

## GraphLib

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## Chapter 1

## Todo List

**Member `gl::Edge::weight () const`**

This function must be overwritten to adapt the behavior of the Dijkstra algorithm



## Chapter 2

# Class Index

### 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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<a href="#">gl::Graph</a>	<a href="#">Graph</a> is the base class representing a graph as parent of nodes and edges . . . . .	<a href="#">10</a>
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<a href="#">gl::Node</a>	<a href="#">Node</a> is the base class representing nodes (vertices) in a graph . . . . .	<a href="#">13</a>





## Chapter 3

# File Index

### 3.1 File List

Here is a list of all documented files with brief descriptions:

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## Chapter 4

# Class Documentation

### 4.1 gl::Edge Class Reference

[Edge](#) is the base class representing unidirectional edges (arrows, flows) in a graph.

```
#include <edge.h>
```

#### Public Member Functions

- [Edge](#) ([Graph](#) &graph, [Node](#) &src, [Node](#) &dst)  
*Constructor to create a new edge between source and destination node The constructor registers the edge with the parent graph and with the connected nodes.*
- [Edge](#) (const [Edge](#) &other)  
*Constructor to create a new edge as a copy of an existing edge The constructor registers the edge with the parent graph and with the connected edges.*
- virtual [~Edge](#) ()  
*Virtual destructor for edge The destructor deregisters the edge from the connected nodes and from the graph before destroying.*
- bool [isConnectedTo](#) (const [Node](#) &node) const  
*Constant member function checking if a node is connected to this edge.*
- [Node](#) & [source](#) ()  
*Member function returning a reference of the source node.*
- [Node](#) & [destination](#) ()  
*Member function returning a reference of the destination node.*
- virtual double [weight](#) () const  
*Virtual constant member function defining the weight (or distance, or cost) of the edge Currently set to 1.0, so the shortest path algorithm searches for the path with the least number of edges involved.*

#### Protected Member Functions

- virtual const std::string [name](#) () const  
*Virtual constant member function returning a description of the edge as string [Edge](#) as base class does not have a name by its own, but builds the string from the names of the connected nodes.*

## Friends

- `std::ostream & operator<< (std::ostream &os, const Edge &edge)`

*Streaming operator as friend function, streaming the return value of the [name\(\)](#) function to the output stream.*

### 4.1.1 Detailed Description

[Edge](#) is the base class representing unidirectional edges (arrows, flows) in a graph.

### 4.1.2 Constructor & Destructor Documentation

#### 4.1.2.1 [Edge\(\)](#) [1/2]

```
gl::Edge::Edge (
    Graph & graph,
    Node & src,
    Node & dst )
```

Constructor to create a new edge between source and destination node The constructor registers the edge with the parent graph and with the connected nodes.

##### Parameters

<i>graph</i>	parent graph
<i>src</i>	source node
<i>dst</i>	destination node

#### 4.1.2.2 [Edge\(\)](#) [2/2]

```
gl::Edge::Edge (
    const Edge & other )
```

Constructor to create a new edge as a copy of an existing edge The constructor registers the edge with the parent graph and with the connected edges.

##### Parameters

<i>other</i>	existing edge
--------------	---------------

### 4.1.3 Member Function Documentation

#### 4.1.3.1 destination()

```
Node& gl::Edge::destination ( ) [inline]
```

Member function returning a reference of the destination node.

##### Returns

**Node&** reference of the destination node

#### 4.1.3.2 isConnectedTo()

```
bool gl::Edge::isConnectedTo (
    const Node & node ) const
```

Constant member function checking if a node is connected to this edge.

##### Parameters

<i>node</i>	const reference of node
-------------	-------------------------

##### Returns

**bool** true if node is connected to this edge (either as source or destination node), and false otherwise

#### 4.1.3.3 name()

```
const std::string gl::Edge::name ( ) const [protected], [virtual]
```

Virtual constant member function returning a description of the edge as string [Edge](#) as base class does not have a name by its own, but builds the string from the names of the connected nodes.

##### Returns

**std::string** the description of the edge, in the format "source -> destination"

#### 4.1.3.4 source()

```
Node& gl::Edge::source ( ) [inline]
```

Member function returning a reference of the source node.

##### Returns

**Node&** reference of the source node

#### 4.1.3.5 weight()

```
virtual double gl::Edge::weight ( ) const [inline], [virtual]
```

Virtual constant member function defining the weight (or distance, or cost) of the edge. Currently set to 1.0, so the shortest path algorithm searches for the path with the least number of edges involved.

**Todo** This function must be overwritten to adapt the behavior of the Dijkstra algorithm

#### Returns

**double** the value representing the weight (or distance or cost) of the edge

### 4.1.4 Friends And Related Function Documentation

#### 4.1.4.1 operator<<

```
std::ostream& operator<< (
    std::ostream & os,
    const Edge & edge ) [friend]
```

Streaming operator as friend function, streaming the return value of the [name\(\)](#) function to the output stream.

#### Returns

**std::ostream&** reference to the output stream

The documentation for this class was generated from the following files:

- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/[edge.h](#)
- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/[edge.cpp](#)

## 4.2 gl::Graph Class Reference

[Graph](#) is the base class representing a graph as parent of nodes and edges.

```
#include <graph.h>
```

## Public Member Functions

- virtual `~Graph()`  
*Virtual destructor for graph The destructor destroys all remaining edges and nodes connected for this graph.*
- `std::list< Node * > & nodes()`  
*Member function returning a reference to the list of nodes connected to this graph.*
- `std::list< Edge * > & edges()`  
*Member function returning a reference to the list of edges connected to this graph.*
- `Node * findNode (const std::string &name) const`  
*Member function returning the pointer to the node with the given name, if such node exists.*
- `std::vector< Edge * > findEdges (const Node &src, const Node &dst) const`  
*Member function returning a vector of pointers to all edges connecting the source and destination node, and an empty vector if no such edges exist.*
- `std::deque< Edge * > dijkstra (const Node &src, const Node &dst) const`  
*Member function returning a vector of pointers to all edges connecting the source and destination node, and an empty vector if no such edges exist.*

## Protected Attributes

- `std::list< Node * > m_nodes`
- `std::list< Edge * > m_edges`

### 4.2.1 Detailed Description

`Graph` is the base class representing a graph as parent of nodes and edges.

### 4.2.2 Member Function Documentation

#### 4.2.2.1 dijkstra()

```
std::deque< Edge * > gl::Graph::dijkstra (
    const Node & src,
    const Node & dst ) const
```

Member function returning a vector of pointers to all edges connecting the source and destination node, and an empty vector if no such edges exist.

#### Returns

**std::vector<Edge\*>** vector of pointers to all edges connecting the given node, or empty vector

#### 4.2.2.2 edges()

```
std::list<Edge*>& gl::Graph::edges ( ) [inline]
```

Member function returning a reference to the list of edges connected to this graph.

Returns

**std::list<Edge\*>&** reference of the list of edges

#### 4.2.2.3 findEdges()

```
std::vector< Edge * > gl::Graph::findEdges (
    const Node & src,
    const Node & dst ) const
```

Member function returning a vector of pointers to all edges connecting the source and destination node, and an empty vector if no such edges exist.

Returns

**std::vector<Edge\*>** vector of pointers to all edges connecting the given node, or empty vector

#### 4.2.2.4 findNode()

```
Node * gl::Graph::findNode (
    const std::string & name ) const
```

Member function returning the pointer to the node with the given name, if such node exists.

Returns

**Node\*** pointer to the node with the specified name if such nodes exists, or nullptr otherwise

#### 4.2.2.5 nodes()

```
std::list<Node*>& gl::Graph::nodes ( ) [inline]
```

Member function returning a reference to the list of nodes connected to this graph.

Returns

**std::list<Node\*>&** reference of the list of nodes

The documentation for this class was generated from the following files:

- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/graph.h
- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/graph.cpp



## 4.3 gl::GraphLibException Class Reference

[GraphLibException](#) is a specific exception class for this library.

```
#include <graph.h>
```

### Public Member Functions

- [GraphLibException](#) (const char \*error)  
*Constructor to create a library exception carrying the error string.*
- const char \* [what](#) () const  
*Member function returning reason for error.*

#### 4.3.1 Detailed Description

[GraphLibException](#) is a specific exception class for this library.

#### 4.3.2 Constructor & Destructor Documentation

##### 4.3.2.1 GraphLibException()

```
gl::GraphLibException::GraphLibException (
    const char * error ) [inline]
```

Constructor to create a library exception carrying the error string.

##### Parameters

<i>error</i>	error string
--------------	--------------

The documentation for this class was generated from the following file:

- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/[graph.h](#)

## 4.4 gl::Node Class Reference

[Node](#) is the base class representing nodes (vertices) in a graph.

```
#include <node.h>
```

## Public Member Functions

- `Node (Graph &graph, std::string name)`  
*Constructor to create a new named node The constructor registers the node with the parent graph.*
- `Node (Graph &graph)`  
*Constructor to create a new node and assign a auto-generated name to it The constructor registers the node with the parent graph The auto-generated name follows the "Node\_0001", "Node\_0002", etc. convention.*
- `virtual ~Node ()`  
*Virtual destructor for node The destructor destroys the connected edges and deregisters the node from the parent graph before destroying.*
- `virtual std::string name () const`  
*Virtual constant member function returning the name (description) of the node as string.*
- `std::list< Edge * > & outEdges ()`  
*Member function returning a reference to the list of outgoing edges.*
- `std::list< Edge * > & inEdges ()`  
*Member function returning a reference to the list of incoming edges.*
- `const Graph & graph () const`  
*Constant member function returning a const reference to the parent graph of the node.*

## Static Protected Attributes

- `static int s_instance_number = 0`

## Friends

- `bool operator== (const Node &lhs, const Node &rhs)`  
*Comparison operator as friend function, returning true if two nodes are identical (not just having the same member variable content)*
- `std::ostream & operator<< (std::ostream &os, const Node &node)`  
*Streaming operator as friend function, streaming the return value of the `name()` function to the output stream.*

### 4.4.1 Detailed Description

`Node` is the base class representing nodes (vertices) in a graph.

### 4.4.2 Constructor & Destructor Documentation

#### 4.4.2.1 Node() [1/2]

```
gl::Node::Node (
    Graph & graph,
    std::string name )
```

Constructor to create a new named node The constructor registers the node with the parent graph.

## Parameters

<i>graph</i>	parent graph
<i>name</i>	name of the node

## 4.4.2.2 Node() [2/2]

```
gl::Node::Node (
    Graph & graph )
```

Constructor to create a new node and assign a auto-generated name to it The constructor registers the node with the parent graph The auto-generated name follows the "Node\_0001", "Node\_0002", etc. convention.

## Parameters

<i>graph</i>	parent graph
--------------	--------------

## 4.4.3 Member Function Documentation

## 4.4.3.1 graph()

```
const Graph& gl::Node::graph ( ) const [inline]
```

Constant member function returning a const reference to the parent graph of the node.

## Returns

**Graph&** const reference to the parent graph of the node

## 4.4.3.2 inEdges()

```
std::list<Edge*>& gl::Node::inEdges ( ) [inline]
```

Member function returning a reference to the list of incoming edges.

## Returns

**std::list<Edge\*>&** reference of the list of incoming edges

#### 4.4.3.3 name()

```
virtual std::string gl::Node::name ( ) const [inline], [virtual]
```

Virtual constant member function returning the name (description) of the node as string.

##### Returns

**std::string** the name of the node

#### 4.4.3.4 outEdges()

```
std::list<Edge*>& gl::Node::outEdges ( ) [inline]
```

Member function returning a reference to the list of outgoing edges.

##### Returns

**std::list<Edge\*>&** reference of the list of outgoing edges

### 4.4.4 Friends And Related Function Documentation

#### 4.4.4.1 operator<<

```
std::ostream& operator<< (
    std::ostream & os,
    const Node & node ) [friend]
```

Streaming operator as friend function, streaming the return value of the [name\(\)](#) function to the output stream.

##### Returns

**std::ostream&** reference to the output stream

#### 4.4.4.2 operator==

```
bool operator== (
    const Node & lhs,
    const Node & rhs ) [friend]
```

Comparison operator as friend function, returning true if two nodes are identical (not just having the same member variable content)

##### Returns

**bool** true if the two nodes are identical, false otherwise

The documentation for this class was generated from the following files:

- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/[node.h](#)
- C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/node.cpp

## Chapter 5

# File Documentation

### 5.1 C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/edge.h File Reference

```
#include "node.h"
```

#### Classes

- class [gl::Edge](#)  
*[Edge](#) is the base class representing unidirectional edges (arrows, flows) in a graph.*

#### 5.1.1 Detailed Description

##### Version

1.0

##### Author

Carsten Thomas

##### Date

December 2020

## 5.2 C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/graph.h File Reference

```
#include <list>
#include <vector>
#include <deque>
#include <string>
#include <exception>
#include <iostream>
#include "node.h"
#include "edge.h"
```

### Classes

- class [gl::Graph](#)  
*Graph is the base class representing a graph as parent of nodes and edges.*
- class [gl::GraphLibException](#)  
*GraphLibException is a specific exception class for this library.*

### 5.2.1 Detailed Description

#### Version

1.0

#### Author

Carsten Thomas

#### Date

December 2020

## 5.3 C:/Users/admin/source/repos/lectures/C23/GraphLibDev/GraphLib/node.h File Reference

```
#include <string>
#include <list>
#include <iostream>
```

### Classes

- class [gl::Node](#)  
*Node is the base class representing nodes (vertices) in a graph.*

### 5.3.1 Detailed Description

Version

1.0

Author

Carsten Thomas

Date

December 2020





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