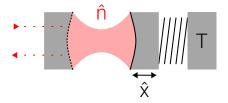
Noise Analysis Optomechanical Cavity

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Problem Statement



Hamiltonian

Optical Cavity \hat{a} , $\omega_o(\hat{x}_{\mathsf{mech}}) = \omega_o + \frac{g}{\omega_o}\hat{x}_{\mathsf{mech}}$; mechanical oscillations \hat{b} , ω_m ; coupling g; Drive E, ω_L

$$H = \underbrace{\omega_o \ a^\dagger a}_{\text{Cavity}} + \underbrace{\omega_m \ b^\dagger b}_{\text{Mechanical}} - \underbrace{g \ a^\dagger a \ (b + b^\dagger)}_{\text{Interaction}} + \underbrace{E(a e^{i\omega_L t} + a^\dagger e^{-i\omega_L t})}_{\text{Drive}}$$

Rotating Wave Approximation at ω_L with $\Delta = \omega_o - \omega_L$, $a \to ae^{i\omega_L t}$:

$$H_{\text{RWA}} = \Delta \ a^{\dagger} a + \omega_m \ b^{\dagger} b - g \ a^{\dagger} a \left(b^{\dagger} + b \right) + E(a + a^{\dagger})$$

 $\hbar = 1$

Hamiltonian Linearization

$$H_{\text{RWA}} = \Delta \ a^{\dagger} a + \omega_m \ b^{\dagger} b - g \ a^{\dagger} a \left(b^{\dagger} + b \right) + E(a + a^{\dagger})$$

Linearize $a = \alpha + \delta a$, $b = \beta + \delta b$; with α, β steady state.

$$H_{\text{Interaction}} = -g \ a^{\dagger} a \ (b^{\dagger} + b)$$

$$\approx -\underbrace{g|\alpha|}_{G} \left(\delta a + \delta a^{\dagger} + \mathcal{O}(a^{2} + \delta a \delta a^{\dagger})\right) \left(\delta b + \delta b^{\dagger} + 2\beta\right)$$

Therefore for small G:

$$H \approx \Delta \, \delta a^{\dagger} \delta a + \omega_m \delta b^{\dagger} \delta b - G(\delta a + \delta a^{\dagger})(\delta b + \delta b^{\dagger}) + E(a + a^{\dagger})$$
$$\sim \frac{\Delta}{2} (\hat{X}^2 + \hat{Y}^2) + \frac{\omega}{2} (\hat{Q}^2 + \hat{P}^2) - G\hat{X}\hat{Q} + E\hat{X}$$

Dissipation

Optical decay κ :

$$L_O = \sqrt{\kappa} \, \delta a$$

Mechanical resonator with γ and a thermal bath at the n-th thermal state:

$$L_M = \sqrt{\gamma(n+1)} \, \delta b + \sqrt{\gamma n} \, \delta b^{\dagger}$$

Implementation

truncated Fock Basis: $F_{\text{optical}} \otimes F_{\text{mechanical}}$

definition of H, J with $\delta a \otimes 1$

$$\psi(0) = |0\rangle \otimes |0\rangle$$

Time Evolution using the *Lindblad equation*:

$$\dot{\rho} = -i[H, \rho] + J\rho J^{\dagger} - \frac{1}{2} \{J^{\dagger}J, \rho\}$$

Continous measurement

Lindblad Master Equation:

$$\dot{\rho} = -i[H, \rho] + J\rho J^{\dagger} - \frac{1}{2} \{J^{\dagger}J, \rho\}$$

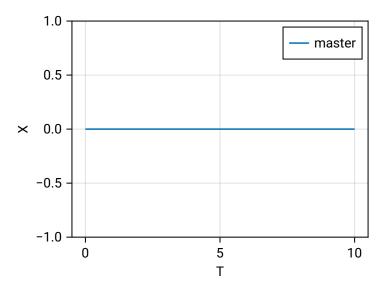
Stochastic Master Equation:

$$\dot{\rho} = -i[H, \rho] + J\rho J^{\dagger} - \frac{1}{2} \{J^{\dagger}J, \rho\} + \left(C\rho + \rho C^{\dagger} - \text{Tr}(C\rho + \rho C^{\dagger})\right) \xi(t)$$

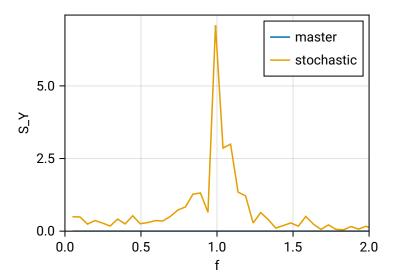
Let's look at the Quadrature $C = \eta \sqrt{\kappa} (\delta a + \delta a^{\dagger})$

QuantumOptics.jl, Krämer et al. 2024 (Stochastic Master equation, Quantum Zeno Effect)
"A Straightforward Introduction to Continuous Quantum Measurement", Jacobs et al. 2006

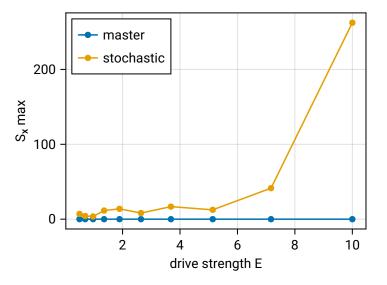
Time Evolution



Spectrum



Power Dependence ~ G

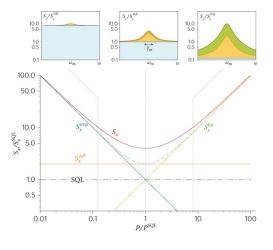


Took ≈ 1 min of compute time. Why is the SME so much slower? True Random Values?

Expectation

$$S_x = S_x^{\text{imp}} + S_x^{\text{ba}} + S_x^{\text{zpf}}$$

 $S_x^{\text{imp}} \propto P^{-1}\omega^0$: Imprecision / Shot noise $S_x^{\text{ba}} \propto P$: Back action S_x^{zpf} : Zero Point Fluctuation



Uncerstanding $S_{\text{det}}(\omega, P_{\text{in}})$

Where is the power dependence?

$$\overline{S}_{\text{det}}(\omega) = \frac{1}{8\eta\Gamma|C_{\text{eff}}|} + 2\Gamma|\chi(\omega)|^2|C_{\text{eff}}|$$

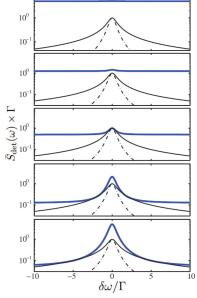
$$C_{\mathsf{eff}}(\omega) = \frac{4g^2}{\kappa\Gamma(1-2i\omega/\kappa)^2}$$
$$\chi(\omega) = \frac{\Omega}{\Omega^2 - \omega^2 - i\omega\gamma}$$

 η : Detection efficiency

 $\Gamma = \gamma$: Damping of oscillator

$$\overline{S}_{\mathsf{det}}(\omega) = \frac{\kappa \Gamma |1 - 2i\omega/\kappa|}{8\eta \Gamma 4g^2} + 2\Gamma \frac{\Omega^2}{|\Omega^2 - \omega^2 - i\omega\gamma|^2} \frac{4g^2}{\kappa \Gamma (1 - 2i\omega/\kappa)^2}$$

Quantum Optomechanics, Bowen et al. 2015 (eq. 3.51)



$$P/P^{SQL} = \{0.1, 0.4, 1, 4, 10\}$$

Quantum Optomechanics, Bowen et al. 2015 (Fig. 3.5)

Looking for a source that derives $S_{det}(\omega, P)$?

Or even states $S_{\text{det}}(\omega, P)$.

Or, selecting a simpler system?

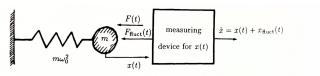


Fig. 8.4 Detection of a classical force by monitoring the coordinate of an oscillator on which it acts.

Not simulating the detector, just the oscillator and adding the Backaction in the measurement operator . . .