Reverse Color Transfer between Images

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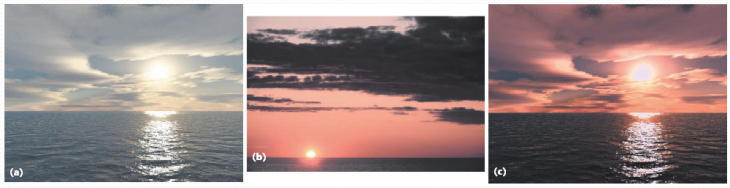
The original paper

- E. Reinhard, M. Ashikhmin, B. Gooch, and P. Shirley, "Color transfer between images," *IEEE Computer Graphics and Applications*, vol. 21, no. 5, pp. 34-41, September/October 2001.
- Four authors:
  - First author: E. Reinhard
- Co-authors: three co-authors
  - M. Ashikhmin, B. Gooch, P. Shirley
- Corresponding author:
  - If not mention, usually the first author is also the corresponding author
- See the paper PDF

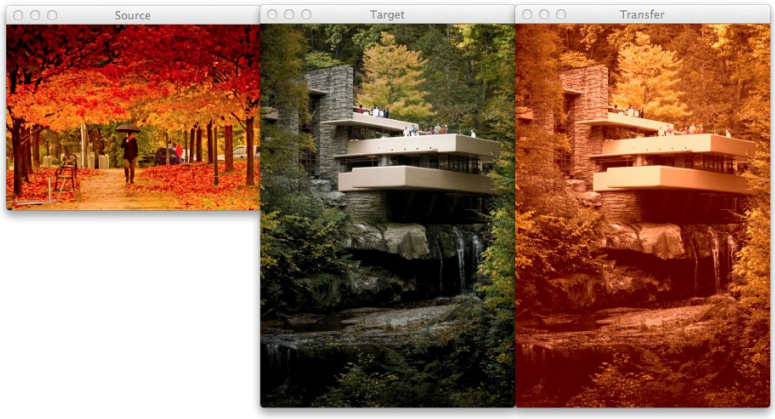
Color Transfer

- One of tasks for image processing: altering an image's color
- Goal of this paper
  - Describing a method that borrows one image's color characteristics from another
  - Source image: the original (standard image)
  - Target image: the colors of an image intends to be altered



source target Result

Example



Target Image Source Image Result Image

http://www.pyimagesearch.com/2014/06/30/super-fast-color-transfer-images/

Basic RGB Color Transfer Algorithm: 3 Steps

- A **three** steps approaches with two images, the source and the target image
- Input: Source image (MxN), Target image (UxV)
- Output: result image (MxN)
- Step 1:
  - Determining mean (m), standard deviation (d) values of the source image
  - Determining mean, standard deviation of the target image
- Step 2: Statistical pixel processing using eq. 1
  - Note: we repeat step 2 until all of the pixels (MxN) in the source image are processed
- Step 3: Pixel Validation: make sure that pixel values are within the valid range

Step 1

- Determining mean, variance values of the source image
- How to derive mean and standard deviation?

Mean and Standard Deviation

- Mean and Standard Deviation

$$\sigma = \sqrt{\frac{1}{N}\sum_{i=1}^{N}(x_i - \mu)^2}, \quad \text{where} \quad \mu = \frac{1}{N}\sum_{i=1}^{N} x_i.$$

- Example: considering the following 8 values

$$2,\ 4,\ 4,\ 4,\ 5,\ 5,\ 7,\ 9.$$

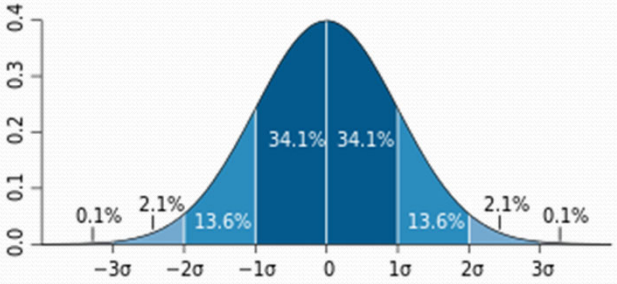
- Mean is 5 since $\frac{2+4+4+4+5+5+7+9}{8} = 5.$

$$\begin{array}{ll} (2-5)^2 = (-3)^2 = 9 & (5-5)^2 = 0^2 = 0 \\ (4-5)^2 = (-1)^2 = 1 & (5-5)^2 = 0^2 = 0 \\ (4-5)^2 = (-1)^2 = 1 & (7-5)^2 = 2^2 = 4 \\ (4-5)^2 = (-1)^2 = 1 & (9-5)^2 = 4^2 = 16. \end{array}$$

- Standard deviation is 2 since $\sqrt{\frac{9+1+1+1+0+0+4+16}{8}} = 2.$

Standard Deviation (SD) (σ)

- a measure used to **quantify** the amount of variation (變化程度)or dispersion (偏差) of a set of data values
- σ is near 0 indicating that the data points tend to be very close to the mean



A plot of a normal distribution (or bell-shaped curve) where each band has a width of 1 standard deviation
Rule: 68.2-95.4-99.7

http://en.wikipedia.org/wiki/Standard_deviation

- After Step 1 we produce 12 values
- Source image: three channels r, g, b
  - RGB mean values: mr_s, mg_s, mb_s
  - RGB standard deviation values: dr_s, dg_s, db_s
- Target image: three channels r, g, b
  - RGB mean values mr_t, mg_t, mb_t
  - RGB standard deviation values: dr_t, dg_t, db_t

Step 2: Statistical pixel processing

$$R(x,y) = \frac{d_t}{d_s}[S(x,y) - m_s] + m_t \qquad \text{Eq. 1}$$

R(x, y): pixel (x, y) in the result image

S(x, y): pixel (x, y) in the source image

d_t: standard deviation in the target image

d_s: standard deviation in the source image

m_s: mean in the source image

m_t: mean in the target image

Step 3: Pixel Validation

- We need to derive an integer representation after pixel processing.
- Use Floor function to derive an integer that is close to the floating value
- Make sure the pixel value is within [0, 255]

$$R(x,y) = \left\lfloor \frac{d_t}{d_s}[S(x,y) - m_s] + m_t + 0.5 \right\rfloor$$

Source Image

Target Image

Result Image

Target Image

Source Image

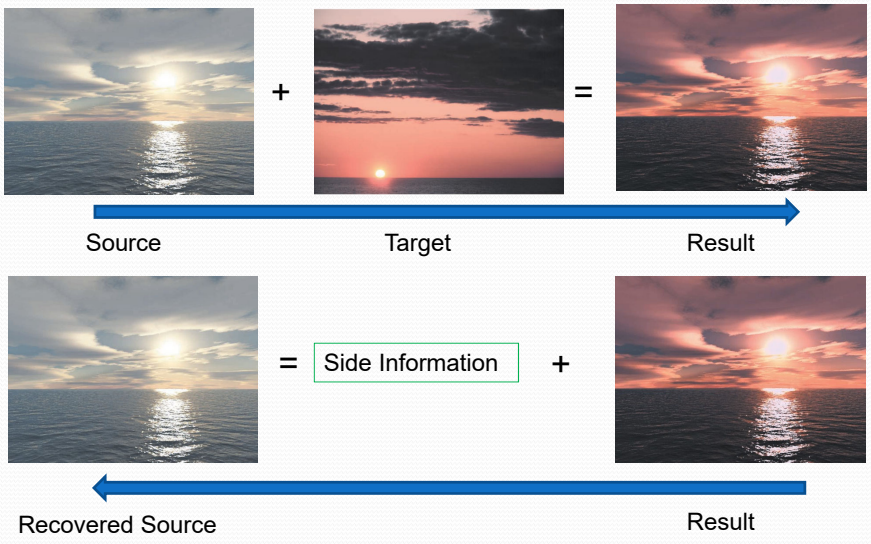
Result Image

Reversible Color Transfer

- Color transfer is a forward process:
- source + target → result image

- Can we reverse color transfer process?
- Reverse process:
- result + side information → recovered source
- Source and Recovered Source may have a subtle difference
- How to measure the difference between two images?

Forward and Reverse Process



Immediately Reverse pixel processing

Forward $\mathrm{R}(x,y) = \left\lfloor \frac{d_t}{d_s}[S(x,y) - m_s] + m_t \right\rfloor$ Eq. 1

Reverse $S(x,y) = \left\lceil \frac{d_s}{d_t}[\mathrm{R}(x,y) - m_t] + m_s \right\rceil$ Eq. 2

R(x, y): pixel (x, y) in the result image

S(x, y): pixel (x, y) in the ***source*** image

Side information

d_t: standard deviation in the target image

d_s: standard deviation in the source image

m_s: mean in the source image

m_t: mean in the target image

How to record side information

d_t: standard deviation in the target image

d_s: standard deviation in the source image

m_s: mean in the source image

m_t: mean in the target image

- Side information contains 12 floating-point values
- How to represent a floating-point value in a computer?
- Using IEEE-754 single precision representation?
- (1+8+23)=32 bits for a single floating-point value
- A total of 32*12 bits are required for 12 floating-point values
- Using IEEE-754 double precision representation?
- (1+11+52)=64 bits for a double floating-point value
- A total of 64*12 bits are required for 12 floating-point values
-

IEEE 754 Conversion

- Github source code
- https://gist.github.com/AlexEshoo/d3edc53129ed010b0a5b693b88c7e0b5
- ieee_754.py
- https://gist.github.com/robclewley/8a4f66bc0b9d8665856d
- https://www.technical-recipes.com/2012/converting-between-binary-and-decimal-representations-of-ieee-754-floating-point-numbers-in-c/

- Python source code
- Remember that in Python floats are represented by IEEE 754 floating-point format which are 64 bits long – not 32 bit

https://www.796t.com/content/1549004412.html

```
import struct

getBin = lambda x: x > 0 and str(bin(x))[2:] or "-" + str(bin(x))[3:]

def floatToBinary64(value):
    val = struct.unpack('Q', struct.pack('d', value))[0]
    return getBin(val)

def binaryToFloat(value):
    hx = hex(int(value, 2))
    return struct.unpack("d", struct.pack("q", int(hx, 16)))[0]

# floats are represented by IEEE 754 floating-point format which are
# 64 bits long (not 32 bits)

# float to binary
binstr = floatToBinary64(19.5)
print('Binary equivalent of 19.5:')
print(binstr + '\n')

# binary to float
fl = binaryToFloat(binstr)
print('Decimal equivalent of ' + binstr)
print(fl)
```

Example: A Pixel Color Transfer

- Source: kodim17.bmp
  - Mean: (R, G, B)=(88.68, 77.05, 69.01)
  - Std: (R, G, B)=(46.94, 50.11, 47.93)
- Target: kodim23.bmp
  - Mean: (R, G, B)=(121.66, 109.59, 75.79)
  - Std: (R, G, B)=(57.45, 50.80, 53.61)
- One pixel in kodim17.bmp
- S(x, y)= (R, G, B)= (98, 89, 156)
- Color transfer in three channels:
  - $R(x, y)_r$=(57.45/46.94)*[98-88.68]+121.66
  - $R(x, y)_g$=(50.80/50.51)*[89-77.05]+109.59
  - $R(x, y)_b$=(53.61/47.93)*[156-69.01]+75.79

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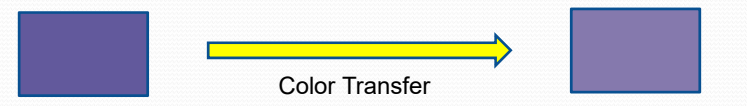
- $Round(R(x, y)_r)$=(57.45/46.94)*[98-88.68]+121.66=133
- $Round(R(x, y)_g)$=(50.80/50.51)*[89-77.05]+109.59=122
- $Round(R(x, y)_b)$=(53.61/47.93)*[156-69.01]+75.79=173
- S(x, y)= (R, G, B)= (98, 89, 156)
- R(x, y)=(R, G, B)=(133, 122, 173)



(98, 89, 156) (133, 122, 173)

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Example: A Reversible Color Transfer

- R(x, y)=(R, G, B)=(133, 122, 173)→ S(x, y)= (R, G, B)= (98, 90, 156)

d_s: Std: (R, G, B)=(46.94, 50.11, 47.93)

d_t: Std: (R, G, B)=(57.45, 50.80, 53.61)

m_s: Mean: (R, G, B)=(88.68, 77.05, 69.01)

m_t: Mean: (R, G, B)=(121.66, 109.59, 75.79)

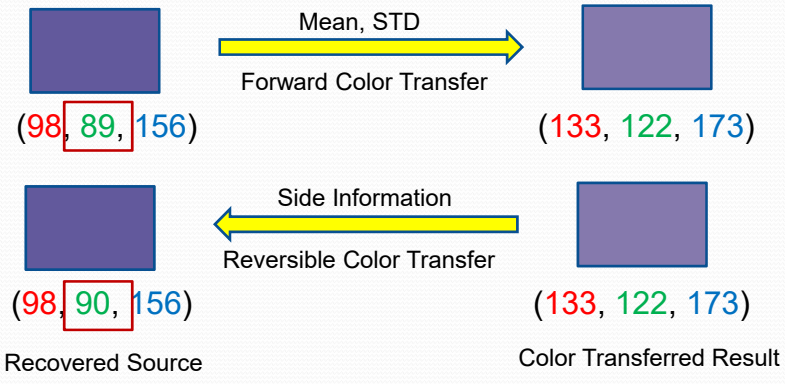
Reverse $S(x,y) = \left\lceil \frac{d_s}{d_t}[\mathrm{R}(x,y) - m_t] + m_s \right\rceil$ Eq. 2

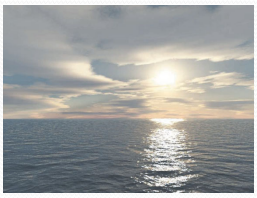
$S(x,y) = \left\lceil \frac{46.94}{57.45}[133 - 121.66] + 88.68 \right\rceil = [97.94] = 98$

$S(x,y) = \left\lceil \frac{50.11}{50.80}[122 - 109.59] + 77.05 \right\rceil = [89.29] = 90$

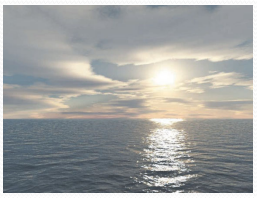
$S(x,y) = \left\lceil \frac{47.93}{53.61}[173 - 75.79] + 69.01 \right\rceil = [155.92] = 156$

Forward CT and Reversible CT Comparison





Source



Recovered Source

Source and Recovered Source may not be exactly identical

How similarities are they?

Quantify image quality using a metric

Peak Signal Noise Ratio: PSNR

https://en.wikipedia.org/wiki/Peak_signal-to-noise_ratio

- **Structure Similarity Index (SSIM)**
- **https://zh.wikipedia.org/wiki/%E7%B5%90%E6%A7%8B%E7%9B%B8%E4%BC%BC%E6%80%A7**
- **計算兩影像的PSNR、SSIM和Python程式碼**