

# Session 3: The rank

Optimization and Computational Linear Algebra for Data Science

# Contents

1. The rank
2. The rank-nullity Theorem
3. More on the inverse of a matrix
4. Transpose of a matrix
5. Why do we care about all these things ?

Is the rank useful in practice?

# The rank

# Recap of the videos

## Definition

We define the rank of a family  $x_1, \dots, x_k$  of vectors of  $\mathbb{R}^n$  as the dimension of its span:

$$\text{rank}(x_1, \dots, x_k) \stackrel{\text{def}}{=} \dim(\text{Span}(x_1, \dots, x_k)).$$

## Definition

Let  $M \in \mathbb{R}^{n \times m}$ . Let  $c_1, \dots, c_m \in \mathbb{R}^n$  be its columns. We define

$$\text{rank}(M) \stackrel{\text{def}}{=} \text{rank}(c_1, \dots, c_m) = \dim(\text{Im}(M)).$$

## Proposition

Let  $M \in \mathbb{R}^{n \times m}$ . Let  $r_1, \dots, r_n \in \mathbb{R}^m$  be the rows of  $M$  and  $c_1, \dots, c_m \in \mathbb{R}^n$  be its columns. Then we have

$$\text{rank}(r_1, \dots, r_n) = \text{rank}(c_1, \dots, c_m) = \text{rank}(M).$$



# How do we compute the rank ?

For  $v_1, \dots, v_k \in \mathbb{R}^n$ , and  $\alpha \in \mathbb{R} \setminus \{0\}$ ,  $\beta \in \mathbb{R}$  we have

$$\text{rank}(v_1, \dots, v_k) = \begin{cases} \text{rank}(v_1, \dots, v_{i-1}, \underline{\alpha v_i}, v_{i+1}, \dots, v_k) \\ \text{rank}(v_1, \dots, v_{i-1}, v_i + \beta v_j, v_{i+1}, \dots, v_k) \end{cases}$$

*Handwritten notes:*  
A red arrow points from the first case to the text "multiply one vector by  $\alpha \neq 0$ ".  
A red arrow points from the second case to the text "replace  $v_i$  by  $v_i + \beta v_j$  for some  $j \neq i$ ".

As a consequence, the Gaussian elimination method keeps the rank of a matrix unchanged!

# Example

Let's compute the rank of

$$A = \begin{pmatrix} 1 & -1 & 0 & 1 \\ 2 & 0 & 1 & -1 \\ -1 & 5 & 2 & 0 \end{pmatrix}$$

$R_1$   
 $R_2$   
 $R_3$

$$A' = \begin{pmatrix} 1 & -1 & 0 & 1 \\ 0 & 2 & 1 & -3 \\ 0 & 4 & 2 & 1 \end{pmatrix}$$

$R_2 - 2R_1$   
 $R_3 + R_1$

here:

$$\text{rank}(A) = \text{rank}(A')$$

$$A'' = \begin{pmatrix} 1 & -1 & 0 & 1 \\ 0 & 2 & 1 & -3 \\ 0 & 0 & 0 & 7 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$R_3 - 2R_2$

$$\text{rank}(A'') = \text{rank}(A)$$

but

$$\dim \text{Im } A'' = \dim \text{Im } A$$

# Example

Claim:  $\text{rank}(A'') = 3$

$$A'' = \begin{pmatrix} \overset{c_1}{\textcircled{1}} & \overset{c_2}{-1} & 0 & \overset{c_4}{1} \\ 0 & \textcircled{2} & 1 & -3 \\ 0 & 0 & 0 & \textcircled{7} \end{pmatrix}$$

"leading coefficients"

Claim:  $c_1, c_2, c_4$  are linearly independent

Let  $a, b, c \in \mathbb{R}$  such that  $\underline{a}c_1 + \underline{b}c_2 + \underline{c}c_4 = 0$

$$\begin{cases} a - \underline{b} + \underline{c} = 0 \\ \underline{2b} - 3\underline{c} = 0 \\ \underline{7c} = 0 \end{cases} \Leftrightarrow \begin{cases} a = 0 \\ b = 0 \\ c = 0 \end{cases}$$

Hence  $c_1, c_2, c_4$  are lin indep.

$$\text{Span}(c_1, c_2, c_4) = \mathbb{R}^3 \quad \Leftrightarrow \quad \text{Im}(A'') = \mathbb{R}^3$$

# The rank-nullity Theorem



# Rank-nullity Theorem

## Theorem

Let  $L : \mathbb{R}^m \rightarrow \mathbb{R}^n$  be a linear transformation. Then

$$\text{rank}(L) + \dim(\text{Ker}(L)) = m.$$

$\text{rank}(L)$   
 $\dim(\text{Im}(L))$

$\dim(\mathbb{R}^m)$

Very usefull to get  $\dim \text{Ker } L$  from  
 $\text{rank}(L)$  and vice-versa !

# Intuition

Let us solve the linear system  $Ax = 0$ .

$$\left( \begin{array}{cccc|c} 1 & -1 & 0 & 1 & 0 \\ 2 & 0 & 1 & -1 & 0 \\ -1 & 5 & 2 & 0 & 0 \end{array} \right) \rightarrow \left( \begin{array}{cccc|c} 1 & -1 & 0 & 1 & 0 \\ 0 & 2 & 1 & -3 & 0 \\ 0 & 4 & 2 & 1 & 0 \end{array} \right) \begin{array}{l} (R_1) \\ (R_2) - 2(R_1) \\ (R_3) + (R_1) \end{array}$$

$$\left( \begin{array}{cccc|c} 1 & -1 & 0 & 1 & 0 \\ 0 & 2 & 1 & -3 & 0 \\ 0 & 0 & 0 & 7 & 0 \end{array} \right) \begin{array}{l} (R_1) \\ (R_2) \\ (R_3) - 2(R_2) \end{array}$$

$$\begin{cases} x_1 - x_2 + x_4 = 0 \\ 2x_2 + x_3 - 3x_4 = 0 \\ 7x_4 = 0 \end{cases}$$

Span  $\begin{pmatrix} -1/2 \\ -1/2 \\ 1 \\ 0 \end{pmatrix}$

$$\begin{cases} x_1 - x_2 = 0 \\ 2x_2 = -x_3 \\ x_4 = 0 \end{cases}$$

$$\begin{cases} x_1 = -\frac{x_3}{2} \\ x_2 = -x_3/2 \\ x_3 = x_3 \\ x_4 = 0 \end{cases}$$

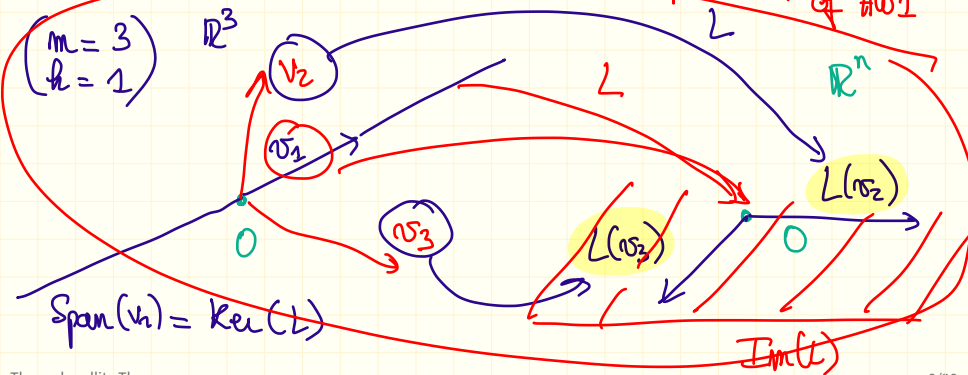
$$\left\{ \begin{pmatrix} -t/2 \\ -t/2 \\ t \\ 0 \end{pmatrix} \mid t \in \mathbb{R} \right\} = \text{Ker}(A)$$

$$\dim \text{Ker}(A) = 4 - \text{"number of leading coeffs"} = 4 - \text{rank}(A)$$

The rank-nullity Theorem

# Proof of the rank-nullity Theorem

- let  $k = \dim \text{Ker}(L)$  and  $(v_1, \dots, v_k)$  be a basis of  $\text{Ker}(L)$ .
- I can add vectors  $v_{k+1}, \dots, v_m$  to it to obtain a basis  $(v_1, \dots, v_m)$  of  $\mathbb{R}^m$  this follows from P. 1.3 of Hw1



# Proof of the rank-nullity Theorem

Claim:  $(L(v_{k+1}) \dots L(v_m))$  is a basis of  $\text{Im}(L)$

Given the claim, the theorem follows.

$$\dim \text{Im}(L) = m - k = m - \dim \text{Ker}(L)$$

$$\textcircled{1} \quad \underbrace{\text{Span}(L(v_{k+1}) \dots L(v_m))}_S = \text{Im}(L).$$

- $S \subset \text{Im}(L)$  because  $L(v_{k+1}) \dots L(v_m) \in \text{Im}(L)$   
and  $\text{Im}(L)$  is a subspace.

# Proof of the rank-nullity Theorem

- $\text{Im}(L) \subset \underbrace{\text{Span}(L(v_{i+1}) \dots L(v_m))}_S$
  - Let  $y \in \text{Im}(L)$ , there exists  $x \in \mathbb{R}^m$  such that  $y = L(x)$ .
  - Let  $(\alpha_1 \dots \alpha_m)$  be the coord. of  $x$  in  $(v_1 \dots v_m)$   
$$y = L(x) = L(\alpha_1 v_1 + \dots + \alpha_m v_m)$$
$$= \alpha_1 \underbrace{L(v_1)}_{=0} + \dots + \alpha_i \underbrace{L(v_i)}_{=0} + \alpha_{i+1} L(v_{i+1}) + \dots + \alpha_m L(v_m)$$

$\in S$ .
- $y \in S$
- hence
- $\text{Im}(L) = \text{Span}(L(v_{i+1}) \dots, L(v_m))$

# Proof of the rank-nullity Theorem

② let's show that  $\{L(v_{n+1}) - L(v_m)\}$  lin. indep.

let  $\alpha_{n+1} \dots \alpha_m \in \mathbb{R}$  such that  $\alpha_{n+1} L(v_{n+1}) + \dots + \alpha_m L(v_m) = 0$

$$\begin{aligned} \rightarrow \underline{0} &= L(\alpha_{n+1} v_{n+1} + \dots + \alpha_m v_m) \\ &= \alpha_1 v_1 + \dots + \alpha_n v_n \\ &\leftarrow L(u) = 0 \end{aligned}$$

Hence  $u \in \text{Ker}(L)$  therefore there exists  $\alpha_1 \dots \alpha_n$  s.t.

$$u = \alpha_1 v_1 + \dots + \alpha_n v_n$$

$$\text{we get: } \alpha_1 v_1 + \dots + \alpha_n v_n - \alpha_{n+1} v_{n+1} - \dots - \alpha_m v_m = 0$$

$(v_1 - v_m)$  lin. indep hence  $\alpha_1 = \dots = \alpha_m = 0$ .

# Proof of the rank-nullity Theorem

# Invertible matrices

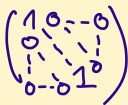


# Invertible matrices

## Definition (Matrix inverse)

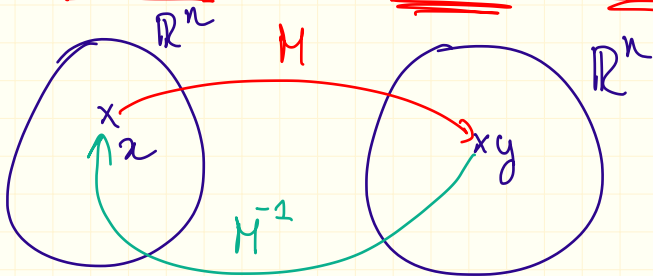
A **square** matrix  $M \in \mathbb{R}^{n \times n}$  is called *invertible* if there exists a matrix  $M^{-1} \in \mathbb{R}^{n \times n}$  such that

$$\underline{MM^{-1}} = \underline{M^{-1}M} = \underline{\text{Id}_n}.$$



Such matrix  $M^{-1}$  is unique and is called the *inverse* of  $M$ .

**Exercise:** Let  $A, B \in \mathbb{R}^{n \times n}$ . Show that if  $\underline{AB = \text{Id}_n}$  then  $\underline{BA = \text{Id}_n}$ .




# Invertible matrices

## Theorem

Let  $M \in \mathbb{R}^{n \times n}$ . The following points are equivalent:

1.  $M$  is invertible.
2.  $\text{rank}(M) = n$ .
3.  $\text{Ker}(M) = \{0\}$ .  $\Leftrightarrow \dim \text{Ker}(M) = 0$
4. For all  $y \in \mathbb{R}^n$ , there exists a unique  $x \in \mathbb{R}^n$  such that  $Mx = y$ .

- The rank nullity theorem gives (2)  $\Leftrightarrow$  (3)
- $(1) \xRightarrow{\checkmark} \begin{pmatrix} (2) \\ (3) \end{pmatrix} \xRightarrow{\checkmark} (4) \xRightarrow{\checkmark} (1)$   


# Proof

(1)  $\Rightarrow$  (3) Assume  $M$  invertible.

Let  $x \in \text{Ker } M$ :  $Mx = 0$

$$\rightarrow \underbrace{M^{-1}M}_{\text{Id}_n} x = M^{-1}0 = 0$$

$$x = \text{Id}_n x = 0$$

$$\boxed{x = 0}$$

this gives

$$\boxed{\text{Ker}(L) = \{0\}}$$

# Proof

$\begin{pmatrix} (2) \\ (3) \end{pmatrix} \Rightarrow (4)$  let's assume that  $\begin{cases} \text{rank}(M) = n \\ \text{ker}(M) = \{0\} \end{cases}$

$\text{Im}(M)$  is a subspace of  $\mathbb{R}^n$   $\dim(\mathbb{R}^n) = n$   
 $\dim \text{Im}(M) = n$

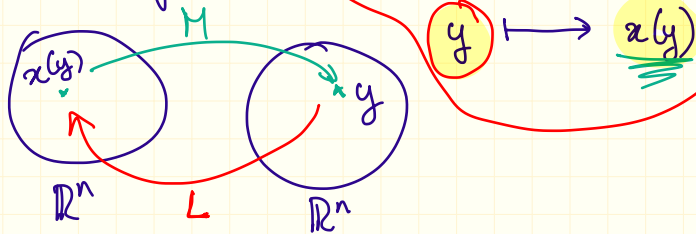
Hence  $\boxed{\text{Im}(M) = \mathbb{R}^n}$

• From what we have seen last week, for every  $y \in \mathbb{R}^n$ , there exists (because  $\text{Im}(M) = \mathbb{R}^n$ ) a unique (because  $\text{ker } M = \{0\}$ ) such that  $Mx = y$

# Proof

(4)  $\Rightarrow$  (1) For every  $y \in \mathbb{R}^n$  there exists  $x(y) \in \mathbb{R}^n$  such that  $M x(y) = y$ .

Let's define :



Claim:  $L$  is linear.  $\leftarrow$

# Proof

By construction of  $L$ , we have for all  $y \in \mathbb{R}^n$

$$M \circ L(y) = y$$

$$\text{Id}_n: \mathbb{R}^n \rightarrow \mathbb{R}^n \\ y \mapsto y$$

$$M \circ L(y) = \text{Id}_n(y)$$

This gives that the linear transformations

$M \circ L$  and  $\text{Id}_n$  are the same:  $M \circ L = \text{Id}_n$

Hence their matrices are equal:

<sup>a matrix product</sup>  $\boxed{\tilde{M} \tilde{L} = \tilde{\text{Id}}_n}$  :  $\tilde{M}$  is invertible

# Transpose of a matrix

# Transpose of a matrix

## Definition

Let  $M \in \mathbb{R}^{n \times m}$ . We define its *transpose*  $M^T \in \mathbb{R}^{m \times n}$  by

$$(M^T)_{i,j} = M_{j,i}$$

for all  $i \in \{1, \dots, m\}$  and  $j \in \{1, \dots, n\}$ .

Example:  $M = \begin{pmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{pmatrix}$

$$M^T = \begin{pmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{pmatrix}$$

"the col. of  $M$  become  
the rows of  $M^T$ "

## Remark:

- ❖ We have  $(M^T)^T = M$ .
- ❖ The mapping  $M \mapsto M^T$  is linear.

$$\begin{aligned} (A+B)^T &= A^T + B^T \\ (\alpha A)^T &= \alpha A^T \end{aligned}$$



# Properties of the transpose

## Proposition

For all  $A \in \mathbb{R}^{n \times m}$ ,

$$\text{rank}(A) = \text{rank}(A^T).$$

because "rank of rows"  
= "rank of cols."

proved in recitation

## Proposition

Let  $A \in \mathbb{R}^{n \times m}$  and  $B \in \mathbb{R}^{m \times k}$ . Then

$$(AB)^T = B^T A^T.$$

**Proof.**

Let's compute

$$\begin{aligned} (AB^T)_{i,j} &= (AB)_{j,i} = \sum_{l=1}^m A_{j,l} B_{l,i} \\ &= \sum_{l=1}^m (A^T)_{l,j} (B^T)_{i,l} = \sum_{l=1}^m (B^T)_{i,l} (A^T)_{l,j} \\ &= (B^T A^T)_{i,j} \end{aligned}$$

□

# Symmetric matrices

## Definition

A square matrix  $A \in \mathbb{R}^{n \times n}$  is said to be *symmetric* if

$$\forall i, j \in \{1, \dots, n\}, A_{i,j} = A_{j,i}$$

or, equivalently if  $A = A^T$ .

**Remark:** For all  $M \in \mathbb{R}^{n \times m}$  the matrix  $MM^T$  is symmetric.

$(MM^T)^T = (M^T)^T M^T = MM^T$  :  $MM^T$  is sym.

Ex:  $\begin{pmatrix} 1 & 4 & 6 \\ 4 & 2 & 5 \\ 6 & 5 & 3 \end{pmatrix}$  is symmetric

# **Is the rank useful in practice?**

# Back to the movies ratings example

Assume that you are given the matrix of movies ratings:

users  $\rightarrow$

$$\begin{pmatrix} 1 & 1 & 5 & 5 & 5 \\ 2 & 2 & 2 & 0 & 0 \\ 1 & 1.001 & 5 & 5 & 5 \\ 2 & 2 & 2 & 0.0001 & 0 \\ 2.0001 & 2 & 2 & 0 & 0 \end{pmatrix}$$

$M$

**Goal:** how many different « user profiles » do we have ?

$$\text{rank}(M) = 5$$

# Conclusion

- ❖ The rank is not «robust» !
- ❖ We need to have a way to check if a matrix has «approximately a small rank».
- ❖ Equivalently, given  $m$  vectors, one would like to be able to see if there exists a subspace of dimension  $k \ll m$  from which the vectors are « close ».
- ❖ The singular value decomposition (lecture 6-7) will solve our problems !

# Questions?

$$\begin{array}{c} U \cap V = \{0\} \\ | \quad \quad \quad \backslash \\ (u_1 - u_n) \quad (v_1 - v_m) \end{array}$$

$(u_1 \dots u_n \ v_1 \dots v_m)$  lin indep.

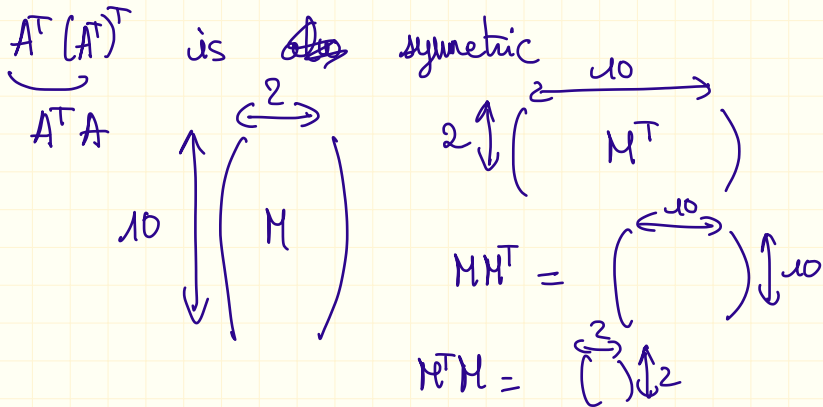
$$\alpha_1 u_1 + \dots + \alpha_n u_n + \beta_1 v_1 + \dots + \beta_m v_m = 0$$

$\rightarrow \alpha_i = \beta_i$  are all zero

# Questions?

$MM^T$  is always symmetric

Let's apply this to  $M = A^T$



# Questions?

$MM^T$  is  $10 \times 10$  when  $M$  is  $10 \times 2$ .

$MM^T$  is not invertible!

$$\text{rank}(MM^T) \leq \min(\text{rank } M, \text{rank } M^T) \leq 2$$

$\Leftrightarrow$

$$\text{rank}(MM^T) \leq \text{rank}(M)$$

$$\text{rank}(MM^T) \leq \text{rank}(M^T)$$

-