

Problem 5.1.

Notice that  $M \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  so  $\lambda_1 = 1$  is an eigenvalue of  $M$ .

By contradiction, assume that  $M$  is diagonalizable. Then there exist  $P \in \mathbb{R}^{2 \times 2}$  invertible and  $\lambda_2 \in \mathbb{R}$  such that

$$M = P \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} P^{-1}$$

Since  $\text{Tr}(M) = \lambda_1 + \lambda_2 = 2$ , we get  $\lambda_2 = 1$

So

$$M = P \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} P^{-1} = PP^{-1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} : \text{ we}$$

get a contradiction.

Conclusion:  $M$  is not diagonalizable

## Problem 5.2

a) Compute  $MM^T = (\text{Id}_n - 2P_S)(\text{Id}_n - 2P_S^T)$   
 (because  $P_S^T = P_S$ )  $= (\text{Id}_n - 2P_S)(\text{Id}_n - 2P_S)$   
 $= \text{Id}_n - 4P_S + 4P_S^2$   
 $= \text{Id}_n$

because  $P_S^2 = P_S$ .

$M$  is therefore orthogonal.

b)  $M$  is symmetric ( $M^T = M$ ) so we get from a) that  $M^2 = \text{Id}_n$

Let  $\lambda \in \mathbb{R}$  be an eigenvalue of  $M$ , and  $v \in \mathbb{R}^n \setminus \{0\}$  an associated eigenvector.

We get  $M^2 v = v$

so  $M(\lambda v) = \lambda v$

$\lambda^2 v = v$  which gives  $\lambda^2 = 1$

since  $v \neq 0$ :  $\lambda = 1$  or  $\lambda = -1$ .

c) Let  $k = \dim S$ . Let  $(v_1, \dots, v_k)$  be a basis of  $S$  and  $(v_{k+1}, \dots, v_n)$  be a basis of  $S^\perp$  (recall that  $\dim S^\perp = n - k$ ).

Then  $(v_1, \dots, v_k, v_{k+1}, \dots, v_n)$  is a basis of  $\mathbb{R}^n$

• For  $i \in \{1, \dots, k\}$ , compute:

$Mv_i = v_i - 2P_S v_i = v_i - 2v_i = -v_i$

because  $P_S v_i = v_i$  since  $v_i \in S$ . We get that  $v_i$  is an eigenvector of  $M$  (with eigenvalue  $-1$ )

• For  $i \in \{k+1, \dots, n\}$ , compute

$Mv_i = v_i - 2P_S v_i = v_i$  (because  $P_S v_i = 0$ , since  $v_i \in S^\perp$ ). We get that  $v_i$  is an eigenvector of  $M$  (with eigenvalue  $1$ ).

$(v_1, \dots, v_n)$  is therefore a basis of  $\mathbb{R}^n$  consisting of eigenvectors of  $M$ .

Problem 5.3.

a) Compute:  $\cdot v_1^T A v_2 = v_1^T (\lambda_2 v_2) = \lambda_2 v_1^T v_2$   
 $\cdot v_1^T A v_2 = (A^T v_1)^T v_2$   
(because  $A = A^T$ )  $= (A v_1)^T v_2$   
 $= \lambda_1 v_1^T v_2.$

We get that  $\lambda_1 v_1^T v_2 = \lambda_2 v_1^T v_2$ . Since  $\lambda_1 \neq \lambda_2$ , we deduce that  $v_1^T v_2 = 0 : v_1 \perp v_2$

b) Assume that  $A$  is diagonalizable.

For  $\lambda \in \text{Sp}(A)$ , we write

$$\begin{cases} E_\lambda = \ker(A - \lambda \text{Id}_n) & \text{the corresponding eigenspace} \\ m_\lambda = \dim E_\lambda & \text{the multiplicity of } \lambda. \end{cases}$$

By the Gram-Schmidt procedure, we can find an orthonormal basis  $(e_1^{(\lambda)}, \dots, e_{m_\lambda}^{(\lambda)})$  of  $E_\lambda$

Let  $B$  be the family of vectors obtained by putting together all the vectors  $e_1^{(\lambda)}, \dots, e_{m_\lambda}^{(\lambda)}$ :

$$B = \{ e_1^{(\lambda)}, \dots, e_{m_\lambda}^{(\lambda)} \mid \lambda \in \text{Sp}(A) \}.$$

- The vectors of  $\mathcal{B}$  are all eigenvectors of  $A$  (because they all belong to  $E_\lambda$  for some  $\lambda \in \text{Sp}(A)$ )
- They all have unit norm (by construction).
- Let us now take two vectors  $u \neq u' \in \mathcal{B}$  and verify that  $u \perp u'$ . We have  $u \in E_\lambda$  and  $u' \in E_{\lambda'}$  for some  $\lambda, \lambda' \in \text{Sp}(A)$ .

- Case 1:  $\lambda \neq \lambda'$ . Then by (a):  $u \perp u'$ .

- Case 2:  $\lambda = \lambda'$ . Then by construction  $u \perp u'$ .

Conclusion:  $\mathcal{B}$  is orthonormal.

It remains to check that  $\mathcal{B}$  is a basis of  $\mathbb{R}^n$ .

Let  $x \in \mathbb{R}^n$ . Since  $A$  is diagonalizable  $x$  can be expressed as a linear combination of eigenvectors of  $A$ :

$$x = \sum_{\lambda \in \text{Sp}(A)} \alpha_\lambda v_\lambda$$

for some  $\alpha_\lambda \in \mathbb{R}$ ,  $v_\lambda \in E_\lambda$ .

Since  $E_\lambda \subset \text{Span}(\mathcal{B})$  we get that  $x \in \text{Span}(\mathcal{B})$ : hence  $\mathcal{B}$  spans  $\mathbb{R}^n$  (and is hence a basis because it is orthonormal).

# Problem 5.4

$$\begin{aligned}
 a) \quad x_t &= \frac{A x_{t-1}}{\|A x_{t-1}\|} = \frac{A \frac{A x_{t-2}}{\|A x_{t-2}\|}}{\|A \frac{A x_{t-2}}{\|A x_{t-2}\|}\|} \\
 &= \frac{A^2 x_{t-2}}{\|A^2 x_{t-2}\|} \\
 &= \frac{A^2 \frac{A x_{t-3}}{\|A x_{t-3}\|}}{\|A^2 \frac{A x_{t-3}}{\|A x_{t-3}\|}\|} = \frac{A^3 x_{t-3}}{\|A^3 x_{t-3}\|} \\
 &= \dots = \frac{A^t x_0}{\|A^t x_0\|}
 \end{aligned}$$

b) The set of vectors that have their first coordinate in the basis  $(v_1, \dots, v_n)$  equal to zero is  $\text{Span}(v_2, \dots, v_n)$ . This is an hyperplane of  $\mathbb{R}^n$ : a randomly chosen vector has zero probability to belong to it (for instance in  $\mathbb{R}^3$  a randomly chosen vector will be outside of the horizontal plane with probability 1).

$$c) \quad x_0 = \alpha_1 v_1 + \dots + \alpha_n v_n \quad \text{so}$$

$$\begin{aligned} A^t x_0 &= \alpha_1 A^t v_1 + \dots + \alpha_n A^t v_n \\ &= \alpha_1 \lambda_1^t v_1 + \dots + \alpha_n \lambda_n^t v_n. \end{aligned}$$

Consequently:

$$x_t = \frac{A^t x_0}{\|A^t x_0\|} = \frac{\alpha_1 v_1 + \left(\frac{\lambda_2}{\lambda_1}\right)^t \alpha_2 v_2 + \dots + \left(\frac{\lambda_n}{\lambda_1}\right)^t \alpha_n v_n}{\left\| \alpha_1 v_1 + \left(\frac{\lambda_2}{\lambda_1}\right)^t \alpha_2 v_2 + \dots + \left(\frac{\lambda_n}{\lambda_1}\right)^t \alpha_n v_n \right\|}$$

Since  $\left(\frac{\lambda_i}{\lambda_1}\right)^t \xrightarrow{t \rightarrow +\infty} 0$  for all  $i \in \{2, \dots, n\}$ , we get

$$x_t \xrightarrow{t \rightarrow +\infty} \frac{\alpha_1 v_1}{\|\alpha_1 v_1\|} = \frac{\alpha_1}{|\alpha_1|} v_1.$$

and

$$\begin{aligned} \|A x_t\| &\xrightarrow{t \rightarrow +\infty} \left\| A \frac{\alpha_1}{|\alpha_1|} v_1 \right\| = \|A v_1\| \\ &= \|\lambda_1 v_1\| = \lambda_1 \end{aligned}$$

### Problem: 5.5

The function  $f$  is continuous over the unit sphere  $S = \{x \in \mathbb{R}^n \mid \|x\| = 1\}$  and admits therefore a maximum on  $S$ , at some  $x_*$

Since for all  $\alpha \neq 0$  and  $x \in S$ ,  $f(\alpha x) = f(x)$ ,  $x_*$  is a global maximizer of  $f$  on  $\mathbb{R}^n \setminus \{0\}$ .

Hence  $\nabla f(x_*) = 0$ . By definition:

$$f(x) = \frac{\sum_{i,j=1}^n A_{i,j} x_i x_j}{\sum_{i=1}^n x_i^2} \quad \text{so}$$

$$\frac{\partial}{\partial x_k} f(x) = \frac{(2 A_{k,k} x_k + \sum_{i \neq k} (A_{i,k} + A_{k,i}) x_i) \|x\|^2 - 2 x_k x^T A x}{\|x\|^4}$$

For  $x \in S$ , this simplifies to (using that  $A_{i,k} = A_{k,i}$ )

$$\frac{\partial}{\partial x_k} f(x) = 2 \sum_{i=1}^n A_{k,i} x_i - 2 x_k x^T A x.$$

Hence,  $\frac{\partial}{\partial x_k} f(x_*) = 0$  gives that for all  $k$ :

$$\sum_{i=1}^n A_{k,i} (x_*)_i = (x_*^T A x_*) (x_*)_k$$

$$\text{ie : } (A x_*)_k = (x_*^T A x_*) (x_*)_k$$

We conclude that  $A x_* = \lambda x_*$ , where  $\lambda = x_*^T A x_*$