now, suppose τ is a bijection, and $[\tau^{-1} - \text{Id}] \in W^{k,\infty}$ too. Then $\tau = \text{Id} + g = G$, $\tau^{-1} = \text{Id} + h = H$ almost everywhere. Here, G, H are at least Lipschitz. But then $\tau \circ H = \text{Id}$ a.e., and since H is Lipschitz, we can conclude also $G \circ H = \text{Id}$ a.e., so, everywhere. With a symmetric reasoning, we are lead to $G = H^{-1}$, so that G is bi-Lipschitz.

Thus, $[\tau] \circ [\tau^{-1}] := [U(\tau) \circ U(\tau^{-1})] = [G \circ G^{-1}] = \text{Id}$ and an analogous reasoning leads to $[\tau] \in \mathcal{T}^k$ as we have defined it.

The other implication

It is immediate for \mathcal{V}^k and for \mathcal{T}^k , in the equivalence class of $\tau \in \mathcal{T}^k$ there is a unique $U(\tau)$ at least bi-Lipschitz, hence invertible, with $[U(\tau)] = \tau$.

This shows that:

1. $\{\tau : \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ with } [\tau - \text{Id}] \in W^{k,\infty}\} / \sim = \mathcal{V}^k$
2. $\{\tau : \mathbb{R}^n \rightarrow \mathbb{R}^n \text{ bijection with } [\tau^{\pm 1} - \text{Id}] \in W^{k,\infty}\} / \sim = \mathcal{T}^k$

We need to check the well-posedness of \circ .

Proposition C.1.4

$\circ : \mathcal{V}^1 \times \mathcal{V}^1 \rightarrow \mathcal{V}^1$ and $\circ : W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n) \times \mathcal{V}^1 \rightarrow W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n)$ are well defined.

Proof.

We start by $\circ : W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n) \times \mathcal{V}^1 \rightarrow \mathcal{V}^1$. We have $\theta \circ \tau = [U(\theta) \circ U(\tau)]$ for instance (see proposition C.1.1); the latter is a bounded Lipschitz map, so it remains in $W^{1,\infty}$.

For the second claim, just write $\eta \circ \tau - \text{Id} = (\eta - \text{Id}) \circ \tau + \tau - \text{Id}$ and use the first part.

□

Proposition C.1.5 (Chain rule for $k = 1$)

Let $f \in W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n)$ or \mathcal{V}^1 , together with $\psi \in \mathcal{T}^1$. Then:

- $f \circ \psi$ has essentially bounded weak derivatives, and $D(f \circ \psi) = Df \circ \psi D\psi$. The equality holds a.e. also for the classical derivatives.
- $D(\psi^{-1}) = (D\psi)^{-1} \circ \psi^{-1}$, where $(D(\psi^{-1}))^{-1} := [(DU(\psi^{-1}))^{-1}]$, the representative being a.e. invertible. The equality holds a.e. also for the classical derivatives.
- $|\det(D\psi)|$ is an essentially bounded measurable function with $|\det(D\psi)| \geq \delta > 0$ a.e..

Proof.

Weak derivatives

We notice that $f \circ \phi$ has a unique Lipschitz representative, that is $U(f) \circ U(\phi)$. The desired formula follows as in [29], lemme 2.1 at page II-6, for the classical derivatives, because Lipschitz function are almost everywhere differentiable by the Rademacher theorem (**see here**). The chain rule holds for functions differentiable only at one point.

Now, to identify the weak derivatives:

- $U(f)$ is Lipschitz, so that $DU(f)$, the classical derivative, is also the weak derivative Df (note that f need not to be essentially bounded to state this). The latter is a measurable function, as a.e. limit of difference quotients.
- $DU(f) \circ U(\psi)$, is measurable, see proposition C.1.1. It is also essentially bounded.
- By proposition C.1.1 we observe that $DU(f) \circ U(\psi)$ represents $Df \circ \psi$
- $D\psi = [DU(\psi)]$ as seen above

- the product of equivalence classes is always defined as the product of their representatives

Therefore $Df \circ \psi D\psi = [DU(f) \circ U(\psi)DU(\psi)]$.

And now, because $f \circ \phi$ is Lipschitz, it has weak derivatives, $D(f \circ \phi)$, equal to the classical derivatives $DU(f \circ \phi) = D(U(f) \circ U(\psi)) = DU(f) \circ U(\psi)DU(\psi)$, where the last equality holds a.e., as mentioned at the beginning of the proof.

This let us conclude the first claim.

Inverse Jacobian

For the second one, put $f = \psi^{-1}$. Then, for the classical derivatives, $I = DU(\psi) \circ U(\psi)^{-1}DU(\psi^{-1})$ a.e., so that both $DU(\psi) \circ U(\psi)^{-1}, DU((\psi)^{-1})$ are invertible as matrices, a.e..

Determinant

We have defined $|\det(D\psi)| := [| \det DU(\psi) |]$, see proposition C.1.1. The claim follows as in lemme 4.2, pag. IV-7 of [29], and because \det is a polynomial of essentially bounded functions.

□

We go on to define the space of admissible transformations.

Definition C.1.6 (Admissible transformations)

We define $\Theta := \{\theta \in W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n) \text{ with } \theta = 0 \text{ on } \mathbb{R}^n \setminus D\}$, a Banach subspace of $W^{1,\infty}(\mathbb{R}^n, \mathbb{R}^n)$.

We also define $\mathcal{T} := \{\tau \in \mathcal{T}^1, \tau^{\pm 1}|_{\mathbb{R}^n \setminus D} = \text{Id}\}$.

Proposition C.1.7 (Some group properties of \mathcal{T})

Let $\eta, \tau \in \mathcal{T}, \theta \in \Theta$. Then:

- $\eta \circ \tau \in \mathcal{T}$
- $\theta \circ \tau \in \Theta$
- Id is the neutral element
- $\eta^{-1} \in \mathcal{T}$

Proof.

Stability under inversion

It is trivial, because the definition of \mathcal{T} is symmetric with respect to inversion.

Stability under composition (\mathcal{T}^1)

$\eta \circ \tau$ is surely in \mathcal{V}^1 by proposition C.1.1. Now, by the above point, $\tau^{-1} \circ \eta^{-1}$ is in \mathcal{V}^1 too, and the composition yields: $(\eta \circ \tau) \circ (\tau^{-1} \circ \eta^{-1}) = [U(\eta) \circ U(\tau)] \circ [(U\tau)^{-1} \circ (U\eta)^{-1}] = \text{Id}$.

□

Proposition C.1.8 (Small perturbations of \mathcal{T})

Let $\theta \in \Theta$ with small enough $\|\theta\|_{W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)}$. Then, $\text{Id} + \theta \in \mathcal{T}$.

Let $\delta\theta \in \Theta$ with small enough $\|\delta\theta\|_{W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)}$, and $\tau \in \mathcal{T}$. Then, $\tau + \delta\theta \in \mathcal{T}$.

Proof.

Perturbation of identity

We only need to check the properties of the inverse map.

$U(\tau)^{-1}$ exists and is Lipschitz, see the proof of lemme 2.4 of [29], page II-16. We can therefore define τ^{-1} and we obtain that it is \mathcal{V}^1 . So, $\tau \in \mathcal{T}^1$. The fact that $\tau = \text{Id}$ outside of D automatically implies $\tau^{-1} = \text{Id}$ outside of D , which can be seen more precisely by going to the smooth representatives of τ, τ^{-1} .

Perturbation, not of identity

We solve the equation $\tau + \delta\theta = \eta \circ \tau$, i.e., we define $\eta := \text{Id} + \delta\theta \circ \tau^{-1}$. Because $\tau^{-1} \in \mathcal{T}$ and $\delta\theta \in \Theta$ we observe that $\delta\theta \circ \tau^{-1} \in \Theta$, thanks to proposition C.1.7.

We only need to prove that $\delta\theta \circ \tau^{-1}$ is small, and then use the first part.

But by proposition C.1.5 this follows immediately. One can alternatively apply point i) of lemme 2.2, [29].

□

Theorem C.1.9

Small perturbations of identity, Lipschitz property Let $U \subset\subset D$ be Lipschitz bounded. There exists $0 < C(U) < 1$ such that, for $\tau \in W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)$ and $\|\tau - \text{Id}\|_{W^{1,\infty}(\mathbb{R}^n; \mathbb{R}^n)} \leq C(U)$, then $T(U)$ is also bounded Lipschitz, where T is $U(\tau)$, the unique Lipschitz continuous representative of τ (see proposition A.1.3).

This result can be applied to, e.g., $\tau \in \mathcal{T}$ which is a small perturbation of identity in the $W^{1,\infty}$ topology.

Proof.

It is done in [5], lemma 3, page 629.

□

C.2. Transforming Sobolev spaces**Theorem C.2.1** (Change of variables)

Let U be open and $T = U(\tau)$ for $\tau \in \mathcal{T}^1$, and let $p \in [1, \infty]$. Then:

1. $f \in L^p(T(U)) \iff f \circ T \in L^p(U)$ and there holds, for $f \in L^p(T(U))$:

$$\|f\|_{L^p(T(Q))} \leq \left(\|\det DT\|_{L^\infty(\mathbb{R}^n)} \right)^{1/p} \|f \circ T\|_{L^p(Q)}$$

2. $f \in W^{1,p}(T(U)) \iff f \circ T \in W^{1,p}(U)$ and there holds, for $f \in W^{1,p}(T(U))$:

$$Df \circ T = (Df)^{-t} D(f \circ T)$$

$$\|Df\|_{L^p(T(Q); \mathbb{R}^n)} \leq \left(\|\det DT\|_{L^\infty(\mathbb{R}^n)} \right)^{1/p} \|(DT)^{-1}\|_{L^\infty(\mathbb{R}^n; \mathbb{R}^{n \times n})} \|D(f \circ T)\|_{L^p(Q; \mathbb{R}^n)}$$

3. **add the rest of this proposition**

4. if $p \in (1, \infty)$, $f \in W_0^{1,p}(T(U)) \iff f \circ T \in W_0^{1,p}(U)$

5. therefore, composition by T is a linear isomorphism between $W^{k,p}(T(U)) \rightarrow W^{k,p}(U)$ for $k = 0, 1$, and between $W_0^{1,p}(T(U)) \rightarrow W_0^{1,p}(U)$ for $k = 0, 1$, $p \in (1, \infty)$

6. for D a bounded Lipschitz domain and \mathcal{T}, Θ defined before, we get, for $f \in H^1(D)$, that $\text{tr} f = \text{tr}(f \circ T)$

7. if moreover, $\Omega, T(\Omega) \subset\subset D$ are also bounded Lipschitz domains, letting $U := D \setminus \Omega$, another bounded Lipschitz domain, for $f \in H^1(T(U))$ and $\text{tr}_{T(U)} f = 0$ on $\partial T(\Omega)$, then $\text{tr}_U f \circ T = 0$ on $\partial \Omega$ and $\text{tr}_{T(U)} f = \text{tr}_U f \circ T$ on ∂D

8. so, $\circ T$ is a linear isomorphism of $H_c^1(U)$ and $H_c^1(T(U))$ (H_c^1 is defined in appendix B.2.1)

Proof.

We need to prove only the last points, for the other are proved in [29], pages IV.4, IV.5, IV.6.

Static strace

To do so, let $f_n \in C(\overline{D}) \cap H^1(D)$ converging in $H^1(D)$ to f . By point 4, we have $f_n \circ T \rightarrow f \circ T$ in $H^1(D)$ (remember, $T(D) = D$ by invertibility of T and the fact that $T(x) = x$ outside of D). Therefore we have:

$$\text{tr} f \leftarrow_{L^2(\partial D)} \text{tr}(f_n) = f_n|_{\partial D} = (f_n \circ T)|_{\partial D} = \text{tr}(f_n \circ T) \rightarrow_{L^2(\partial D)} \text{tr}(f \circ T)$$

Zero moving trace

First of all, as T is a homeomorphism of \mathbb{R}^n , $TU = D \setminus T(\Omega)$, $T\partial U = \partial D \sqcup \partial\Omega$, $T\partial\Omega = \partial T\Omega$.

Now, an application of theorem A.1.1 yields that the extension to 0 in $T\Omega$ of f , call it \bar{f} , is $H^1(D)$, with $\partial_i \bar{f} = \partial_i f$ in TU , 0 in $T(\Omega)$.

We claim that $\text{tr}_D \bar{f} = \text{tr}_{T(U)} f|_{\partial D}$. In fact, approximate \bar{f} by restrictions to D of $C_c^\infty(\mathbb{R}^n)$ functions f_n (see theorem 3.18 of [1], page 54), which also approximate f on $T(U)$, by the observation that $\|f_n|_{T(U)}\|_{H^1(T(U))} \leq \|f_n|_D\|_{H^1(D)}$. Then:

$$\text{tr}_{T(U)}(f_n|_{T(U)})|_{\partial D} = (f_n|_{T(U)})|_{\partial T(U)}|_{\partial D} = f_n|_{\partial D} = \text{tr}_D(f_n|_D)$$

Now, by what we observed before, $\text{tr}_{T(U)}(f_n|_{T(U)}) \rightarrow \text{tr}_{T(U)}(f)$ in $L^2(\partial T(U))$, so that $\text{tr}_{T(U)}(f_n|_{T(U)})|_{\partial D} \rightarrow \text{tr}_{T(U)}(f)|_{\partial D}$. On the other hand $\text{tr}_D(f_n|_D) \rightarrow \text{tr}_D \bar{f}$, which yields the claim.

Using this: $\text{tr}_{T(U)}(f)|_{\partial D} = \text{tr}_D \bar{f} = \{ \text{point 5} \} = \text{tr}_D(\bar{f} \circ T) = \text{tr}_D(\overline{f \circ T}) = \text{tr}_U(f \circ T)|_{\partial D}$, where we used that $\bar{f} \circ T$ is zero in $T^{-1}T\Omega = \Omega$ (because again T maps null sets into null sets), so it is the zero extension $\bar{f} \circ \overline{T}$ of $f \circ T$, and applied the same reasoning as above to conclude $\text{tr}_D(\bar{f} \circ \overline{T}) = \text{tr}_U(f \circ T)|_{\partial D}$. Both $\bar{f} \circ T$ and $f \circ T$ are H^1 functions by point 2.

We can now also say that $\text{tr}_U f \circ T = 0$ on $\partial\Omega$.

$$(\eta\phi_n)|_{\partial\Omega} = \text{tr}_U(\phi_n|_U)|_{\partial\Omega} \rightarrow \text{tr}_U(f \circ T)|_{\partial\Omega}$$

Multiplication by a $W^{1,\infty}$ function

We claim that, for $\psi \in W^{1,\infty}(\mathbb{R}^n; \mathbb{R})$ and $f \in H^1(U)$, then $f\psi$ has the same trace as f as long as $\psi = 1$ in a neighbourhood of ∂U .

Note that $f\psi \in H^1(U)$ still. Now: approximate f by restriction of test functions f_n . Then $f_n\psi$ is $C(\overline{U}) \cap H^1(U)$ (thanks also to corollary A.1.4), so that $\text{tr}_U(f_n\psi) = \text{tr}_U(f_n)$. Because $f_n\psi \rightarrow f\psi$ is $H^1(U)$ the claim is valid.

This last convergence follows from $\|(f_n - f)\psi\|_{L^2} \leq \|(f_n - f)\|_{L^2} \|\psi\|_{L^\infty}$, the chain rule $\partial_i(f_n\psi) = \partial_i f_n\psi + \partial_i \psi f_n$ (see [corollary 4.1.18 here](#)) and again $\|\partial_i(f_n - f)\psi\|_{L^2} \leq \|\partial_i(f_n - f)\|_{L^2} \|\psi\|_{L^\infty}$, $\|(f_n - f)\partial_i \psi\|_{L^2} \leq \|(f_n - f)\|_{L^2} \|\partial_i \psi\|_{L^\infty}$.

Reducing to a function of 0 trace

Let η be a smooth cut-off function which is 1 close to ∂D and 0 close to $\partial T\Omega$, $\beta = 0$ close to ∂D and 1 close to $\partial T\Omega$. This can be accomplished by e.g. building a suitable partition of unity of the compact sets $\partial\Omega$ and ∂D . ([can I do this? Yes, see bachelor's thesis, take \$K = \partial\Omega\$ etc. Also, be careful with all of these equalities...](#)).

$f\beta$ has zero trace, as it can be verified by approximating f by smooth functions again:

$$\text{tr}_{T(U)} f\beta \leftarrow_{L^2(\partial T(U))} \text{tr}_{T(U)} f_n\beta$$

where the latter quantity is $\text{tr}_{T(U)} f_n$ on $\partial T(U)$ and 0 on ∂D . By restricting the convergence to first ∂D and then to $\partial T(U)$, and using almost everywhere convergent subsequences, we conclude that $\text{tr}_{T(U)} f\beta = \text{tr}_{T(U)} f$ on $\partial T(U)$ and $\text{tr}_{T(U)} f\beta = 0$ on ∂D , i.e. $f\beta$ has zero trace.

Domain transformation

But zero trace functions in $H^1(T(U))$, since $T(U)$ is assumed to be bounded Lipschitz, are exactly the functions $H_0^1(T(U))$ (theorem 18.7 at page 595 of [23]).

By then point 4, $(f\beta) \circ T \in H_0^1(U)$.

Because T is bi-Lipschitz, we can write $(f\beta) \circ T = f \circ T\beta \circ T$ almost everywhere.

We have that $\beta \circ T + \eta \circ T$ is $W^{1,\infty}$ and 1 near ∂U .

So, $\text{tr}_U f \circ T = \text{tr}_U f \circ T(\beta \circ T + \eta \circ T) = \text{tr}_U(f \circ T\beta \circ T) + \text{tr}_U(f \circ T\eta \circ T)$.

Approximate $f \circ T$ by g_n smooth as seen above. Then, $\text{tr}_U(g_n\eta \circ T)$ is 0 on $\partial\Omega$ and $\text{tr}_U g_n$ on ∂D . By selecting an almost everywhere convergent subsequence, we conclude $\text{tr}_U(f \circ T\eta \circ T) = 0$ on $\partial\Omega$.

Hence $\text{tr}_U f \circ T|_{\partial\Omega} = \text{tr}_U f \circ T(\beta \circ T)|_{\partial\Omega} = 0$.

C.3. Transforming Bochner spaces

Proposition C.3.1 (Isomorphism between Q spaces)

$$\circ T : Q(I, V_T) \rightarrow Q(I, V)$$

is a linear isomorphism, and so is:

$$\circ T : Q_0(I, V_T) \rightarrow Q_0(I, V)$$

In particular, $(u \circ T)' = u' \circ T$ (under suitable identifications, see the proof).

Proof.

Existence of derivative

Consider the following commutative diagram:

$$\begin{array}{ccccccc} V_T & \xrightarrow{a_T} & H_T & \xrightarrow{r_T} & H_T^* & \xrightarrow{a_T^*} & V_T^* \\ \circ T_H =: t_V \downarrow & & \downarrow \circ T_H =: t_H & & & & \\ V & \xrightarrow{a} & H & \xrightarrow{r} & H^* & \xrightarrow{a^*} & V^* \end{array}$$

We know that $f \in Q(I, V_T)$ satisfies $a_T f \in H^1(I, H_T)$. Therefore, by proposition A.2.2, $t_H a_T f = a_V f \in H^1(I, H)$, and $t_V \in L^2(I, V)$, so that $t_V : Q(I, V_T) \rightarrow Q(I, V)$ is well defined.

Boundedness

We have that $t_V : V_T \rightarrow V$ is linear bounded, so that $t_V : L^2(I, V_T) \rightarrow L^2(I, V)$ is also linear and bounded. Still by proposition A.2.2, we have $(a_V f)' = (t_H a_T f)' = t_H (a_T f)'$.

Thus $\|t_V f\|_{L^2(I, V)} \leq C(T) \|f\|_{L^2(I, V_T)}$, together with $\|(a_V f)'\|_{L^2(I, H)} \leq C(T) \|(a_T f)'\|_{L^2(I, H_T)}$.

By noting that $(t_V)^{-1} = (\circ T)^{-1}$ is bijective, and by the bounded inverse theorem:

$$\circ T : Q(I, V_T) \rightarrow Q(I, V)$$

is a linear isomorphism.

Zero initial value

Consider $a_V f$. It has a unique $C([0, T], H)$ representative, $U(a_V f)$. Also, $a_T f$ has a unique continuous representative $U(a_T f)$. Now, $a_V f = t_H a_T f$, so that $[U(a_V f)] = [t_H U(a_T f)]$. By continuity, $U(a_V f) = t_H U(a_T f)$ on $[0, T]$ and thus, whenever $U(a_T f)(0) = 0$, so is $U(a_V f)$, informally, also $t_V f(0) = 0$.

So, $t_V(Q_0(I, V_T)) \subseteq Q_0(I, V)$.

$(t_V)^{-1} = (\circ T)^{-1}$ and we can conclude that $t_V^{-1}(Q_0(I, V)) \subseteq Q_0(I, V_T)$.

C.4. Transforming partial differential equations

We consider again the two parabolic equations of interest, namely, problem B.2.1.2 and problem B.2.2.2.

We continue from proposition B.3.5.

$$\begin{aligned}
w &\in Q_0(I, H_c^1), v_0 \in Q_0(I, H_0^1) \\
\int_I (w', q)_H + (\nabla w, \nabla q)_H &= \int_I (g, \text{tr} q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, H_c^1) \\
\int_I (v_0', p)_H + (\nabla v_0, \nabla p)_H &= - \int_I (\bar{u}', p)_H + (\nabla \bar{u}, \nabla p)_H, \quad \forall p \in Q^0(I, H_0^1)
\end{aligned}$$

We are working under the assumption:

Assumption C.4.1

We have $T = U(\tau), \tau \in \mathcal{T}, U \subset\subset D$ bounded Lipschitz domains and we also assume that $T(U)$ is bounded Lipschitz.

Suppose the problem is formulated on $T(U)$. To ease the notation, call $H_c^1(T(U)) = V_T, H_c^1(U) = V, H_0^1(U) = W$ and analogously for the other spaces.

We write the problem as:

$$\begin{aligned}
w^T &\in Q_0(I, V_T), v_0^T \in Q_0(I, W_T) \\
\int_I (w_t^T, q)_{H_T} + (\nabla w^T, \nabla q^T)_{H_T} &= \int_I (g, \text{tr}_{T(U)} q^T)_{L^2(\Gamma_f)}, \quad \forall q^T \in Q^0(I, V) \\
\int_I (v_{0t}^T, p)_{H_T} + (\nabla v_0^T, \nabla p^T)_{H_T} &= - \int_I (\bar{u}', p^T)_{H_T} + (\nabla \bar{u}, \nabla p^T)_{H_T}, \quad \forall p^T \in Q^0(I, W_T)
\end{aligned}$$

Applying a change of variables, we get equivalently:

$$\begin{aligned}
w^T &\in Q_0(I, V_T), v_0^T \in Q_0(I, W_T) \\
\int_I (w_t^T \circ T, q^T \circ T | \det(DT)|)_{H_T} + (A_T \nabla(w^T \circ T), \nabla(q^T \circ T))_{H_T} &= \\
&= \int_I (g, \text{tr}_{T(U)} q^T)_{L^2(\Gamma_f)}, \quad \forall q^T \in Q^0(I, V_T) \\
\int_I (v_{0t}^T \circ T, p^T \circ T | \det(DT)|)_{H_T} + (A_T \nabla(v_0^T \circ T), \nabla(p^T \circ T))_{H_T} &= \\
- \int_I ((\bar{u}') \circ T, p^T \circ T | \det(DT)|)_{H_T} + (A_T \nabla(\bar{u} \circ T), \nabla(p^T \circ T))_{H_T}, \quad \forall p^T \in Q^0(I, W_T)
\end{aligned}$$

Here $A_T = |\det(DT)|DT^{-1}(DT)^{-t}$.

Now, we note that:

- $\text{tr}_{T(U)} q = \text{tr}_U(q \circ T)$ on Σ_f by theorem C.2.1
- $w_t^T \circ T = (w^T \circ T)_t$ by the proof of proposition C.3.1 and analogously for v_0
- by proposition C.3.1, $\circ T$ is a bijection between $Q^0(I, V_T)$ and $Q^0(I, V)$ and analogously for W
- $\bar{u} \in H^1(I, V_T)$ and that \bar{u}' denoted the weak derivative in the $H^1(I, V_T)$ sense, so that A.2.1 yields $\bar{u} \circ T \in H^1(I, V)$ and $(\bar{u} \circ T)' = \bar{u}' \circ T$

We therefore get, equivalently:

$$\begin{aligned}
& w^T \in Q_0(I, V_T), v_0^T \in Q_0(I, W_T) \\
& \int_I ((w^T \circ T)_t, q | \det(DT)|)_H + (A_T \nabla(w^T \circ T), \nabla q)_H = \\
& \int_I (g, \text{tr}_U q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, V) \\
& \int_I ((v_0^T \circ T)_t, p | \det(DT)|)_H + (A_T \nabla(v_0^T \circ T), \nabla p)_H = \\
& - \int_I ((\bar{u} \circ T)', p | \det(DT)|)_H + (A_T \nabla(\bar{u} \circ T), \nabla p)_H, \quad \forall p \in Q^0(I, W)
\end{aligned}$$

and by proposition C.3.1, we also get $w^T \circ T \in Q_0(I, V)$, $v_0^T \circ T \in Q_0(I, W)$.

On the other hand, consider:

$$\begin{aligned}
& w \in Q_0(I, V), v_0 \in Q_0(I, W) \\
& \int_I (w_t, q | \det(DT)|)_H + (A_T \nabla w, \nabla q)_H = \int_I (g, \text{tr}_U q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, V) \\
& \int_I (v_{0t}, p | \det(DT)|)_H + (A_T \nabla v_0, \nabla p)_H = \\
& - \int_I ((\bar{u} \circ T)', p | \det(DT)|)_H + (A_T \nabla(\bar{u} \circ T), \nabla p)_H, \quad \forall p \in Q^0(I, W)
\end{aligned}$$

Then, we note the following:

- by proposition C.3.1, $w \circ T^{-1} \in Q_0(I, V_T)$, $v_0 \circ T^{-1} \in Q_0(I, W_T)$, and as seen above, $((w \circ T^{-1}) \circ T)_t = (w \circ T^{-1})_t \circ T$ and the same goes for $v_0 \circ T^{-1}$

Therefore we obtain, equivalently:

$$\begin{aligned}
& w \circ T^{-1} \in Q_0(I, V_T), v_0 \circ T^{-1} \in Q_0(I, W_T) \\
& \int_I ((w \circ T^{-1})_t, q^T)_{H_T} + (\nabla(w \circ T^{-1}), \nabla q^T)_{H_T} = \\
& \int_I (g, \text{tr}_{T(U)} q^T)_{L^2(\Gamma_f)}, \quad \forall q^T \in Q^0(I, V_T) \\
& \int_I ((v_0 \circ T^{-1})_t, p^T)_{H_T} + (\nabla(v_0 \circ T^{-1}), \nabla p^T)_{H_T} = \\
& - \int_I (\bar{u}', p^T)_{H_T} + (\nabla \bar{u}, \nabla p^T)_{H_T}, \quad \forall p^T \in Q^0(I, W_T)
\end{aligned}$$

and $w \circ T^{-1} \in Q_0(I, V_T)$, $v_0 \circ T^{-1} \in Q_0(I, W_T)$.

These findings can be summarized as follows.

Theorem C.4.2 (Equivalent formulations with transported domain)

Let assumption B.2.1.1, assumption B.2.2.1, assumption C.4.1 hold.

Consider the following problems.

Problem C.4.3 (Joint parabolic problem, moving domain)

$$\begin{aligned} w^T &\in Q_0(I, V_T), v_0^T \in Q_0(I, W_T) \\ \int_I (w_t^T, q^T)_{H_T} + (\nabla w^T, \nabla q^T)_{H_T} &= \int_I (g, \text{tr}_{T(U)} q^T)_{L^2(\Gamma_f)}, \quad \forall q^T \in Q^0(I, V_T) \\ \int_I (v_{0t}^T, p^T)_{H_T} + (\nabla v_0^T, \nabla p^T)_{H_T} &= - \int_I (\bar{u}', p^T)_{H_T} + (\nabla \bar{u}, \nabla p^T)_{H_T}, \quad \forall p^T \in Q^0(I, W_T) \end{aligned}$$

Problem C.4.4 (Joint parabolic problem, reference domain)

$$\begin{aligned} w &\in Q_0(I, V), v_0 \in Q_0(I, W) \\ \int_I (w_t, q | \det(DT)|)_{H_T} + (A_T \nabla w, \nabla q)_H &= \int_I (g, \text{tr}_U q)_{L^2(\Gamma_f)}, \quad \forall q \in Q^0(I, V) \\ \int_I (v_{0t}, p | \det(DT)|)_{H_T} + (A_T \nabla v_0, \nabla p)_H &= \\ - \int_I ((\bar{u} \circ T)', p | \det(DT)|)_{H_T} + (A_T \nabla (\bar{u} \circ T), \nabla p)_H, \quad \forall p \in Q^0(I, W) \end{aligned}$$

We have the following:

- consider $w^T \in Q_0(I, V_T), v_0^T \in Q_0(I, W_T)$. They solve problem C.4.3 $\iff w^T \circ T, v_0^T \circ T$ solve problem C.4.4
- consider $w \in Q_0(I, V), v_0 \in Q_0(I, W)$. They solve problem C.4.4 $\iff w \circ T^{-1}, v_0 \circ T^{-1}$ solve problem C.4.3

Here, $A_T := (DT)^{-1}(DT)^{-t} |\det(DT)|$.

D. Inhomogenous FEM on smooth domains

please make precise the mesh assumptions

D.1. Elliptic problems

We consider a finite element method for approximating problems of the following form.

Assumption D.1.1 (Basic assumptions for elliptic problems)

Consider $\Omega \subseteq \mathbb{R}^n$, $n = 2, 3$, with C^2 boundary, and data $f \in L^2(\Omega)$, $g_D \in H^{3/2}(\Gamma_D)$, $g_N \in H^{1/2}(\Gamma_N)$, where $\Gamma_D \sqcup \Gamma_N = \partial\Omega$ and $\overline{\Gamma_D} \cap \overline{\Gamma_N} = \emptyset$. We assume Γ_D to be non-empty.

Problem D.1.2 (Inhomogeneous elliptic problem)

Under assumption D.1.1, the problem is:

$$\begin{cases} -\Delta u + ku = f & \text{on } \Omega \\ u = g_D & \text{on } \Gamma_D \\ \partial_\nu u = g_N & \text{on } \Gamma_N \end{cases}$$

where $k \geq 0$ is a constant.

By this we mean to find $u \in H^1(\Omega)$ with:

$$a(u, v) = l(v), \text{ for all } v \in H_{0,D}^1$$

where $a(u, v) = \int_{\Omega} \nabla u \nabla v + k \int_{\Omega} uv$, and $l(v) = \int_{\Omega} fv + \int_{\Gamma_N} g_N v$ and $H_{0,D}^1$ is the space of all H^1 functions with vanishing trace on Γ_D .

Add existence, uniqueness, regularity

We define a polygonal/polyhedral meshing Ω_h of Ω , which has boundary nodes on $\partial\Omega$. We denote by $\Gamma_{D,h}, \Gamma_{N,h}$ the discrete Dirichlet and Neumann boundaries, and by $S_{h,D}^1$ the space of piecewise linear lagrangian FEM S_h^1 which are zero on $\Gamma_{D,h}$.

We collect some useful tools to relate Ω and Ω_h .

Proposition D.1.3 (Deformation into smooth boundary)

Assume a quasi-uniform mesh. There exists, for h small enough, $G_h : \Omega_h \rightarrow \overline{\Omega}$ satisfying:

- G_h is a homeomorphism **Injectivity is actually not so easy, let's assume this**
- $G_h|_T$ is of class $C^2(T)$ for all closed simplices T composing Ω_h
- $G_h|_T = \text{Id}$ on interior simplices T (those with at most one node on $\partial\Omega$)
- $G_h(\partial\Omega_h) = \partial\Omega$
- $G_h|_e = p$, where e is an edge/face of $\partial\Omega_h$ and p is the closest point operator to $\partial\Omega$ (so that $G_h|_{\partial\Omega_h}$ coincides with the boundary lift in Definition 4.12 of [14])

Proof.

See Section 4.1 of [14] for the first three points, while the second-last one follows from G_h being a homeomorphism.

The last one is a consequence of the definition of G_h , see [14].

□

Given G_h , we can define pullbacks and pushforwards of functions defined on Ω or Ω_h .

Proposition D.1.4 (Lift)

We define, for $u : \Omega \rightarrow \mathbb{R}$, $u^{-l} := u \circ G_h : \Omega_h \rightarrow \mathbb{R}$, and analogously for $u_h : \Omega_h \rightarrow \mathbb{R}$ we define $u_h^l := u_h \circ G_h^{-1}$. We also need the mesh to be quasi-uniform (see Proposition 4.7 of [14]).

There holds:

- if $v \in H^m(T)$ if and only if $v^{-l} \in H^m(G_h(T))$, for $m = 0, 1$
- for $v_h \in S_h^1$, we have $v_h^l \in H^1(\Omega)$
- for $v_h \in S_{h,D}^1$, we have $v_h^l \in H^1(\Omega)$, with zero trace on Γ_D
- for $v_h \in S_h^1$, one has the following norm equivalences, which don't depend on h :
 1. $\|v_h\|_{L^2(\partial\Omega_h)} \sim \|v_h^l\|_{L^2(\partial\Omega)}$
 2. $\|v_h\|_{L^2(\Omega_h)} \sim \|v_h^l\|_{L^2(\Omega)}$
 3. $\|\nabla v_h\|_{L^2(\Omega_h)} \sim \|\nabla v_h^l\|_{L^2(\Omega)}$
- consequently, the lifting operator $S_{h,D}^1 \rightarrow H_{0,D}^k(\Omega)$ is bounded, for the L^2 norms if $k = 0$, and H^1 norms if $k = 1$

Proof.

We refer to [6] for the first point, to Lemma 2.3. This is applicable as $G_h(T)$ is a curved simplex of class C^1 in the notation of [6], and this fact is guaranteed by lemma 8.13 and by following example 2 of [6].

The second and third points follow by applying the arguments about conformity outlined in section 5 of [6]. Following again Example 2 therein, we discover that we can apply Proposition and Corollary 5.1.

The last point can be found in [14], see e.g Proposition 4.9 and 4.13.

□

Now, define $f_h \in S_h^1$, $g_{N,h} \in S_h^1(\Gamma_{N,h})$ to be any finite element approximations of f, g_N . Note, here $S_h^1(\Gamma_{N,h})$ means the usual piecewise linear FEM space over $\Gamma_{N,h}$.

We can now define the discrete approximation of problem D.1.2.

Problem D.1.5 (FEM approximation of problem D.1.2)

We find $u_h \in S_h^1$ with $u_h(p) = g_D(p)$ for all p external nodes of $\partial\Omega_h$, and solving:

$$a_h(u_h, v_h) = l_h(v_h), \text{ for all } v_h \in S_{h,D}^1$$

$$\text{where } a_h(u_h, v_h) = \int_{\Omega_h} \nabla u_h \nabla v_h + k \int_{\Omega_h} u_h v_h, \text{ and } l_h(v_h) = \int_{\Omega_h} f_h v_h + \int_{\Gamma_{N,h}} g_{h,N} v_h$$

Add existence, uniqueness, connection with Fenics

Note, we assumed $g_D \in H^{3/2}(\partial\Omega)$. Thanks to the C^2 smoothness of $\partial\Omega$ we can apply theorem 1.5.1.2 of [20] and obtain a $G \in H^2(\Omega)$ with $\text{tr}_2 G = g_D$. Here tr_2 denotes the trace operator from $H^2(\Omega)$. By Sobolev embeddings, $G \in C(\overline{\Omega})$.

Now, we can pick $G_k \in C^\infty(\overline{\Omega}) \cap H^2(\Omega)$ converging in $H^2(\Omega)$ to G . We can do so by [1], theorem 3.18 at page 54. Then: $G_k|_{\partial\Omega} = \text{tr}_2 G_k \rightarrow \text{tr}_2 G = g_D$, and by $H^2(\Omega) \hookrightarrow C(\overline{\Omega})$ we obtain $G|_{\partial\Omega} = g_D$, so that g_D is continuous in both $n = 2, 3$ and so we can define its pointwise interpolation.

Alternatively we could have used Sobolev embeddings on manifolds to arrive to the same conclusion.

Proposition D.1.6 (Interpolation on curved domains)

Let $u \in H^2(\Omega)$, let $g \in H^2(\partial\Omega)$.

Let $u \in H^2(\Omega)$ and define $\Pi_c u = (\Pi_h u)^l$, where Π_h is the usual pointwise Lagrange interpolator on S_h^1 .

We can also define $\Pi_c g$ for $g \in H^2(\partial\Omega)$ in the same fashion.

It follows that:

- $\|u - \Pi_c u\|_{L^2(\Omega)} + h \|u - \Pi_c u\|_{H^1(\Omega)} \lesssim h^2 \|u\|_{H^2(\Omega)}$
- $\|g - \Pi_c g\|_{L^2(\partial\Omega)} + h \|g - \Pi_c g\|_{H^1(\partial\Omega)} \lesssim h^2 \|g\|_{H^2(\partial\Omega)}$

Here $a \lesssim b$ means $a \leq Cb$ for $C \geq 0$ not depending on h .

Proof.

See Proposition 5.4 of [14]. □

Proposition D.1.7 (Approximation of linear and bilinear forms)

Prop. 4.6 of Edelmann, add this.

Theorem D.1.8 (H^1 estimate)

For h small enough, we have $\|u - u_h^l\|_{H^1(\Omega)} \lesssim h + \|f - f_h^l\|_{L^2(\Omega)} + \|g_N - g_{h,N}^l\|_{L^2(\Gamma_N)}$

Proof.

We partially follow the structure of the arguments in [12], making some simplifications, and modifications to adapt them to our case.

Conclusion

$\|u - u_h^l\|_{H^1(\Omega)} \leq \|u - \Pi_c u\|_{H^1(\Omega)} + \|\Pi_c u - u_h^l\|_{H^1(\Omega)}$. The interpolation estimates proposition D.1.6 allow us to worry only about the second term. It is $\|(\Pi_h u - u_h)^l\|_{H^1(\Omega)} \lesssim \|\Pi_h u - u_h\|_{H^1(\Omega_h)}$ by proposition D.1.4. We estimate the latter quantity, calling $e_h := u_h - \Pi_h u$, which is zero on $\Gamma_{D,h}$.

Defect, e_h and u

Let $d_h \in S_{h,D}^1$ be the unique solution to $a_h(d_h, v_h) = l_h(v_h) - a_h(\Pi_h u, v_h)$, $v_h \in S_{h,D}^1$.

Using $0 = l_h(v_h) - a_h(u_h, v_h)$, $v_h \in S_{h,D}^1$, we come to $a_h(d_h - e_h, v_h) = 0$, $v_h \in S_{h,D}^1$. Testing with $d_h - e_h = 0$ on $\Gamma_{D,h}$ and using the connectedness of Ω_h , we conclude that $e_h = d_h$.

Moreover, by proposition D.1.4, we have $v_h^l \in H_{0,D}^1$, so that $a(u, v_h^l) = l(v_h^l)$ and thus :

$$a_h(e_h, v_h) = l_h(v_h) - l(v_h^l) + a(u, v_h^l) - a_h(\Pi_h u, v_h)$$

Estimation of e_h

The form a_h is H^1 coercive, h -uniformly. This we show by the following estimate, C not depending on h :

$$\begin{aligned} a_h(v_h, v_h) &= a(v_h^l, v_h^l) + a_h(v_h, v_h) - a(v_h^l, v_h^l) \\ &\geq C \|v_h^l\|_{H^1(\Omega)}^2 - |a_h(v_h, v_h) - a(v_h^l, v_h^l)| \\ &\geq C \|v_h\|_{H^1(\Omega_h)}^2 - Ch \|v_h^l\|_{H^1(\Omega)}^2 \\ &\geq C(1 - h) \|v_h\|_{H^1(\Omega_h)}^2 \end{aligned}$$

We used, in order:

- the h -uniform coercivity of a (descending from the Poincaré inequality in which functions vanish only on part of the boundary, Γ_D , see e.g. lemma 1 of [11])

- proposition D.1.4 on $\|v_h^l\|_{H^1(\Omega)}^2$
- Proposition 4.6 of [12]

Therefore $\|e_h\|_{H^1(\Omega_h)}^2 \lesssim a_h(e_h, e_h) = l_h(e_h) - l(e_h^l) + a(u, e_h^l) - a_h(\Pi_h u, e_h)$, where we can test by $e_h = 0$ on $\Gamma_{D,h}$.

This last term is estimated exactly as in Proposition 5.5 of [12]. In particular, we make use of the H^2 regularity of u , and we extend $g_{N,h}, g_N$ to zero, on $\Gamma_{D,h}, \Gamma_D$

□

Note, the assumption of non-emptiness of the Dirichlet boundary is not strictly necessary, and can be removed, when $k > 0$. In this case, we have to modify the above arguments because a is not coercive anymore, but this is possible by consider a slightly different defect equation, where an L^2 scalar product is added.

For an L^2 error estimate we apply the Aubin-Nitsche trick, following [16] and [12].

Theorem D.1.9 (L^2 estimate)

Assume either that $f \in H^1(\Omega)$ or that $\|f_h^l\|_{H^1(\Omega)} \lesssim \|f\|_{L^2(\Omega)}$. Then, for h small enough, we have $\|u - u_h^l\|_{L^2(\Omega)} \lesssim h^2 + \|f - f_h^l\|_{L^2(\Omega)} + \|g_N - g_{h,N}^l\|_{L^2(\Gamma_N)} + \|g_D - \Pi_c g_D\|_{L^2(\Gamma_D)} + A$, where $A = 0$ if $\|f_h^l\|_{H^1(\Omega)} \lesssim \|f\|_{L^2(\Omega)}$ and $A = h^2 \|f - f_h^l\|_{H^1(\Omega)}$ otherwise.

Proof.

Define $e := u - u_h^l$ (whose boundary values at Γ_D are not necessarily 0!), and z solving the dual problem:

$$\begin{cases} -\Delta z + kz = e & \text{on } \Omega \\ z = 0 & \text{on } \Gamma_D \\ \partial_\nu z = 0 & \text{on } \Gamma_N \end{cases}$$

This problem possesses H^2 regularity, so that we can write, after multiplying both sides by $e \in H^1$ (thanks to proposition D.1.4):

$$\|e\|_{L^2(\Omega)}^2 = a(z, e) - \int_{\partial\Omega} e \partial_\nu z$$

Using that $z \in H^2$ we have that $\partial_\nu z = 0$ on Γ_N , together with the estimate $\|z\|_{H^2(\Omega)} \lesssim \|e\|_{L^2(\Omega)}$ (check!! It's done at page 92 of Grisvard) and thus:

$$\begin{aligned} \|e\|_{L^2(\Omega)}^2 &= a(z, e) + \|e\|_{L^2(\Gamma_D)} \|\partial_\nu z\|_{L^2(\partial\Omega)} \\ &\leq a(z, e) + C \|e\|_{L^2(\Gamma_D)} \|e\|_{L^2(\Omega)} \end{aligned}$$

Only $a(z, e)$ remains to be estimated, and this is done in the proof of Theorem 5.3 of [12], and in remark 5.6.

□

Corollary D.1.10 (Actual estimates)

By assuming f, g_N, g_D in H^2 we conclude $\|u - u_h^l\|_{H^1(\Omega)} \lesssim h, \|u - u_h^l\|_{L^2(\Omega)} \lesssim h^2$.

Proof.

It suffices to take $f_h := \Pi_h f$, $g_{N,h} = \Pi_h g$ and employ proposition D.1.6.

□

Unfortunately the smoothness assumptions to obtain optimal order of convergence are quite strict. However, the advantage of this approach is that it is straightforward to implement, and works in both dimensions $n = 2, 3$.

If one is concerned with just H^1 error estimates, without taking numerical integration into account, we can relax the requirements on f . Incidentally, how we are about to choose f , is more in line with the implementation of Fenics.

Proposition D.1.11 (H^1 estimate with rougher f)

We choose $f_h = f$ on $\Omega \cap \Omega_h$ and 0 otherwise, assuming $f \in H^1(\Omega)$. Then we obtain, for h small enough,

$$\|u - u_h^l\|_{H^1(\Omega)} \lesssim h + \|g_N - g_{h,N}^l\|_{L^2(\Gamma_N)}$$

Proof.

Analysing the proof of Proposition 5.5 in [12] we see that we only need to prove that $\left| \int_{\Omega} f v_h^l - \int_{\Omega_h} f_h v_h \right| \lesssim h \|v_h^l\|_{H^1(\Omega)}$, for $v_h \in S_{h,D}^1$.

We can rewrite the difference as follows:

$$\begin{aligned} & \int_{\Omega} f v_h^l - \int_{\Omega_h} f_h v_h = \\ & \int_{\Omega \cap \Omega_h} f v_h^l - \int_{\Omega_h \cap \Omega} f_h v_h + \int_{\Omega \setminus \Omega_h} f v_h^l - \int_{\Omega_h \setminus \Omega} f_h v_h = \\ & \int_{\Omega \cap \Omega_h} f v_h^l - \int_{\Omega_h \cap \Omega} f_h v_h + \int_{\Omega \setminus \Omega_h} f v_h^l = \\ & \int_{\Omega \cap \Omega_h^{\partial}} f(v_h^l - v_h) + \int_{\Omega \setminus \Omega_h} f v_h^l \end{aligned}$$

where we used that $f = 0$ outside of Ω , that $f = f_h$ in $\Omega \cap \Omega_h$ and that $v_h^l = v_h$ for all simplices with at most one node on $\partial\Omega$ (by the definition of G_h). The set of all the other (straight) simplices is denoted by Ω_h^{∂} .

For the first integral we have that for h small enough, $\Omega \setminus \Omega_h \subseteq N_{ch^2}$ (see [32] for this), for $N_{\delta} := \{x \in \Omega, 0 < \text{dist}(x, \partial\Omega) < \delta\}$.

Using the assumption $f \in H^1(\Omega)$, together with Lemma 4.10 of [14], we conclude that:

$$\left| \int_{\Omega \setminus \Omega_h} f v_h^l \right| \leq \|f\|_{L^2(N_{\delta})} \|v_h^l\|_{L^2(N_{\delta})} \lesssim \delta \|f\|_{H^1(\Omega)} \|v_h^l\|_{H^1(\Omega)}$$

To control the other integral, we note that $\Omega \cap \Omega_h^{\partial} \subseteq N_h$, also for h small enough. Then:

$$\begin{aligned} \left| \int_{\Omega \cap \Omega_h^{\partial}} f(v_h^l - v_h) \right| & \leq \|f\|_{L^2(N_h)} (\|v_h^l\|_{L^2(N_h)} + \|v_h\|_{L^2(\Omega \cap \Omega_h^{\partial})}) \\ & \lesssim h^{1/2} \|f\|_{H^1(\Omega)} (h^{1/2} \|v_h^l\|_{H^1(\Omega)} + \|v_h\|_{L^2(\Omega \cap \Omega_h^{\partial})}) \end{aligned}$$

But $\|v_h\|_{L^2(\Omega \cap \Omega_h^{\partial})} \leq \|v_h\|_{L^2(\Omega_h^{\partial})} \lesssim \|v_h^l\|_{L^2(G_h(\Omega_h^{\partial}))}$, the last inequality resulting upon a change of variables applied element-wise, and an application of (4.10b) from [14] to estimate the appearing determinant.

Because $G_h(\Omega_h^{\partial}) \subseteq N_h$ (this is said in lemma 8.24 of 9, see edelmann), the proof is concluded. □

This same strategy brings us to an optimal L^2 error estimate, too.

Proposition D.1.12 (L^2 estimate with rougher f)

We choose $f_h = f$ on $\Omega \cap \Omega_h$ and 0 otherwise, assuming $f \in H^1(\Omega)$. Then we obtain, for h small enough, we have

$$\|u - u_h^l\|_{L^2(\Omega)} \lesssim h^2 + \|g_N - g_{h,N}^l\|_{L^2(\Gamma_N)} + \|g_D - \Pi_c g_D\|_{L^2(\Gamma_D)}.$$

Proof.

Analyzing the proof of the L^2 estimate, and of Theorem 5.3 in [12], we see that we only need to prove that $\left| \int_{\Omega} f \Pi_c z - \int_{\Omega_h} f_h \Pi_h z \right| \lesssim h^2 \|e\|_{L^2(\Omega)}$.

Just like before, we arrive at:

$$\int_{\Omega} f \Pi_c z - \int_{\Omega_h} f_h \Pi_h z = \int_{\Omega \cap \Omega_h^{\partial}} f (\Pi_c z - \Pi_h z) + \int_{\Omega \setminus \Omega_h} f \Pi_c z$$

Here, proposition D.1.6 lets us estimate $\|\Pi_c z\|_{H^1(\Omega)} \lesssim \|z\|_{H^2(\Omega)}$, for h small, so that, just like in the previous proof, and using the H^2 regularity of z :

$$\left| \int_{\Omega \setminus \Omega_h} f \Pi_c z \right| \lesssim h^2 \|f\|_{H^1(\Omega)} \|z\|_{H^2(\Omega)} \lesssim h^2 \|f\|_{H^1(\Omega)} \|e\|_{L^2(\Omega)}$$

Now, Ω is smooth enough for the existence of a bounded extension operator $E : H^2(\Omega) \rightarrow H^2(\mathbb{R}^n)$ (see [23], theorem 13.17 at page 425, 13.13 at page 424, and definition 9.57 at page 273). Therefore:

$$\left| \int_{\Omega \cap \Omega_h^{\partial}} f (\Pi_c z - \Pi_h z) \right| \lesssim h^{1/2} \|f\|_{H^1(\Omega)} \|\Pi_c z - \Pi_h z\|_{L^2(\Omega \cap \Omega_h^{\partial})}$$

But $\|\Pi_c z - \Pi_h z\|_{L^2(\Omega \cap \Omega_h^{\partial})} \leq \|\Pi_c z - z\|_{L^2(\Omega)} + \|Ez - \Pi_h Ez\|_{L^2(\Omega_h)}$.

By proposition D.1.6 and by Theorem 3.1.6 of [8], with constants independent of h , we obtain $\|\Pi_c z - \Pi_h z\|_{L^2(\Omega \cap \Omega_h^{\partial})} \leq Ch^2(\|z\|_{H^2(\Omega)} + \|Ez\|_{H^2(\Omega_h)}) \leq Ch^2(\|z\|_{H^2(\Omega)} + \|Ez\|_{H^2(\mathbb{R}^n)}) \lesssim h^2 \|z\|_{H^2(\Omega)} \leq h^2 \|e\|_{L^2(\Omega)}$.

Hence $\left| \int_{\Omega \cap \Omega_h^{\partial}} f (\Pi_c z - \Pi_h z) \right| \lesssim h^{5/2} \|e\|_{L^2(\Omega)}$ and the proof is concluded.

□

Summing up, here are the assumptions we used to obtain optimal order estimates.

Assumption D.1.13 (Assumptions for optimal order estimates)

On top of assumption D.1.1 we have assumed:

- quasi-uniformity of the mesh
- h small enough (all the estimates are asymptotic)
- $g_D, g_N \in H^2$
- $f \in H^1$

D.2. Parabolic problems

We partly build upon the previous section, to deal with problems of the following form.

Add a more precise reference to the triangulation, quasi uniformity...

Problem D.2.1 (Inhomogeneous parabolic problem)

With reference to problem B.2.3.1, we define:

$$\begin{cases} \partial_t u - \Delta u = f & \text{on } \Omega \times I \\ u = g_D & \text{on } \Gamma_D \times I \\ \partial_\nu u = g_N & \text{on } \Gamma_N \times I \\ u(0) = u_0 \end{cases}$$

We ask assumption B.2.3.2.

We provide a semidiscrete estimate, in the sense that only space is discretized. To do so we follow a classical argument involving the use of Ritz projections, see [31] in e.g. theorem 1.2. To deal with the polygonal/polyhedral domain approximation we adapt some arguments contained in [13], where parabolic problems are treated on moving domains, but with homogeneous boundary conditions. The inhomogeneous Dirichlet boundary conditions require special care.

We start indeed from the Ritz projection, by keeping the same notation as in the last section for the lift.

Throughout this section, \lesssim means $\leq C$, for C independent of both the discretization parameter h , and time.

Definition D.2.2 (Inhomogeneous Ritz projection)

Consider $z \in H^2(\Omega)$. We define $R_h z \in S_h^1$ by:

$$\begin{aligned} a_h(R_h z, v_h) &= a(z, v_h^l), v_h \in S_{h,D}^1 \\ R_h z &= \Pi_h z \text{ on } \partial\Omega_h \end{aligned}$$

We denote $R_c z := (R_h z)^l$.

Here are some useful properties of such projection.

Proposition D.2.3 (Properties of the Ritz projection)

The following facts hold true about R_h , where we assume that h is small enough:

1. R_h is well defined
2. R_h is continuous, uniformly in h , from $H^2(\Omega)$, to S_h^1 , i.e., $\|R_h z\|_{H^1(\Omega_h)} \lesssim \|z\|_{H^2(\Omega)}$
3. $\|R_c z - z\|_{H^1(\Omega)} \lesssim h \|z\|_{H^2(\Omega)}$
4. $\|R_c z - z\|_{L^2(\Omega)} \lesssim h^2 \|z\|_{H^2(\Omega)} + \|z - \Pi_c z\|_{L^2(\Gamma_D)}$
5. for $z \in H^1(I, H^2(\Omega))$, $R_c \frac{d}{dt} = \frac{d}{dt} R_c$ and we can therefore use the above properties also for z_t

Proof.

Well posedness and stability

Consider $\delta_h := R_h z - \Pi_h z$. Then, $a_h(\delta_h, v_h) = a(z, v_h^l) - a_h(\Pi_h z, v_h)$, $v_h \in S_{h,D}^1$, $\delta_h = 0$ on $\Gamma_{D,h}$.

The right hand side is a bounded functional on S_h^1 , also by proposition D.1.4, and a_h is (h -uniformly) coercive on $S_{D,h}^1$ by the proof of theorem D.1.8.

Therefore, δ_h exists, and we see that $\delta_h + \Pi_h z$ satisfies the equation for $R_h z$. Defining $R_h z := \delta_h + \Pi_h z$ is a well posed operation, since we can check that $R_h z$ doesn't depend on the (discrete) extension of $\Pi_h z|_\Gamma$: if we had two candidates $R^i h z$, $i = 1, 2$, we could form a difference, 0 on $\Gamma_{D,h}$, that would qualify as a test function in both variational formulations. Coercivity of a_h would then yield $R_h^1 = R_h^2$.

Now, for the stability.

By uniform coercivity and the definition of R_h : $\|R_h z\|_{H^1(\Omega_h)}^2 \lesssim a_h(R_h z, R_h z) = a_h(\delta_h, R_h z) + a_h(\Pi_h z, R_h z)$, so that $\|R_h z\|_{H^1(\Omega_h)} \lesssim \|\delta_h\|_{H^1(\Omega_h)} + \|\Pi_h z\|_{H^1(\Omega_h)}$.

For the second term.

Employing proposition D.1.4 $\|\Pi_h z\|_{H^1(\Omega_h)} \lesssim \|\Pi_c z\|_{H^1(\Omega)} \leq \|\Pi_c z - z\|_{H^1(\Omega)} + \|z\|_{H^1(\Omega)} \lesssim (1+h) \|z\|_{H^2(\Omega)}$, where in the last step we used proposition D.1.6.

For the first term, we know that $\|\delta_h\|_{H^1(\Omega_h)}^2 \lesssim a_h(\delta_h, \delta_h) = a(z, \delta_h^l) - a_h(\Pi_h z, \delta_h)$. We can insert a 0 term: $\|\delta_h\|_{H^1(\Omega_h)}^2 \lesssim a(z - \Pi_c z, \delta_h^l) + a(\Pi_c z, \delta_h^l) - a_h(\Pi_h z, \delta_h)$ and use proposition D.1.6, proposition D.1.4 and proposition D.1.7, to get:

$$\|\delta_h\|_{H^1(\Omega_h)}^2 \lesssim h \|z\|_{H^2(\Omega)} \|\delta_h\|_{H^1(\Omega_h)} + h \|\Pi_h z\|_{H^1(\Omega_h)} \|\delta_h\|_{H^1(\Omega_h)}$$

For the second term, we obtain, for h small, that $\|\delta_h\|_{H^1(\Omega_h)} \lesssim \|z\|_{H^2(\Omega)}$, and the stability is shown.

Error bounds

We start from the H^1 error bound.

We follow [13] closely here, adapting the proof of Lemma 3.8 at page 1720, where in particular we make sure that H^2 stability of R_h is sufficient, instead of the stronger H^1 stability they use. We are also using a slightly different bilinear form and function spaces.

Calling $F_h(v) := a(z - R_c z, v)$ for $v \in H^1$, we readily obtain:

$$|F_h(v_h^l)| \lesssim h \|v_h^l\|_{H^1(\Omega)} \|z\|_{H^2(\Omega)}$$

For $\eta \in H^2(\Omega)$ we instead have:

$$|F_h(\eta)| \lesssim \left(h^2 \|z\|_{H^2(\Omega)} + h \|z - R_c z\|_{H^1(\Omega)} \right) \|\eta\|_{H^2(\Omega)}$$

The above estimates are shown in detail in [13].

Using again the same arguments of [13] we come to:

$$\|z - R_c z\|_{H^1(\Omega)}^2 \lesssim h \|z - R_c z\|_{H^1(\Omega)} \|z\|_{H^2(\Omega)} + h \|z\|_{H^2(\Omega)} (h \|z\|_{H^2(\Omega)} + \|z - R_c z\|_{H^1(\Omega)})$$

Applying Young's inequality brings us finally to:

$$\|z - R_c z\|_{H^1(\Omega)} \lesssim h \|z\|_{H^2(\Omega)}$$

For the L^2 error bound, we apply a variant of the Aubin-Nitsche trick. Call $e := z - R_c z \in H^1(\Omega)$ (this holds by proposition D.1.4), and define w , just like in theorem D.1.9, by:

$$\begin{cases} -\Delta w = e & \text{on } \Omega \\ w = 0 & \text{on } \Gamma_D \\ \partial_\nu w = 0 & \text{on } \Gamma_N \end{cases}$$

As in the proof of theorem D.1.9:

$$\|e\|_{L^2(\Omega)}^2 = a(w, e) - \int_{\partial\Omega} e \partial_\nu w$$

and:

$$\|e\|_{L^2(\Omega)}^2 \leq a(w, e) + C \|e\|_{L^2(\Gamma_D)} \|e\|_{L^2(\Omega)} = F_h(w) + C \|e\|_{L^2(\Gamma_D)} \|e\|_{L^2(\Omega)}$$

For the first term we can emply the estimates derived at the beginning and the H^1 error norm, so as to obtain:

$$|F_h(w)| \lesssim h^2 \|z\|_{H^2(\Omega)} \|w\|_{H^2(\Omega)}$$

Using H^2 regularity for w we are able to conclude:

$$\|z - R_c z\|_{L^2(\Omega)} \lesssim h^2 \|z\|_{H^2(\Omega)} + \|z - \Pi_c z\|_{L^2(\Gamma_D)}$$

Commutation with time derivative

Follows from proposition A.2.2, and the fact that R_c is linear and bounded. The latter is true as lifting a finite element function is a linear bounded map, see proposition D.1.4.

□

Assumption D.2.4 (Smoothness on solution)

We assume that $u \in H^1(I, H^2(\Omega))$.

Note, for the parabolic problems arising from shape optimization as we can see in chapter 2, we can get away with asking particular smoothness and compatibility assumptions on the problem data, see **SOME FUTURE CHAPTER** and theorem B.2.3.6. For more general problems with non-null initial conditions, a finer analysis is most likely necessary.

We now can attempt an error estimate for problem D.2.1, for the following spatial semidiscrete formulation.

Problem D.2.5 (Spatially semidiscrete approximation of problem D.2.1)

We look for $u_h \in H^1(I, S_h^1)$ satisfying:

$$\begin{aligned} (\partial_t u_h, v_h)_{L^2(\Omega_h)} + a_h(u_h, v_h) &= (f_h, v_h)_{L^2(\Omega_h)} + (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})}, v_h \in S_{D,h}^1, \text{ a.e. } t \\ u_h &= g_{D,h} \text{ for a.e. } t, \text{ on } \Gamma_{D,h} \\ u_h(0) &= u_{0h} \end{aligned}$$

We are making the following assumptions on the data:

Assumption D.2.6 (Assumptions for the spatial semidiscretization)

- $\partial\Omega \in C^2$
- $g_N \in L^2(I, H^2(\Omega))$, so that $g_{N,h} := \Pi_h g_N \in L^2(I, S_h^1(\Gamma_{N,h}))$
- $g_D \in H^1(I, H^2(\Gamma_D))$, so that, with reference to proposition A.2.6, we have $G_D := E g_D \in H^1(I, H^2(\Omega))$ and therefore (see proposition A.2.2), there holds $G_{D,h} := \Pi_h G_D \in H^1(I, S_h^1)$ and $g_{D,h} := G_{D,h}|_{\Gamma_{D,h}} \in H^1(I, S_h^1(\Gamma_{D,h}))$ (note, $g_{D,h} = \Pi_h g_D$)
- $f \in L^2(I, L^2(\Omega))$ and $f_h \in L^2(I, S_h^1)$, with error bound $\|f - f_h^l\| \lesssim C_f h^2$, for a.e. t , and also $\|f_h\|_{H^1(\Omega_h)} \lesssim C_f$, C_f independent of h and belonging to $L^2(I)$.
- $u_0 \in H^2(\Omega)$, with the compatibility condition $u_0 = g_D(0)$ on Γ_D , and $u_{0h} := \Pi_h u_0$

(note that these assumptions can be relaxed for proving the well posedness of the scheme, and other choices of the discrete data might be possible. They become important when proving error bounds, so that we assume them right away. In particular, one could choose $f_h = \Pi_h f$, for $f \in L^2(U, H^2(\Omega))$ and obtain the same results).

Proposition D.2.7 (Well posedness of problem D.2.5)

There exists a unique solution to problem D.2.5, and this satisfies the stability estimate, holding for small enough h :

$$\begin{aligned} \|u_h\|_{C([0,T], L^2(\Omega_h))} + \|u_h\|_{L^2(I, H^1(\Omega_h))} &\lesssim \\ C_f + \|g_N\|_{L^2(I, H^2(\Gamma_N))} + \|g_D\|_{H^1(I, H^{3/2}(\Gamma_D))} + \|u_0\|_{H^2(\Omega)} \end{aligned}$$

We remember that \lesssim stands for $\leq C$, $C \geq 0$ independent of h and t .

Proof.

Existence

A function $\delta_h \in H^1(I, S_{D,h}^1)$ can be written as $u_h = \sum_j d_j(t) v_{hj}$, for the usual finite element basis $\{v_{hj}\}_j$ of $S_{D,h}^1$. We employ the splitting technique $\delta_h = u_h - G_{D,h}$, where $G_{D,h} \in H^1(I, S_h^1)$ is a suitable extension. By testing with the equation of problem D.2.5 with the basis functions v_{hj} we obtain the problem:

$$\begin{aligned} M d'(t) + A d(t) &= F(t), \text{ a.e. } t \\ d(0) &= D_0 \end{aligned}$$

Here, $M_{ij} = (v_{hi}, v_{hj})_{L^2(\Omega_h)}$, $A_{ij} = a(v_{hi}, v_{hj})$ are the so called mass and stiffness matrices, both invertible. We also have $F_j(t) := -(\partial_t G_{D,h}, v_{hj})_{L^2(\Omega_h)} - a_h(G_{D,h}, v_{hj}) + (f_h, v_{hj})_{L^2(\Omega_h)} + (g_{N,h}, v_{hj})_{L^2(\Gamma_{N,h})}$, together with $D_0 := u_{0h} - G_{D,h}$ (we are able to come to this problem thanks to the assumed compatibility between $u_{0h}, g_{D,h}$).

Thanks to the smoothness assumptions on the data, we have that F has $L^2(I)$ entries.

Hence, by basic theory of ordinary differential equations (Theorem 3.4 of [28], for instance), we conclude the existence (and uniqueness) of $d \in H^1(I)$ solving the problem above. The function $u_h := \sum_j d_j(t) v_{hj} + G_{D,h}$ is therefore a solution to the original problem.

Uniqueness by energy estimates

Uniqueness (and hence, independence on the particular extension $G_{D,h}$) follows by proving an energy estimate at first. In fact, let $e := u_h^1 - u_h^2$ be the difference of two solutions. It satisfies:

$$\begin{aligned} (\partial_t e_h, v_h)_{L^2(\Omega_h)} + a_h(e_h, v_h) &= 0, v_h \in S_{D,h}^1, a.e. t \\ e_h &= 0 \text{ for a.e. } t, \text{ on } \Gamma_{D,h} \\ e_h(0) &= 0 \end{aligned}$$

We can test the equation by e_h , use that $a_h(v_h, v_h) = \|v_h\|_{H^1(\Omega_h)}^2 - \|v_h\|_{L^2(\Omega_h)}^2$, that $e_h(0) = 0$ and Gronwall's lemma to conclude the desired uniqueness.

Stability

Following [19], page 20, 21, we can prove, for δ_h , that:

$$\begin{aligned} &\|\delta_h\|_{C([0,T], L^2(\Omega_h))} + \|\delta_h\|_{L^2(I, H^1(\Omega_h))} \lesssim \\ &\|f_h\|_{L^2(I, L^2(\Omega_h))} + \|g_{N,h}\|_{L^2(I, L^2(\Gamma_{N,h}))} + \|G_{D,h}\|_{H^1(I, H^1(\Omega_h))} + \|u_{0h}\|_{L^2(\Omega_h)} \end{aligned}$$

so that, by triangle inequality:

$$\begin{aligned} &\|u_h\|_{C([0,T], L^2(\Omega_h))} + \|u_h\|_{L^2(I, H^1(\Omega_h))} \lesssim \\ &\|f_h\|_{L^2(I, L^2(\Omega_h))} + \|g_{N,h}\|_{L^2(I, L^2(\Gamma_{N,h}))} + \|G_{D,h}\|_{H^1(I, H^1(\Omega_h))} + \|u_{0h}\|_{L^2(\Omega_h)} \end{aligned}$$

Now, thanks to assumption D.2.6:

- $\|f_h\|_{L^2(I, L^2(\Omega_h))}^2 \lesssim \int_I C_f^2$ (here we use the same arguments as in proposition D.1.12)
- $\|g_{N,h}\|_{L^2(I, L^2(\Gamma_{N,h}))} \lesssim \|g_N\|_{L^2(I, H^2(\Gamma_N))}$ (here it suffices to use proposition D.1.6))
- because the Lagrange interpolator is linear bounded $H^2(\Omega) \rightarrow S_h^1$ there holds, by proposition D.1.6: $\partial_t G_{D,h} = \Pi_h \partial_t G_D$, so that $\|\partial_t G_{D,h}\|_{H^1(\Omega_h)} = \|\Pi_h \partial_t G_D\|_{H^1(\Omega_h)} \lesssim \|\partial_t G_D\|_{H^2(\Omega)}$, where we used proposition D.1.6 and proposition D.1.4. Thanks to the properties of G_D , and the fact that the extension E of proposition A.2.6 commutes with Π_h (by proposition A.2.2), there holds $\|\partial_t G_{D,h}\|_{H^1(\Omega_h)} \lesssim \|\partial_t g_D\|_H^{3/2}(\Gamma_D)$. With analogous reasonings we can conclude that $\|G_{D,h}\|_{H^1(I, H^1(\Omega_h))} \lesssim \|g_D\|_{H^1(I, H^{3/2}(\Gamma_D))}$
- similarly, $\|u_{0h}\|_{L^2(\Omega_h)} \lesssim \|u_0\|_{H^2(\Omega)}$

All in all:

$$\|u_h\|_{C([0,T], L^2(\Omega_h))} + \|u_h\|_{L^2(I, H^1(\Omega_h))} \lesssim \|C_f\|_{L^2(I)} + \|g_N\|_{L^2(I, H^2(\Gamma_N))} + \|g_D\|_{H^1(I, H^{3/2}(\Gamma_D))} + \|u_0\|_{H^2(\Omega)}$$

□

Theorem D.2.8 (Semidiscrete error bound)

There holds:

$$\|u(t) - u_h^l(t)\|_{L^2(\Omega)}^2 + h^2 \int_0^T \|u - u_h^l\|_{H^1(\Omega)}^2 \lesssim h^4 A^2$$

where $A^2 := \|u\|_{H^1(I, H^2(\Omega))}^2 + \|g_D\|_{H^1(I, H^2(\Gamma_D))}^2 + \|u_0\|_{H^2(\Omega)}^2 + \int_0^T C_f^2 + \int_0^T \|g_N\|_{H^2(\Gamma_N)}^2$.

For this to hold, assumption D.2.4, assumption D.2.6 and assumption B.2.3.2 must be fulfilled.

Proof.

Also here, we adapt the argument from [13], in particular, those of pages 1727, 1728, 1729, which are modifications of standard techniques that can be traced in e.g. [31], theorem 1.2. We make it clear where one could use other approximations of the data, provided that they enjoy similar properties.

Error split

We want to bound $e := u - u_h = u - R_c u + R_c u - u_h^l =: \rho + \theta_h^l$. We already have the needed bounds on ρ by proposition D.2.3.

An equation for θ_h

Consider then $\theta_h := R_h u - u_h$. Is is an element of $H^1(I, S_{D,h}^1)$ (i.e. it is 0 on the Dirichlet boundary), making it a suitable test function: this is the primary reason to impose boundary conditions on R_h .

So, we have, for $v_h \in S_{D,h}^1$:

$$\begin{aligned} (\partial_t R_h u, v_h)_{L^2(\Omega_h)} + a_h(R_h u, v_h) &= \{ \text{definition of Ritz projection} \} = \\ &= (\partial_t R_h u, v_h)_{L^2(\Omega_h)} + a(u, v_h^l) = \\ &= (\partial_t R_h u, v_h)_{L^2(\Omega_h)} - (\partial_t u, v_h^l)_{L^2(\Omega)} + (f, v_h^l)_{L^2(\Omega)} + (g_N, v_h^l)_{L^2(\Gamma_N)} \end{aligned}$$

Adding the equation for u_h we obtain:

$$\begin{aligned} (\partial_t \theta_h, v_h)_{L^2(\Omega_h)} + a_h(\theta_h, v_h) &= (\partial_t R_h u, v_h)_{L^2(\Omega_h)} - (\partial_t u, v_h^l)_{L^2(\Omega)} \\ &\quad + (f, v_h^l)_{L^2(\Omega)} - (f_h, v_h)_{L^2(\Omega_h)} \\ &\quad + (g_N, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})} \end{aligned}$$

Adding and subtracting $(\partial_t R_c u, v_h^l)_{L^2(\Omega)}$:

$$(\partial_t \theta_h, v_h)_{L^2(\Omega_h)} + a_h(\theta_h, v_h) = (\partial_t R_h u, v_h)_{L^2(\Omega_h)} - (\partial_t R_c u, v_h^l)_{L^2(\Omega)} \quad (\text{D.2.9})$$

$$- (\partial_t \rho, v_h^l)_{L^2(\Omega)} \quad (\text{D.2.10})$$

$$+ (f, v_h^l)_{L^2(\Omega)} - (f_h, v_h)_{L^2(\Omega_h)} \quad (\text{D.2.11})$$

$$+ (g_N, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})} \quad (\text{D.2.12})$$

This means that we can estimate the right hand sides of the above equation to quantify the size of θ_h .

Estimating the size of θ_h : right hand sides

By proposition A.2.2 we can write $\partial_t R_h u = R_h \partial_t u$, $\partial_t R_c u = (R_h \partial_t u)^l$.

Hence, $|(\partial_t R_h u, v_h)_{L^2(\Omega_h)} - (\partial_t R_c u, v_h^l)_{L^2(\Omega)}| \lesssim h^2 \|\partial_t u\|_{H^2(\Omega)} \|v_h\|_{H^1(\Omega_h)}$, where we used proposition D.1.7, and proposition D.2.3.

Similarly, we have $\partial_t \rho = \partial_t u - R_c \partial_t u$.

Thus $|(\partial_t \rho, v_h^l)_{L^2(\Omega)}| \lesssim h^2 \|\partial_t u\|_{H^2(\Omega)} \|v_h\|_{H^1(\Omega_h)} + \|\partial_t(g_D - g_{D,h})\|_{L^2(\Gamma_D)} \|v_h\|_{H^1(\Omega_h)}$ by proposition D.2.3. By the choice of $g_{D,h}$ and by proposition D.1.6, $|(\partial_t \rho, v_h^l)_{L^2(\Omega)}| \lesssim h^2(\|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}) \|v_h\|_{H^1(\Omega_h)}$.

Moreover:

$$\begin{aligned} & |(g_N, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})}| \leq \\ & |(g_N - g_{N,h}^l, v_h^l)_{L^2(\Gamma_N)}| + |(g_{N,h}^l, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})}| \end{aligned}$$

By proposition D.1.7 and trace theorems there holds:

$$\begin{aligned} & |(g_N, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})}| \lesssim \\ & \|g_N - g_{N,h}^l\|_{L^2(\Gamma_N)} \|v_h^l\|_{H^1(\Omega)} + h^2 \|g_{N,h}\|_{L^2(\Gamma_{N,h})} \|v_h\|_{H^1(\Omega_h)} \end{aligned}$$

Using the choice of $g_{N,h}$ and also proposition D.1.6, proposition D.1.4, we obtain:

$$|(g_N, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})}| \lesssim h^2 \|g_N\|_{H^2(\Gamma_N)} \|v_h\|_{H^1(\Omega_h)}$$

Analogously:

$$\begin{aligned} & |(f, v_h^l)_{L^2(\Omega)} - (f_h, v_h)_{L^2(\Omega_h)}| \lesssim \\ & \|f - f_h^l\|_{L^2(\Omega)} \|v_h\|_{H^1(\Omega_h)} + h^2 C_f \|v_h\|_{H^1(\Omega_h)} \lesssim C_f h^2 \|v_h\|_{H^1(\Omega_h)} \end{aligned}$$

We used throughout assumption D.2.6.

Calling $E_h(v_h) := (\partial_t \theta_h, v_h)_{L^2(\Omega_h)} + a_h(\theta_h, v_h)$, we discovered that:

$$|E_h(v_h)| \lesssim h^2 \|v_h\|_{H^1(\Omega_h)} (C_f + \|g_N\|_{H^2(\Gamma_N)} + \|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}) \quad (\text{D.2.13})$$

Estimating the size of θ_h : energy estimate

By the equation of θ_h , and by the possibility of testing with $v_h = \theta_h$ itself, we obtain:

$$\frac{1}{2} \frac{d}{dt} \|\theta_h\|_{L^2(\Omega_h)}^2 + \|\theta_h\|_{H^1(\Omega_h)}^2 - \|\theta_h\|_{L^2(\Omega_h)}^2 = E_h(\theta_h)$$

Hence:

$$\frac{1}{2} \frac{d}{dt} \|\theta_h\|_{L^2(\Omega_h)}^2 + \|\theta_h\|_{H^1(\Omega_h)}^2 \lesssim \|\theta_h\|_{L^2(\Omega_h)}^2 + Q h^2 \|\theta_h\|_{H^1(\Omega_h)}$$

Here we called $Q := C_f + \|g_N\|_{H^2(\Gamma_N)} + \|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}$.

By Young's inequality:

$$\frac{1}{2} \frac{d}{dt} \|\theta_h\|_{L^2(\Omega_h)}^2 + \|\theta_h\|_{H^1(\Omega_h)}^2 \lesssim \|\theta_h\|_{L^2(\Omega_h)}^2 + 2Q^2 h^4 + \frac{1}{2} \|\theta_h\|_{H^1(\Omega_h)}^2$$

Re-arranging:

$$\frac{1}{2} \frac{d}{dt} \|\theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h\|_{H^1(\Omega_h)}^2 \lesssim \|\theta_h\|_{L^2(\Omega_h)}^2 + 2Q^2 h^4$$

We now integrate from 0 to t :

$$\frac{1}{2} \|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \int_0^t \|\theta_h\|_{H^1(\Omega_h)}^2 \lesssim 2 \int_0^t \frac{1}{2} \|\theta_h\|_{L^2(\Omega_h)}^2 + 2h^4 \int_0^t Q^2 + \frac{1}{2} \|\theta_h(0)\|_{L^2(\Omega_h)}^2$$

Adding non-negative terms on the right hand side yields:

$$\begin{aligned} \frac{1}{2} \|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \int_0^t \|\theta_h\|_{H^1(\Omega_h)}^2 &\lesssim 2 \left(\int_0^t \frac{1}{2} \|\theta_h\|_{L^2(\Omega_h)}^2 + \frac{t}{2} \int_0^t \|\theta_h\|_{H^1(\Omega_h)}^2 \right) + 2h^4 \int_0^t Q^2 \\ &\quad + \frac{1}{2} \|\theta_h(0)\|_{L^2(\Omega_h)}^2 \end{aligned}$$

Gronwall's inequality (25, page 19 of [19]) now yields:

$$\|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \int_0^t \|\theta_h\|_{H^1(\Omega_h)}^2 \lesssim e^{2t} \left(4h^4 \int_0^t Q^2 + \|\theta_h(0)\|_{L^2(\Omega_h)}^2 \right)$$

Therefore, for all $t \in [0, T]$ we have:

$$\|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \int_0^T \|\theta_h\|_{H^1(\Omega_h)}^2 \lesssim 8h^4 \int_0^T Q^2 + 2 \|\theta_h(0)\|_{L^2(\Omega_h)}^2 \quad (\text{D.2.14})$$

We can apply also D.1.4 to obtain an estimate in spaces that don't depend on h :

$$\|\theta_h^l(t)\|_{L^2(\Omega)}^2 + \int_0^T \|\theta_h^l\|_{H^1(\Omega)}^2 \lesssim h^4 \int_0^T Q^2 + \|\theta_h^l(0)\|_{L^2(\Omega)}^2$$

Conclusion

We have, for $e = u - u_h^l$ (and $h < 1$, at least), that:

$$\begin{aligned} &\|e(t)\|_{L^2(\Omega)}^2 + h^2 \int_0^T \|e\|_{H^1(\Omega)}^2 \lesssim \\ &\|\rho(t)\|_{L^2(\Omega)}^2 + h^2 \int_0^T \|\rho\|_{H^1(\Omega)}^2 + \|\theta_h^l(t)\|_{L^2(\Omega)}^2 + \int_0^T \|\theta_h^l\|_{H^1(\Omega)}^2 \lesssim \{ \text{proposition D.2.3} \} \\ &h^4 \|u(t)\|_{H^2(\Omega)}^2 + h^4 \|g_D(t)\|_{L^2(\Gamma_D)}^2 + h^2 h^2 \int_0^T \|u\|_{H^2(\Omega)}^2 + h^4 \int_0^T Q^2 + \|\theta_h^l(0)\|_{L^2(\Omega)}^2 \end{aligned}$$

A triangle inequality applied to $\|\theta_h^l(0)\|_{L^2(\Omega)}^2$, an application of proposition D.2.3 and the definition of Q bring us to:

$$\begin{aligned} &h^{-4} \|e(t)\|_{L^2(\Omega)}^2 + h^{-2} \int_0^T \|e\|_{H^1(\Omega)}^2 \lesssim \\ &\|u(t)\|_{H^2(\Omega)}^2 + \|g_D(t)\|_{L^2(\Gamma_D)}^2 + \int_0^T \|u\|_{H^2(\Omega)}^2 + \|u_0\|_{H^2(\Omega)}^2 \\ &+ \int_0^T C_f^2 + \int_0^T \|g_N\|_{H^2(\Gamma_N)}^2 + \int_0^T \|\partial_t u\|_{H^2(\Omega)}^2 + \int_0^T \|\partial_t g_D\|_{H^2(\Gamma_D)}^2 \end{aligned}$$

This means that:

$$h^{-4} \|e(t)\|_{L^2(\Omega)}^2 + h^{-2} \int_0^T \|e\|_{H^1(\Omega)}^2 \lesssim \|u\|_{H^1(I, H^2(\Omega))}^2 + \|g_D\|_{H^1(I, H^2(\Gamma_D))}^2 + \|u_0\|_{H^2(\Omega)}^2 + \int_0^T C_f^2 + \int_0^T \|g_N\|_{H^2(\Gamma_N)}^2$$

□

We can also prove convergence of the derivatives in a rather strong norm.

Corollary D.2.15 (Refined error estimate)

Apart from assumption D.2.4, assumption D.2.6 and assumption B.2.3.2, further assume that $g_N \in H^1(I, H^2(\Gamma_N))$. Then, for all $t \in (0, T)$:

$$\int_0^T \|\partial_t u - (\partial_t u_h)^l\|_{L^2(\Omega)}^2 + \|u(t) - u_h^l(t)\|_{H^1(\Omega)}^2 \lesssim h^2 B^2$$

$$\text{where } B := \|u\|_{H^1(I, H^2(\Omega))}^2 + \|g_D\|_{H^1(I, H^2(\Gamma_D))}^2 + \int_0^T C_f^2 + \|g_N\|_{H^1(H^2(\Gamma_N))}^2 + \|u_0\|_{H^2(\Omega)}^2.$$

Proof.

We employ again the error decomposition $e = \rho + \theta_h^l$.

Another estimate for θ_h

Consider again eq. (D.2.9):

$$\begin{aligned} (\partial_t \theta_h, v_h)_{L^2(\Omega_h)} + a_h(\theta_h, v_h) &= (\partial_t R_h u, v_h)_{L^2(\Omega_h)} - (\partial_t R_c u, v_h^l)_{L^2(\Omega)} \\ &\quad - (\partial_t \rho, v_h^l)_{L^2(\Omega)} \\ &\quad + (f, v_h^l)_{L^2(\Omega)} - (f_h, v_h)_{L^2(\Omega_h)} \\ &\quad + (g_N, v_h^l)_{L^2(\Gamma_N)} - (g_{N,h}, v_h)_{L^2(\Gamma_{N,h})} \end{aligned}$$

We intend to test by $\partial_t \theta_h \in L^2(I, S_{h,D}^1)$. This is possible also by the reasonings in [21], (1.61), page 42. Integrate from 0 to t to obtain:

$$\begin{aligned} \int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{2} (a_h(\theta_h(t), \theta_h(t)) - a_h(\theta_h(0), \theta_h(0))) &= \int_0^t (\partial_t R_h u, \partial_t \theta_h)_{L^2(\Omega_h)} - \int_0^t (\partial_t R_c u, \partial_t \theta_h^l)_{L^2(\Omega)} \\ &\quad - \int_0^t (\partial_t \rho, \partial_t \theta_h^l)_{L^2(\Omega)} \\ &\quad + \int_0^t (f, \partial_t \theta_h^l)_{L^2(\Omega)} - \int_0^t (f_h, \partial_t \theta_h)_{L^2(\Omega_h)} \\ &\quad + \int_0^t (g_N, \partial_t \theta_h^l)_{L^2(\Gamma_N)} - \int_0^t (g_{N,h}, \partial_t \theta_h)_{L^2(\Gamma_{N,h})} \end{aligned}$$

Estimating the left hand side:

$$\begin{aligned}
\int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(t)\|_{H^1(\Omega_h)}^2 &\leq \frac{1}{2} \|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(0)\|_{H^1(\Omega_h)}^2 \\
&+ \int_0^t (\partial_t R_h u, \partial_t \theta_h)_{L^2(\Omega_h)} - \int_0^t (\partial_t R_c u, \partial_t \theta_h^l)_{L^2(\Omega)} \\
&- \int_0^t (\partial_t \rho, \partial_t \theta_h^l)_{L^2(\Omega)} \\
&+ \int_0^t (f, \partial_t \theta_h^l)_{L^2(\Omega)} - \int_0^t (f_h, \partial_t \theta_h)_{L^2(\Omega_h)} \\
&+ \int_0^t (g_N, \partial_t \theta_h^l)_{L^2(\Gamma_N)} - \int_0^t (g_{N,h}, \partial_t \theta_h)_{L^2(\Gamma_{N,h})}
\end{aligned}$$

For the terms with $g_N, g_{N,h}$ we integrate by parts and find:

$$\begin{aligned}
\int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(t)\|_{H^1(\Omega_h)}^2 &\leq \frac{1}{2} \|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(0)\|_{H^1(\Omega_h)}^2 \\
&+ \int_0^t (\partial_t R_h u, \partial_t \theta_h)_{L^2(\Omega_h)} - \int_0^t (\partial_t R_c u, \partial_t \theta_h^l)_{L^2(\Omega)} \\
&- \int_0^t (\partial_t \rho, \partial_t \theta_h^l)_{L^2(\Omega)} \\
&+ \int_0^t (f, \partial_t \theta_h^l)_{L^2(\Omega)} - \int_0^t (f_h, \partial_t \theta_h)_{L^2(\Omega_h)} \\
&- \int_0^t (\partial_t g_N, \theta_h^l)_{L^2(\Gamma_N)} + \int_0^t (\partial_t g_{N,h}, \theta_h)_{L^2(\Gamma_{N,h})} \\
&+ (g_N(t), \theta_h^l(t))_{L^2(\Gamma_N)} - (g_{N,h}(t), \theta_h(t))_{L^2(\Gamma_{N,h})} \\
&- (g_N(0), \theta_h^l(0))_{L^2(\Gamma_N)} + (g_{N,h}(0), \theta_h(0))_{L^2(\Gamma_{N,h})}
\end{aligned}$$

For the right hand side, estimating every piece but the first two, with the help of D.1.7, and C independent of h and t :

$$\begin{aligned}
\int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(t)\|_{H^1(\Omega_h)}^2 &\leq \frac{1}{2} \|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(0)\|_{H^1(\Omega_h)}^2 \\
&+ Ch \int_0^t \|\partial_t u\|_{H^2(\Omega)} \|\partial_t \theta_h\|_{L^2(\Omega_h)} \\
&+ Ch \int_0^t (\|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}) \|\partial_t \theta_h\|_{L^2(\Omega_h)} \\
&+ Ch \int_0^t C_f \|\partial_t \theta_h\|_{L^2(\Omega_h)} \\
&+ Ch \int_0^t \|\partial_t g_N\|_{H^2(\Gamma_N)} \|\theta_h\|_{H^1(\Omega_h)} \\
&+ Ch \|g_N(t)\|_{H^2(\Gamma_N)} \|\theta_h(t)\|_{H^1(\Omega_h)} \\
&+ Ch \|g_N(0)\|_{H^2(\Gamma_N)} \|\theta_h(0)\|_{H^1(\Omega_h)}
\end{aligned}$$

Applying Young's inequality several times, with possibly a different C , still independent of h and t :

$$\begin{aligned}
 \int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(t)\|_{H^1(\Omega_h)}^2 &\leq \frac{1}{2} \|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \frac{1}{2} \|\theta_h(0)\|_{H^1(\Omega_h)}^2 \\
 &\quad + Ch^2 \int_0^t \|\partial_t u\|_{H^2(\Omega)}^2 + \frac{1}{6} \int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 \\
 &\quad + Ch^2 \int_0^t (\|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)})^2 + \frac{1}{6} \int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 \\
 &\quad + Ch^2 \int_0^t C_f^2 + \frac{1}{6} \int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 \\
 &\quad + Ch^2 \int_0^t \|\partial_t g_N\|_{H^2(\Gamma_N)}^2 + \int_0^t \|\theta_h\|_{H^1(\Omega_h)}^2 \\
 &\quad + Ch^2 \|g_N(t)\|_{H^2(\Gamma_N)}^2 + \frac{1}{4} \|\theta_h(t)\|_{H^1(\Omega_h)}^2 \\
 &\quad + Ch^2 \|g_N(0)\|_{H^2(\Gamma_N)}^2 + \frac{1}{2} \|\theta_h(0)\|_{H^1(\Omega_h)}^2
 \end{aligned}$$

We re-arrange, and apply eq. (D.2.14) to the term $\|\theta_h(t)\|_{L^2(\Omega_h)}^2 + \int_0^t \|\theta_h\|_{H^1(\Omega_h)}^2$.

Calling $q = \int_0^T \left[\|\partial_t u\|_{H^2(\Omega)}^2 + \|\partial_t g_D\|_{H^2(\Gamma_D)}^2 + C_f^2 + Q^2 + \|g_N\|_{H^2(\Gamma_N)}^2 + \|\partial_t g_N\|_{H^2(\Gamma_N)}^2 \right]$ we read:

$$\frac{1}{2} \int_0^t \|\partial_t \theta_h\|_{L^2(\Omega_h)}^2 + \frac{1}{4} \|\theta_h(t)\|_{H^1(\Omega_h)}^2 \lesssim \|\theta_h(0)\|_{H^1(\Omega_h)}^2 + h^4 q$$

or also, upon using proposition D.1.4, proposition D.2.3 and proposition D.1.6:

$$\int_0^T \|\partial_t \theta_h^l\|_{L^2(\Omega)}^2 + \|\theta_h(t)^l\|_{H^1(\Omega)}^2 \lesssim \|\theta_h(0)\|_{H^1(\Omega_h)}^2 + h^4 q \lesssim h^2 \|u_0\|_{H^2(\Omega)}^2 + h^4 q$$

Conclusion

There holds

$$\begin{aligned}
 &\|e(t)\|_{H^1(\Omega)}^2 + \int_0^T \|\partial_t e\|_{L^2(\Omega)}^2 \leq \\
 &\int_0^T \|\partial_t \rho\|_{L^2(\Omega)}^2 + h^2 \|\rho(t)\|_{H^1(\Omega)}^2 + \int_0^T \|\partial_t \theta_h^l\|_{L^2(\Omega)}^2 + \|\theta_h^l(t)\|_{H^1(\Omega)}^2 \leq \{ \text{above, and proposition D.2.3} \} \leq \\
 &h^2 \int_0^T (\|\partial_t u\|_{H^2(\Omega)}^2 + \|\partial_t g_D\|_{H^2(\Gamma_D)}^2) + h^2 \|u(t)\|_{H^2(\Omega)}^2 + h^2 \|u_0\|_{H^2(\Omega)}^2 + h^4 q
 \end{aligned}$$

□

If however we content ourselves with estimating the convergence of the derivatives in a weaker norm, we can actually obtain $O(h^2)$ convergence, in every case. To do so, it will be crucial to establish the H^1 stability of the L^2 projection in our context. This fact is known for polyhedral domains with some assumptions on the meshes, see e.g. [4].

Corollary D.2.16 (Order two convergence of derivatives in dual norm)

Under assumption D.2.4, assumption D.2.6 and assumption B.2.3.2 we have, for all $w \in L^2(I, H^1(\Omega))$:

something

Proof.

We introduce the L^2 projection $\pi_h : L^2(\Omega) \rightarrow S_{h,D}^1$, given by:

$$(\pi_h w, v_h)_{L^2(\Omega_h)} = (w, v_h^l)_{L^2(\Omega)}, \quad \forall v_h \in S_{h,D}^1$$

The definition is reminiscent of that of the Ritz projection. We will prove well-posedness and H^k stability of such projection, i.e. $\|\pi_h w\|_{H^k(\Omega_h)} \lesssim \|w\|_{H^k(\Omega)}$, for $k = 0, 1$.

First, let us show how this projection helps in the estimate.

Conclusion

For $w \in H^1(\Omega)$ we estimate $(\partial_t(\theta_h^l), w)_{L^2(\Omega)} = (w, (\partial_t \theta_h^l))_{L^2(\Omega)} = (\pi_h w, \partial_t \theta_h)_{L^2(\Omega_h)}$. We have also used that lifting and differentiating with respect to time commute, by proposition D.1.4 and proposition A.2.2. We can now apply eq. (D.2.9):

$$\begin{aligned} (\partial_t(\theta_h^l), w)_{L^2(\Omega)} &= a_h(\theta_h, \pi_h w) - E_h(\pi_h w) \lesssim \{ \text{eq. (D.2.13)} \} \lesssim \\ &\|\theta_h\|_{H^1(\Omega_h)} \|\pi_h w\|_{H^1(\Omega_h)} + h^2 \|\pi_h w\|_{H^1(\Omega_h)} (C_f + \|g_N\|_{H^2(\Gamma_N)} + \|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}) \lesssim \\ &\|\theta_h\|_{H^1(\Omega_h)} \|w\|_{H^1(\Omega)} + h^2 \|w\|_{H^1(\Omega)} (C_f + \|g_N\|_{H^2(\Gamma_N)} + \|\partial_t u\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}) \end{aligned}$$

where in the last step we used the supposed stability of π_h . Integrating in time and using the Cauchy-Schwarz inequality:

$$\begin{aligned} &\left| \int_I (\partial_t(\theta_h^l), w)_{L^2(\Omega)} \right| \lesssim \\ &\left(\sqrt{\int_I \|\theta_h\|_{H^1(\Omega_h)}^2} + h^2 \sqrt{\int_I (C_f^2 + \|g_N\|_{H^2(\Gamma_N)}^2 + \|\partial_t u\|_{H^2(\Omega)}^2 + \|\partial_t g_D\|_{H^2(\Gamma_D)}^2)} \right) \sqrt{\int_I \|w\|_{H^1(\Omega)}^2} \lesssim \{ \text{eq. (D.2.14)} \} \lesssim \\ &h^2 \left(\sqrt{\int_T Q^2 + \|u_0\|_{H^2(\Omega)}^2} + \sqrt{\int_I (C_f^2 + \|g_N\|_{H^2(\Gamma_N)}^2 + \|\partial_t u\|_{H^2(\Omega)}^2 + \|\partial_t g_D\|_{H^2(\Gamma_D)}^2)} \right) \|w\|_{L^2(I, H^1(\Omega))} \end{aligned}$$

We can also estimate:

$$\begin{aligned} &\left| \int_I (\rho_t, w)_{L^2(\Omega)} \right| \lesssim \{ \text{as in the proof of theorem D.2.8} \} \lesssim \\ &h^2 (\|\partial_t w\|_{H^2(\Omega)} + \|\partial_t g_D\|_{H^2(\Gamma_D)}) \|w\|_{H^1(\Omega_h)} \lesssim \{ \text{Cauchy-Schwarz} \} \lesssim \\ &h^2 \sqrt{\|\partial_t u\|_{H^2(\Omega)}^2 + \|\partial_t g_D\|_{H^2(\Gamma_D)}^2} \|w\|_{L^2(I, H^1(\Omega))} \end{aligned}$$

and by the usual splitting $e = \rho + \theta_h^l$ we can conclude.

L^2 projection: well-posedness

From the definition of π_h we obtain:

$$(\pi_h w, v_h)_{L^2(\Omega_h)} = (w, v_h^l)_{L^2(\Omega)} = (w^{-l} \xi, v_h)_{L^2(\Omega_h)}$$

where $\xi \in L^\infty(\Omega_h)$ is a term originating from the change of variables. We therefore recognize that $\pi_h w$ is the usual L^2 projection of $w^{-l} \xi \in L^2(\Omega_h)$ onto the closed subspace $S_{h,D}^1$, for which we know existence and uniqueness.

To be precise we don't know whether G_h takes measurable functions into measurable functions. But for L^2 arguments, we can reason as follows: w^{-l} we know to be piecewise in L^2 , so we can glue it to an L^2 fcn by in case modifying it on a null set. Also ξ is piecewise measurable (it is piecewise C^1). So $w^{-l} \xi$ is measurable and L^2

L^2 projection: stability

L^2 stability of π_h follows by testing with $\pi_h w$ itself and using proposition D.1.4.

Also, denote by π_h^* the usual L^2 projector:

$$(\pi_h^* v - v, v_h)_{L^2(\Omega_h)} = 0, \quad \forall v_h \in S_{h,D}^1$$

We have, for $w \in L^2(\Omega)$, that $(\pi_h w - \pi_h^* w^{-l}, v_h)_{L^2(\Omega_h)} = (w, v_h^l)_{L^2(\Omega)} - (w^{-l}, v_h)_{L^2(\Omega_h)}$. An application of proposition D.1.7 and of proposition D.1.4 (4.6 still applies here, do the reasonings elementwise and use lemma 8.16 of [13]) yields:

$$\|\pi_h w - \pi_h^* w^{-l}\|_{L^2(\Omega_h)}^2 \lesssim h \|w\|_{L^2(\Omega)} \|\pi_h w - \pi_h^* w^{-l}\|_{L^2(\Omega_h)}$$

Now, we can adapt the original proof of [3] to our case, see in particular (A.1).

In fact: $|\pi_h w|_{H^1(\Omega_h)} \leq |\pi_h w - \pi_h^* w^{-l}|_{H^1(\Omega_h)} + |\pi_h^* w^{-l}|_{H^1(\Omega_h)}$.

We can apply an inverse inequality to the first member: $|\pi_h w - \pi_h^* w^{-l}|_{H^1(\Omega_h)} \lesssim h^{-1} \|\pi_h w - \pi_h^* w^{-l}\|_{L^2(\Omega_h)} \lesssim \|w\|_{L^2(\Omega)}$.

For the second term, consider a suitable $w_h \in S_{h,D}^1$. We have: $|\pi_h^* w^{-l}|_{H^1(\Omega_h)} \leq |\pi_h^*(w^{-l} - w_h)|_{H^1(\Omega_h)} + |\pi_h^* w_h|_{H^1(\Omega_h)} \lesssim h^{-1} \|\pi_h^*(w^{-l} - w_h)\|_{L^2(\Omega_h)} + \|w_h\|_{H^1(\Omega_h)}$, where we again applied inverse inequalities, together with the fact that $\pi_h^* w_h = w_h$ for $w_h \in S_{h,D}^1$ (i.e π_h^* is really a projection, unlike π_h). Moreover, $\|\pi_h^* v\|_{L^2(\Omega_h)} \leq \|v\|_{L^2(\Omega_h)}$.

So, if there holds $\|w^{-l} - w_h\|_{L^2(\Omega_h)} \lesssim h \|w\|_{H^1(\Omega)}$ and $\|w_h\|_{H^1(\Omega_h)} \lesssim \|w\|_{H^1(\Omega)}$, then we are done.

what is h??? Also throughout the rest of the thesis... I checked this, it is the maximum h_K in the linear triangulation for Ranner, and a parameter that I can choose to be h of Ranner, in Bernardi

Finding w_h

Such w_h will be the optimal order interpolator with boundary conditions described in (5.9) at page 1230, [6]. We need to check that our framework matches that of [6] to apply such a result.

But this is ensured by the construction outlined in [13], sections 8.5 and 8.6. The assumptions of Theorem 5.1, in particular, are all satisfied: that the triangulations satisfy the so called 1-regularity is proved in lemma 8.13 or [13], whereas all the other properties are already discussed in [6] following example 2 (see pages 1216, 1221, 1228, and remark 5.2 at page 1230).

Applying Corollary 5.1 of [6] to $\Gamma_0 = \Gamma_D$ (Γ_0 is in the notation of [6]) we find $w_h \in S_{h,D}^1$ (true by Proposition and Corollary 5.1, [6]), with:

- $\|w - w_h^l\|_{L^2(\Omega)} \lesssim h \|w\|_{H^1(\Omega)}$
- $|w - w_h^l|_{H^1(\Omega)} \lesssim \|w\|_{H^1(\Omega)}$

Therefore we also get $\|w_h^l\|_{H^1(\Omega)} \lesssim (C(1+h) + 1) \|w\|_{H^1(\Omega)}$.

Applying proposition D.1.4 we see that w_h satisfies all the requirements.

□

Make a comment on why imposing BCs with interpolation of nodal values exactly on the boundary, is the right thing to do, in shape optimization... for instance, when the boundary moves, a projected bc would also move and we would need to know the exact transformation etc

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