

CS189/CS289A

Introduction to Machine Learning

Lecture 8: More on the Multivariate Normal Distribution

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February 12, 2015

- Review: Diagonal covariance matrices.

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- Non-diagonal covariance and diagonalization.

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- Symmetric: $\Sigma_{i,j} = \Sigma_{j,i}$.
- Non-negative diagonal entries: $\Sigma_{i,i} \geq 0$.
- Positive semidefinite: for all $v \in \mathbb{R}^d$, $v' \Sigma v \geq 0$.

Review: Diagonal covariance

Consider $X \sim N(\mu, \Sigma)$ where Σ is diagonal:

$$\Sigma = \begin{bmatrix} \sigma_1^2 & 0 & \cdots & 0 \\ 0 & \sigma_2^2 & & 0 \\ \vdots & & \ddots & \vdots \\ 0 & 0 & \cdots & \sigma_d^2 \end{bmatrix}.$$

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Consider the super-level sets of the pdf:

$$\mathcal{E}_r = \left\{ x \in \mathbb{R}^d : (x - \mu)' \Sigma^{-1} (x - \mu) \leq r^2 \right\}$$

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correspond to *axis-aligned ellipsoids* in \mathbb{R}^d , of length $2r\sigma_i$ in the x_i direction.

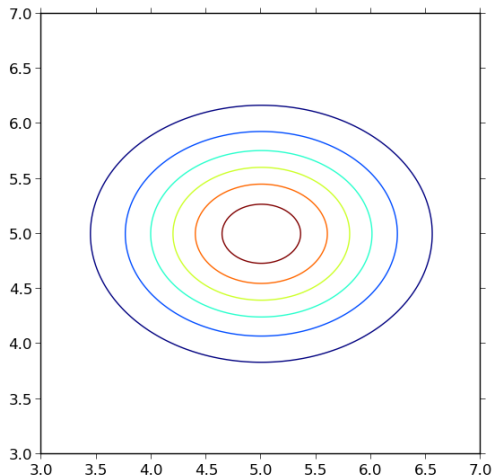
The volume of \mathcal{E}_r is proportional to $\prod_{i=1}^d \sigma_i = \sqrt{|\Sigma|}$.

Hence, for a fixed r , $\Pr(\mathcal{E}_r)$ does not depend on μ and Σ (but does depend on d).

Review: Diagonal covariance

$$\mu = \begin{bmatrix} 5.0 \\ 5.0 \end{bmatrix}$$

$$\Sigma = \begin{bmatrix} 0.8 & 0.0 \\ 0.0 & 0.6 \end{bmatrix}$$



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where Q is a matrix that corresponds to a rotation about the origin.

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e.g. $Q = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

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This leaves the mean unchanged:

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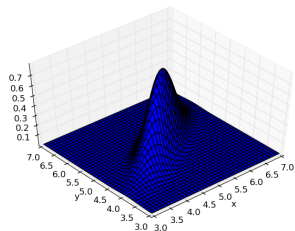
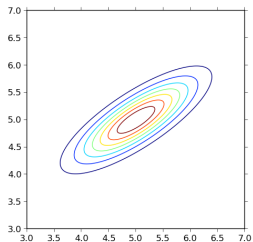
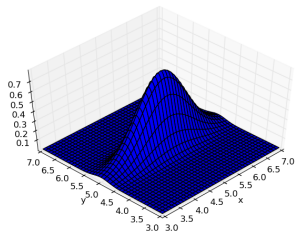
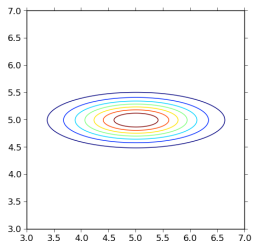
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It is no longer diagonal.

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Eigenvalues and eigenvectors

For a square matrix A , λ is an *eigenvalue* and x is an *eigenvector* if

$$Ax = \lambda x.$$

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(Eigenvalues are roots of the *characteristic polynomial*, $\det(A - \lambda I)$.)

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For a symmetric real matrix $A \in \mathbb{R}^{n \times n}$, we can find n orthonormal eigenvectors of A (v_1, \dots, v_n), and the eigenvalues ($\lambda_1, \dots, \lambda_n$) are real.

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$$AU = U\Lambda, \quad A = U\Lambda U',$$

(this is called *diagonalization*), where

$$U = [v_1 \quad v_2 \quad \cdots \quad v_n], \quad \Lambda = \text{diag} \left(\begin{bmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_n \end{bmatrix} \right).$$

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(Why “hence”? $U'U = I$, so $UU' = I$.)

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Also, the *precision matrix* can be written

$$\Sigma^{-1} = U\Lambda^{-1}U'.$$

(Check!)

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Gaussian pdf

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In this new basis, the covariance is the diagonal matrix Λ^{-1} .

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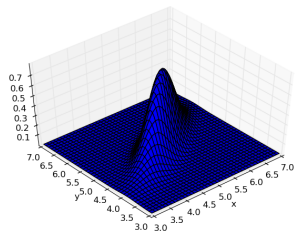
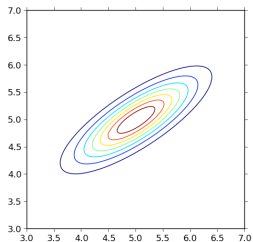
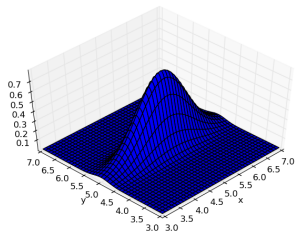
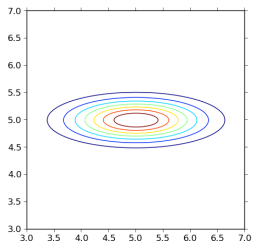
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$$(v_1(x - \mu))^2 \leq r^2 \lambda_1^2 \quad \Leftrightarrow \quad |v_1(x - \mu)| \leq r \lambda_1.$$

This is the same as the diagonal case, but with a new coordinate system, defined by the eigenvectors.

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(As in the diagonal case.)

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Probability measure

$$\int_{\mathbb{R}^d} p(x; \mu, \Sigma) dx = 1.$$

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Covariance

$$\text{Cov}[X] = \mathbb{E}[(X - \mu)(X - \mu)'] = \int_{\mathbb{R}^d} (x - \mu)(x - \mu)' p(x; \mu, \Sigma) dx = \Sigma.$$

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- NB: Adding the random variables, not the densities!
This corresponds to *convolving* the densities.
The family of Gaussian densities is closed under convolutions.

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The family of Gaussian densities is closed under convolutions.
- Since $X + Y$ is Gaussian, we only need its mean and covariance.

Properties of multivariate Gaussians

Sum of two scalar standard normals: completing the square

$$\begin{aligned} p_{X+Y}(z) &= \int p_X(x) p_Y(z-x) dx = (p_X * p_Y)(z) \\ &= \frac{1}{2\pi} \int \exp\left(-\frac{1}{2} (2x^2 - 2xz + z^2)\right) dx \\ &= \frac{1}{2\pi} \int \exp\left(-\frac{1}{2} (2(x - z/2)^2 - z^2/2 + z^2)\right) dx \\ &= \frac{\exp(-z^2/4)}{\sqrt{2\pi} \cdot 2} \frac{1}{\sqrt{2\pi/2}} \int \exp\left(-\frac{1}{2} \left(\frac{(x - z/2)^2}{1/2}\right)\right) dx \\ &= \frac{\exp(-z^2/4)}{\sqrt{2\pi} \cdot 2} \quad \text{i.e., } \mathcal{N}(0, 2). \end{aligned}$$

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But (X, Y) is not jointly Gaussian.

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But (X, Y) is not jointly Gaussian.

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And $X + Y$ is not Gaussian.

(Check!)

And, replacing the threshold 1 with a suitable constant, we can ensure that X , Y are uncorrelated but dependent.

(Check!)

Properties of multivariate Gaussians

Marginals

Given a d -dimensional Gaussian $X \sim \mathcal{N}(\mu, \Sigma)$, write

$$X = \begin{bmatrix} Y \\ Z \end{bmatrix}, \quad \mu = \begin{bmatrix} \mu_Y \\ \mu_Z \end{bmatrix}, \quad \Sigma = \begin{bmatrix} \Sigma_{YY} & \Sigma_{YZ} \\ \Sigma_{ZY} & \Sigma_{ZZ} \end{bmatrix},$$

where $Y \in \mathbb{R}^m$ and $Z \in \mathbb{R}^{d-m}$.

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- The mean and covariance of Y are immediate from the definitions.
- To show that Y has a Gaussian distribution, we write its density as an integral (integrating out the Z variables), *complete the squares* to compute the integral, and recognize the answer as a normal density. (And necessarily it's a $\mathcal{N}(\mu_Y, \Sigma_{YY})$ density.)

Properties of multivariate Gaussians

Affine transformations

Given a d -dimensional Gaussian $X \sim \mathcal{N}(\mu, \Sigma^2)$, matrix $A \in \mathbb{R}^{m \times d}$ and vector $b \in \mathbb{R}^m$, define

$$Y = AX + b.$$

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Properties of multivariate Gaussians

Example

Given a d -dimensional standard normal $X \sim \mathcal{N}(0, I)$, we have

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This is called *whitening* X .

What is $\Sigma^{-1/2}$? We can write $\Sigma = U\Lambda U'$ for U with orthonormal columns and Λ diagonal. Then defining $\Sigma^{-1/2} = U\Lambda^{-1/2}U'$, we have

$$\Sigma^{-1/2}\Sigma^{-1/2} = U\Lambda^{-1/2}U'U\Lambda^{-1/2}U' = U\Lambda^{-1}U' = \Sigma^{-1}.$$

- Review: Diagonal covariance matrices.
- Non-diagonal covariance and diagonalization.
- Properties of multivariate Gaussians.
- **Estimating Gaussians.**

Gaussian Estimation

- Work with the log likelihood:

$$\ell(\mu, \sigma^2) = \log \left(\prod_{i=1}^n \left(\frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left(-\frac{(x_i - \mu)^2}{2\sigma^2} \right) \right) \right)$$

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Set $\nabla \ell(\theta) = 0$ and solve.

Maximum likelihood

Gaussian maximum likelihood estimation

$\nabla \ell(\theta) = 0$ for

$$\mu = \frac{1}{n} \sum_{i=1}^n x_i,$$

$$\frac{n}{2\sigma^2} = \frac{1}{2\sigma^4} \sum_{i=1}^n (x_i - \mu)^2$$

$$\sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \mu)^2.$$

Other estimators for Gaussian parameters

Gaussian Estimation

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Gaussian Estimation

- We can also use penalized maximum likelihood estimators:

$$\begin{aligned} & \ell(\mu, \sigma^2) - \text{penalty}(\mu, \sigma^2) \\ &= \log \left(\prod_{i=1}^n \left(\frac{1}{(2\pi\sigma^2)^{1/2}} \exp \left(-\frac{(x_i - \mu)^2}{2\sigma^2} \right) \right) \right) - \text{penalty}(\mu, \sigma^2) \end{aligned}$$

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- And Bayesian estimators:

$$\begin{aligned} \text{prior distribution:} & \quad \pi(\theta) = 1 \\ \text{posterior distribution:} & \quad p(\theta|X_1 = x_1) \propto \underbrace{p(X_1 = x_1|\theta)}_{\text{likelihood}} \underbrace{\pi(\theta)}_{\text{prior}} \\ & \quad = \frac{p(X_1 = x_1|\theta)\pi(\theta)}{\int p(X_1 = x_1|q) d\pi(q)} \end{aligned}$$

Gaussian Estimation

- Penalized maximum likelihood estimators and Bayesian estimators are particularly effective in the high-dimensional setting, when the number of parameters is large compared to the amount of data.

Multivariate Gaussian Estimation

- Log likelihood:

$$\ell(\mu, \Sigma) = \log \left(\prod_{i=1}^n \left(\frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp \left(-\frac{1}{2} (x_i - \mu)' \Sigma^{-1} (x_i - \mu) \right) \right) \right)$$

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Set $\nabla \ell(\theta) = 0$ and solve.

Maximum likelihood

Gaussian maximum likelihood estimation

$\nabla_{\mu} \ell(\mu, \Sigma) = 0$ for

$$\sum_{i=1}^n \Sigma^{-1}(\mu - x_i) = 0$$

$$\text{check: } \nabla_{\mu}^2 \ell = -\frac{n}{2} \Sigma^{-1}$$

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i. \quad (\text{sample mean})$$

And it's possible to show that the maximum of $\ell(\mu, \Sigma)$ occurs at

$$\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})(x_i - \hat{\mu})'. \quad (\text{sample covariance})$$

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