

RAISED COSINE FILTERS: sono filtri che sono adattando
i criteri di Nyquist

LA BANDA OCCUPATA ϵ' : $B_{\text{RC}} = \frac{1+\alpha}{T}$ dove $\alpha \in \epsilon'$ li ha scritti
 ϵ con α so una rett cos ϵ' vicino a banda interessante.

MATCHED FILTER: trasmettendo effetti del canale, e
prevedendo problemi gli si presenta di
risolvere questo.

$$g_R(t) = g(-t) \circ G_R(f) = G_R^*(f)$$

massimizzo il rapporto sintonia - rumore
al ricevitore

→ ricevuto "matched" to
trasmettit filter.

Root RAISED COSINE FILTER: FILTRI CHE VENGONO COSTRUITI CON UNA FREQUENZA A UN RADICE QUADRATICA DI UN RAISED COSINE

$$\text{SE } Q_T(f) = Q_T(f) = H_{REC}(f\alpha)$$

(1)

IL TRANSMITTER FILTER E' IL RECEIVE
FILTER SOLO SE FONOZ
CONDIZIONI DI OMOSTERIA'

WIDEPENDENT

(2)

QIA ASINTOTICA DI $g_R(t) \approx g_R(t)$ RISPOSTA CRITICO DI
MEANIST

(3) IL RECEIVE FILTER E' GUARDED CON IL TRANSMITTER
FILTER

$$H_{REC}(f\alpha) = \sqrt{H_{RC}(f\alpha)}$$

BANDA PI UN SCENARIOS PARE;

- COMPLEX ENVELOPE

$$B_{PARE}^{(BB)} = \frac{1+\alpha}{2} \frac{R_b}{\log_2 4}$$

- PASSBAND SPECTRUM

$$B_{PARE}^{(RB)} = 1+\alpha \frac{R_b}{\log_2 4}$$

POTENZA DI UN SCENARIO PARE;

- COMPLEX ENVELOPE

$$P_S^{\text{C}} = \frac{A}{T}$$

- PA SUBBAND SCENARIO

$$P_S = \frac{A}{2T}$$

ENERGIA DI UN SEGNALE E' DATA:

- MEAN SQUARED VALUE

$$A = \mathbb{E} \{ |a_i|^2 \} = \frac{\sigma^2 - 1}{3}$$

- ENERGIA PER STABOLO

$$E_S = \bar{P}_{ST} = \frac{A}{2T} T = \frac{\sigma^2 - 1}{6}$$

RISERVA ADDITIVO BIANCO CAUSSATO:

$$\tilde{w}(t) = \bar{w}_I(t) + j\bar{w}_Q(t)$$

$$m(t) = g_R(t) \otimes w(t)$$

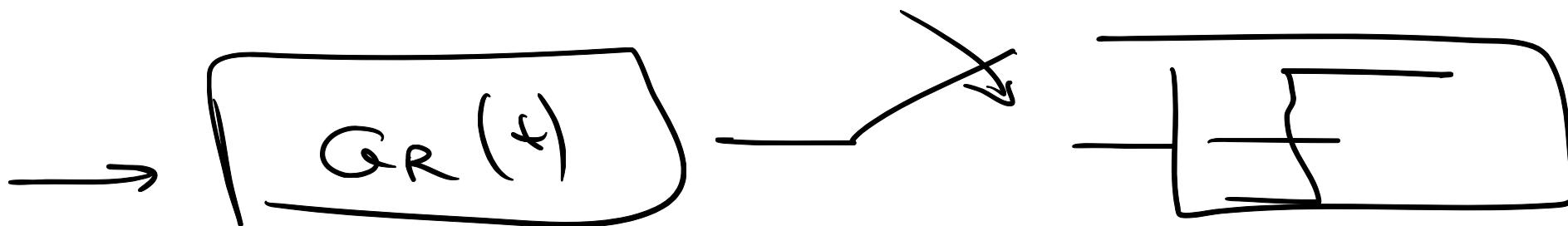
PROCESSO GAUSSIANO COMPLESSO E
STOCHASTICO A SECONDA NUOVA

SE IL FUTTO RISERVA ϵ' ON RRC \Rightarrow

$$PSD = S_{\epsilon'}(f) = S_w(f) |K_R(f)|^2 = \left| \mathcal{F}[w_R(f)] \right|^2 = \mathcal{F}[w_R^2(f)]$$

POWER SPECTRAL DENSITY

MOLTIORI ↴
 ϵ' BIANCO!



$$x(m) = \alpha_m + n(m)$$

$$\sigma_n^2 = 2N_0, \quad \sigma^2 = N_0$$

$$\hat{\alpha}_m = \arg \max_{\alpha^{(i)} \in \mathcal{A}} p(\alpha^{(i)} | x(m))$$

MASSIMIZZO LA
 PROBABILITÀ DI RECEVENDO
 IL SIEBUCCO
 CORRETTO

$$p(x(m) | \alpha^{(i)}) \approx p(\alpha^{(i)} | x(m)) \rightarrow \text{ai cui è MASSIMIZZATA}$$

UNA, VAI E ANCHE PER ACTRA

Two density functions

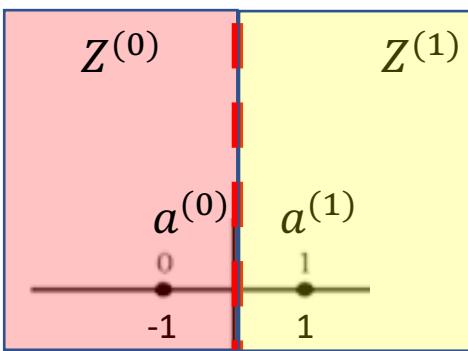
$$P(x(m) | \alpha^i) = \frac{1}{\sqrt{2\pi} \sigma} e^{-\frac{(x(m) - \alpha^{(i)})^2}{2\sigma^2}}$$

$$\hat{x}(m) = \arg \min_{\alpha^{(i)} \in \mathcal{A}} |x(m) - \alpha^{(i)}|$$

Decision strategy

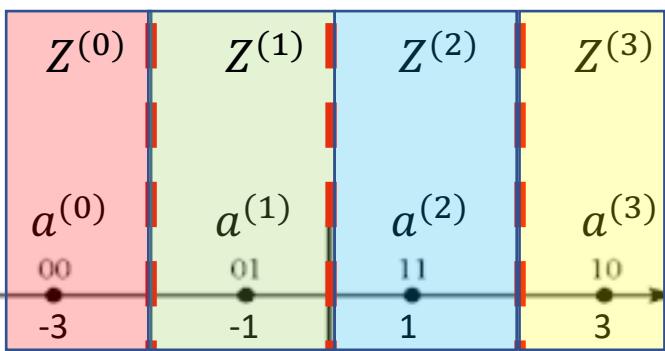
- Adopting the maximum likelihood criterion, we can partition the signal space in **zone of decisions**, where zone $Z^{(i)}$ is the set of points that are closer to the symbol $a^{(i)}$ than to any other symbol

$$Z^{(i)} = \{x | d(x, a^{(i)}) < d(x, a^{(j)}), j \neq i, j = 1, \dots, M\}$$



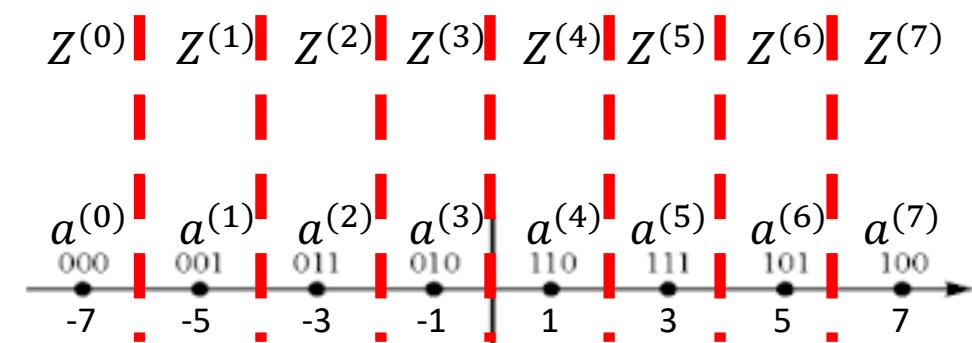
$$M = 2$$

$$m = 1$$



$$M = 4$$

$$m = 2$$



$$M = 8$$

$$m = 3$$

The decision thresholds are in the midpoints of the segments connecting any two adjacent symbols. For example, for $M = 4$ the thresholds are in $-2, 0$ and 2 .

$$x(m) = \alpha_m + n(m) \Rightarrow$$

PAM error probability $\Rightarrow x(m) = 1 + n(m)$

~~COSE STO
TRANSCEIVE ->
1~~

- Even if the maximum likelihood decision strategy is optimal, the receiver still make errors due to the presence of noise.
- The error probability is averaged over all the symbol of the constellation

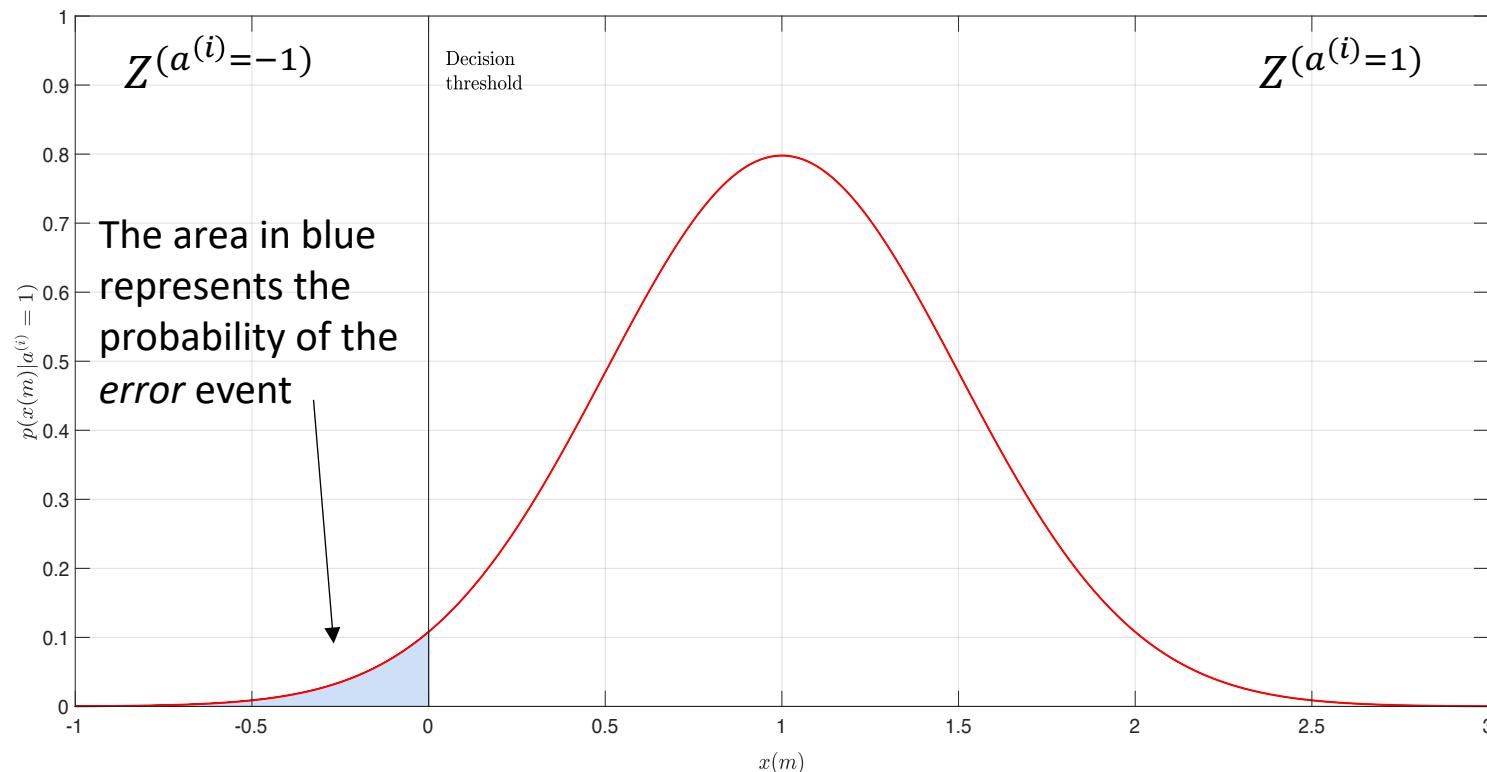
$$P_e = \lim_{N^{(s)} \rightarrow \infty} \frac{N_e^{(s)}}{N^{(s)}} = \frac{1}{M} \sum_{i=0}^{M-1} P(e|a^{(i)})$$

where $N_e^{(s)}$ is the number of symbol errors and $N^{(s)}$ is the number of transmitted symbols.

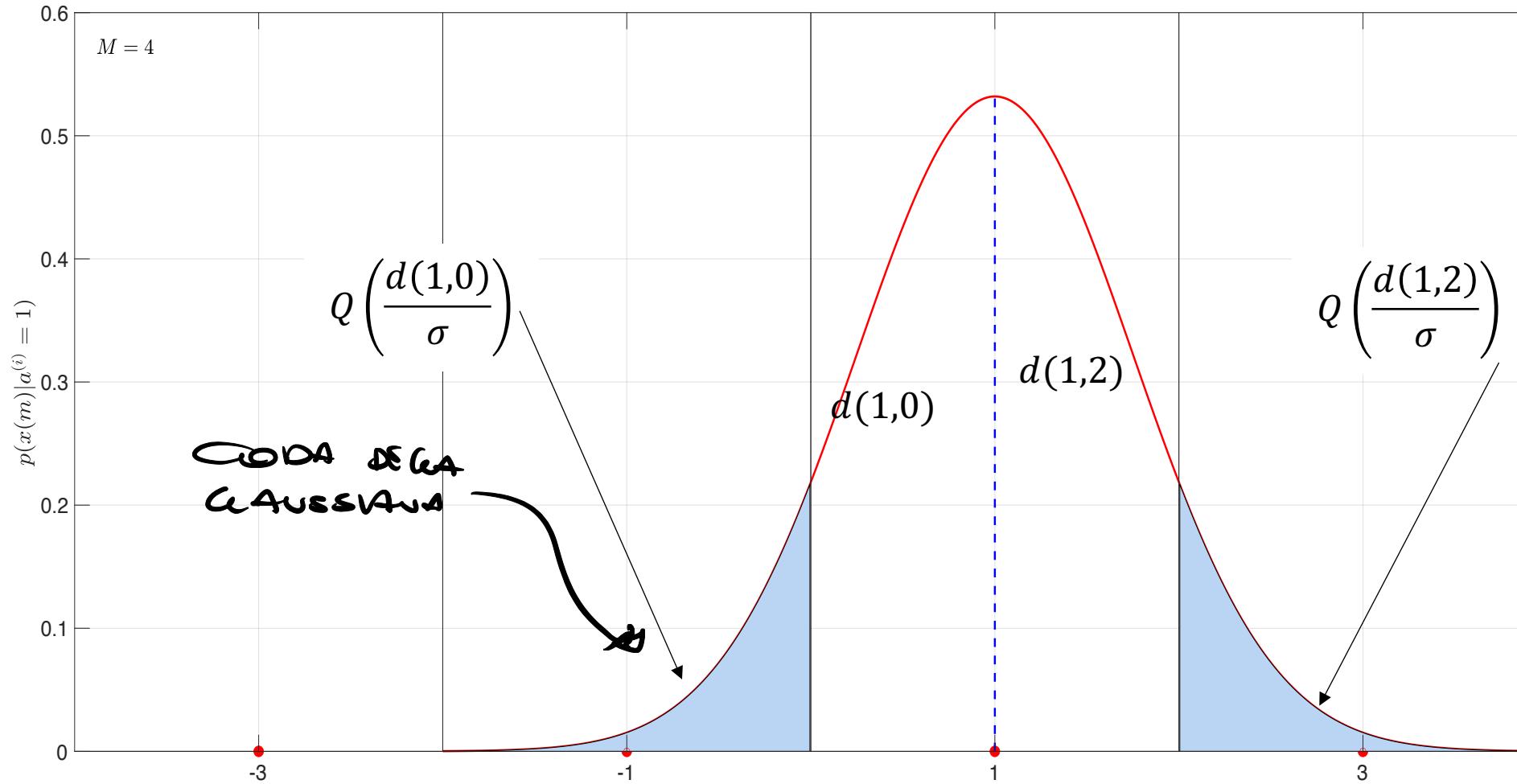
- The probability of error $P(e|a^{(i)})$ is the probability that, having transmitted $a^{(i)}$, the decision variable $x(m)$ does not fall in the decision region $Z^{(i)}$.

PAM error probability

- To compute $P(e|a^{(i)})$ we assume that the transmitted symbol is $a_m = a^{(i)}$, so that it is $x(m) = a^{(i)} + n(m)$ and the probability of error is
$$P(e|a^{(i)}) = \Pr\{x(m) \notin Z^{(i)} | a_m = a^{(i)}\}$$



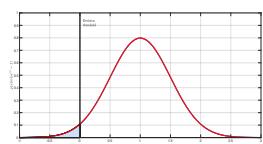
PAM error probability



$$P(e|a^{(i)} = 1) = \int_{-\infty}^0 p(x|a^{(i)} = 1)dx + \int_2^{+\infty} p(x|a^{(i)} = 1)dx = Q\left(\frac{d(1,0)}{\sigma}\right) + Q\left(\frac{d(1,2)}{\sigma}\right) = 2Q\left(\frac{1}{\sigma}\right)$$

PAM error probability: Q -function

- The Q -function computes the integral of the *tail* of a Gaussian distribution.
- The probability that $x \in \mathcal{N}(m, \sigma^2)$ is smaller than t_1 or larger than t_2 are the integral of Gaussian tails and they are computed as



$$\left. \begin{aligned} \int_{-\infty}^{t_1} pdf(x)dx &= Q\left(\frac{m - t_1}{\sigma}\right) \\ \int_{t_2}^{+\infty} pdf(x)dx &= Q\left(\frac{t_2 - m}{\sigma}\right) \end{aligned} \right\} = Q\left(\frac{d(t_i, m)}{\sigma}\right), i = 1, 2$$

- In our case, m is the symbol $a^{(i)}$ and t_1 or t_2 are the detection thresholds.
- The main properties of the Q -function are
$$Q(-\infty) = 1, Q(\infty) = 0, Q(0) = 0.5, Q(-x) = 1 - Q(x).$$

PAM error probability

- 2-PAM

$$P_e^{(2-PAM)} = \frac{1}{2} \left(Q\left(\frac{d(-1,0)}{\sigma}\right) + Q\left(\frac{d(1,0)}{\sigma}\right) \right) = Q\left(\frac{1}{\sigma}\right)$$

- 4-PAM

$$P_e^{(4-PAM)} = \frac{1}{4} \left(Q\left(\frac{d(-3,-2)}{\sigma}\right) + Q\left(\frac{d(-1,-2)}{\sigma}\right) + Q\left(\frac{d(-1,0)}{\sigma}\right) \right. \\ \left. + Q\left(\frac{d(1,0)}{\sigma}\right) + Q\left(\frac{d(1,2)}{\sigma}\right) + Q\left(\frac{d(3,2)}{\sigma}\right) \right) = \frac{3}{2} Q\left(\frac{1}{\sigma}\right)$$

PAM symbol error probability

- It is often useful to express the P_e in terms of E_s/N_0 .

- 2-PAM: $E_s = \frac{2^2 - 1}{6} = \frac{1}{2}$ $\Rightarrow 2E_s = 1$ and $\sigma^2 = N_0$, and $\frac{1}{\sigma} = \sqrt{\frac{1}{\sigma^2}} = \sqrt{\frac{2E_s}{N_0}}$.

$$P_e^{(2-PAM)} = Q\left(\sqrt{\frac{2E_s}{N_0}}\right)$$

- 4-PAM: $E_s = \frac{4^2 - 1}{6} = \frac{5}{2}$ $\Rightarrow \frac{2}{5}E_s = 1$, and $\frac{1}{\sigma} = \sqrt{\frac{1}{\sigma^2}} = \sqrt{\frac{2E_s}{5N_0}}$.

$$P_e^{(4-PAM)} = \frac{3}{2} Q\left(\sqrt{\frac{2E_s}{5N_0}}\right)$$

PAM bit error probability

- To have a fair comparison, the modulation performance are expressed in terms of *bit error probability* $P_e^{(b)}$ as function of E_b/N_0 .
- The energy E_b per bit is computed as the energy per symbol divided by the number of bits per symbol

$$E_b = \frac{E_s}{\log_2 M}$$

- Although one symbol carries $\log_2 M$ bits, it is reasonable to assume that in a well-designed system (*Gray mapping* and medium-high SNR) *a symbol error causes only one-bit errors*.
- If $N^{(b)}$ and $N_e^{(b)}$ are the number of transmitted bits and the number of bit errors, the bit error probability is computed as

$$P_e^{(b)} = \lim_{N^{(b)} \rightarrow \infty} \frac{N_e^{(b)}}{N^{(b)}} \approx \lim_{N^{(s)} \rightarrow \infty} \frac{N_e^{(s)}}{\log_2 M N^{(s)}} = \frac{1}{\log_2 M} \lim_{N^{(s)} \rightarrow \infty} \frac{N_e^{(s)}}{N^{(s)}} = \frac{1}{\log_2 M} P_e.$$

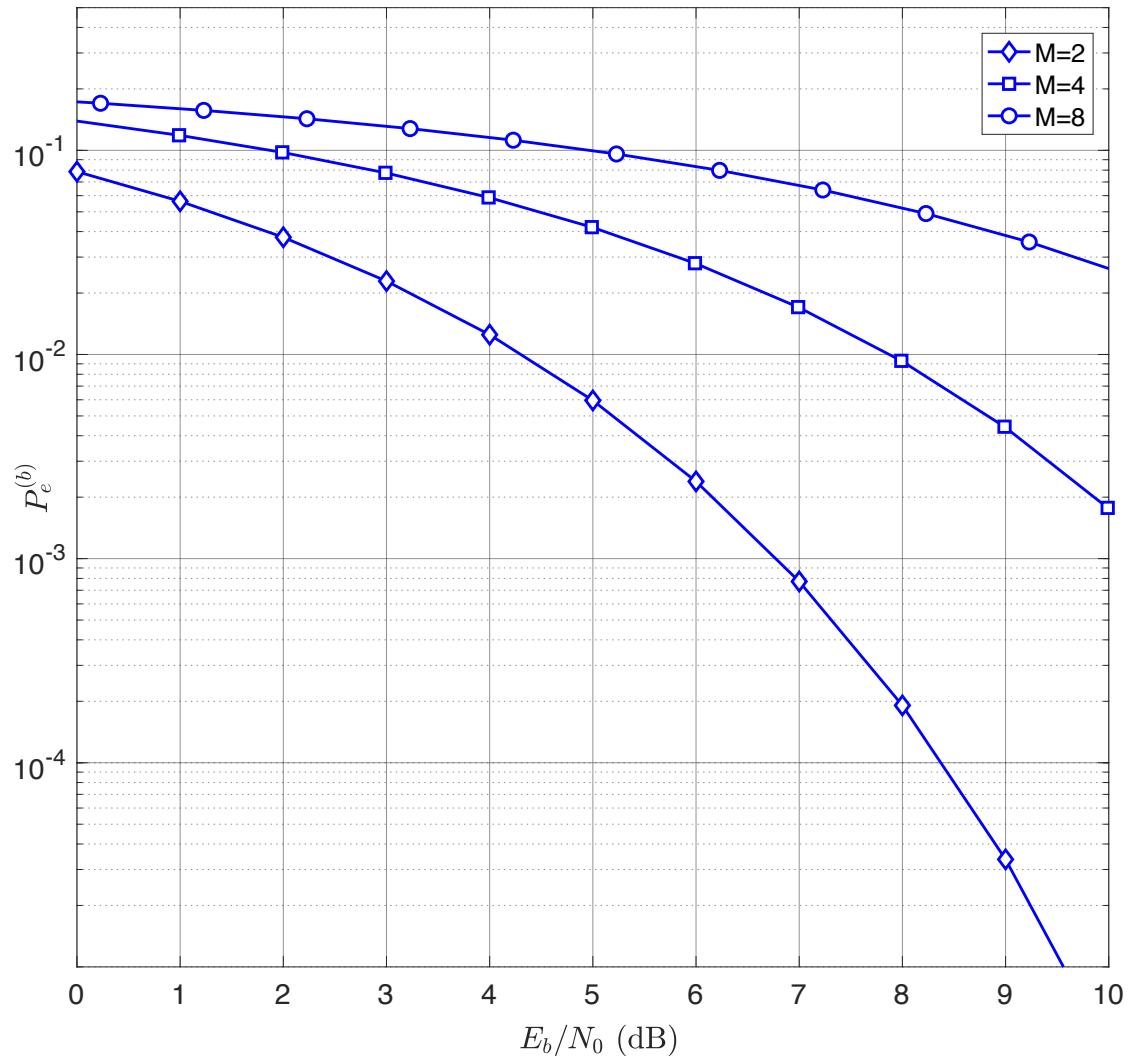
PAM bit error probability

- 2-PAM: $M = 2$, $m = 1$ bit per symbol $\Rightarrow P_e^{(b)} = P_e, E_b = E_s$

$$P_e^{(2\text{-PAM}),b} = Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

- 4-PAM: $M = 4$, $m = 2$ bit per symbol $\Rightarrow P_e^{(b)} = \frac{1}{2}P_e, E_b = \frac{1}{2}E_s$

$$P_e^{(4\text{-PAM}),b} = \frac{3}{4}Q\left(\sqrt{\frac{4E_b}{5N_0}}\right)$$



Digital communications

Quadrature modulations (QAM)

Quadrature modulations

- In analog modulations, QAM is obtained by transmitting two orthogonal DSB signals $m_I(t), m_Q(t)$ and the complex envelope is

$$\tilde{s}_{QAM}(t) = m_I(t) + j m_Q(t)$$

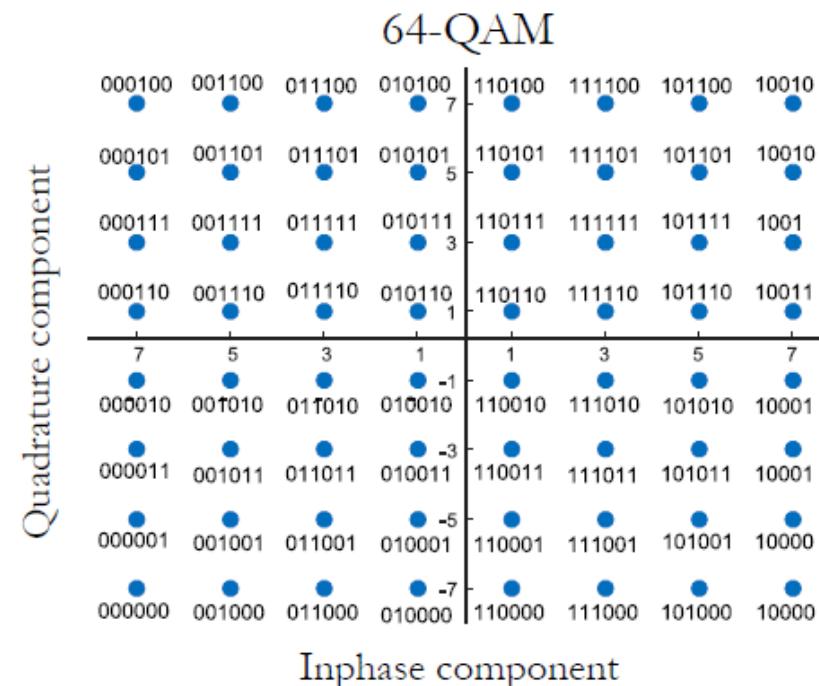
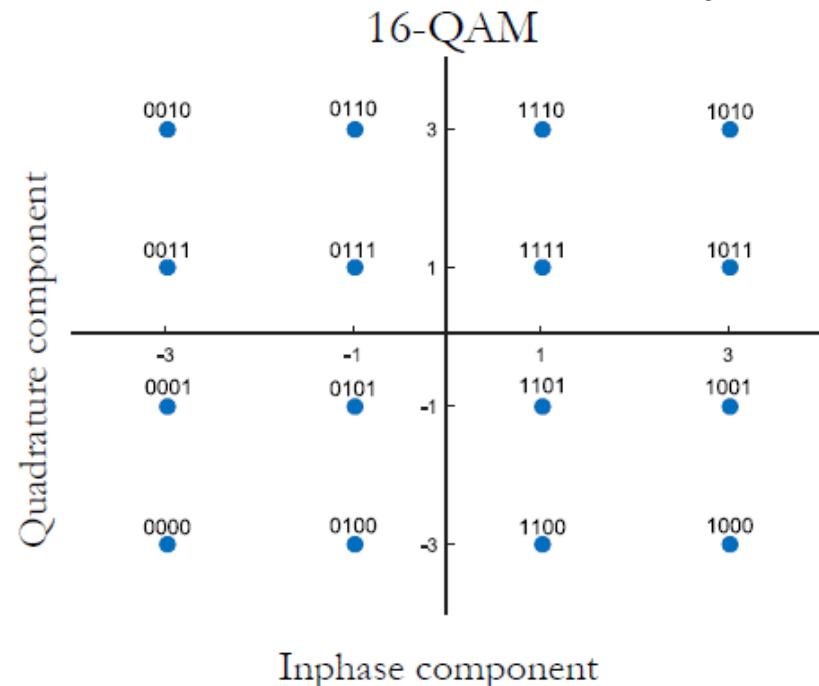
- Quadrature PAM is obtained exactly in the same manner by transmitting two PAM signals in quadrature $m_I(t) = \sum_i a_i g_T(t - iT)$ and $m_Q(t) = \sum_i b_i g_T(t - iT)$, with a_i, b_i PAM symbols.
- The QAM signal is

$$s_{QAM}(t) = \sum_i (a_i + j b_i) g_T(t - iT) = \sum_i c_i g_T(t - iT)$$

and the QAM complex symbols take the form $c_i = a_i + j b_i$.

QAM symbols

- Because QAM is the combination of two orthogonal PAM, the values of $M_{QAM} = M_{PAM}^2$ are squared powers of 2, i.e. m is always even.
 - If the two PAMs have $M_{PAM} = 4$ symbols than the QAM has $M_{QAM} = 16$ symbols, if $M_{PAM} = 8$ than $M_{QAM} = 64$.



Energy of a QAM symbol

- In the computation of power and energy the only difference between PAM and QAM is in the mean square value of the symbols.
- Keeping in mind that the in-phase and quadrature symbols are independent and zero-mean, it is

$$A = E\{c_i c_i^*\} = E\{a_i^2\} + E\{b_i^2\} = 2 \frac{M_{PAM}^2 - 1}{3} = 2 \frac{M_{QAM} - 1}{3}$$

- The energy per symbol is

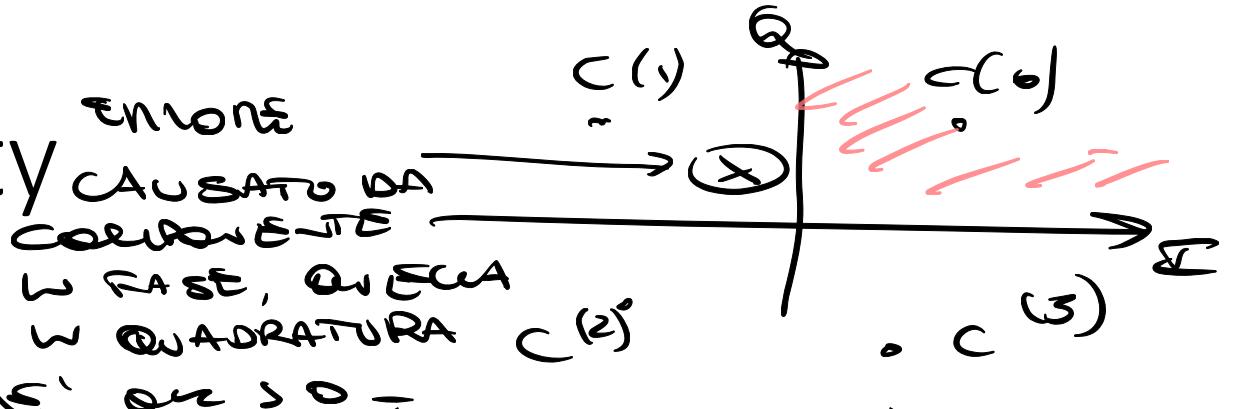
$$E_s = \frac{A}{2} = \frac{M_{QAM} - 1}{3}$$

- QAM constellation is much more compact and requires less energy per symbol compared to PAM.

$$\bullet A^{(4-PAM)} = \frac{16-1}{3} = 5; \quad A^{(4-QAM)} = 2 \frac{4-1}{3} = 2$$

$$\bullet A^{(16-PAM)} = \frac{256-1}{3} = 85; \quad A^{(16-QAM)} = 2 \frac{16-1}{3} = 10.$$

QAM error probability



- The *complex* decision variable is

$$\begin{aligned} x(m) &= c_m + n(m) = (a_m + jb_m) + (n_I(m) + jn_Q(m)) \\ &= a_m + n_I(m) + j(b_m + n_Q(m)) \end{aligned}$$

- The in-phase and quadrature noise components $n_I(m)$ and $n_Q(m)$ are independent.

- Error events depends on noise. If the noise is independent also the error events on the two components are independent.

- The error probability can be approximated as the sum of the probability of making an error on the in-phase symbol a_m and probability of making an error on the quadrature symbol b_m .

4-QAM error probability

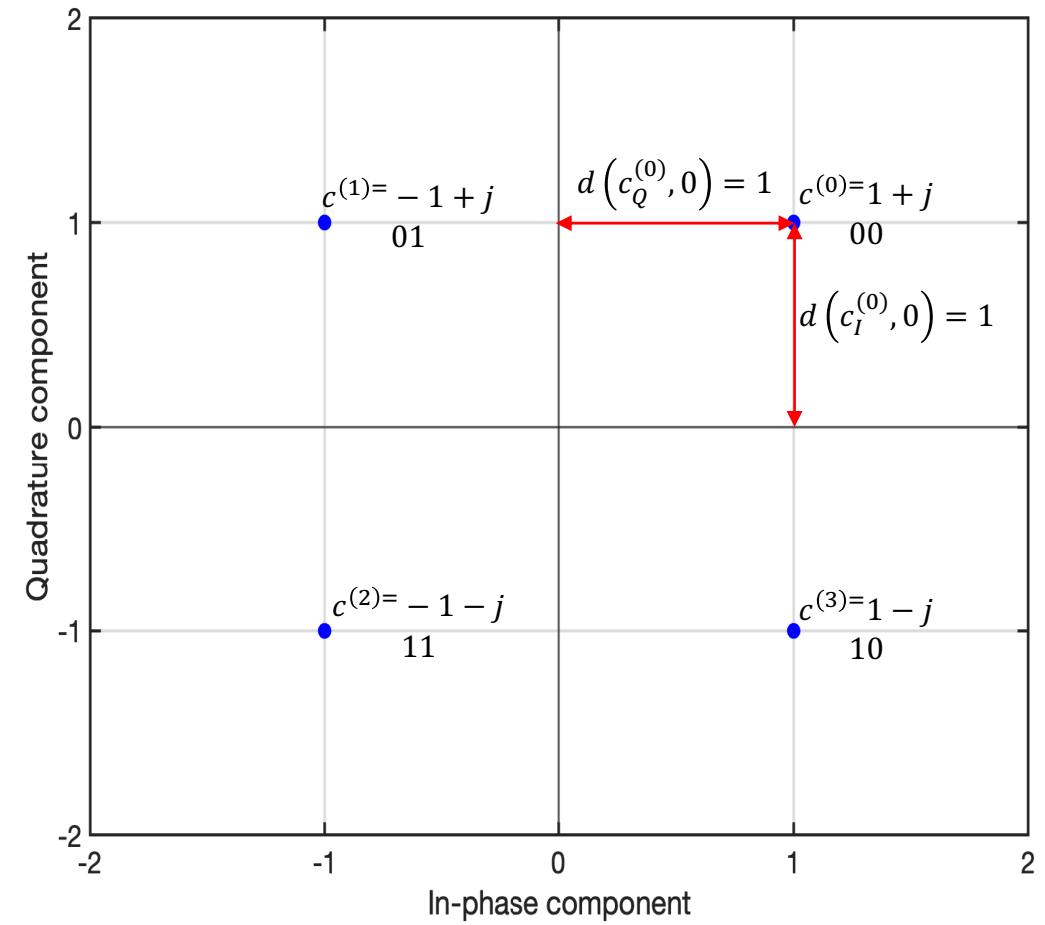
- 4-QAM is obtained as the composition of two 2-PAM in quadrature.
- The symbol error probability is

$$P_e^{(4-QAM)} = \frac{1}{4} \sum_{i=0}^3 P(e|c^{(i)}) = P(e|c^{(0)})$$

$$P(e|c^{(0)}) \approx Q\left(\frac{d(c_I^{(0)}, 0)}{\sigma_{nI}}\right) + Q\left(\frac{d(c_Q^{(0)}, 0)}{\sigma_{nQ}}\right)$$

$$= 2Q\left(\frac{1}{\sigma}\right)$$

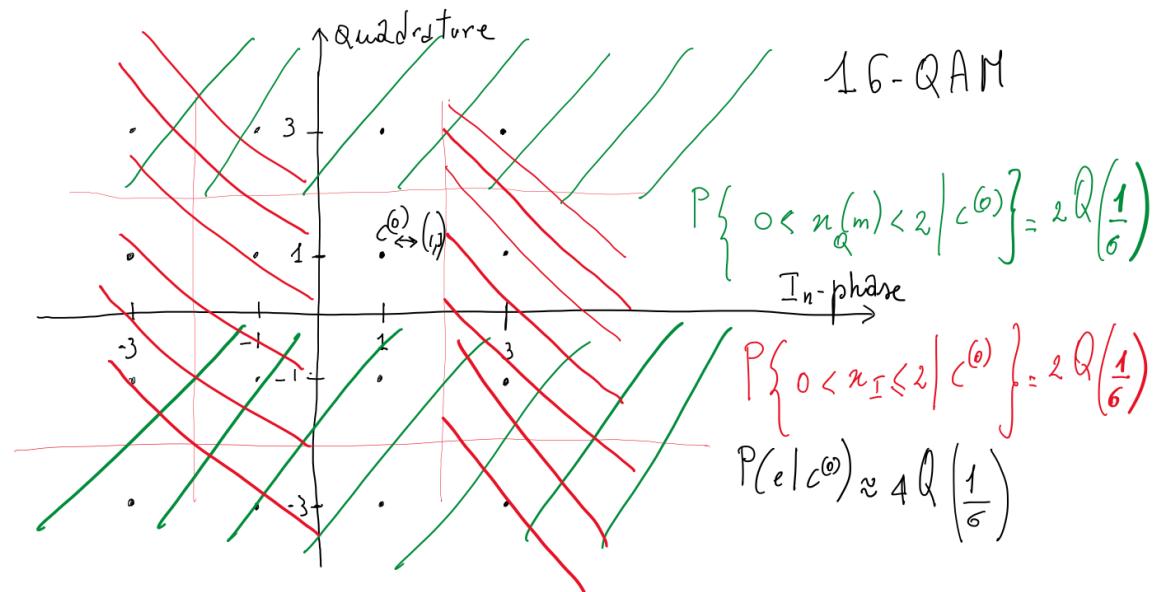
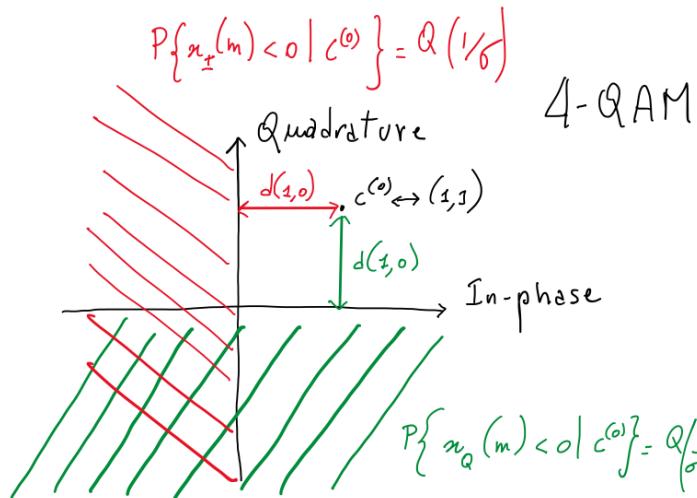
$$P_e^{(4-QAM)} \approx 2P_e^{(2-PAM)}$$



M-QAM error probability

- M-QAM is obtained as the composition of two PAM in quadrature, each with \sqrt{M} symbols.
- The symbol error probability can always be approximated as

$$P_e^{(M-QAM)} \approx 2P_e^{(\sqrt{M}-PAM)}$$



QAM symbol error probability

- 4-QAM: $E_s = \frac{4-1}{3} = 1 \Rightarrow E_s = 1, M = 4, m = 2$ and $\frac{1}{\sigma} = \sqrt{\frac{1}{\sigma^2}} = \sqrt{\frac{E_s}{N_0}}$

$$P_e^{(4-QAM)} \approx 2Q\left(\sqrt{\frac{E_s}{N_0}}\right);$$

Penetrate noise? Penetrate
DPE ~ DS \cup \rightarrow voice DPE
radio \in \cup ~~radio~~ ~~radio~~ ~~radio~~ ~~radio~~

- 16-QAM: $E_s = \frac{16-1}{3} = 5 \Rightarrow \frac{1}{5}E_s = 1, M = 16, m = 4$ and $\frac{1}{\sigma} = \sqrt{\frac{1}{\sigma^2}} = \sqrt{\frac{E_s}{5N_0}}$.

$$P_e^{(16-QAM)} \approx 2 \frac{3}{2} \left(\sqrt{\frac{1}{\sigma}} \right) = 3Q\left(\sqrt{\frac{E_s}{5N_0}}\right); P_e^{(16-QAM),b} \approx \frac{1}{4} 3Q\left(\sqrt{\frac{4E_b}{5N_0}}\right) = \frac{3}{4} Q\left(\sqrt{\frac{4E_b}{5N_0}}\right)$$

M-QAM error probability

- The total number of M-QAM transmitted bits is the sum of the number of bits transmitted on the in-phase and quadrature channels.
- Because each channel is independent, the bit error probability per channel is independent.
- Accordingly, $P_e^{(M-QAM),b}$ can be *exactly* computed as the sum of the bit error probability on the in-phase channel and the quadrature channel, divided by two.

$$P_e^{(M-QAM),b} = \frac{1}{2} 2 P_e^{(\sqrt{M}-PAM),b} = P_e^{(\sqrt{M}-PAM),b}$$

QAM bit error probability

- 4-QAM:

$$P_e^{(4-QAM),b} = P_e^{(2-PAM),b} \approx Q\left(\sqrt{\frac{2E_b}{N_0}}\right)$$

- 16-QAM

$$P_e^{(16-QAM),b} = P_e^{(4-PAM),b} \approx \frac{3}{4}Q\left(\sqrt{\frac{4E_b}{5N_0}}\right)$$

