Applied Bayesian Modeling module 3: Bayesian inference for 1 continuous parameter "Everything's normal"

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Recap from modules 1 and 2: introduction to Bayesian inference

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- We draw statistical conclusions about parameters of interest using probability statements.
- ▶ General approach for some outcome of interest θ , i.e. regression coefficient, is based on learning via Bayes' rule
 - \blacktriangleright start off with *prior* probability distribution to quantify information related to θ
 - collect data, and use Bayes' rule to update the prior into the posterior distribution
 - use posterior distribution to draw conclusions

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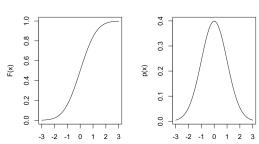
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 - ► Inference using radon data

A probability distribution for a continuous random variable (RV) X can be defined using its cumulative distribution function (cdf) F(x) and its probability density function (pdf) p(x) with:

$$F(x) = Pr(X \le x) = \int_{-\infty}^{x} p(x')dx'.$$

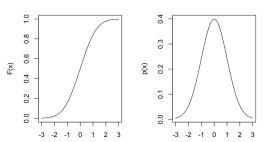




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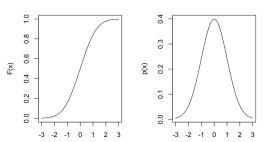




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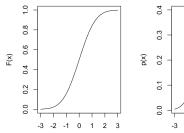


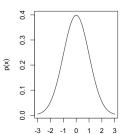


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Main differences between discrete and continuous pdfs:

- ightharpoonup p(x) is NOT the probability that X=x,
- ► Sums are replaced by integrals • • • •

A joint probability distribution for two continuous RVs X and Y can be defined using their joint cdf $F_{X,Y}(x,y)$ and joint pdf $p_{X,Y}(x,y)$:

$$F_{X,Y}(x,y) = Pr(X \le x \cap Y \le y) = \int_{x'=-\infty}^{x} \int_{y'=-\infty}^{y} p_{X,Y}(x',y') dx' dy'.$$

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- ► Conditional pdf is defined as p(x|y) = p(x,y)/p(y)
- From the definition of conditional pdf's, we can obtain Bayes' rule:

$$p(x|y) = p(x,y)/p(y) = p(y|x)p(x)/p(y)$$

(compare to Bayes' rule for events/discrete RV)



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- For standard distributions, we can use names or write out the density
 - i.e., for normal distribution: $\mu \sim N(m, s^2)$ is equivalent to $p(\mu) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(\frac{-1}{2s^2}(\mu m)^2\right)$

Inference using radon data

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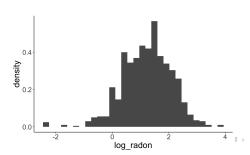
From intro:

- Radon is a naturally occurring radioactive gas. Its decay products are also radioactive; in high concentrations, they can cause lung cancer (several 1000 deaths/year in the USA).
- Radon levels vary greatly across US homes.
- Data:
 - Radon measurements in over 80K houses throughout the US (we focus on Minnesota)
 - Possible predictors: floor (basement or 1st floor) in the house, soil uranium level at county level.
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- ► This module: estimate mean radon, assuming that all log-radon measurements are independent draws from a normal distribution.

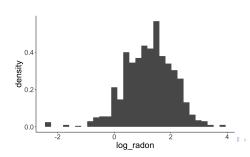
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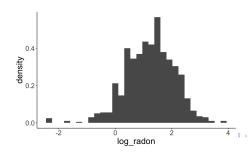


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▶ Goal: estimate mean log-radon level μ , assume that σ^2 is known.



Bayesian inference about $\boldsymbol{\mu}$

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Details in next module, current focus is on seeing how posterior depends on prior and data, and what to do with it.

$$y_i|\mu,\sigma^2 \sim N(\mu,\sigma^2); \ \mu \sim N(m_0,s_{\mu 0}^2); \mu|\mathbf{y},\sigma^2 \sim N\left(\frac{m_0/s_{\mu 0}^2 + n \cdot \bar{y}/\sigma^2}{1/s_{\mu 0}^2 + n/\sigma^2}, \frac{1}{1/s_{\mu 0}^2 + n/\sigma^2}\right)$$

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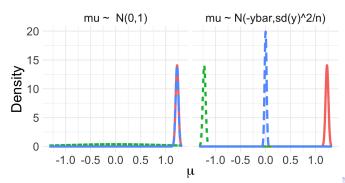
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- Results based on 2 different priors:

$$\mu \sim N(0,1)$$
 [LEFT] and $\mu \stackrel{\cdot}{\sim} N(-\bar{y},s\{y\}^2/n)$ [RIGHT]

like - prior - post

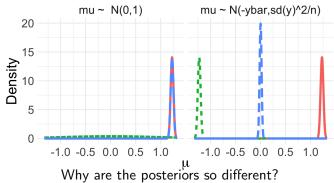


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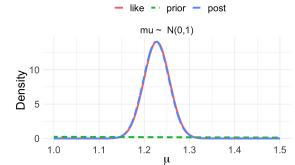
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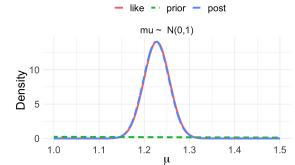
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- More details on this in the next module

Inference based on posterior distribution

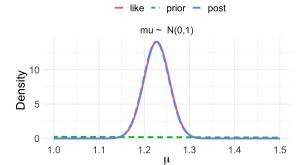
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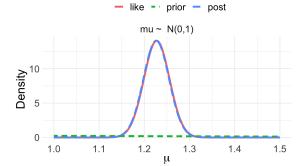
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- ▶ Bayesian point estimates are often given by:



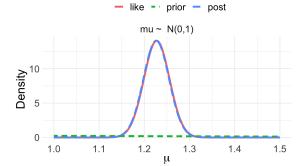
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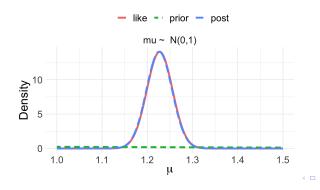


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• Here $E(\mu|\mathbf{y}) =$ median = 1.23.

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 - ► Highest posterior density (HPD) intervals
- ▶ For the radon example with $\mu \sim N(0,1)$, the quantile-based 95% CI is (1.17, 1.28).



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 - (1) relate data ${m y}$ to ${m \mu}$ through a likelihood function $p({m y}|{m \mu})$
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$$p(\mu|\mathbf{y}) = \frac{p(\mu)p(\mathbf{y}|\mu)}{p(\mathbf{y})},$$

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- Model set-up in this module: everything's normal;When data and prior are normal, the posterior is normal too.
- ▶ Next module: derive the posterior using Bayes' rule, discuss the role of prior information, bias-variance trade-off.