

Problem 2.1.

a)  $T$  is not linear:  $T(1,0) = (1,1)$

$$T(2,0) = (4,2) \neq 2 \cdot T(1,0).$$

b)  $T$  is not linear:  $T(0,0) = (1,0) \neq (0,0)$ .

c)  $T$  is linear. Indeed, for all  $A, B \in \mathbb{R}^{n \times m}$  and  $\alpha \in \mathbb{R}$ : we have for all  $i \in \{1, \dots, m\}$  and  $j \in \{1, \dots, n\}$

$$T(\alpha A + B)_{ij} = (\alpha A + B)_{ji}$$

$$= (\alpha A + B)_{j,i} = \alpha A_{j,i} + B_{j,i} = \alpha (A^T)_{ij} + (B^T)_{ij}$$

$$= \alpha T(A)_{ij} + T(B)_{ij}$$

Hence  $T(\alpha A + B) = \alpha T(A) + T(B)$ , which proves that  $T$  is linear (take  $\alpha=1$  to obtain that  $T(A+B) = T(A) + T(B)$  and  $B=0$  to get  $T(\alpha A) = \alpha T(A)$ ).

$T$  is linear.

d) Let  $A, B \in \mathbb{R}^{n \times n}$  and  $\alpha \in \mathbb{R}$

$$T(\alpha A + B) = \sum_{i=1}^n (\alpha A + B)_{ii}$$

$$= \sum_{i=1}^n \alpha A_{ii} + B_{ii} = \alpha \sum_{i=1}^n A_{ii} + \sum_{i=1}^n B_{ii}$$

$$= \alpha T(A) + T(B)$$

Problem 2.2.

a) We have to compute: by linearity of  $f$ .

$$f\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = f\left(\begin{pmatrix} 2 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \end{pmatrix}\right) = f\left(\begin{pmatrix} 2 \\ 2 \end{pmatrix}\right) - f\left(\begin{pmatrix} 1 \\ 2 \end{pmatrix}\right)$$

$$\left(\begin{smallmatrix} 1 \\ 0 \\ 1 \end{smallmatrix}\right) = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} - \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} 0 \\ -2 \\ -2 \end{pmatrix}$$

$$f\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = f\left(\frac{1}{2}\left(\begin{pmatrix} 1 \\ 2 \end{pmatrix} - \begin{pmatrix} 1 \\ 0 \end{pmatrix}\right)\right) = \frac{1}{2}f\left(\begin{pmatrix} 1 \\ 2 \end{pmatrix}\right) - \frac{1}{2}f\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right)$$

$$= \frac{1}{2}\begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} - \frac{1}{2}\begin{pmatrix} 0 \\ -2 \\ -2 \end{pmatrix} = \begin{pmatrix} 1/2 \\ 2 \\ 5/2 \end{pmatrix}$$

The matrix of  $f$  is therefore  $\begin{pmatrix} 0 & 1/2 \\ -2 & 2 \\ -2 & 5/2 \end{pmatrix}$

b) For  $a, b, c \in \mathbb{R}$  we solve the system  $f\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$ :

$$\begin{cases} \frac{1}{2}y = a \\ -2x + 2y = b \\ -2x + \frac{5}{2}y = c \end{cases} \Leftrightarrow \begin{cases} y = 2a \\ x = y - \frac{b}{2} \\ x = \frac{5}{4}y - \frac{c}{2} \end{cases}$$

$$\Leftrightarrow \begin{cases} y = 2a \\ x = 2a - \frac{b}{2} \\ x = \frac{5a}{2} - \frac{c}{2} \end{cases}$$

Consequently, the system has no solution if  $2a - \frac{b}{2} \neq \frac{1}{2}(5a - \frac{c}{2})$  and has a unique solution  $(x, y) = (2a - \frac{b}{2}, 2a)$  otherwise.

In this question  $a=1, b=4, c=5$  hence  $2a - \frac{b}{2} = 2 - 2 = 0 = \frac{1}{2}(5a - c)$ .

We conclude:  $\{x \in \mathbb{R}^2 \mid f(x) = (1, 4, 5)\} = \left\{ \begin{pmatrix} 0 \\ 2 \end{pmatrix} \right\}$ .

c) In this case  $a=2, b=4, c=5$  so  $2a - \frac{b}{2} = 2$  and  $\frac{1}{2}(5a - c) = \frac{5}{2} \neq 2$ : there is no solution:  
 $\{x \in \mathbb{R}^2 \mid f(x) = (1, 4, 5)\} = \emptyset$

Problem 2.3.

Let us look at the "target" matrix ABC:

$$ABC = \begin{pmatrix} B_{1,2} & B_{1,1} & B_{1,3} & B_{1,2} \\ B_{2,2} + B_{3,2} & B_{2,1} + B_{3,1} & B_{2,3} + B_{3,3} & B_{2,2} + B_{3,2} \\ B_{4,2} & B_{4,1} & B_{4,3} & B_{4,2} \end{pmatrix}$$

$\underbrace{\hspace{1.5cm}}_{\text{coeff. of the}} \quad \underbrace{\hspace{1.5cm}}_{B_{*,1}} \quad \underbrace{\hspace{1.5cm}}_{B_{*,3}} \quad \underbrace{\hspace{1.5cm}}_{B_{*,2}}$

form  $B_{*,2}$ : they belong to the second column of B

We see that the order of the columns of B have changed, and that the second column of B has been duplicated. Such operation can be done by multiplying B with a matrix with 0 and 1:

$$\begin{pmatrix} 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{pmatrix} \Bigg\} C.$$

$$\begin{pmatrix} B_{1,1} & B_{1,2} & B_{1,3} \\ B_{2,1} & B_{2,2} & B_{2,3} \\ B_{3,1} & B_{3,2} & B_{3,3} \\ B_{4,1} & B_{4,2} & B_{4,3} \end{pmatrix} \begin{pmatrix} B_{1,2} & B_{1,1} & B_{1,3} & B_{1,2} \\ B_{2,2} & B_{2,1} & B_{2,3} & B_{2,2} \\ B_{3,2} & B_{3,1} & B_{3,3} & B_{3,2} \\ B_{4,2} & B_{4,1} & B_{4,3} & B_{4,2} \end{pmatrix}$$

Now, by looking at the rows of ABC we see rows 1 and 4 has been untouched but that the rows 2 and 3 have been added together:

$$A \left\{ \begin{array}{c|cccc} & B_{1,2} & B_{1,1} & B_{2,3} & B_{1,2} \\ & B_{2,2} & B_{4,1} & B_{2,3} & B_{2,2} \\ & B_{3,2} & B_{3,1} & B_{3,3} & B_{3,2} \\ & B_{4,2} & B_{4,1} & B_{4,3} & B_{4,2} \end{array} \right\} BC$$

$$A \left\{ \begin{array}{c|cccc} & 1 & 0 & 0 & 0 \\ & 0 & 1 & 1 & 0 \\ & 0 & 0 & 0 & 1 \end{array} \right\} \begin{array}{cccc} B_{1,2} & B_{1,1} & B_{2,3} & B_{1,2} \\ B_{2,2}+B_{3,2} & B_{2,1}+B_{3,1} & B_{2,3}+B_{3,3} & B_{2,2}+B_{3,2} \\ B_{4,2} & B_{4,1} & B_{4,3} & B_{4,2} \end{array}$$

Problem 2.4

- a) •  $0 \in \text{Im}(A)$  because  $A \cdot 0 = 0 : \text{Im}(A) \neq \emptyset$ .
- let  $u, v \in \text{Im}(A)$  and  $\alpha \in \mathbb{R}$ . By definition there exists  $u_0, v_0 \in \mathbb{R}^m$  such that  $u = Au_0$  and  $v = Av_0$ .
- Then:  $\alpha u + v = \alpha Au_0 + Av_0 = A(\alpha u_0 + v_0) \in \text{Im}(A)$ .

- $0 \in \text{Ker}(A)$  because  $A \cdot 0 = 0 : \text{Ker}(A) \neq \emptyset$ .
- let  $u, v \in \text{Ker}(A)$  and  $\alpha \in \mathbb{R}$ .
- $A(\alpha u + v) = \alpha Au + Av = 0 + 0 = 0$ .
- Hence  $\alpha u + v \in \text{Ker}(A)$ .

$\text{Im}(A)$  is therefore a subspace of  $\mathbb{R}^n$  and  $\text{Ker}(A)$  a subspace of  $\mathbb{R}^m$ .

⑥ let  $y = (y_1, y_2, y_3) \in \mathbb{R}^3$ . We will solve

$$Ax = y \Leftrightarrow \begin{cases} x_1 + 2x_2 + x_3 + 2x_4 = y_1 \\ -x_1 + x_2 - x_3 + x_4 = y_2 \\ x_2 + 2x_4 = y_3 \end{cases} \quad (R_2)$$

$$\Leftrightarrow \begin{cases} x_1 + 2x_2 + x_3 + 2x_4 = y_1 \\ 3x_2 + 3x_4 = y_2 + y_1 \quad (R_2) + (R_1) \\ x_2 + 2x_4 = y_3 \end{cases}$$

$$\Leftrightarrow \begin{cases} x_1 + 2x_2 + x_3 + 2x_4 = y_1 \\ x_2 + 2x_4 = y_3 \quad (R_3) \\ -3x_4 = y_2 + y_1 - 3y_3 \quad (R_2) - 3(R_3) \end{cases}$$

- In order to find a basis of  $\text{Ker}(A)$  we first consider the case where  $y_1 = y_2 = y_3 = 0$ .

In that case we obtain that

$$Ax = 0 \Leftrightarrow x_1 + x_3 = 0$$

$$\Leftrightarrow x \in \text{Span}\left(\begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}\right).$$

Hence  $\text{Ker}(A) = \text{Span}\left(\begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}\right)$  and  $\left(\begin{pmatrix} 1 \\ 0 \\ -1 \\ 0 \end{pmatrix}\right)$  is a basis of  $\text{Ker}(A)$ .

- In order to show that  $\text{Im}(A) = \mathbb{R}^3$  we have to show that  $Ax = y$  has at least 1 solution for all  $y \in \mathbb{R}^3$ .

Coming back to the resolution of  $Ax=y$   
we have :

$$Ax=y \Leftrightarrow \begin{cases} x_1 = y_1 - x_3 - 2x_2 - 2x_4 \\ x_2 = y_3 - 2x_4 \\ x_4 = -\frac{1}{3}(y_2 + y_1 - 3y_3) \end{cases}$$

$$\Leftrightarrow \begin{cases} x_1 = y_1 - x_3 - 2\left(y_3 + \frac{2}{3}(y_2 + y_1 - 3y_3)\right) + \frac{2}{3}(y_2 + y_1 - 3y_3) \\ x_2 = y_3 + \frac{2}{3}(y_2 + y_1 - 3y_3) \\ x_4 = -\frac{1}{3}(y_2 + y_1 - 3y_3) \end{cases}$$

Consequently, the vector

$$\begin{pmatrix} y_1 - 2\left(y_3 + \frac{2}{3}(y_2 + y_1 - 3y_3)\right) + \frac{2}{3}(y_2 + y_1 - 3y_3) \\ y_3 + \frac{2}{3}(y_2 + y_1 - 3y_3) \\ 0 \\ -\frac{1}{3}(y_2 + y_1 - 3y_3) \end{pmatrix}$$

is a solution of  $Ax=y$ . We conclude that  
 $\text{Im}(A) = \mathbb{R}^3$ .



### Problem 5:

- Assume that there exists  $C \in \mathbb{R}^{m \times k}$  such that  $A = CB$ .  
Then for all  $x \in \text{Ker}(B)$ ,  $Ax = CBx$   

$$= C \cdot 0 \quad (\text{because } Bx = 0)$$

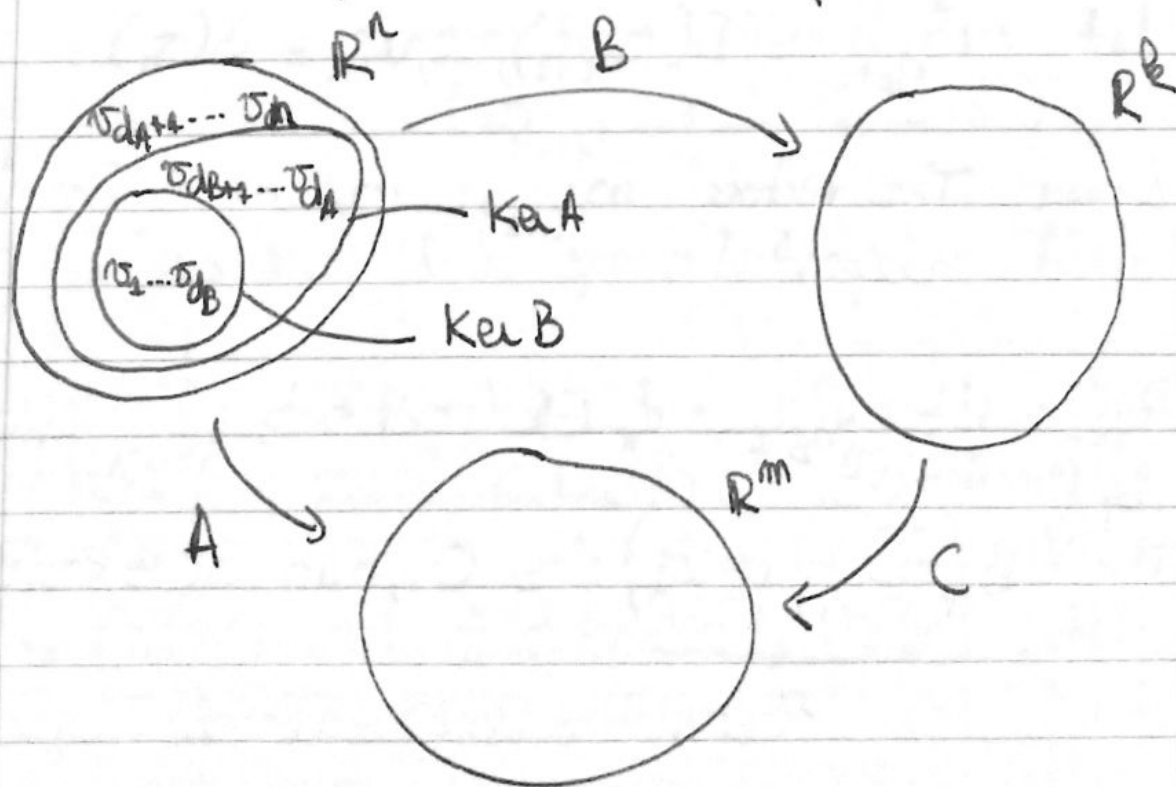
$$= 0.$$

Hence  $x \in \text{Ker}(A)$ .

This gives that  $\text{Ker}(B) \subset \text{Ker}(A)$ . Because we know that  $\text{Ker}(B)$  is a subspace of  $\mathbb{R}^n$ , it is then a subspace of the vector space  $\text{Ker}(A)$ .

- Assume that  $\text{Ker}(B) \subset \text{Ker}(A)$ . Let  $A, B$  be the linear maps associated to  $A$  and  $B$ .

Finding a matrix  $C \in \mathbb{R}^{m \times k}$  such that  $A = CB$  is equivalent to finding a linear map  $C: \mathbb{R}^k \rightarrow \mathbb{R}^m$  such that  $A = C \circ B$ , i.e. such that for all  $x \in \mathbb{R}^n$ ,  $Ax = C(Bx)$ .



Let  $d_B = \dim(\text{Ker } B)$      $d_A = \dim(\text{Ker } A)$ .

Since  $\text{Ker } B$  is a subspace of  $\text{Ker } A$  (which is itself a subspace of  $\mathbb{R}^n$ ) we have  $d_B \leq d_A \leq n$ .

Let  $(v_1, \dots, v_{d_B})$  be a basis of  $\text{Ker } B$ . By Pb 1.4, one can ~~find~~ add vectors  $v_{d_B+1}, \dots, v_{d_A}$  to ~~this~~ it to obtain a basis of  $\text{Ker } A$ .

Applying Pb 1.4 again we can add vectors  $v_{d_A+1}, \dots, v_n$  to obtain a basis of  $\mathbb{R}^n$ .

To summarize we have:

$$\underbrace{v_1 \dots v_{d_B}}_{\text{Basis of Ker}(B)} \quad \underbrace{v_{d_B+1} \dots v_{d_A}}_{\text{Basis of Ker}(A)} \quad v_{d_A+1} \dots v_n$$

Basis of  $\mathbb{R}^n$

Let  $w_{d_B+1} = B(v_{d_B+1}), \dots, w_n = B(v_n)$ .

Lemma: The vectors  $w_{d_B+1}, \dots, w_n$  are linearly independent.

Proof: Let  $\alpha_{d_B+1}, \dots, \alpha_n \in \mathbb{R}$  such that  $\sum_{i=d_B+1}^n \alpha_i w_i = 0$   
by linearity of  $B$

Then  $\forall B \left( \underbrace{\sum_{i=d_B+1}^n \alpha_i v_i}_{u} \right) = 0$ , i.e.  $u \in \text{Ker}(B)$ .

$u \dots$



Hence  $u = \sum_{i=1}^{d_B} \alpha_i v_i$  for some  $\alpha_1 \dots \alpha_{d_B} \in \mathbb{R}$  (because  $v_1 \dots v_{d_B}$  is a basis of  $\text{Ker}(B)$ ). This gives  
 $\sum_{i=1}^{d_B} \alpha_i v_i - \sum_{i=d_B+1}^n \alpha_i v_i = 0$  and we obtain that

$\alpha_1 = \dots = \alpha_{d_B+1} = \dots = \alpha_n = 0$  because  $(v_1 \dots v_n)$  are linearly independent.  $\square$

Using the lemma and Pb. 1.4 we can find vectors  $w'_1, \dots, w'_l$  (with  $l = k - (n - d_B)$ ) such that  $w_{d_B+1}, \dots, w_n, w'_1, \dots, w'_l$  is a basis of  $\mathbb{R}^k$ .

We define now the linear map  $C$ :

$$C: \mathbb{R}^k \longrightarrow \mathbb{R}^m$$

$$x \longmapsto \alpha_{d_B+1} A(v_{d_B+1}) + \dots + \alpha_n A(v_n)$$

where  $(\alpha_{d_B+1}, \dots, \alpha_n, \alpha'_1, \dots, \alpha'_l)$   
 are the coordinates of  $x$  in the basis  
 $(w_{d_B+1}, \dots, w_n, w'_1, \dots, w'_l)$ .

Let us verify that for all  $i=1 \dots n$ ,  $A(v_i) = C(B(v_i))$ .

- If  $i \in \{1 \dots d_B\}$  then  $B(v_i) = 0$  and  $A(v_i) = 0$  because  $\text{Ker}(B) \subset \text{Ker}(A)$ . Hence  $A(v_i) = C(B(v_i))$ .
- If  $i \in \{d_B+1, \dots, n\}$ , then by definition  $B(v_i) = w_i$  and by definition of  $C$ :  $C(w_i) = A(v_i)$ . Hence  $C(B(v_i)) = C(w_i) = A(v_i)$ .

The linear transformations  $A$  and  $C \circ B$  are thus equal over the vectors of the basis  $(v_1, \dots, v_n)$ , they are therefore equal because for all  $x \in \mathbb{R}^n$  we have

$$\begin{aligned} C(B(x)) &= \sum_{i=1}^n \lambda_i C(B(v_i)) \\ &= \sum_{i=1}^n \lambda_i A(v_i) = A(x), \text{ where} \end{aligned}$$

$(\lambda_1, \dots, \lambda_n)$  denotes the coordinates of  $x$  in the basis  $(v_1, \dots, v_n)$ .