Algebra

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1 Group theory

1.1 Basic

Def 1. A non-empty set G with a binary function $f: G \times G \to G, (a,b) \mapsto ab$ is a *group* if it satisfies

- 1. (ab)c = a(bc).
- 2. $\exists 1 \in G \text{ s.t. } 1a = a1 = a, \forall a \in G.$
- 3. $\exists a^{-1} \in G \text{ s.t. } aa^{-1} = a^{-1}a = 1.$

CONCON

Def 2. Let G be a group. Then G is said to be abelian if $\forall a, b \in G, ab = ba$.

Ex 1.1.1. Let G be a semigroup. Then TFAE (the following are equivalent)

- 1. G is a group.
- 2. For all $a, b \in G$ and the equations bx = a, yb = a, each of them has a solution in G.
- 3. $\exists e \in G \text{ s.t. } ae = a \ \forall a \in G \text{ and if we fix such } e, \text{ then } \forall b \in G \ \exists b' \in G \text{ s.t. } bb' = e.$

Ex 1.1.2. Let G be a group. Show that

- 1. $\forall a \in G, a^2 = 1$, then G is abelian.
- 2. G is abelian $\iff \forall a, b \in G, (ab)^n = a^n b^n$ for three consecutive integer n.

Def 3. Let G be a group and $H \subseteq G, H \neq \phi$. Then H is said to be a subgroup of G, denoted by $H \subseteq G$, if

- 1. $\forall a, b \in H, ab \in H$.
- 2. $1 \in H$.
- 3. $\forall a \in H, a^{-1} \in H$.

<u>useful criterion</u>: $H \leq G \iff \forall a, b \in H, ab^{-1} \in H$.

pf:

$$\Rightarrow$$
 $b \in H \implies b^{-1} \in H$, and $a \in H$, so $ab^{-1} \in H$.

- \Leftarrow 1. $H \neq \phi \implies \exists a \in H \implies aa^{-1} = 1 \in H$.
 - 2. $1, a \in H \implies 1a^{-1} = a^{-1} \in H$.

3.
$$a, b^{-1} \in H \implies a(b^{-1})^{-1} = ab \in H$$
.

Eg 1.1.1. $(\mathbb{Z}, +, 0) \le (\mathbb{Q}, +, 0) \le (\mathbb{R}, +, 0) \le (\mathbb{C}, +, 0)$; $(\mathbb{Q}^{\times}, \times, 1) \le (\mathbb{R}^{\times}, \times, 1) \le (\mathbb{C}^{\times}, \times, 1)$

Eg 1.1.2.

- Special linear group $SL(n, \mathbb{F}) = \{ A \in GL(n, \mathbb{F}) \mid \det A = 1 \}$
- Orthogonal group $O(n) = \{ A \in GL(n, \mathbb{R}) \mid A^t A = I_n \}$
- Unitary group $U(n) = \{ A \in GL(n, \mathbb{C}) \mid A^*A = I_n \}$
- Special orthogonal group $SO(n) = SL(n, \mathbb{R}) \cap O(n)$

• Special unitary group $SU(n) = SL(n, \mathbb{C}) \cap U(n)$

Def 4. Let $f: G_1 \to G_2$. f is called an *isomorphism* if

- 1. f is 1-1 and onto.
- 2. $\forall a, b \in G_1, f(ab) = f(a)f(b)$. (homomorphism)

, denoted by $G_1 \cong G_2$.

Remark 1. (practice)

- 1. f(1) = 1.
- 2. $f(a^{-1}) = f(a)^{-1}$.
- 3. If f is an isomorphism, then $\exists f^{-1}$ is also a homomorphism.

Eg 1.1.3.

- $U(1) = \{ z \in \mathbb{C}^{\times} \mid \bar{z}z = 1 \}, z = \cos \theta + \sin \theta i \}$
- $SO(2) = \left\{ \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} : \theta \in \mathbb{R} \right\}$

notice that $U(1) \cong SO(2)$. $S^1 = \{(a,b) \in \mathbb{R}^2 \mid a^2 + b^2 = 1\}$, 可被賦予群的結構.

Eg 1.1.4. Let $A \in SU(2) \implies A = \begin{pmatrix} \alpha & \beta \\ -\bar{\beta} & \bar{\alpha} \end{pmatrix}, \alpha\bar{\alpha} + \beta\bar{\beta} = 1, \alpha, \beta \in \mathbb{C}.$

Quaternion(四元數): $\mathbb{H} = \{ a + bi + cj + dk \mid a, b, c, d \in \mathbb{R} \}$ with $i^2 = j^2 = k^2 = -1, ij = k, jk = i, ki = j (\Longrightarrow ij = -ji).$

Let x = a + bi + cj + dk, $\bar{x} = a - bi - cj - dk$, then $N(x) = x\bar{x} = a^2 + b^2 + c^2 + d^2$, For $x \neq 0, N(x) \neq 0, x^{-1} = \frac{1}{N(x)}\bar{x}$

Now, for x = a + bi + cj + dk = (a + bi) + (c + di)j. So SU(2) $\cong \{x \in \mathbb{H}^{\times} \mid N(x) = 1\}$. $S^3 = \{(a, b, c, d) \in \mathbb{R}^4 \mid a^2 + b^2 + c^2 + d^2 = 1\}$, 可被賦予群的結構.

 \star The only spheres with continuous group law are S^1, S^3 .

Ex 1.1.3. Find a way to regard $M_{n\times n}(\mathbb{H})$ as a subset of $M_{2n\times 2n}(\mathbb{C})$, which preserves addition and multiplication, and then there is a way to characterize $GL(n,\mathbb{H})$.

Def 5 (symplectic group). $\operatorname{Sp}(n,\mathbb{F}) = \{ A \in \operatorname{GL}(2n,\mathbb{F}) \mid A^{\operatorname{t}}JA = J \}$ where $J = \begin{pmatrix} O & I_n \\ -I_n & O \end{pmatrix}$. $(A^{\operatorname{t}}JA = J \text{ preserving non-degenerate skew-symmetric forms})$ $\operatorname{Sp}(n) = \{ A \in \operatorname{GL}(n,\mathbb{H}) \mid A^*A = I_n \}$.

Ex 1.1.4. Show $\operatorname{Sp}(n) \cong \operatorname{U}(2n) \cap \operatorname{Sp}(n, \mathbb{C})$.

Ques: Find the smallest subgroup of SU(2) containing $\begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}$.

1.2 Permutation groups and Dihedral groups

Def 6. A permutation of a set B is a 1-1 and onto function from B to B. Let $S_B :=$ the set of permutations of B. Then $(S_B, \cdot, \operatorname{Id}_B)$ forms a group.

If $B = \{a_1, \ldots, a_n\}$, then $S_B \cong S_{\{1,\ldots,n\}}$ and write $S_n = S_{\{1,\ldots,n\}}$, called the symmetric group of degree n.

Theorem 1 (Cayley theorem). Any group is isomorphic to a subgroup of some permutation group.

(Hint): Let G be a group. Set B=G. Consider $a\in G$ as $\sigma_a:G\to G, x\mapsto ax$. Then $\sigma_a\in S_G\implies G\le S_G$.

Fact 1. S_n is a finite group of order n!, i.e. $|S_n| = n!$.

$$\mathbf{pf}$$
: EASY =O

<u>Cyclic notation</u>: $\sigma \in S_5$, say $\sigma = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 4 & 3 & 5 & 1 & 2 \end{pmatrix}$. Write $\sigma = (1\ 4)(2\ 3\ 5)$.

⇒ Any permutation can be written as a product of disjoint cycles.

Eg 1.2.1. In
$$S_7$$
, $\sigma_1 = (1\ 2\ 3)(4\ 5\ 6)(7)$, $\sigma_2 = (1\ 3\ 5\ 6)(2\ 4\ 7)$. Then $\sigma_1\sigma_2 = (2\ 5\ 4\ 7\ 3\ 6)$, $\sigma_1^{-1} = (1\ 3\ 2)(4\ 6\ 5)$.

Def 7. A 2 cycle is called a transposition.

Eg 1.2.2. $(1\ 2\ 3) = (1\ 3)(1\ 2), (1\ 2\ 3\ 4\ 5) = (1\ 5)(1\ 4)(1\ 3)(1\ 2).$ Any permutation is a product of 2 cycles.

<u>Useful formula</u>: $\sigma \in S_n$, $\sigma(j_1 \ldots j_m)\sigma^{-1} = (\sigma(j_1) \ldots \sigma(j_m))$.

Eg 1.2.3. Let
$$\sigma = (1\ 2\ 3)(4\ 5\ 6\ 7), \ \sigma(2\ 3\ 4)\sigma^{-1} = (3\ 1\ 5).$$

pf: Note that both sides are functions. For $i \in \{1, ..., n\}$,

<u>Case 1</u>: $\exists k \text{ s.t. } \sigma(j_k) = i, \text{ CONCON}$

Case 2: Otherwise, CONCON

Fact 2. $S_n = \langle (1 \ 2), \dots, (1 \ n) \rangle$.

pf:
$$(1 i)^{-1} = (1 i)$$
 and $(i j) = (1 i)(1 j)(1 i)^{-1}$.

Def 8. Let G be a group and $S \subset G$. The subgroup generated by S defined to be the smallest subgroup of G which contains S, denoted by $\langle S \rangle$.

Ex 1.2.1.

1.
$$S_n = \langle (1\ 2), (2\ 3), \dots, (n-1\ n) \rangle$$
.

2.
$$S_n = \langle (1 \ 2), (1 \ 2 \ \dots \ n) \rangle$$
.

Def 9. $A_n = \{\text{even permutations of } S_n\} \leq S_n, |A_n| = \frac{n!}{2}.$

Ex 1.2.2.

1.
$$A_n = \langle (1\ 2\ 3), (1\ 2\ 4), \dots, (1\ 2\ n) \rangle, n \geq 3.$$

2.
$$A_n = \langle (1\ 2\ 3), (2\ 3\ 4), \dots, (n-2\ n-1\ n) \rangle, n \geq 3.$$

Remark 2. $\langle S \rangle = \bigcap_{S \subseteq H \leq G} H = \{a_1 a_2 \dots a_k \mid k \in \mathbb{N}, a_i \in S \cup S^{-1}\} \cup \{1\}$

The orthogonal transformations on \mathbb{R}^2 : O(2).

Let
$$A = \begin{pmatrix} a_1 & a_2 \\ b_1 & b_2 \end{pmatrix} \in \mathcal{O}(2)$$
.

略... (這邊討論旋轉和反射的矩陣)

<u>Case 1</u>: $A = \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix}$ is counterclockwise roration w.r.t. α .

<u>Case 2</u>: $A = \begin{pmatrix} \cos \alpha & \sin \alpha \\ \sin \alpha & -\cos \alpha \end{pmatrix}$ is the reflection. $A^2 = I_2 \implies$ eigenvalues are ± 1 .

Easy to show that $L_A(v) = v - 2\langle v, v_2 \rangle v_2$.

 $O(2) = \{ \text{rotations} \} \cup \{ \text{reflections} \}.$

Def 10. The dihedral group D_n is the group of symmetries of a regular n-gon. In general, $D_n = \langle \mathbf{T}, \mathbf{R} \mid \mathbf{T}^n = 1, \mathbf{R}^2 = 1, \mathbf{T}\mathbf{R} = \mathbf{R}\mathbf{T}^{-1} \rangle \leq O(2) \leq S_n, |D_n| = 2n.$

Def 11. Let T be a linear transformation from $\mathbb{R}^n \to \mathbb{R}^n$.

- T is called a rotation if \exists a T-invariant subspace $W \subseteq \mathbb{R}^n$ with dim W = 2 s.t. $\begin{cases} T|_W \text{ is a rotation} \\ T|_{W^{\perp}} = \mathrm{id}_{W^{\perp}} \end{cases}$
- T is called a reflection if \exists a T-invariant subspace $W \subseteq \mathbb{R}^n$ with dim W = 2 s.t. $\begin{cases} T|_W = -\mathrm{id}_W \\ T|_{W^{\perp}} = \mathrm{id}_{W^{\perp}} \end{cases}$

<u>Main result</u>: the group of orthogonal transformations = $\langle \text{rotations}, \text{reflections} \rangle$. <u>Prop</u>: For $T : \mathbb{R}^n \to \mathbb{R}^n$, \exists a T-invariant subspace $W \subseteq \mathbb{R}^n$ with $1 \le \dim W \le 2$.

pf: Let $A = [T]_{\alpha} \in M_{n \times n}(\mathbb{R}) \subseteq M_{n \times n}(\mathbb{C})$. Consider $\widetilde{L_A} : \mathbb{C}^n \to \mathbb{C}^n, v \mapsto Av$. Then \exists an eigenvalue $\lambda \in \mathbb{C}$ and an eigenvector $v \in \mathbb{C}^n$ for $\widetilde{L_A}$. Let $\lambda = \lambda_1 + \lambda_2 i, v = v_1 + v_2 i$. By definition, we have

$$Av = \widetilde{\mathcal{L}_A}(v) = \lambda v = (\lambda_1 + \lambda_2 i)(v_1 + v_2 i) \implies \begin{cases} Av_1 = \lambda_1 v_1 - \lambda_2 v_2 \\ Av_1 = \lambda_2 v_1 + \lambda_1 v_2 \end{cases},$$

so
$$W = \langle v_1, v_2 \rangle$$
.

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Ex 1.2.3.

- 1. If T is orthogonal, then W^{\perp} is also T-invariant.
- 2. Use induction on n to show the main result.

For
$$n = 3, A \in O(3)$$
, we have $A \sim \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \\ & \pm 1 \end{pmatrix}$.