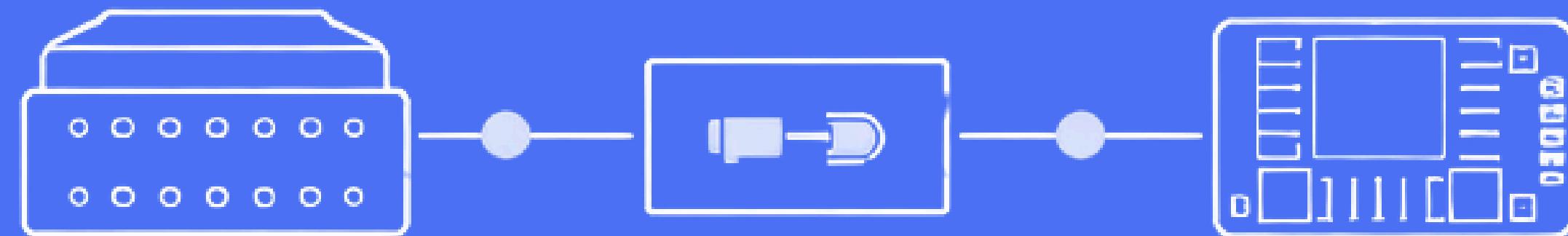


OBD Car Monitor

PROJECT GROUP N. 35

Leonardo Begnoni
Leonardo Magaraggia
Tommaso Lo Magno



OBD

CAN Bus

ESP32



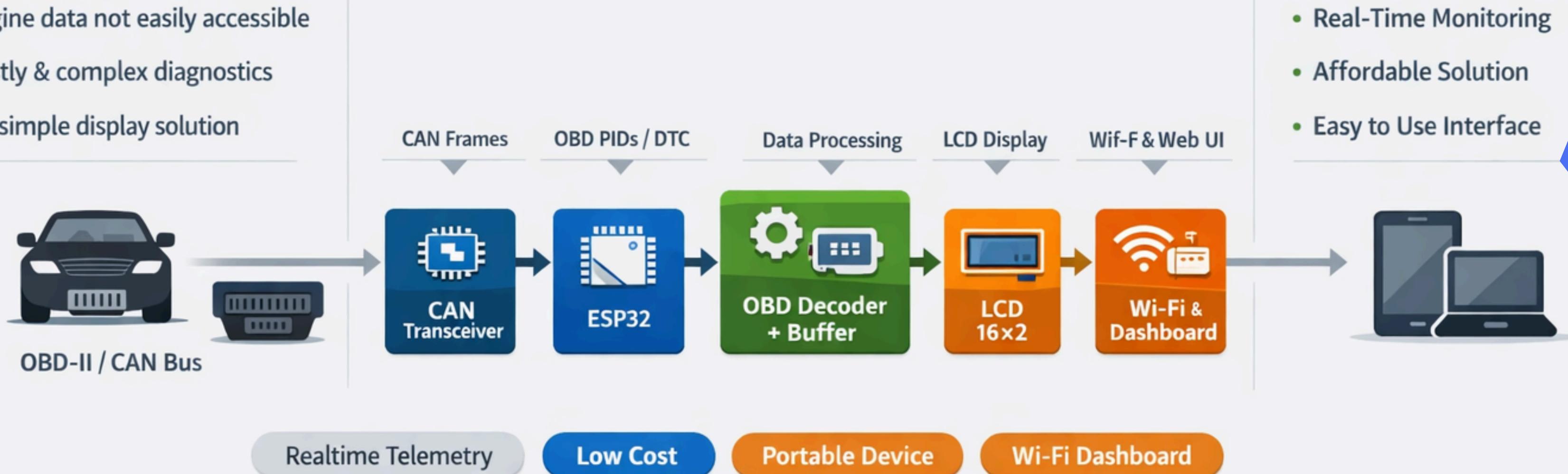
UNIVERSITÀ
DI TRENTO

! Problem

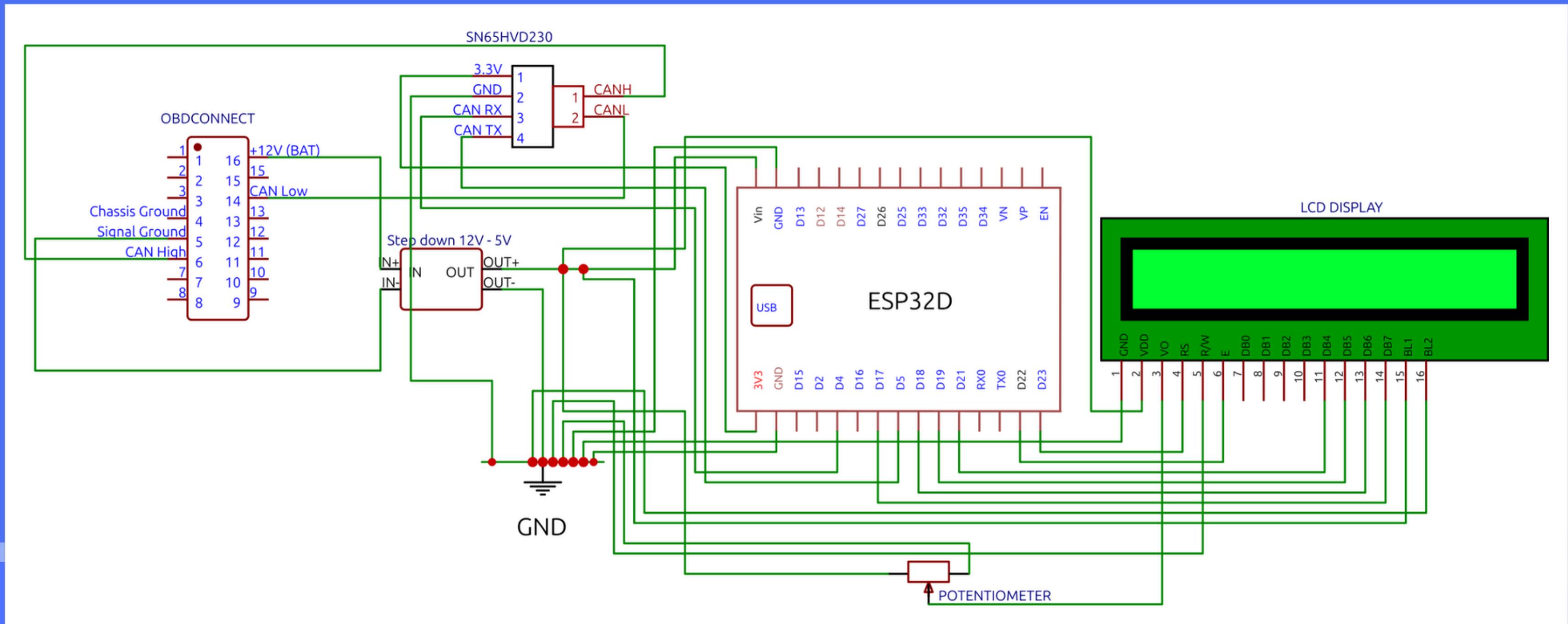
- Engine data not easily accessible
- Costly & complex diagnostics
- No simple display solution

System

✓ Value



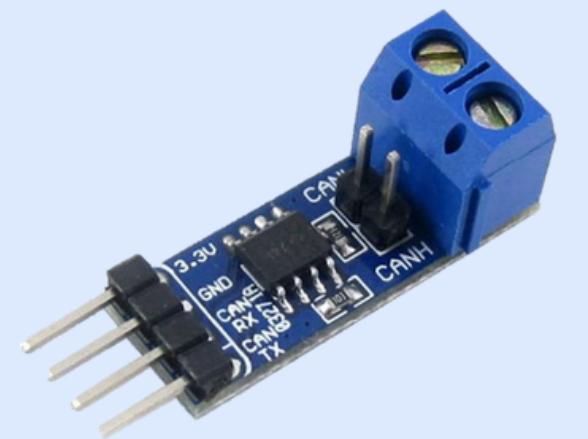
SCHEMATICS



Components



ESP32D



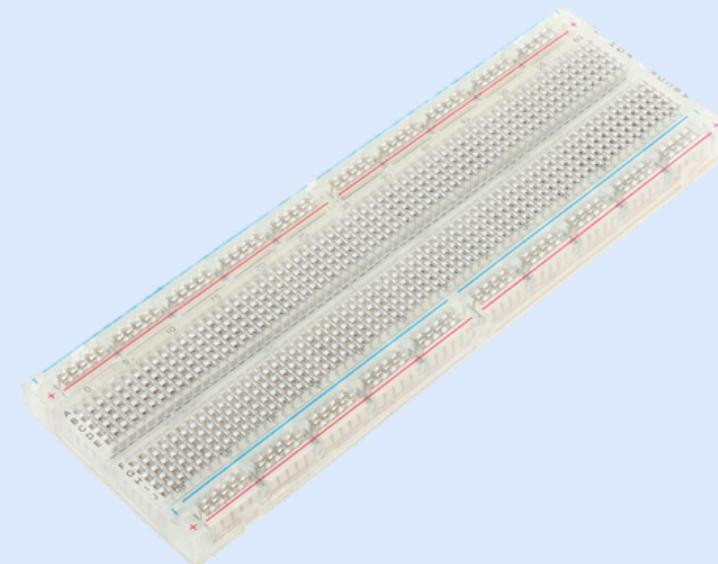
TRANSCEIVER CAN



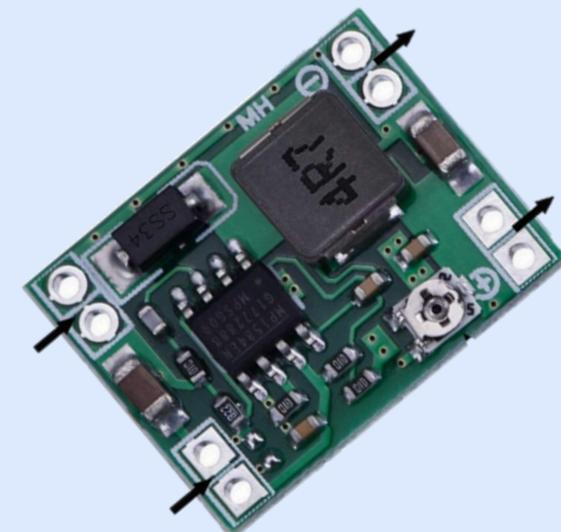
LCD 16X2



OBD CABLE
and WIRING



BREADBOARD



STEPDOWN
12V-5V

```
void obd_init(void);

bool obd_read_pid(uint8_t pid, uint8_t out[4]);

void obd_data_init(void);
|
void obd_data_start_polling(void);

obd_full_data_t obd_get_all_data(void);
```

obd.c

MODULES

```
void can_bus_init(void)
{...}
esp_err_t can_bus_send(twai_message_t *msg)
{...}
esp_err_t can_bus_receive(twai_message_t *msg, TickType_t timeout)
{...}
```

can-bus.c

```
obd_full_data_t d;
static esp_err_t data_handler(httpd_req_t *req)
{...
}

static blob_t get_blob_for_uri(const char *uri, const char **mime_out)
{...
}
static esp_err_t static_handler(httpd_req_t *req)
{...
}

void web_server_start(void)
{...
```

web_server.c

```
void lcd_init(void);

void lcd_clear(void);

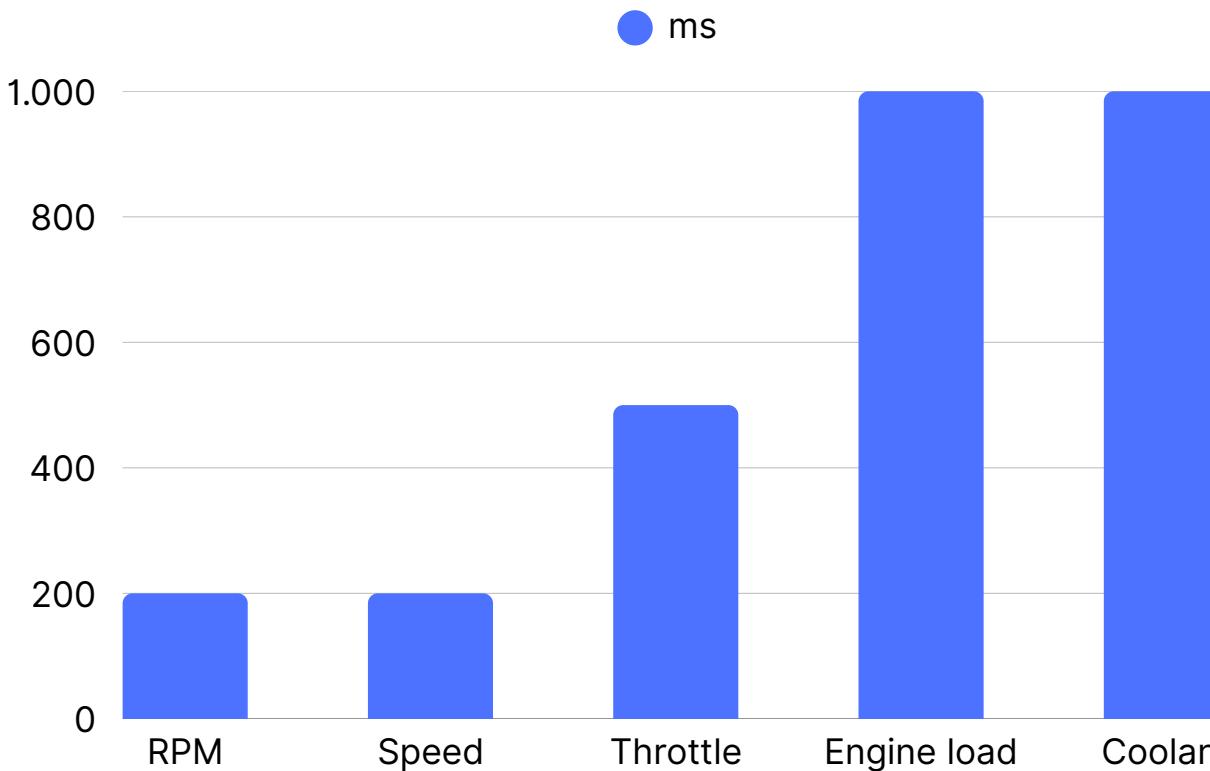
void lcd_gotoxy(uint8_t col, uint8_t row);

void lcd_print(const char *str);
```

lcd.c

Real-Time scheduling

- **Scheduling & periodicity:** polling multiple PIDs with different rates (fast/medium/slow).
- **Policies:** choose the next job using a policy that combines priority and lateness (deadline miss / delay)
- **Data structures:** maintain a job list/array with timing metadata and failure state for each PID.



```
static int pick_next_job(uint32_t tnow)
{
    int best = -1;
    int best_prio = 999;
    int32_t best_lateness = -2147483647;

    for (int i = 0; i < (int)(sizeof(s_jobs) / sizeof(s_jobs[0])); i++)
    {
        pid_job_t *j = &s_jobs[i];

        if (tnow < j->backoff_until)
            continue;
        if (tnow < j->next_due_ms)
            continue;

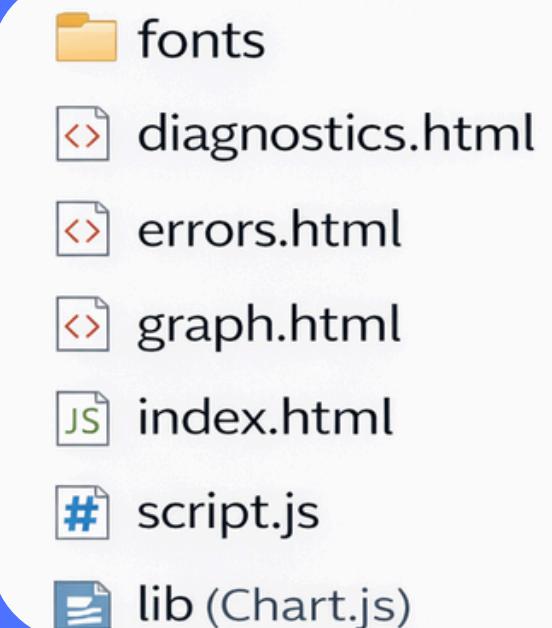
        int prio = (int)j->prio;
        int32_t lateness = (int32_t)(tnow - j->next_due_ms);

        if (prio < best_prio || (prio == best_prio && lateness > best_lateness))
        {
            best = i;
            best_prio = prio;
            best_lateness = lateness;
        }
    }
    return best;
}
```

IoT interface

- **Endpoint HTTP:** expose vehicle sensor as a resource (/data), implemented with esp_http_server (ESP-IDF)
- **JSON schema:** small, stable keys for dashboard use
- **Refresh rate:** client-side polling interval (UI refresh every 100ms)
- **static file hosting:** HTML/CSS/JS embedded in firmware (no external server)

static UI hosting



Testing and issues

Testing approach

- Can > OBD > Scheduler > Web
 - **Debug** using *idf.py monitor + log*
 - *Real testing on vehicles (OBD-II)*
 - Test JSON on browser (*endpoint /data*)
-

Issues Encountered

- JSON value always 0 → unsupported PID/ incorrect timing → filtered supported PIDs + implemented timeout handling
- Firmware too large → application partition too small → extended factory partition to 3MB
- LCD not communicating correctly → fixed init sequence, correct row offset, added microsecond delays

Future improvements

UI update

- **adding DTC reading:** DTC page with status, timestamp, “clear DTC” button.
 - **live notification** and **alerts** (es. over-temp, low-battery)
 - **Trip summary:** start/stop session, estimated distance, avg values.
 - **customizable dashboard:** select widgets
-

Hardware update

- **strong power path:** TVS on 12V, EMI filter...
- **Ignition-aware power management:** reduce drain battery
- **printed case** and **LED status** indicator for alerts

Team contributions:

- **Leonardo Begnoni:** IoT Interface and algorithms
- **Leonardo Magaraggia:** Software architecture and real time scheduling
- **Tommaso Lo Magno:** Hardware and system working scheme