

PLL Transient response - Leonardo Vazquez

February 23, 2022

1 PLL Transient response

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[1]: import matplotlib.pyplot as plt
import matplotlib as mpl
import numpy as np
from scipy import signal

[2]: # Constants
RC = 2.2*10**(-5)
KC = 3.2
K0 = 4775
K = 1/K0

wn2 = RC*KC*K0
e_1 = 0.7
e_2 = 0.1

[3]: # The system
sys1 = signal.lti([K], [RC/(KC*K0), 1/(KC*K0), 1])
sys2 = signal.lti([K], [wn2, e_1 * 2 / wn2 ** 0.5, 1])
sys3 = signal.lti([K], [wn2, e_2 * 2 / wn2 ** 0.5, 1])

[4]: # Transient response
t, y1 = signal.step2(sys1)
t, y2 = signal.step2(sys2)
t, y3 = signal.step2(sys3)

[5]: plt.plot(t, (110*10**3)*y1, color="blue", linewidth=2, linestyle="--", label="e_1 ↵
↵= 0.89")
plt.plot(t, (110*10**3)*y2, color="red", linewidth=2, linestyle="--", ↵
↵label="e=0.7")
plt.plot(t, (110*10**3)*y3, color="green", linewidth=2, linestyle="--", ↵
↵label="e=0.1")

plt.legend(loc='upper right')
plt.xlabel('Time t(s)')
plt.ylabel('Out Vd(V)')
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[5]: Text(0, 0.5, 'Out Vd(V)')

