

An Encoding of the CSP Stopping operator to ACP_τ

Leon Lee

February 6, 2025

1.1 Prerequisites

Definition 1.1.1: Subsets of A

We define some subsets of A which we will use in our encodings

- $A_0 \subseteq A$ is the set of actions that actually get used in processes
- $H_0 = A - A_0$ is the set of working space operators, or any other action that doesn't get used
- $H_1 = A_0 \uplus \{\mathbf{first}, \mathbf{next}, \mathbf{left}, \mathbf{right}\}$ is the set of actions, plus some working operators

In general, $A_0 \subseteq H_1 \subseteq A$.

Note that the silent step is not defined in A , and we will define A_τ to be $A \cup \{\tau\}$

Definition 1.1.2: F_1

Define a function $f_1 : A \rightarrow A$ where

$$\begin{aligned} f_1(a_{\mathbf{first}}) &= a_{\mathbf{first}} \\ f_1(a_{\mathbf{next}}) &= a \end{aligned}$$

Definition 1.1.3: Communications

Define Communications where

$$\begin{aligned} a|\mathbf{first} &= a_{\mathbf{first}} \\ a|\mathbf{next} &= a_{\mathbf{next}} \\ a|\mathbf{left} &= a_{\mathbf{left}} \end{aligned}$$

We define triggering as the same as external choice

Definition 1.1.4: Triggering

The operator $\Gamma(P)$ turns a trace of a process P , $a.b.c.\dots$ into the trace

$$a_{\mathbf{first}}.b.c.\dots$$

and is defined as

$$\Gamma(P) = \rho_{f_1}[\partial_{H_1}(p||\mathbf{first}(\mathbf{next}^\infty))]$$

We also define an operator which will tag every action in a process with the identifier of “left”.

Definition 1.1.5: Left-Tagging

The operator $\Phi(P)$ turns a trace of a process P , $a.b.c$ into the trace

$$a_{\text{left}}.b_{\text{left}}.c_{\text{left}}$$

and is defined as

$$\Phi(P) = \partial_{H_1} (P || (\text{left})^\infty)$$

1.2 Translating the CSP Stopping Operator

The stopping operator \triangle is defined with the following rules:

$$\frac{P \xrightarrow{\alpha} P'}{P \triangle Q \xrightarrow{\alpha} P' \triangle Q} \quad \frac{Q \xrightarrow{\tau} Q'}{P \triangle Q \xrightarrow{\tau} P \triangle Q'} \quad \frac{Q \xrightarrow{a} Q'}{P \triangle Q \xrightarrow{a} Q'}$$

In other words, we can take an external choice from P without interrupting the operator, in addition to internal choices from Q . However, the moment an external choice is made from Q , the process will then never return to P .

For our encoding, we take $H_1 = \{\mathbf{first}, \mathbf{next}, \mathbf{left}, \mathbf{origin}, \mathbf{split}\}$ as defined in 1.1.1. We then modify Definition 1.1.3 to include additional communications for the operators **origin** and **split**

Definition 1.2.1: Communications Modified

In addition to the communications defined in 1.1.3:

$$a|\mathbf{first} = a_{\mathbf{first}} \quad a|\mathbf{next} = a_{\mathbf{next}} \quad a|\mathbf{left} = a_{\mathbf{left}}$$

We define communications for the operators **origin** as follows:

$$a_{\mathbf{left}}|\mathbf{origin} = a_{\mathbf{post}} \quad a_{\mathbf{first}}|\mathbf{split} = a_{\mathbf{post}}$$

Definition 1.2.2: Functions Modified

In addition to the function f_1 defined in 1.1.2,

$$f_1(a_{\mathbf{first}}) = a_{\mathbf{first}} \quad f_1(a_{\mathbf{next}}) = a$$

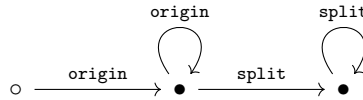
We define a compatibility function to prevent issues with transitivity. Let $f_2 : A \rightarrow A$ where

$$f_2(a_{\mathbf{post}}) = a$$

We can now define an encoding of the CSP Stopping operator \triangle in ACP_τ . We start off with a new process, which we will call σ . This is defined as the process

$$\sigma = (\mathbf{origin})^\infty.(\mathbf{split})^\infty$$

Or, visualised as a process graph:



From this, an encoding can be written in the following way:

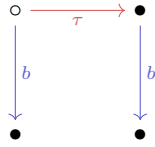
$$\mathcal{T}(P \triangle Q) = \partial_{H_0} \left(\rho_{f_2} \left[(\Phi(\mathcal{T}(P)) || \sigma) || \Gamma(\mathcal{T}(Q)) \right] \right)$$

Similarly to external choice, this is also Rooted Branching Bisimilar.

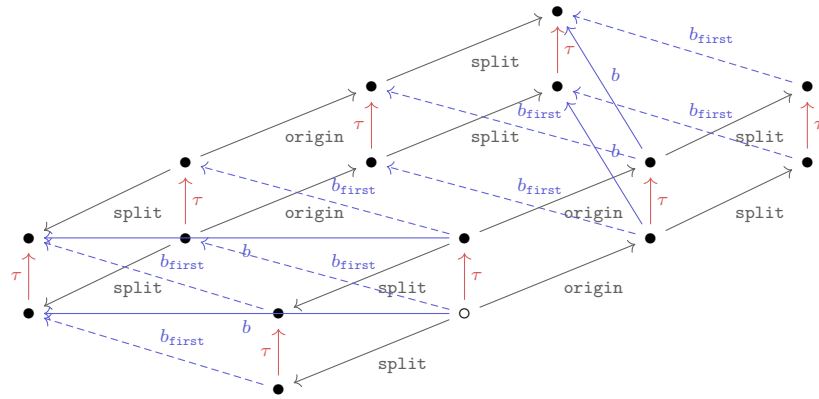
A counterexample to the encoding being Strongly Bisimilar is with the trivial example

$$P = \tau, Q = b$$

This should yield the following process graph:



However, it yields the following



Which reduces down to:

