

Human Activity Recognition

Deep Learning Lab



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Human Activity Recognition

- Input Pipeline

- Model

- Training and hyperparameter optimization

- Evaluation and Visualization

- Conclusions

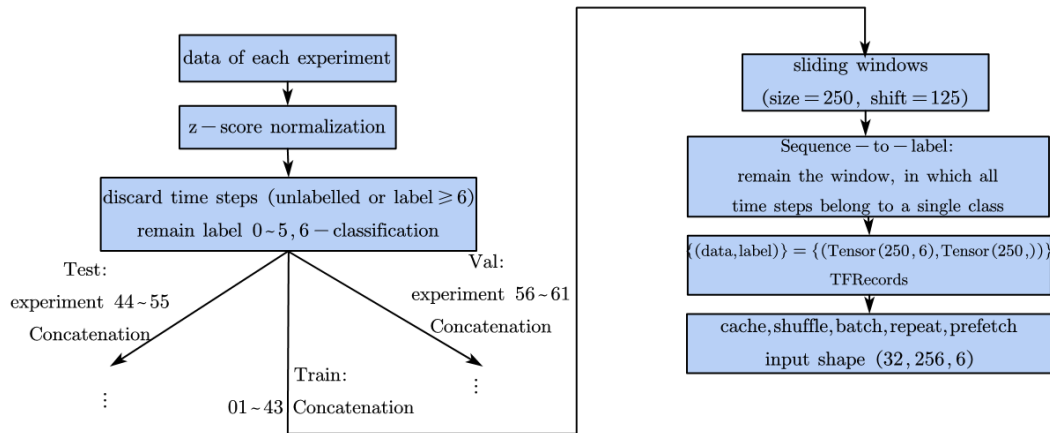


Figure: Input Pipeline

- Selection of classification tasks
 - Sequence-to-Label (S2L) classification tasks
- LSTM
 - LSTM blocks: which include one LSTM layer, one BN layer to avoid overfitting, and use tanh as the activation function
 - Each LSTM Block returns a sequence result
 - Dropout layer
 - Pooling layer and dense layer to get a certain label
- GRU
 - GRU blocks: which include one GRU layer, one BN layer to avoid overfitting, and use tanh as the activation function
 - Each GRU Block returns a sequence result
 - Dropout layer
 - Pooling layer and dense layer to get a certain label

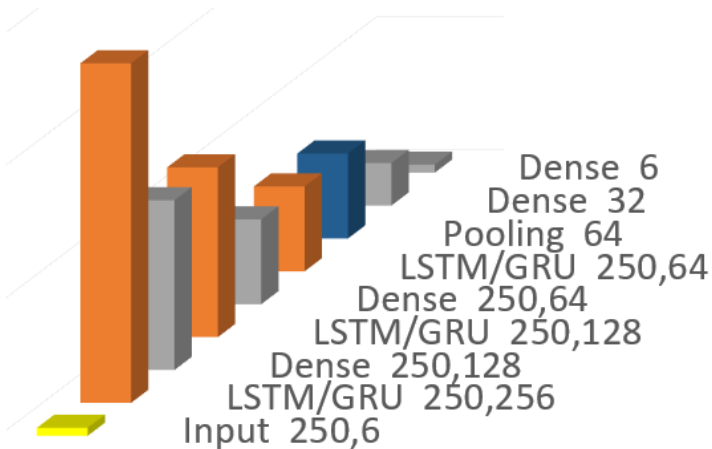


Figure: Model architecture

- Training
 - Loss function: sparse categorical cross entropy
 - Optimizer: Adam
- Hyperparameter optimization
 - Hyperparameter tuning for LSTM/GRU

Table: Some results of hyperparameter tuning

Trial	1	2
Block type	GRU	LSTM
Pooling type	GlobalMax	GlobalMax
Total steps	7500	4000
Learning rate	6.58e-5	5.40e-5
Dropout rate	0.44	0.31
Val accuracy	94.05%	93.83%

- Feed the sliding windows without overlap into the model
- The predict part is thinner than the ground truth
- The prediction fits well with the ground truth

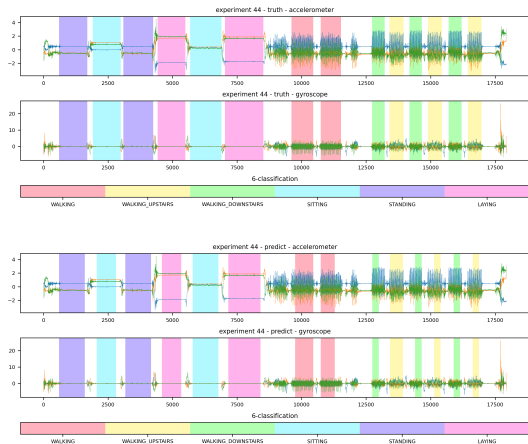


Figure: Ground Truth and Prediction

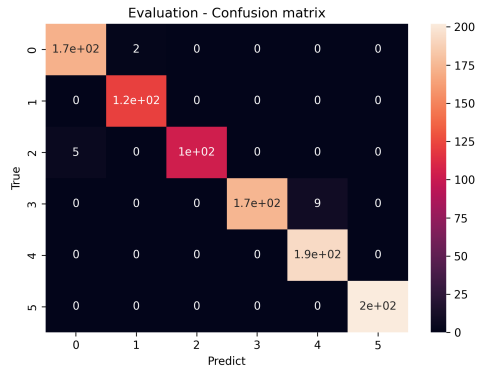


Figure: Confusion Matrix

- At the end, we choose GRU model, we can see that the prediction fits well with the ground truth

Table: Final result

Model	Test accuracy
GRU	98.3%

- The original dataset is highly imbalanced. After we drop out the data of postural transitions, we can get a good result of the human activity recognition task