

Rospy Listener

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#!/usr/bin/python
import rospy
from std_msgs.msg import String

def callback(data):
    rospy.loginfo("I heard %s",data.data)

def listener():
    rospy.init_node('talker')
    rospy.Subscriber("chatter", String, callback)
    # spin() simply keeps python from exiting until this node is stopped
    rospy.spin()

if __name__ == "__main__":
    listener()
```