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1.1

Yes. It is -i. No, just this.

1.2

No. k cannot be orthogonal to both vectors in a 2D plane.

1.3

Both will have an infinite amount of possible vectors.

2.

$$\det(A) = x_1 y_2 + x_3 y_1 + x_2 y_3 - x_3 y_2 - x_1 y_3 - x_3 y_2$$

$$Area = \frac{1}{2} |u \times v| = \frac{1}{2} \begin{bmatrix} x_1 - x_2 \\ y_1 - y_2 \\ 1 - 1 \end{bmatrix} \times \begin{bmatrix} x_3 - x_2 \\ y_3 - y_2 \\ 1 - 1 \end{bmatrix} = \frac{1}{2} |x_1 y_2 + x_3 y_1 + x_2 y_3 - x_3 y_2 - x_1 y_3 - x_3 y_2 |$$

The value would be 0. Yes. Because the 0 is unique.

- 3. Plug in the two points on the matrix including a,b,c and set the determinant to 0. Solve.
- 4.

$$u \times v = \begin{bmatrix} i & j & k \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{bmatrix} = (u_2 v_3 i + u_3 v_1 j + u_1 v_2 k) - (u_3 v_2 i + u_1 v_3 j + u_2 v_1 k)$$

As we can see, if i and j in $\{i, j, k\}$ matches the order of subscripts u_i and v_j , then it will hold its respective vector.

5.

$$\det(A) = \det\begin{bmatrix} x_2 & x_3 & x_4 \\ y_2 & y_3 & y_4 \\ z_2 & z_3 & z_4 \end{bmatrix} - \det\begin{bmatrix} x_1 & x_3 & x_4 \\ y_1 & y_3 & y_4 \\ z_1 & z_3 & z_4 \end{bmatrix} + \det\begin{bmatrix} x_1 & x_2 & x_4 \\ y_1 & y_2 & y_4 \\ z_1 & z_2 & z_4 \end{bmatrix} - \det\begin{bmatrix} x_1 & x_2 & x_3 \\ y_1 & y_2 & y_3 \\ z_1 & z_2 & z_3 \end{bmatrix}$$

$$V = \frac{\begin{bmatrix} x_1 - x_4 \\ y_1 - y_4 \\ z_1 - z_4 \\ 1 - 1 \end{bmatrix} \cdot \begin{pmatrix} \begin{bmatrix} x_2 - x_4 \\ y_2 - y_4 \\ z_2 - z_4 \\ 1 - 1 \end{bmatrix} \times \begin{bmatrix} x_3 - x_4 \\ y_3 - y_4 \\ z_3 - z_4 \\ 1 - 1 \end{bmatrix}}{6}$$

The determinant is 0 when all points lie on a plane as they would not form a tetrahedron.

6. Plug in the 4 points on the matrix and set the determinant to 0. Solve.

7. It is a vector orthogonal between the cross product two vector. It is also the area. The relationship of n and $p-p_0$ in terms of the dot product is the volume. As seen in questions 5 and 6, if the dot product of the cross product vector of the 3 points is 0, then the volume is 0 and thus, it must be on the plane.

8.

$$\begin{split} M(\theta) &= \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \\ M^{-1}(\theta) &= \frac{1}{\cos^2 \theta + \sin^2 \theta} \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \\ M^T(\theta) &= \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \end{split}$$

$$\begin{split} M(\theta_1 + \theta_2) &= M(\theta_1) M(\theta_2) \\ \left[\begin{matrix} \cos \theta_1 + \theta_2 & \sin \theta_1 + \theta_2 \\ -\sin \theta_1 + \theta_2 & \cos \theta_1 + \theta_2 \end{matrix} \right] &= \left[\begin{matrix} \cos \theta_1 \cos \theta_2 - \sin \theta_1 \sin \theta_2 & \cos \theta_1 \sin \theta_2 + \sin \theta_1 \cos \theta_2 \\ -\sin \theta_1 \cos \theta_2 - \cos \theta_1 \sin \theta_2 & -\sin \theta_1 \sin \theta_2 + \cos \theta_1 \cos \theta_2 \end{matrix} \right] \\ &= \left[\begin{matrix} \cos \theta_1 & \sin \theta_1 \\ -\sin \theta_1 & \cos \theta_1 \end{matrix} \right] \left[\begin{matrix} \cos \theta_2 & \sin \theta_2 \\ -\sin \theta_2 & \cos \theta_2 \end{matrix} \right] \\ M(-\theta) &= M(\theta - \pi) &= M(\theta) M(\pi) = \left[\begin{matrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{matrix} \right] \left[\begin{matrix} 1 & 0 \\ 0 & 1 \end{matrix} \right] = \left[\begin{matrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{matrix} \right] \end{split}$$

A sphere.

9.

$$M = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$Mx_1 = b_1, \qquad \begin{bmatrix} (a+b)(x_{1-1} + x_{1-2}) \\ (c+d)(x_{1-1} + x_{1-2}) \end{bmatrix} = \begin{bmatrix} b_{1-1} \\ b_{1-2} \end{bmatrix}$$

$$Mx_2 = b_2, \qquad \begin{bmatrix} (a+b)(x_{2-1} + x_{2-2}) \\ (c+d)(x_{2-1} + x_{2-2}) \end{bmatrix} = \begin{bmatrix} b_{2-1} \\ b_{2-2} \end{bmatrix}$$

Solve the system of linear equations to find abcd. Then apply to Mx_3 .

10.

$$(1-t)p_1 + tp_2$$

 $(1-s-t)p_1 + tp_2 + sp_3$

For (a), all points include $t = [-\infty, \infty]$.

For (b), t >

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11.

$$M = \begin{bmatrix} a & b \\ b & c \end{bmatrix}, \quad x = \begin{bmatrix} x \\ y \end{bmatrix}$$
$$x^{T}Mx = ax^{2} - 2bxy + cy^{2}$$

The matrix is an ellipsoid, thus it can be anywhere in the range between 0 and the max eigenvalue, which is the longest length.

$$Mx = \lambda x = 0, \qquad \lambda = 0$$

The matrix is a hyperboloid, so there exists a vector that is the center.

The both eigenvalues must both be positive.

12.

$$\det(M - \lambda I) = 0$$

$$\det\begin{bmatrix} a - \lambda & b \\ c & d - \lambda \end{bmatrix} = \lambda^2 - (a\lambda + d\lambda) + (ac - cd) = \lambda^2 - trace(M)\lambda + \det(M)$$