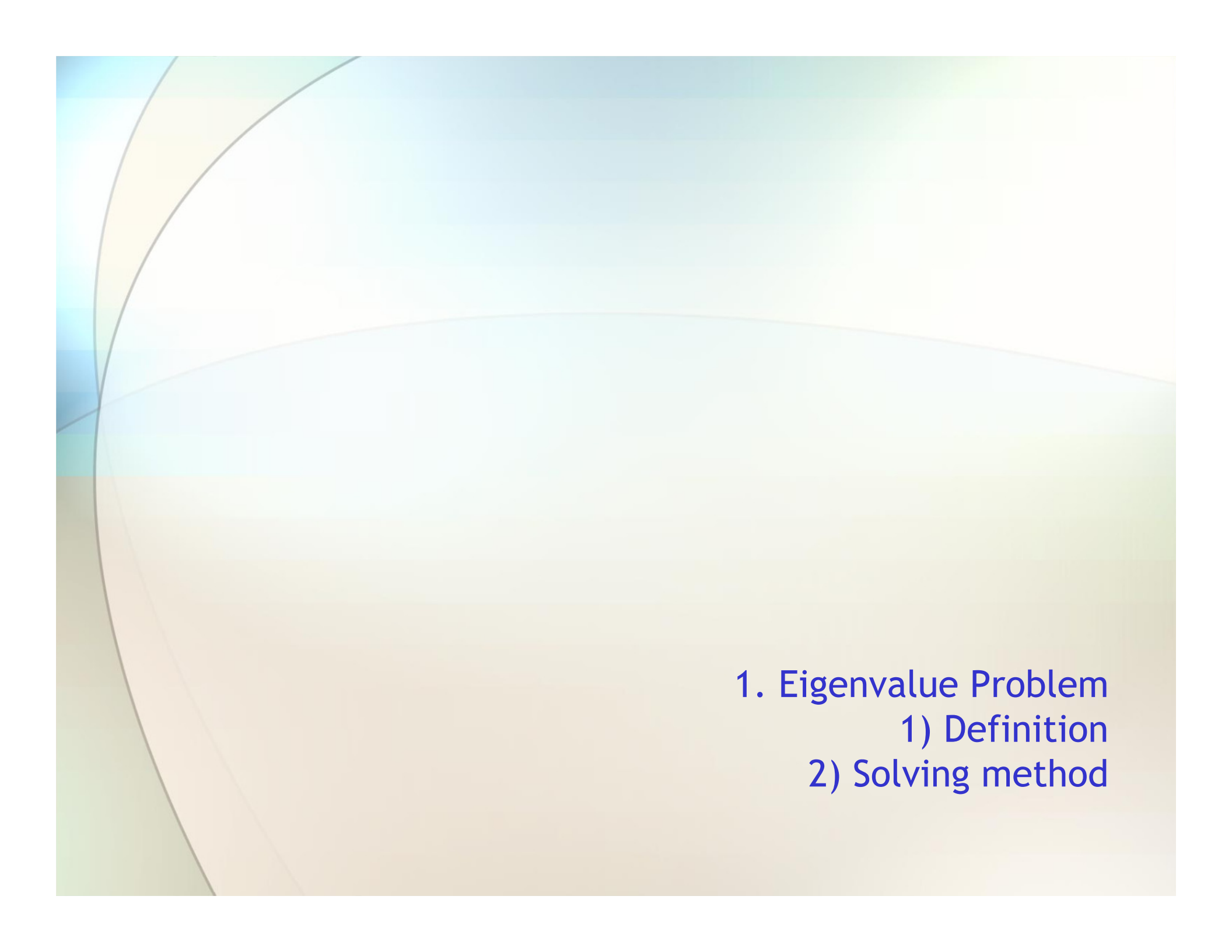




# Eigenvalues and Eigenvectors

with graphical representations

Reference: "Statistics and Data Analysis in Geology, 2<sup>nd</sup> ed., J.C. Davis

- 
- 1. Eigenvalue Problem
    - 1) Definition
    - 2) Solving method

# Definition: Eigenvalue Problem

Let's consider the following matrix form,

The vector of unknowns (the  $x_i$ 's)

some constant ( $\lambda$ )

$$[A] \cdot [X] = \lambda [X]$$

The matrix of coefficients (the  $a_{ij}$ 's)

the unknown vector itself

Our concern is to find values of  $\lambda$  that satisfy this relationship.

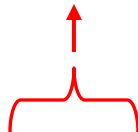
Above relation also can be written as...


$$([A] - \lambda[I]) \cdot [X] = [0] \quad \text{where } [I] \text{ is an identity matrix.}$$

—————→ Eigenvalue Problem!

## Solving Method: Eigenvalue Problems (2×2 case) - 1

$$\lambda[I] = \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$


$$([A] - \lambda[I]) \cdot [X] = [0]$$


$$(a_{11} - \lambda)x_1 + a_{12}x_2 = 0$$

$$a_{21}x_1 + (a_{22} - \lambda)x_2 = 0$$

Let's assume that there are solutions to these equations  
other than the trivial case where all the unknown  $x'_s = 0$ .

## Solving Method: Eigenvalue Problems ( $2 \times 2$ case) - 2

$$([A] - \lambda[I]) \cdot [X] = [0]$$

the determinant must be zero.



$$|A - \lambda I| = 0 = \begin{vmatrix} a_{11} - \lambda & a_{12} \\ a_{21} & a_{22} - \lambda \end{vmatrix}$$

$$(a_{11} - \lambda)(a_{22} - \lambda) - a_{12}a_{21} = 0$$

$$(a_{11}a_{22}) - (a_{21}a_{12}) - (a_{11}\lambda) - (a_{22}\lambda) + \lambda^2 = 0$$

$$\lambda^2 + \alpha_1\lambda + \alpha_2 = 0$$

For a quadratic equation,  $ax^2 + bx + c = 0$ , the general solution is  $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$



## 2. Numerical Examples for Eigenvalue Problem

# Numerical Examples of Eigenvalue Problems (2×2 case)

## Numerical Example 1

$$[A] = \begin{bmatrix} 3 & 6 \\ 6 & 3 \end{bmatrix}$$

Let's get the eigenvalues of matrix [A]

$$\begin{vmatrix} 3-\lambda & 6 \\ 6 & 3-\lambda \end{vmatrix} = 0$$

$$(3-\lambda)^2 - 6 \times 6 = 0$$

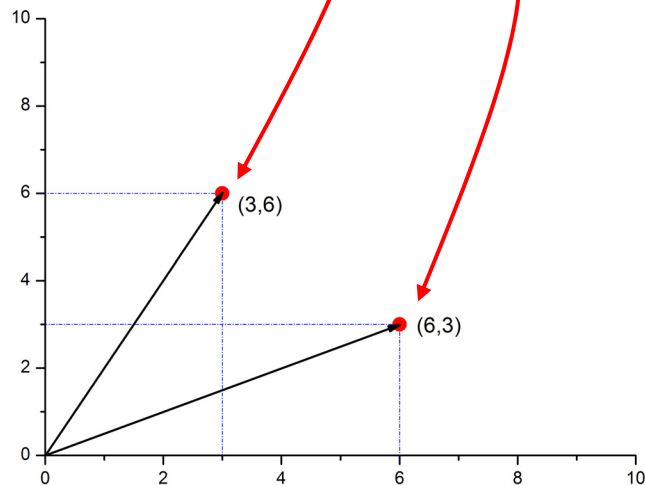
$$9 - 6\lambda + \lambda^2 - 36 = 0$$

$$\lambda^2 - 6\lambda - 27 = 0$$

$$(\lambda - 9)(\lambda + 3) = 0$$

$$\lambda_1 = 9, \lambda_2 = -3$$

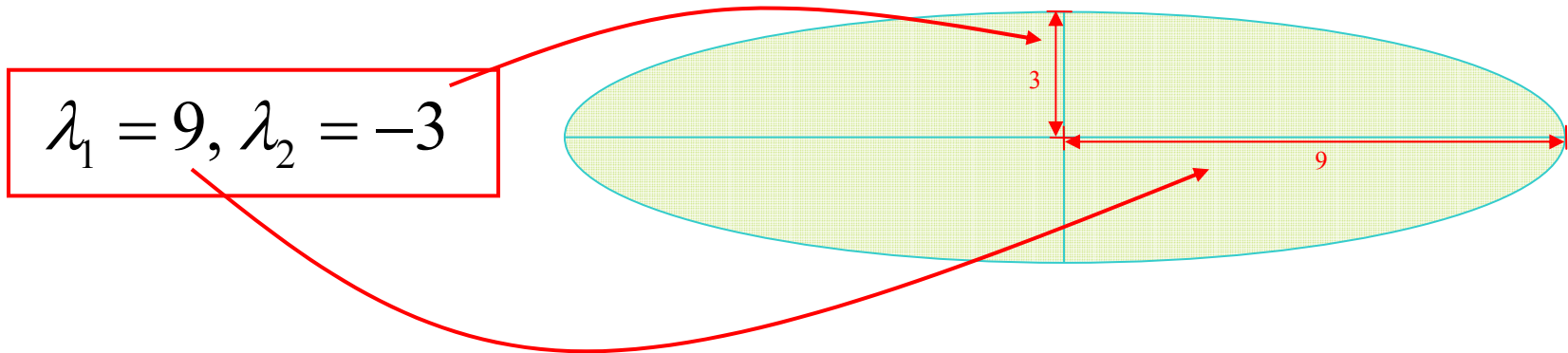
Two eigenvalues from  
2 variables



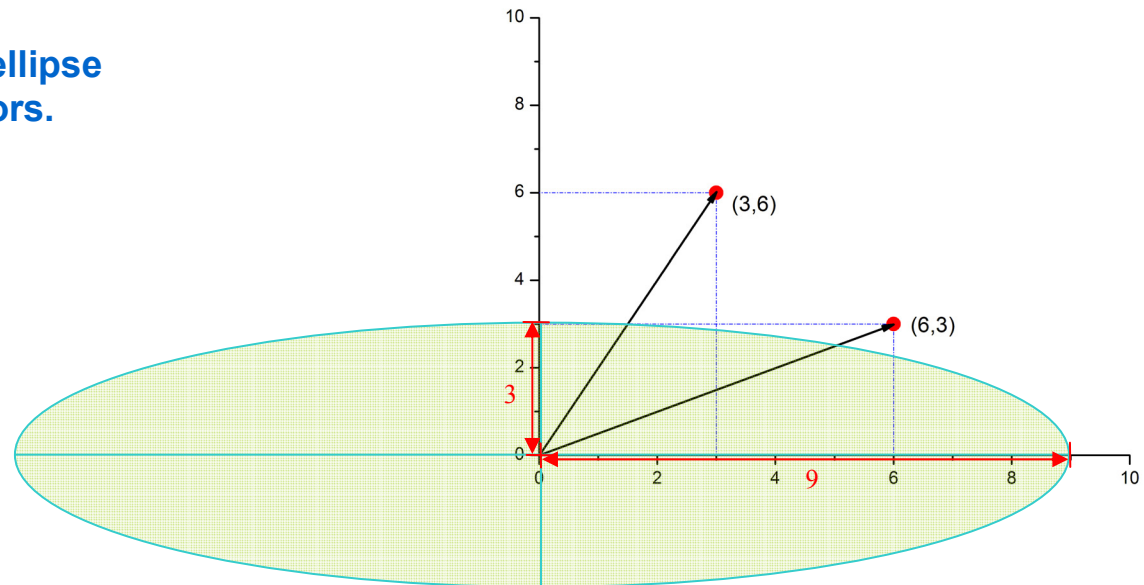
The eigenvalues represent the magnitudes, or lengths, of the major and minor axes of an ellipse.  
See Next Page!

# Numerical Example 1: Continued

The **eigenvalues** represent the **magnitudes, or lengths, of the major and minor axes of an ellipse.**



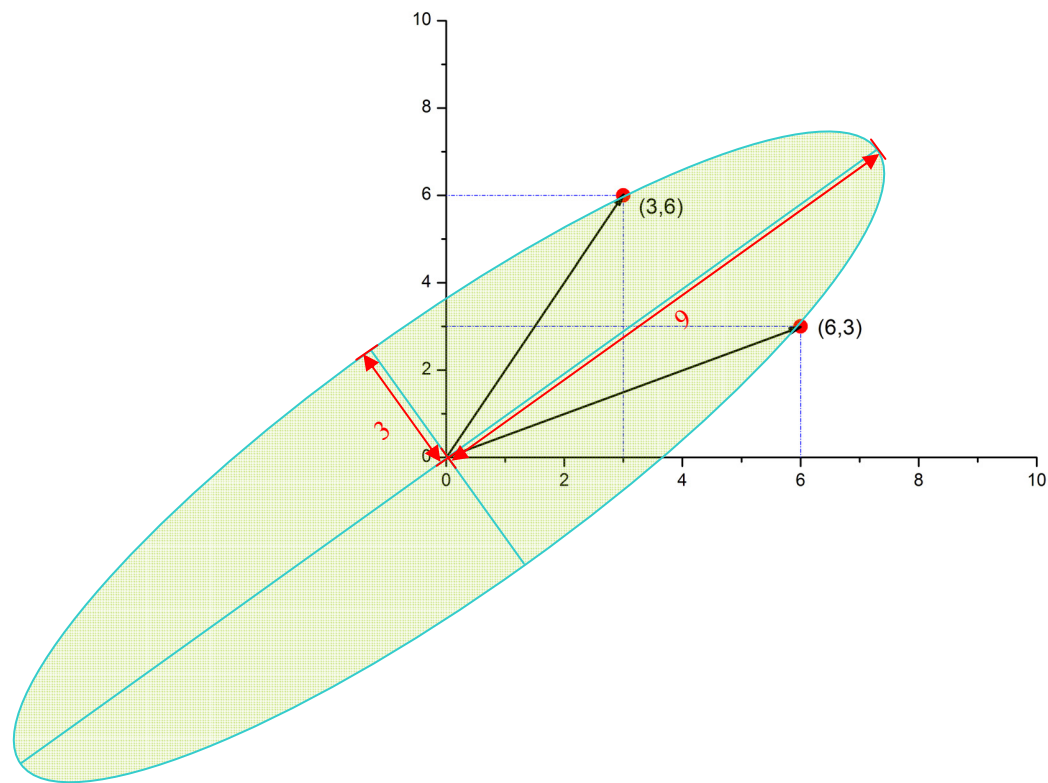
Let's overlap the center of ellipse  
onto **center** of the two vectors.





# Numerical Example 1: Continued

Then rotate the ellipse to its envelope can be on the two points.



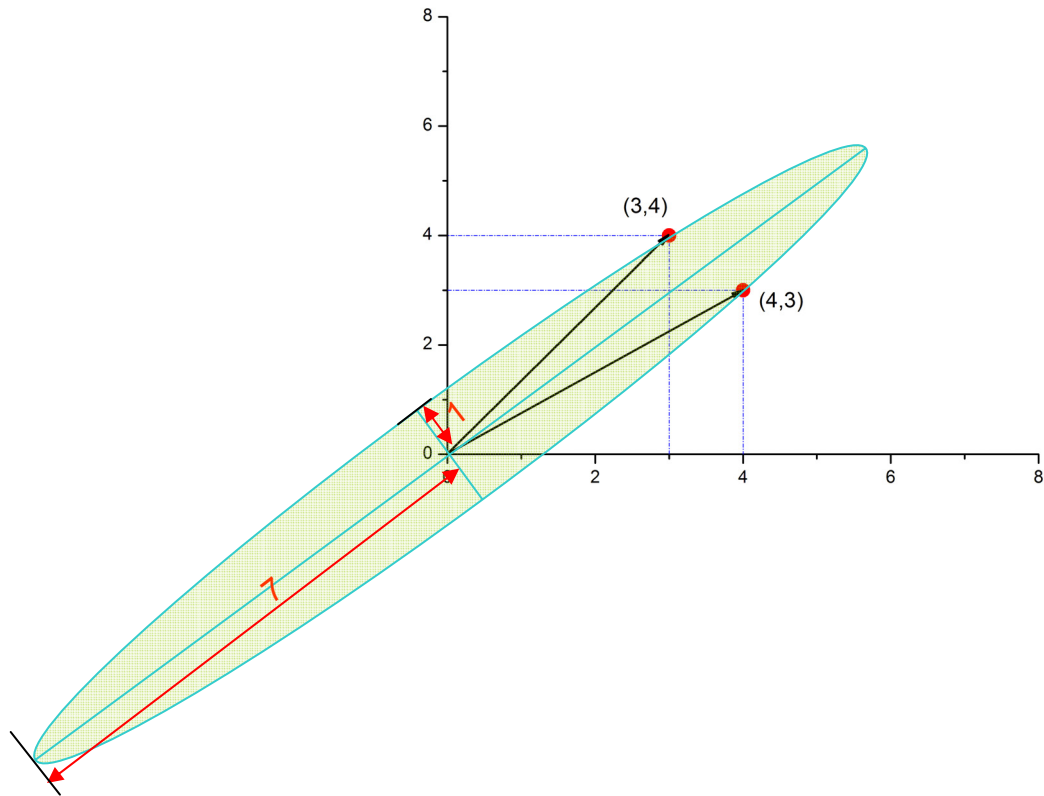
## Numerical Example 2.

If the two points are closer than the case of numerical example 1,

$$[A] = \begin{bmatrix} 3 & 4 \\ 4 & 3 \end{bmatrix}$$

Then the eigenvalues are

$$\lambda_1 = 7, \lambda_2 = -1$$



The sum of the eigenvalues( $=\lambda_1 + \lambda_2 = 7 - 1 = 6$ ) is always equal to the sum of the diagonal elements( $3 + 3$ ), i.e. trace of the original matrix.

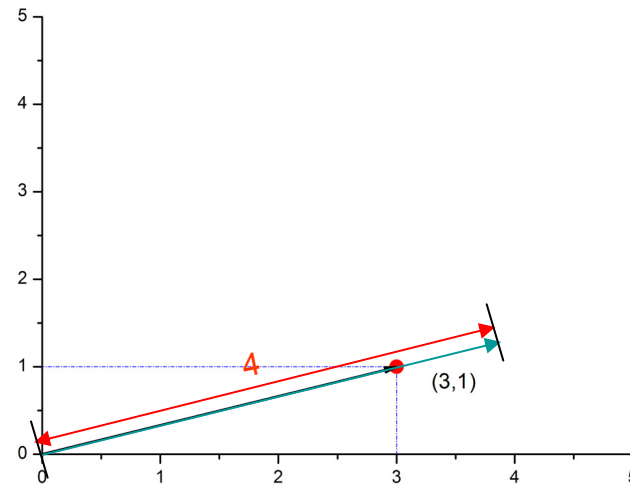
## Numerical Example 3.

If the two points are identical,

$$[A] = \begin{bmatrix} 3 & 1 \\ 3 & 1 \end{bmatrix}$$

Then the eigenvalues are

$$\lambda_1 = 4, \lambda_2 = 0$$



The sum of the eigenvalues is always equal to the sum of the diagonal elements, i.e. trace of the original matrix.

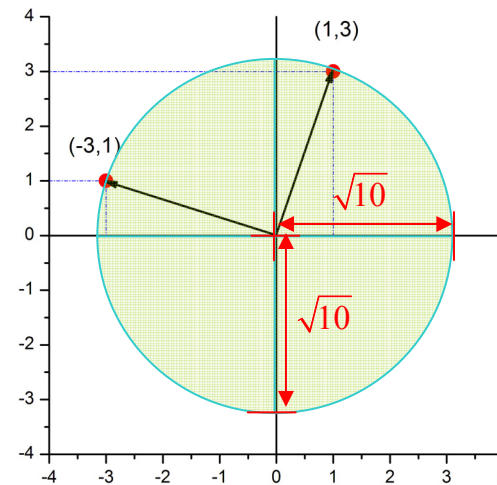
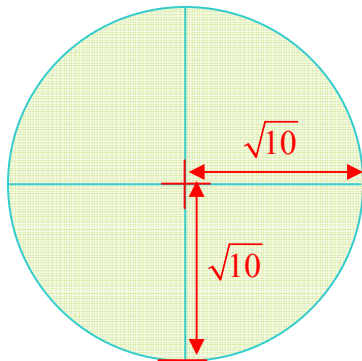
## Numerical Example 4.

If the two points are perpendicular to one another,

$$[A] = \begin{bmatrix} -3 & 1 \\ 1 & 3 \end{bmatrix}$$

Then the eigenvalues are

$$\lambda_1 = \sqrt{10}, \lambda_2 = -\sqrt{10}$$



The sum of the eigenvalues is always equal to the sum of the diagonal elements, i.e. trace of the original matrix.



### 3. Eigenvector Problem

# Eigenvector Problems with Numerical Example 1

We already calculated eigenvalues in example 1

$$[A] = \begin{bmatrix} 3 & 6 \\ 6 & 3 \end{bmatrix} \text{ with } \lambda_1 = 9, \lambda_2 = -3$$

For  $\lambda_1 = 9$

$$\begin{bmatrix} a_{11} - \lambda_1 & a_{12} \\ a_{21} & a_{22} - \lambda_1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3-9 & 6 \\ 6 & 3-9 \end{bmatrix} = \begin{bmatrix} -6 & 6 \\ 6 & -6 \end{bmatrix}$$

$$\begin{bmatrix} -6 & 6 \\ 6 & -6 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Eigenvector

**Eigenvector of the largest eigenvalue represents  
a slope of the major axis of ellipse**

## Eigenvector Problems with Numerical Example 1 (continued)

For  $\lambda_2 = -3$

$$\begin{bmatrix} a_{11} - \lambda_1 & a_{12} \\ a_{21} & a_{22} - \lambda_1 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 - (-3) & 6 \\ 6 & 3 - (-3) \end{bmatrix} = \begin{bmatrix} 6 & 6 \\ 6 & 6 \end{bmatrix}$$

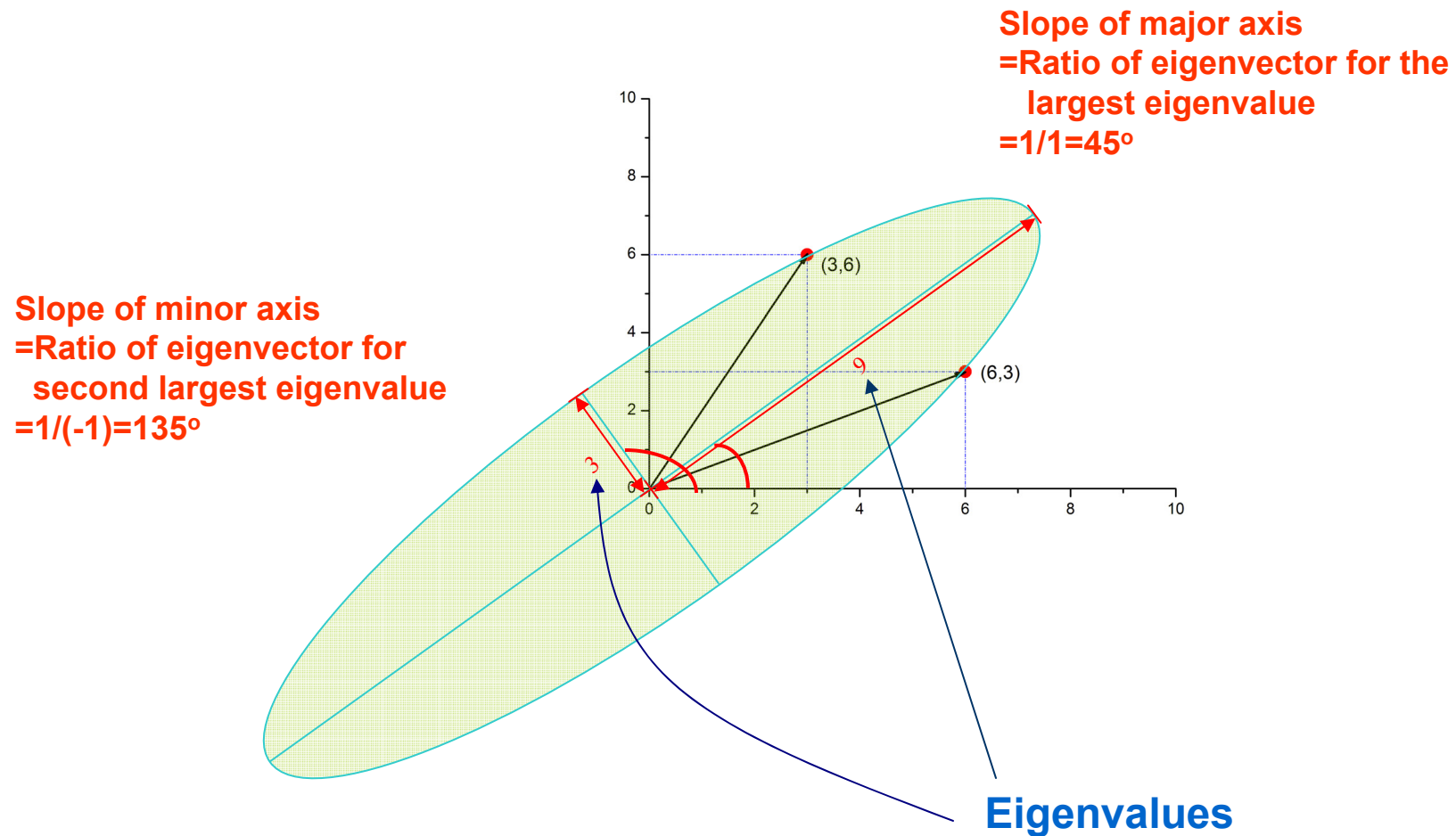
$$\begin{bmatrix} 6 & 6 \\ 6 & 6 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

**Eigenvector**

**The eigenvector of second largest eigenvalue represents a slope of the minor axis of ellipse**

# Eigenvector Problems with Numerical Example 1 (continued)



For symmetric matrices, their eigenvectors always are at right angles to each other: **ORTHOGONAL!!!**