Variational Inference for Hierarchical Poisson Factorization

Computational Statistics Project 1

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1 Introduction

Hierarchical Poisson Factorization (HPF) [2] is a probabilistic model for a recommender system. It is based on the Poisson matrix factorization, that gives the name to the model. This factorization involves the observations on the data matrix y of users and items, where each data point is assumed to be a draw from an independent Poisson distribution.

$\mathbf{2}$ The model

The HPF is based on the data matrix y, of dimensions N (number of users) and M (number of items). Each user is characterized by a vector of K latent components, which represent the latent user preferences. Analogously, each item is characterized by a vector of K latent components, which represent the latent item attributes. Thus, each data point is the inner product of the latent component for the user u and the item i.

On top of that, Gamma hyperpriors are specified for the rate parameters θ and β . ξ_u is the rate parameter of θ_u and captures the prior on the user activity. η_i is the rate parameter of β_i and represents the item popularity.

The generative process is then the following:

- 1. For each user u:

 - (a) Sample an activity value $\xi_u \sim Gamma(a', \frac{a'}{b'})$ (b) For each component k = 1, ..., K, sample a preference $\theta_{u,k} \sim Gamma(a, \xi_u)$
- 2. For each item i:
- (a) Sample a popularity value $\eta_i \sim Gamma(c', \frac{c'}{d'})$ (b) For each component k = 1, ..., K, sample an attribute $\beta_{i,k} \sim Gamma(c, \eta_i)$ 3. For each (u, i), sample an observation (rating) $y_{u,i} \sim Poisson(\theta_u^T \beta_i)$

Thanks to the Poisson matrix factorization, this model scales very efficiently in the context of sparse data. Indeed, since Poisson distribution puts positive mass on zero, the likelihood of the model will only depends on observation points that are different from zero:

$$p(y) = \prod_{u,i} \frac{(\theta_u^T \beta_i)^{y_{u,i}} \cdot e^{-\theta_u^T \beta_i}}{y_{u,i}!} = \prod_{u,i: \ y_{u,i} > 0} \frac{(\theta_u^T \beta_i)^{y_{u,i}}}{y_{u,i}!} \cdot \prod_{u,i} e^{-\theta_u^T \beta_i}$$

As a consequence, inference will be conducted only on a fraction of the data points, speeding up the runtime of the algorithm.

¹ All the Gamma distributions are parameterized with a shape and a rate parameter.

Mean-field Variational Inference 3

We derive the variational algorithm, which is a method for approximating probability densities through optimization. It aims at approximating the untractable posterior distribution of the model. We aim at minimizing the Kullback-Leibler divergence between the true posterior and a variational distribution, which amounts to finding the tightest lower bound for the log-evidence p(y), called evidence lower bound (ELBO), by means of a coordinate ascent algorithm.

We introduce additional latent variables, k of them for each pair of user and item, such that $z_{u,i;k} \sim Poisson(\theta_{uk}\beta_{ik})$, a technical device that simplifies the process of finding the solution of the optimization problem. In this way, $y_{u,i} = \sum_k z_{u,i;k}$. Hence, the posterior of interest is $p(\beta, \theta, \eta, \xi, z|y)$ and the variational will be $q(\beta, \theta, \eta, \xi, z)$. We impose the mean-field assumption, that is, the variational distribution can be factorized, so that each variable is independent and governed by its own distribution.[1]

$$q(\beta, \theta, \xi, \eta, z) = \prod_{i,k} q(\beta_{ik}|\lambda_{ik}) \prod_{u,k} q(\theta_{uk}|\gamma_{uk}) \prod_u q(\xi_u|k_u) \prod_{u,k} q(\eta_i|\tau_i) \prod_{u,k} q(z_{ui}|\phi_{ui})$$

The first step is to derive the complete conditionals of θ_{uk} , β_{ik} , ξ_u , η_i and z_{ui} . By Gamma-Poisson conjugacy, the first four complete conditionals are:

- 1. From θ_{uk} and $z_{uk}|\theta_{uk}$ we get: $\theta_{uk} \sim \text{Gamma}(a + \sum_i z_{uik}, \xi_u + \sum_i \beta_{ik})$. 2. From β_{ik} and $z_{ik}|\beta_{ik}$ we get: $\beta_{ik} \sim \text{Gamma}(c + \sum_i z_{uik}, \eta_i + \sum_u \theta_{uk})$ 3. From ξ_u and $\theta_u|\xi_u$ we obtain: $\xi_u|\theta_u \sim \text{Gamma}(a' + Ka, a'/b' + \sum_k \theta_{uk})$ 4. From η_i and $\beta_i|\eta_i$ we obtain: $\eta_i|\beta_i \sim \text{Gamma}(c' + Kc, c'/d' + \sum_k \beta_{ik})$

Since z_{ui} is a K vector of Poisson that sum to y_{ui} , the complete conditional for the vector z_{ui} is a Multinomial with normalized probabilities:

$$z_{ui}|\beta, \theta, y \sim \text{Mult}\left(y_{ui}, \frac{\theta_u \beta_i}{\sum_k \theta_u k \beta_i k}\right)$$

It can be shown[3] that if all the complete conditionals of the model are in the exponential family, then the update for each variational component is optimal if it is in the same family as the complete conditional: hence, we impose this condition. In this case, the update rule only amounts to update each variational parameter with the expectation of the corresponding natural conditional parameter, given all the other parameters and the observations. For instance, the variational parameter of θ_{uk} will be updated as follows²:

$$\gamma_{uk}^{shape} = E^{q} \left[a + \sum_{i} z_{uik} \right] = a + \sum_{i} (y_{ui} \phi_{uik})$$

$$\gamma_{uk}^{rate} = E^{q} \left[\xi_{u} + \sum_{i} \beta_{ik} \right] = k_{u}^{shape} / k_{u}^{rate} + \sum_{i} (\lambda_{i}^{shape} / \lambda_{i}^{rate})$$

 $^{^2}$ For the sake of brevity, updates for $\lambda,\,k,$ and τ are omitted, but are analogous.

The update for ϕ is $\phi_{u,i} \propto \exp\{E_q [\log \theta_u + \log \beta_i]\}$. Hence, we can write the update rule for $\phi_{u,i}$ as³:

$$\phi_{uik} \propto \Psi(\gamma_{uk}^{shape}) - \log(\gamma_{uk}^{rate}) + \Psi(\lambda_{ik}^{shape}) - \log(\lambda_{ik}^{rate})$$
 (1)

We now have all the update rules we need to implement the algorithm.

3.1 The algorithm

```
Algorithm 1: Variational inference for Poisson Factorization

Initialize \gamma_u, \kappa_u^r, \lambda_i, \tau_i^r to the prior with a small random offset.

Set \kappa_u^s = Ka + a' and \tau_i^s = Kc + c'.

while log-likelihood not converged do

for u and i such that y_{ui} > 0 do

for k = 1, ..., K do

| \phi_{uik} \propto \Psi(\gamma_{uk}^{shp}) - log(\gamma_{uk}^{rte}) + \Psi(\lambda_{ik}^{shp}) - log(\lambda_{ik}^{rte})

end

end

for u = 1, ..., U do

| \gamma_{uk}^{shp} = a + \sum_i y_{ui} \phi_{uik} 

\gamma_{uk}^{rte} = \frac{\kappa_u^{shp}}{\kappa_u^{rte}} + \sum_i \frac{\lambda_{ik}^{shp}}{\lambda_{ik}^{shp}}

\kappa_u^{rte} = a'/b' + \sum_k \frac{\gamma_{uk}^{rte}}{\gamma_{uk}^{rte}}

end

for i = 1, ..., I do

| \lambda_{i,k}^{shp} = c + \sum_i y_{ui} \phi_{uik} 

\lambda_{i,k}^{rte} = \frac{\tau_i^{shp}}{\tau_i^{rte}} + \sum_u \frac{\gamma_{u,k}^{rte}}{\gamma_{u,k}^{shp}}

\tau_i^{rte} = c'/d' + \sum_k \frac{\lambda_{ik}^{shp}}{\lambda_{ik}^{rte}}

end

end
```

3.2 Possible improvements

Although the algorithm implemented scales very well with massive dataset thanks to the sparse matrix estimation, there are other solutions other than the mean-field variational algorithm that may speed up the training process even more. For example, one could implement a stochastic variational inference algorithm [3]. The main advantages would be the use of subsets of data at each iterations and more efficient updates.

³ Recall that the expectation of the log- $\Gamma(\alpha, \beta)$ random variable is $\Psi(\alpha) - \log \beta$, where Ψ is the digamma function.

4 Implementation in Python

The algorithm has been implemented using Python3 and it is available in the hpf_vi.py file. The code is also available in the Appendix of this document. A notebook is also provided with the algorithm applied on simulated data.

4.1 Initialization of the variational parameters

The model implemented initializes the user parameters γ_u and the item parameters λ_i to the prior, plus a small random offset generated with a Uniform (0,1).

In this way, $\gamma_{uk}^{shp}=a$ and $\gamma_{uk}^{rte}=a/b'$, so that the expectation of the variational θ is b'. Similarly, $\lambda_{ik}^{shp}=c$ and $\lambda_{ik}^{rte}=c/d'$, so that the expectation of the variational β is d'. For the same reason, we set the variational parameters of ξ_u and η_i , which are k_u^{rte} and τ_i^{rte} , to the prior, plus the same small random offset.

In addition, as suggested in the original paper, low shape parameters for the Gamma priors on user preferences θ_u and item attributes β_i are set, favouring a sparse representation that better fits the data in most of the cases.

References

- Blei, D.M., Kucukelbir, A., McAuliffe, J.D.: Variational inference: A review for statisticians. Journal of the American statistical Association 112(518), 859–877 (2017)
- Gopalan, P., Hofman, J.M., Blei, D.M.: Scalable recommendation with hierarchical poisson factorization. In: UAI. pp. 326–335 (2015)
- 3. Hoffman, M.D., Blei, D.M., Wang, C., Paisley, J.: Stochastic variational inference. The Journal of Machine Learning Research 14(1), 1303–1347 (2013)

A Appendix – Python Implementation

```
import numpy as np
   from scipy.special import digamma
   import time
   from sklearn.metrics import mean_squared_error
   class hpf_vi():
       def __init__(self, a = 0.3, c = 0.3, a1 = 0.3, b1 = 1, c1 =
7
        \rightarrow 0.3, d1 = 1, K = 10):
            Initialization of the parameter matrices used in the CAVI
       algorithm.
            The user can modify the hyperparameters and the dimension
10
       of latent attributes and preferences K.
11
            Parameters:
12
13
                -a:float
                  shape parameter for the Gamma(a, activity_u) prior
15
                  for user preferences.
16
                -c:float
17
                  shape parameter for the Gamma(c, popularity_i)
       prior
                  for item attributes.
                - a1, b1 : floats
20
                  parameters of the Gamma(a1, a1/b1) prior for user
       activity.
22
                -c_1, d_1: floats
                  parameters of the Gamma(c1, c1/d1) prior for item
23
       popularity.
                -K:int
24
                  dimensionality of latent attributes and
25
       preferences.
            111
26
            self.a, self.c, self.a1, self.b1, self.c1, self.d1, self.K
27
            \rightarrow = a, c, a1, b1, c1, d1, K
28
       def fit(self, train, iterations, tol=0.5, valid=None):
29
30
            Fit the Hierarchical Poisson Factorization model via
31
       Coordinate Ascent Variational Algorithm (CAVI)
            and generates the corresponding observation matrix based
       on the variational parameters.
```

```
The algorithm stops either when the log-likelihood
33
       difference is less than the tolerance or after the number of
       iterations specified.
34
            Parameters:
35
                - train : numpy.array
                  UxI array with U = users and I = items.
                - iterations: int
39
                  number of desired training epochs.
                - tol: float
41
                  tolerance stopping criterion.
42
43
            self.train = train
            self.valid = valid
45
            # Dataset dimensions
47
            self.U, self.I = train.shape
49
            self.initialize()
            self.mse_train = np.zeros(iterations)
            self.ll = np.zeros(iterations)
            self.its = 0
            # Building user preferences and item attributes
            self.theta = self.gamma_shp/self.gamma_rte
57
            self.beta = self.lambda_shp/self.lambda_rte
            old_ll = self.log_likelihood(self.train, self.beta,

    self.theta)

            stop = False
60
61
            self.mse_valid = np.zeros(iterations)
63
            def MSE(pred, values):
                prediction, values = pred[values.nonzero()].flatten(),
65

¬ values[values.nonzero()].flatten()

                return mean_squared_error(prediction, values)
66
            import time
            from sklearn.metrics import mean_squared_error
            tic = time.clock()
70
            while not stop and self.its < iterations:
72
                for u, i in zip(train.nonzero()[0],

    train.nonzero()[1]):
```

```
self.phi[u,i] =
74
                   → np.log(self.gamma_rte[u,k])\
                  + digamma(self.lambda_shp[i,k]) -
75
                   → np.log(self.lambda_rte[i,k])) for k in

    range(self.K)]

                  self.phi[u,i] = self.phi[u,i] /
76

¬ np.sum(self.phi[u,i])

77
              for u in range(self.U):
                  self.gamma_shp[u] = [self.a +
                   → np.sum(train[u]*self.phi[u,:,k]) for k in

→ range(self.K)]

                  self.gamma_rte[u] = [self.k_shp/self.k_rte[u] +

    for k in range(self.K)]

                  self.k_rte[u] = self.a1/self.b1 +
81
                   → np.sum(self.gamma_shp[u]/self.gamma_rte[u])
82
              for i in range(self.I):
                  self.lambda_shp[i] = [self.c +
84

→ np.sum(train[:,i]*self.phi[:,i,k]) for k in

                      range(self.K)]
                  self.lambda_rte[i] = [self.tau_shp/self.tau_rte[i]
85
                   → np.sum(self.gamma_shp[:,k]/self.gamma_rte[:,k])

    for k in range(self.K)]

                  self.tau_rte[i] = self.c1/self.d1 +
86
                   → np.sum(self.lambda_shp[i]/self.lambda_rte[i])
               # Building user preferences and item attributes
               self.theta = self.gamma_shp/self.gamma_rte
               self.beta = self.lambda_shp/self.lambda_rte
91
               # Evaluating the Loglikelihood
               self.ll[self.its] = self.log_likelihood(self.train,
93

    self.beta, self.theta)

94
               # Generating observations y
               self.predicted = np.dot(self.theta, self.beta.T)
               # In-sample MSE
               self.mse_train[self.its] = MSE(self.predicted,

    self.train)
```

```
# Out-of-sample MSE
101
                 if valid is not None:
102
                     self.mse_valid[self.its] = MSE(self.predicted,
103

    self.valid)

104
                 if abs(self.ll[self.its] - old_ll) > tol:
105
                     old_ll = self.ll[self.its]
106
                     self.its += 1
107
                     print(f"Iteration {self.its} completed.
108
                     → Log-likelihood: {self.ll[self.its-1]}")
                 else:
109
                     stop = True
110
111
112
113
            else:
114
                 toc1 = time.clock()
115
                 time1 = np.round(toc1 - tic,3)
                 if self.its < iterations:</pre>
117
                     print(f"Converged in {time1} seconds after
118
                     → {self.its} iterations. Log-likelihood:
                      else:
119
                     print(f"Stopped after {time1} seconds, {self.its}
120
                      → iterations. Log-likelihood:
                         {self.ll[self.its-1]}.")
121
122
123
        def recommend(self, test, t = 0.3):
124
125
             Using the fitted algorithm to make recommendations to
126
        users of our dataset.
127
            Parameters:
128
129
                 -t:float
                   Delta-threshold for activating recommendations
131
             111
132
            for u in range(self.U):
133
                 recomm = []
134
                 for i in range(self.I):
135
136
                     if self.predicted[u,i] > t:
                         recomm.append(i)
137
                 if [i > 0 for i in recomm]:
138
```

```
print(f"User {u} may also like these items:
139
                      140
141
        def initialize(self):
142
            self.gamma_shp = np.random.uniform(0,1, size = (self.U,
143
             \hookrightarrow self.K)) + self.a
            self.gamma_rte = np.repeat(self.a/self.b1,self.K) +
144
             → np.random.uniform(0,1, size = (self.U, self.K))
            self.k_rte = self.a1/self.b1 + np.random.uniform(0,1,
145

    self.U)

            self.k_shp = self.a1 + self.K*self.a
146
147
            self.lambda_shp = np.random.uniform(0,1, size = (self.I,

    self.K)) + self.c

            self.lambda_rte = np.repeat(self.c/self.d1,self.K) +

→ np.random.uniform(0,1, size = (self.I, self.K))
            self.tau_rte = self.c1/self.d1 + np.random.uniform(0,1,
             ⇔ self.I)
            self.tau_shp = self.c1 + self.K*self.c
151
             # Note that the parameters tau_shp and k_shp are not
152
             \rightarrow updated in the algorithm, so they are declared here.
153
            self.phi = np.zeros(shape=[self.U, self.I, self.K])
154
        def log_likelihood(self, train, beta, theta):
156
157
            Evaluating the log-likelihood
158
            self.train = train
160
            self.beta = beta
161
            self.theta = theta
162
            self.sumlog = 0
164
            self.prod = 1
165
            count_array = 0
166
            for u, i in zip(self.train.nonzero()[0],

    self.train.nonzero()[1]):

                 self.dot = float(np.dot(theta[u],beta[i].T))
168
                 self.dot_y = float(self.dot**train[u,i])
169
                 self.dot_y_fact =
170

    float(self.dot/np.math.factorial(train[u,i]))

171
                 self.logdot_y_fact = np.log(self.dot_y_fact)
                 self.sumlog += self.logdot_y_fact
172
                 count_array += 1
173
```

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