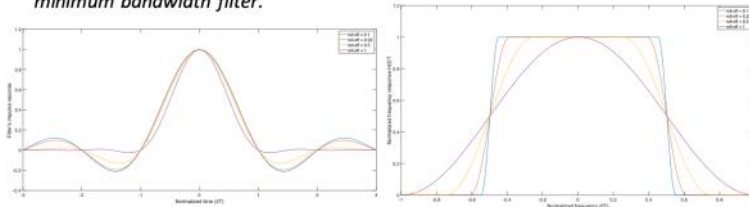


Raised cosine filters

Raised cosine filters satisfy the Nyquist criterion: the occupied bandwidth is

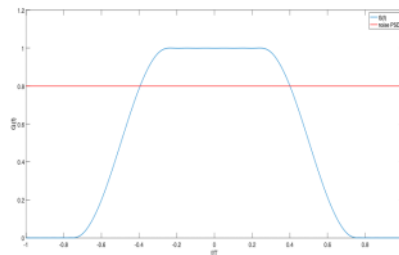
$$B_{RC} = \frac{1 + \alpha}{T}$$

The roll-off factor α is a design parameter, RC with $\alpha = 0$ is a rect and it is the *minimum bandwidth filter*.



Receive filter design: matched filter

- Neglecting, for the moment, the effect of the channel, the other major impairment at the receiver is the presence of Gaussian noise.
- The receiver should be designed to minimize the negative effect of Gaussian noise.
- The choice of $g_R(t) = g_T^*(-t)$, or, being the filter real, $G_R(f) = G_T^*(f)$ in the frequency domain, *maximizes* the signal-to-noise ratio at the receiver.
- The receive filter is said to be *matched* to the transmit filter.



Root raised cosine filters

- Root raised cosine filters are filters whose frequency response is the square root of a raised cosine, i.e., $H_{RRC}(f, \alpha) = \sqrt{H_{RC}(f, \alpha)}$.
- If $G_R(f) = G_T(f) = H_{RRC}(f, \alpha)$, the transmit and receive filter pair satisfies the two independent *optimality* conditions:

- The cascade of $g_T(t)$ and $g_R(t)$ obeys the *Nyquist criterion*:

$$G_R(f)G_T(f) = (H_{RRC}(f, \alpha))^2 = H_{RC}(f, \alpha).$$

- The receive filter is matched to the transmit filter.

Since it is $G_T(f) \in \Re \rightarrow G_R(f) = G_T^*(f) = G_T^*(f)$, the transmit and receive filter are *matched*.

$H_{RC}(f)$ always satisfies the Nyquist criterion

Bandwidth of a PAM signal

- If $G_T(f) = H_{RRC}(f)$ and the symbols are zero-mean, it is

$$S_s(f) = \frac{1}{T} S_a(f) |G_T(f)|^2 = \frac{A}{T} H_{RC}(f, \alpha).$$

- The bandwidth occupied by the PAM complex envelope is

$$B_{PAM}^{(BB)} = \frac{1+\alpha}{2T} = \frac{1+\alpha}{2} \frac{1}{\log_2 M T_b} = \frac{1+\alpha}{2} \frac{R_b}{\log_2 M}$$

- The bandwidth occupied by the corresponding passband signal is

$$B_{PAM}^{(PB)} = 2 B_{PAM}^{(BB)} = \frac{1+\alpha}{T} = (1+\alpha) \frac{R_b}{\log_2 M} \leftarrow$$

↑ !

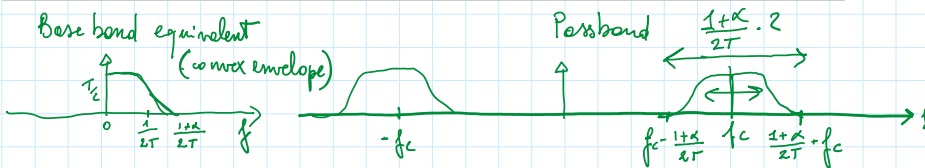
$$S_a(f) \Rightarrow R_e(m) = A \delta(m) \Rightarrow S_e(f) = A$$

$A = E\{a_i^2\}$ mean square value of the symbols

Let $\alpha = 1$, $M = 32$ e $R_b = 50$ Mb/s, bande?

$$B^{(BB)} = \frac{1+1}{2} \cdot \frac{50 \cdot 10^6}{\log_2 32} = 10 \text{ MHz}$$

$$B^{(PB)} = 2 B^{(BB)} = 20 \text{ MHz}$$



Power of a PAM signal

- The mean power of the complex envelope of a PAM signal with zero-mean symbols and root raised cosine filtering is

$$P_s = \int_{-\infty}^{+\infty} S_s(f) df = \frac{A}{T} \int_{-\infty}^{+\infty} |G_T(f)|^2 df = \frac{A}{T} \int_{-\infty}^{+\infty} H_{RC}(f, \alpha) df$$

since it is $\int_{-\infty}^{+\infty} H_{RC}(f, \alpha) df = h_{RC}(t)|_{t=0} = 1$,

$$P_s = \frac{A}{T}$$

- The power of the corresponding passband signal is

$$P_s = \frac{1}{2} P_s = \frac{A}{2T}$$

↑

$$\int_{-\infty}^{+\infty} H_{RC}(f, \alpha) df = \int_{-\infty}^{+\infty} H_{RC}(f) e^{j2\pi f t} df \Big|_{t=0} = h_{RC}(0) = 1$$

Energy of a PAM symbol

- The mean square value of the symbols for a PAM constellation is

$$A = E\{a_i^2\} = \frac{M^2 - 1}{3}$$

- The energy per symbol is computed as the power multiplied by the symbol duration

$$E_s = P_s T = \frac{A}{2T} T = \frac{M^2 - 1}{6}$$

2-PAM; $M=2$

$$A = E\{a_i^2\} = \frac{1}{2} (1^2) + \frac{1}{2} (-1)^2 = 1 \Rightarrow \frac{2^2 - 1}{3} = \frac{4 - 1}{3} = 1$$

4-PAM

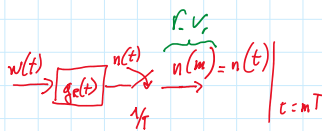
$$A = E\{a_i^2\} = \frac{1}{4} (-3)^2 + \frac{1}{4} (-1)^2 + \frac{1}{4} (1)^2 + \frac{1}{4} (3)^2 = 5 \Rightarrow \frac{4^2 - 1}{3} = 5$$

M-PAM

$$A = \frac{M^2 - 1}{3}$$

Additive white Gaussian noise

- The noise $w(t)$ is the zero-mean white Gaussian process with PSD $S_w(f) = \frac{N_0}{2}$.
- The complex envelope of the noise is $\tilde{w}(t) = w_I(t) + jw_Q(t)$ with PSD $S_{\tilde{w}}(f) = 2N_0$.
- The noise $n(t) = n_I(t) + jn_Q(t) = g_R(t) \otimes \tilde{w}(t)$ is a zero-mean Gaussian complex stochastic process and its PSD is $S_n(f) = S_w(f)|G_R(f)|^2 = 2N_0|G_R(f)|^2$.



Additive white Gaussian noise

- The sample $n(m) = n(t)|_{t=mT} = n_I(m) + jn_Q(m)$ is a zero-mean Gaussian complex random variable and its variance is $\sigma_n^2 = E\{|n(m)|^2\} = \int_{-\infty}^{+\infty} S_n(f) df = 2N_0 \int_{-\infty}^{+\infty} |G_R(f)|^2 df$
- If the receive filter is a RRC, then it is $\int_{-\infty}^{+\infty} |G_R(f)|^2 df = 1$ and $\sigma_n^2 = 2N_0$
- The in-phase and quadrature components $n_I(m), n_Q(m)$ are independent and the variance of each component is $\sigma^2 = \sigma_{n_I}^2 = \sigma_{n_Q}^2 = N_0$.

Decision strategy

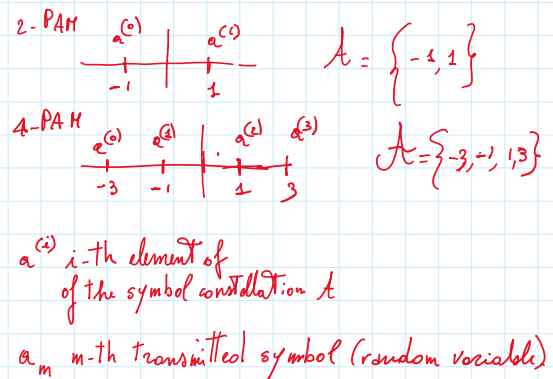


- Under the hypothesis of RRC filtering at the transmit and at the receiver, the decision variable is $x(m) = a_m + n(m)$
- The optimal decision strategy is the one that chooses the symbol maximize the probability conditioned on having received $x(m)$. $\hat{a}_m = \arg \max_{a^{(i)} \in \mathcal{A}} p(a^{(i)}|x(m))$
- It can be shown that in case of equiprobable symbols it is $p(x(m)|a^{(i)}) \approx p(a^{(i)}|x(m))$ so that the symbol $a^{(i)}$ that maximizes $p(x(m)|a^{(i)})$ maximizes also $p(a^{(i)}|x(m))$, maximum likelihood decision.

$$x(m) = a_m + n(m) \Rightarrow x(m) \text{ is a complex sample}$$

$$x(m) = x_I(m) + jx_Q(m) = a_m + n_I(m) + jn_Q(m)$$

$$\Rightarrow x_I(m) = a_m + n_I(m) \Rightarrow x(m) = x_I(m); \quad n(m) = n_I(m)$$



PAM decision strategy



- Since PAM signal is *real*, we consider only the in-phase component of the received signal, i.e. $x(m) = x_I(m)$ and $n(m) = n_I(m)$.
- Because of the conditioning, the symbol value $a^{(i)}$ is fixed and $x(m) \in \mathcal{N}(a^{(i)}, N_0)$ is a Gaussian random variable with mean $a^{(i)}$ and variance $\sigma^2 = \sigma_{n_I}^2 = N_0$.
- The probability density function is

$$p(x(m)|a^{(i)}) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x(m)-a^{(i)})^2}{2\sigma^2}}$$

so that the symbol $a^{(i)}$ that maximizes $p(x(m)|a^{(i)})$ is the one that minimizes the distance between the symbol and the received sample

$$\hat{a}_m = \arg \min_{a^{(i)} \in \mathcal{A}} |x(m) - a^{(i)}|$$

Decision strategy



- Because of the conditioning, the symbol value $a^{(i)}$ is fixed and $x(m) \in \mathcal{N}(a^{(i)}, N_0)$ is a Gaussian random variable with mean $a^{(i)}$ and variance $\sigma^2 = N_0$.
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$$\hat{a}_m = \arg \min_{a^{(i)} \in \mathcal{A}} |x(m) - a^{(i)}|$$

Decision strategy

Received sample = decision variable



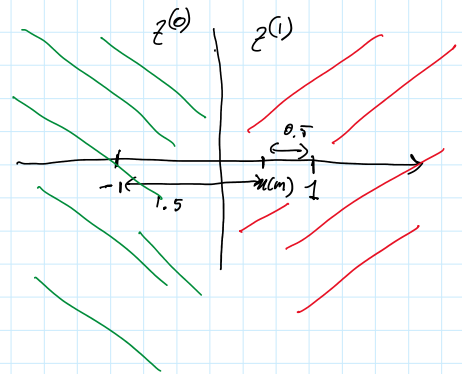
- Example. Consider a 2-PAM ($M = 2$) and assume that $x(m) = 0.5$. The two symbols are $a^{(0)} = -1$ and $a^{(1)} = 1$, i.e. $\mathcal{A} = \{-1, 1\}$.
- The decision block will compute the two distances:

$$d(x(m), a^{(0)}) = |0.5 - (-1)| = 1.5$$

$$d(x(m), a^{(1)}) = |0.5 - 1| = 0.5$$

and will decide for the one that minimizes the distance, so that

$$\hat{a}_m = a^{(1)} = 1.$$

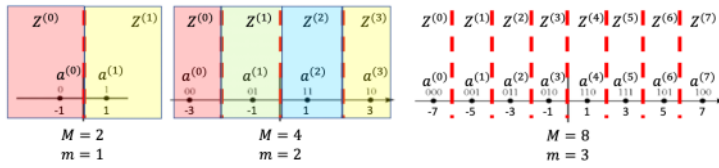


Decision strategy



- Adopting the maximum likelihood criterion, we can partition the signal space in *zone of decisions*, where zone $Z^{(i)}$ is the set of points that are closer to the symbol $a^{(i)}$ than to any other symbol

$$Z^{(i)} = \{x | d(x, a^{(i)}) < d(x, a^{(j)}), j \neq i, j = 1, \dots, M\}$$



The decision threshold are in the midpoints of the segment connecting any two adjacent symbols. For example, for $M = 4$ the thresholds are in $-2, 0$ and 2 .

