

XAVIER POLISETTY

COMPUTER SCIENCE | TAMU '22

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PROFESSIONAL

AMERICAN EXPRESS • SOFTWARE ENGINEERING INTERN • JULY '20 – AUGUST '20

Created API allowing relational database used in global financial compliance to query the internal big data ecosystem. Constructed using Python, Spark, SQL, Hive, and SQOOP, collaborated using Agile.

DALLAS TEXAS CONSULTANTS • MARKETING INTERN • MAY '19 - AUGUST '19

Presented AT&T services to residential customers. Promoted to leadership after 3 weeks. As leader, recruited and developed entry level employees.

NET 360 • AGGIES INVENT (SPONSORED BY NSA) • OCT. '18

Developed NET 360, a virtual reality solution to handle data overflow in Network Operation Centers, with a team of 5 other undergrad and grad students. Achieved 1st place during the 48-hour competition, earning \$1000 and the support to further develop NET 360 for future commercialization.

LAKESIDE ELECTRONICS DOCTOR (LED) • JUN. '17 - CURRENT

Created Lakeside Electronics Doctor, a tech help company designed to provide affordable, in-home help to residents in need. Grew business by soliciting new customers and growing network through referrals.

EDUCATION

TEXAS A&M UNIVERSITY • GPA: 3.71 • AUG. '18 - CURRENT

Majoring in Computer Science at Texas A&M University. Enrolled in University Honors. Planned minors in French and Economics. Expected graduation in May of 2022.

CISTERCIAN PREP SCHOOL • GPA: 4.56 • AUG. '14 - MAY '18

Graduated 4th in high school class. Earned a score of 36 on ACT.

ORGANIZATIONS

AGGIES SERVING IN SELFLESSLY SHAPING TOMORROW (ASSIST) • AUG. '18 - MAY '19

Selected for ASSIST, a service-based Freshman Leadership Organization, after competitive application and interview process. Selected committee philanthropy for 2019 and led organization-wide service projects.

GILBERT LEADERSHIP CONFERENCE • NOV. '18

Selected after competitive application and interview process for 4-day leadership conference held in Dallas.

FIRST ROBOTICS • DEC. '16 - APR. '18

Led Robotics team to the 2018 FIRST Robotics Worlds Championship. Designed, built, and programmed robot to compete against other robots in certain challenges, using both an autonomous and teleoperated mode.