

# **This is the Project Title**

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# Abstract

Formal development of Frank.

# **Chapter 1**

## **Formalisation of Frank**

(data types)	$D$
(value type variables)	$X$
(effect type variables)	$E$
(value types)	$A, B ::= D \bar{R}$ $\quad \mid \{C\} \mid X$
(computation types)	$C ::= \overline{T \rightarrow G}$
(argument types)	$T ::= \langle \Delta \rangle A$
(return types)	$G ::= [\Sigma] A$
(type binders)	$Z ::= X \mid [E]$
(type arguments)	$R ::= A \mid [\Sigma]$
(polytypes)	$P ::= \forall \bar{Z}. A$
(interfaces)	$I$
(term variables)	$x, y, z, f$
(instance variables)	$s, a, b, c$
(seeds)	$\sigma ::= \emptyset \mid E$
(abilities)	$\Sigma ::= \sigma \mid \Xi$
(extensions)	$\Xi ::= \mathfrak{t} \mid \Xi, I \bar{R}$
(adaptors)	$\Theta ::= \mathfrak{t} \mid \Theta, I(S \rightarrow S')$
(adjustments)	$\Delta ::= \Theta \mid \Xi$
(instance patterns)	$S ::= s \mid S a$
(kind environments)	$\Phi, \Psi ::= \cdot \mid \Phi, Z$
(type environments)	$\Gamma ::= \cdot \mid \Gamma, x : A \mid \Gamma, f : P$
(instance environments)	$\Omega ::= s : \Sigma \mid \Omega, a : I \bar{R}$

Figure 1.1: Types

(constructors)	$k$
(commands)	$c$
(uses)	$m ::= x \mid f \bar{R} \mid m \bar{n} \mid \uparrow(n : A)$
(constructions)	$n ::= \downarrow m \mid k \bar{n} \mid c \bar{R} \bar{n} \mid \{e\}$ $\mid \text{let } f : P = n \text{ in } n' \mid \text{letrec } \overline{f : P = e} \text{ in } n$ $\mid \langle \Theta \rangle n$
(computations)	$e ::= \overline{\bar{r} \mapsto n}$
(computation patterns)	$r ::= p \mid \langle c \bar{p} \rightarrow z \rangle \mid \langle x \rangle$
(value patterns)	$p ::= k \bar{p} \mid x$

Figure 1.2: Terms

$\Phi; \Gamma [\Sigma] \vdash m \Rightarrow A$	
$\frac{\text{T-VAR} \quad x : A \in \Gamma}{\Phi; \Gamma [\Sigma] \vdash x \Rightarrow A}$	$\frac{\text{T-POLYVAR} \quad \Phi \vdash \bar{R} \quad f : \forall \bar{Z}. A \in \Gamma}{\Phi; \Gamma [\Sigma] \vdash f \bar{R} \Rightarrow A[\bar{R}/\bar{Z}]}$
$\frac{\text{T-APP} \quad \Sigma' = \Sigma \quad (\Sigma \vdash \Delta_i \dashv \Sigma'_i)_i \quad \Phi; \Gamma [\Sigma] \vdash m \Rightarrow \{\langle \Delta \rangle A \rightarrow [\Sigma'] B\} \quad (\Phi; \Gamma [\Sigma'_i] \vdash n_i : A_i)_i}{\Phi; \Gamma [\Sigma] \vdash m \bar{n} \Rightarrow B}$	$\frac{\text{T-ASCRIBE} \quad \Phi; \Gamma [\Sigma] \vdash n : A}{\Phi; \Gamma [\Sigma] \vdash \uparrow(n : A) \Rightarrow A}$
$\Phi; \Gamma [\Sigma] \vdash n : A$	
$\frac{\text{T-SWITCH} \quad \Phi; \Gamma [\Sigma] \vdash m \Rightarrow A \quad A = B}{\Phi; \Gamma [\Sigma] \vdash \downarrow m : B}$	$\frac{\text{T-DATA} \quad k \bar{A} \in D \bar{R} \quad (\Phi; \Gamma [\Sigma] \vdash n_j : A_j)_j}{\Phi; \Gamma [\Sigma] \vdash k \bar{n} : D \bar{R}}$
$\frac{\text{T-COMMAND} \quad \Phi \vdash \bar{R} \quad c : \forall \bar{Z}. \bar{A} \rightarrow B \in \Sigma \quad (\Phi; \Gamma [\Sigma] \vdash n_j : A_j[\bar{R}/\bar{Z}])_j}{\Phi; \Gamma [\Sigma] \vdash c \bar{R} \bar{n} : B[\bar{R}/\bar{Z}]}$	$\frac{\text{T-THUNK} \quad \Phi; \Gamma \vdash e : C}{\Phi; \Gamma [\Sigma] \vdash \{e\} : \{C\}}$
$\frac{\text{T-LET} \quad P = \forall \bar{Z}. A \quad \Phi, \bar{Z}; \Gamma [\emptyset] \vdash n : A \quad \Phi; \Gamma, f : P [\Sigma] \vdash n' : B}{\Phi; \Gamma [\Sigma] \vdash \text{let } f : P = n \text{ in } n' : B}$	
$\frac{\text{T-LETREC} \quad (P_i = \forall \bar{Z}_i. \{C_i\})_i \quad (\Phi, \bar{Z}_i; \Gamma, \bar{f} : \bar{P} \vdash e_i : C)_i \quad \Phi; \Gamma, \bar{f} : \bar{P} [\Sigma] \vdash n : B}{\Phi; \Gamma [\Sigma] \vdash \text{letrec } \bar{f} : \bar{P} = e \text{ in } n : B}$	$\frac{\text{T-ADAPT} \quad \Sigma \vdash \Theta \dashv \Sigma' \quad \Phi; \Gamma [\Sigma'] \vdash n : A}{\Phi; \Gamma [\Sigma] \vdash \langle \Theta \rangle n : A}$
$\Phi; \Gamma \vdash e : C$	
$\frac{\text{T-COMP} \quad (\Phi \vdash r_{i,j} : T_j \dashv [\Sigma] \exists \Psi_{i,j}. \Gamma'_{i,j})_{i,j} \quad (\Phi, (\Psi_{i,j})_j; \Gamma, (\Gamma'_{i,j})_j [\Sigma] \vdash n_i : B)_i \quad ((r_{i,j})_i \text{ covers } T_j)_j}{\Phi; \Gamma \vdash ((r_{i,j})_j \mapsto n_i)_i : (T_j \rightarrow)_j [\Sigma] B}$	

Figure 1.3: Term Typing Rules

(uses)	$m ::= \dots \mid \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil$
(constructions)	$n ::= \dots \mid \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil$
(use values)	$u ::= x \mid f \bar{R} \mid \uparrow(v : A)$
(non-use values)	$v ::= k \bar{w} \mid \{e\}$
(construction values)	$w ::= \downarrow u \mid v$
(normal forms)	$t ::= w \mid \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil$
(evaluation frames)	$\mathcal{F} ::= [] \bar{n} \mid u (\bar{t}, [], \bar{n}) \mid \uparrow([], A)$ $\mid \downarrow[] \mid k (\bar{w}, [], \bar{n}) \mid c \bar{R} (\bar{w}, [], \bar{n})$ $\mid \mathbf{let} f : P = [] \mathbf{in} n \mid \langle \Theta \rangle []$
(evaluation contexts)	$\mathcal{E} ::= [] \mid \mathcal{F}[\mathcal{E}]$

Figure 1.4: Runtime Syntax

$\Phi; \Gamma[\Sigma] \vdash m \Rightarrow A$	$\Phi; \Gamma[\Sigma] \vdash n : A$
$\frac{\text{T-FREEZE-USE} \quad \neg(\mathcal{E} \text{ handles } c) \quad \Phi; \Gamma[\Sigma] \vdash \mathcal{E}[c \bar{R} \bar{w}] \Rightarrow A}{\Phi; \Gamma[\Sigma] \vdash \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil \Rightarrow A}$	
$\frac{\text{T-FREEZE-CONS} \quad \neg(\mathcal{E} \text{ handles } c) \quad \Phi; \Gamma[\Sigma] \vdash \mathcal{E}[c \bar{R} \bar{w}] : A}{\Phi; \Gamma[\Sigma] \vdash \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil : A}$	

Figure 1.5: Frozen Commands

$$\begin{array}{c}
\boxed{m \rightsquigarrow_{\mathbf{u}} m'} \quad \boxed{n \rightsquigarrow_{\mathbf{c}} n'} \quad \boxed{m \longrightarrow_{\mathbf{u}} m'} \quad \boxed{n \longrightarrow_{\mathbf{c}} n'} \\
\\
\text{R-HANDLE} \\
\frac{k = \min_i \{i \mid \exists \bar{\theta}. (r_{i,j} : \langle \Delta_j \rangle A_j \leftarrow t_j \neg[\Sigma] \theta_j)_j\} \quad (r_{k,j} : \langle \Delta_j \rangle A_j \leftarrow t_j \neg[\Sigma] \theta_j)_j}{\uparrow(\{((r_{i,j})_j \rightarrow n_i)_i\} : \{\langle \Delta \rangle A \rightarrow [\Sigma] B\}) \bar{t} \rightsquigarrow_{\mathbf{u}} \uparrow((\bar{\theta}(n_k) : B))} \\
\\
\begin{array}{ccc}
\text{R-ASCRIBE-USE} & \text{R-ASCRIBE-CONS} & \text{R-LET} \\
\frac{}{\uparrow(\downarrow u : A) \rightsquigarrow_{\mathbf{u}} u} & \frac{}{\downarrow \uparrow(w : A) \rightsquigarrow_{\mathbf{c}} w} & \frac{}{\mathbf{let} f : P = w \mathbf{in} n \rightsquigarrow_{\mathbf{c}} n[\uparrow(w : P)/f]} \\
\\
\text{R-LETREC} & \frac{}{e = \bar{r} \rightarrow n} & \text{R-ADAPT} \\
\frac{}{\mathbf{letrec} f : P = e \mathbf{in} n' \rightsquigarrow_{\mathbf{c}} n'[\uparrow(\{\bar{r} \rightarrow \mathbf{letrec} f : P = e \mathbf{in} n\} : P)/f]} & & \frac{}{\langle \Theta \rangle w \rightsquigarrow_{\mathbf{c}} w} \\
\\
\text{R-FREEZE-COMM} \\
\frac{}{c \bar{R} \bar{w} \rightsquigarrow_{\mathbf{c}} [c \bar{R} \bar{w}]} \\
\\
\begin{array}{cc}
\text{R-FREEZE-FRAME-USE} & \text{R-FREEZE-FRAME-CONS} \\
\frac{\neg(\mathcal{F}[\mathcal{E}] \text{ handles } c)}{\mathcal{F}[[\mathcal{E}[c \bar{R} \bar{w}]]] \rightsquigarrow_{\mathbf{u}} [\mathcal{F}[\mathcal{E}[c \bar{R} \bar{w}]]]} & \frac{\neg(\mathcal{F}[\mathcal{E}] \text{ handles } c)}{\mathcal{F}[[\mathcal{E}[c \bar{R} \bar{w}]]] \rightsquigarrow_{\mathbf{c}} [\mathcal{F}[\mathcal{E}[c \bar{R} \bar{w}]]]} \\
\\
\begin{array}{cccc}
\text{R-LIFT-UU} & \text{R-LIFT-UC} & \text{R-LIFT-CU} & \text{R-LIFT-CC} \\
\frac{m \rightsquigarrow_{\mathbf{u}} m'}{\mathcal{E}[m] \longrightarrow_{\mathbf{u}} \mathcal{E}[m']} & \frac{m \rightsquigarrow_{\mathbf{u}} m'}{\mathcal{E}[m] \longrightarrow_{\mathbf{c}} \mathcal{E}[m']} & \frac{n \rightsquigarrow_{\mathbf{c}} n'}{\mathcal{E}[n] \longrightarrow_{\mathbf{u}} \mathcal{E}[n']} & \frac{n \rightsquigarrow_{\mathbf{c}} n'}{\mathcal{E}[n] \longrightarrow_{\mathbf{c}} \mathcal{E}[n']}
\end{array}
\end{array}
\end{array}$$

Figure 1.6: Operational Semantics



$$\boxed{r : T \leftarrow t \neg[\Sigma] \theta}$$

$$\begin{array}{c} \text{B-VALUE} \\ \Sigma \vdash \Delta \dashv \Sigma' \\ p : A \leftarrow w \dashv \theta \\ \hline p : \langle \Delta \rangle A \leftarrow w \neg[\Sigma] \theta \end{array}$$

B-REQUEST

$$\begin{array}{c} \Sigma \vdash \Delta \dashv \Sigma' \quad \mathcal{E} \text{ poised for } c \\ \Delta = \Theta \mid \Xi \quad c : \forall \bar{Z}. \bar{B} \rightarrow B' \in \Xi \quad (p_i : B_i \leftarrow w_i \dashv \theta_i)_i \\ \hline \langle c \bar{p} \rightarrow z \rangle : \langle \Delta \rangle A \leftarrow [\mathcal{E}[c \bar{R} \bar{w}]] \neg[\Sigma] \bar{\theta}[\uparrow(\{x \mapsto \mathcal{E}[x]\} : \{B' \rightarrow [\Sigma']A\})/z] \end{array}$$

B-CATCHALL-VALUE

$$\begin{array}{c} \Sigma \vdash \Delta \dashv \Sigma' \\ \hline \langle x \rangle : \langle \Delta \rangle A \leftarrow w \neg[\Sigma] [\uparrow(\{w\} : \{[\Sigma']A\})/x] \end{array}$$

B-CATCHALL-REQUEST

$$\begin{array}{c} \Sigma \vdash \Delta \dashv \Sigma' \quad \mathcal{E} \text{ poised for } c \\ \Delta = \Theta \mid \Xi \quad c : \forall \bar{Z}. \bar{B} \rightarrow B' \in \Xi \\ \hline \langle x \rangle : \langle \Delta \rangle A \leftarrow [\mathcal{E}[c \bar{R} \bar{w}]] \neg[\Sigma] [\uparrow(\{[\mathcal{E}[c \bar{R} \bar{w}]]\} : \{[\Sigma']A\})/x] \end{array}$$

$$\boxed{p : A \leftarrow w \dashv \theta}$$

B-VAR

$$\frac{}{x : A \leftarrow w \dashv [\uparrow(w : A)/x]}$$

B-DATA

$$\frac{k \bar{A} \in D \bar{R} \quad (p_i : A_i \leftarrow w_i \dashv \theta_i)_i}{k \bar{p} : D \bar{R} \leftarrow k \bar{w} \dashv \bar{\theta}}$$

Figure 1.7: Pattern Binding

# Chapter 2

## Arbitrary Thread Interruption

### 2.1 Motivation

One important part of our asynchronous effect handling system is the ability to interrupt arbitrary computations. This is essential for pre-emptive concurrency, which relies on being able to suspend computations for resumption later.

For instance, consider the two programs below;

```
controller : {[Stop, Go, Console] Unit}
controller! = go!; stop!; print ``stop 1``;
              go!; stop!; print ``stop 2``;
              go!; stop!; print ``stop 3``

runner : {[Console] Unit}
runner! = print ``1 ``; print ``2 ``; print ``3 ``;
```

We ideally want a multihandler that can run these two programs in parallel, such that the result will be 1 stop 1 2 stop 2 3 stop 3; that is to say, the stop and go operations from

### 2.2 Interruption with Yields

One way we can get this behaviour is using the `Yield` interface. This offers a single operation, `yield : Unit`. With this, we can write a multihandler `suspend`;

```
runner : {[Console, Yield] Unit}
runner! = print "1 "; yield!; print "2 "; yield!; print "3 ";
          yield!
```

```

suspend : {<Yield> Unit -> <Stop, Go> Unit -> Maybe [[Console,
    Yield] Unit] -> [Console] Unit}
suspend <yield -> k> <stop -> l> _ = suspend unit (l unit) (
    just {k unit})
suspend <k> <go -> l> (just res) = suspend (res!) (l
    unit) nothing
suspend <yield -> k> <m> maybe = suspend (k unit) m! maybe
suspend unit _ _ = unit
suspend _ unit _ = unit

```

**TODO:** Maybe make more concise?

**TODO:** change to not be letter l cos it looks like a 1

Running `suspend runner! controller! nothing` then prints out `1 stop 1 2 stop 2 3 stop 3` as desired. So far so good; this works as planned. However, observe that we had to change the code of the original runner program to `yield` every time it prints. We would rather not have this requirement; the threads should be suspendable without knowing in advance they will be suspended, and thus without needing to explicitly `yield`. Furthermore, see that the `yield` operation adds no more information; it is just used as a placeholder operation; any operation would work. As such, we keep searching for a better solution.

## 2.3 Relaxing Catches

The key to this lies in the catchall pattern,  $\langle x \rangle$ , and the pattern binding rules of Figure 1.7.

Recall that the catchall pattern  $\langle x \rangle$  matches either a value — e.g. `unit` — or a command that is handled in the surrounding ability. For instance, the pattern  $\langle k \rangle$  in the code above matches either `unit` or `<yield -> k>`. The variable `k` is then bound to whatever this match is, leaving the (potentially) invoked effect unhandled. This is expressed in the B-CATCHALL-REQUEST rule in Figure 1.7.

Important to note is that only effects that are handled in that position are able to be caught. `runner` also makes use of the `print` effect, but these are not able to be caught by the catchall command. Formally, this is due to the fourth requirement of B-CATCHALL-REQUEST; that the command  $c$  that is invoked is a member of  $\Xi$ .

As such, we propose to remove this constraint from B-CATCHALL-REQUEST. The

$$\begin{array}{c}
\text{B-CATCHALL-REQUEST-LOOSE} \\
\frac{\Sigma \vdash \Delta \dashv \Sigma'}{\langle x \rangle : \langle \Delta \rangle A \leftarrow [\mathcal{E}[c \bar{R} \bar{w}]] \dashv [\Sigma] [\uparrow(\{\mathcal{E}[c \bar{R} \bar{w}]\} : \{\Sigma' A\}) / x]}
\end{array}$$

Figure 2.1: Updated B-CATCHALL-REQUEST

resulting rule can then be seen in Figure 2.1. This lets us update the previous `suspend` code to the following, which yields the same results as last time;

```

runner : {[Console] Unit}
runner! = print "1 "; print "2 "; print "3 "

suspend : {Unit -> <Stop, Go> Unit -> Maybe {[Console] Unit}
         -> [Console] Unit}
suspend <k> <stop -> l> _ = suspend unit (l unit) (
  just {k unit})
suspend <k> <go -> l> (just res) = suspend (res!) (l unit)
  nothing
suspend unit _ _ = unit
suspend _ unit _ = unit

```

**TODO:** Verify that this particular example really works.

Why does this work?

**TODO:** explain

## 2.4 Interrupting Arbitrary Terms

The approach of Section 2.3 can only interrupt command invocations. If `runner` were instead a sequence of pure computations<sup>1</sup>, we would be unable to interrupt it; it does not invoke commands.

As such, we need to further change the pattern binding rules of Figure 1.7. This is to let us interrupt arbitrary computation terms. In Figure 2.2, we see an updated version of the runtime syntax; this allows for the suspension of arbitrary *uses*, being function applications and constructions

**TODO:** verify that *uses* are “just” these

<sup>1</sup>I.e. `runner! = 1 + 1; 1 + 1; 1 + 1; ...`

(uses)	$m ::= \dots \mid \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil$
(constructions)	$n ::= \dots \mid \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil$
(use values)	$u ::= x \mid f \bar{R} \mid \uparrow(v : A)$
(non-use values)	$v ::= k \bar{w} \mid \{e\}$
(construction values)	$w ::= \downarrow u \mid v$
(normal forms)	$t ::= w \mid \lceil \mathcal{E}[c \bar{R} \bar{w}] \rceil \mid !m$
(evaluation frames)	$\mathcal{F} ::= [] \bar{n} \mid u(\bar{l}, [], \bar{n}) \mid \uparrow([], : A)$ $\mid \downarrow[] \mid k(\bar{w}, [], \bar{n}) \mid c \bar{R}(\bar{w}, [], \bar{n})$ $\mid \mathbf{let} f : P = [] \mathbf{in} n \mid \langle \Theta \rangle []$
(evaluation contexts)	$\mathcal{E} ::= [] \mid \mathcal{F}[\mathcal{E}]$

Figure 2.2: Runtime Syntax, Updated with Suspension of Uses

# **Appendix A**

## **Remaining Formalisms**

$$\boxed{\Sigma \vdash \Delta \dashv \Sigma'}$$

$$\begin{array}{c} \text{A-ADJ} \\ \Sigma \vdash \Theta \dashv \Sigma' \quad \Sigma' \vdash \Xi \dashv \Sigma'' \\ \hline \Sigma \vdash \Theta | \Xi \dashv \Sigma'' \end{array}$$

$$\boxed{\Sigma \vdash \Xi \dashv \Sigma'}$$

$$\begin{array}{c} \text{A-EXT-ID} \\ \hline \Sigma \vdash \mathbf{1} \dashv \Sigma \end{array}$$

$$\begin{array}{c} \text{A-EXT-SNOC} \\ \Sigma \vdash \Xi \dashv \Sigma' \\ \hline \Sigma \vdash \Xi, I \bar{R} \dashv \Sigma', I \bar{R} \end{array}$$

$$\boxed{\Sigma \vdash \Theta \dashv \Sigma'}$$

$$\begin{array}{c} \text{A-ADAPT-ID} \\ \hline \Sigma \vdash \mathbf{1} \dashv \Sigma \end{array}$$

$$\begin{array}{c} \text{A-ADAPT-SNOC} \\ \Sigma \vdash \Theta \dashv \Sigma' \quad \Sigma' \vdash I(S \rightarrow S') \dashv \Sigma'' \\ \hline \Sigma \vdash \Theta, I(S \rightarrow S') \dashv \Sigma'' \end{array}$$

$$\boxed{\Sigma \vdash I(S \rightarrow S') \dashv \Sigma'}$$

$$\begin{array}{c} \text{A-ADAPT-COM} \\ \Sigma \vdash S : I \dashv \Sigma'; \Omega \quad \Omega \vdash S' : I \dashv \Xi \quad \Sigma' \vdash \Xi \dashv \Sigma'' \\ \hline \Sigma \vdash I(S \rightarrow S') \dashv \Sigma'' \end{array}$$

$$\boxed{\Sigma \vdash S : I \dashv \Sigma'; \Omega}$$

$$\text{I-PAT-ID}$$

$$\Sigma \vdash s : I \dashv \Sigma; s : \Sigma$$

$$\text{I-PAT-BIND}$$

$$\begin{array}{c} \Sigma \vdash S : I \dashv \Sigma'; \Omega \\ \hline \Sigma, I \bar{R} \vdash S a : I \dashv \Sigma'; \Omega, a : I \bar{R} \end{array}$$

$$\text{I-PAT-SKIP}$$

$$\begin{array}{c} \Sigma \vdash S a : I \dashv \Sigma'; \Omega \quad I \neq I' \\ \hline \Sigma, I' \bar{R} \vdash S a : I \dashv \Sigma', I' \bar{R}; \Omega \end{array}$$

$$\boxed{\Omega \vdash S : I \dashv \Xi}$$

$$\begin{array}{c} \text{I-INST-ID} \\ s \in \text{dom}(\Omega) \\ \hline \Omega \vdash s : I \dashv \mathbf{1} \end{array}$$

$$\begin{array}{c} \text{I-INST-LKP} \\ a \in \text{dom}(\Omega) \quad \Omega \vdash S : I \dashv \Xi \quad \Omega(a) = I \bar{R} \\ \hline \Omega \vdash S a : I \dashv \Xi, I \bar{R} \end{array}$$

Figure A.1: Action of an Adjustment on an Ability and Auxiliary Judgements

$$\mathcal{X} ::= A \mid C \mid T \mid G \mid Z \mid R \mid P \mid \sigma \mid \Sigma \mid \Xi \mid \Theta \mid \Delta \mid \Gamma \mid \exists \Psi. \Gamma \mid \Omega$$

$\Phi \vdash \mathcal{X}$

$\frac{}{\Phi, X \vdash X}$ <p>WF-VAL</p>	$\frac{}{\Phi, [E] \vdash E}$ <p>WF-EFF</p>	$\frac{\Phi, \bar{Z} \vdash A}{\Phi \vdash \forall \bar{Z}. A}$ <p>WF-POLY</p>
$\frac{(\Phi \vdash R)_i}{\Phi \vdash D \bar{R}}$ <p>WF-DATA</p>	$\frac{\Phi \vdash C}{\Phi \vdash \{C\}}$ <p>WF-THUNK</p>	$\frac{(\Phi \vdash T)_i \quad \Phi \vdash G}{\Phi \vdash \bar{T} \rightarrow G}$ <p>WF-COMP</p>
$\frac{\Phi \vdash \Delta \quad \Phi \vdash A}{\Phi \vdash \langle \Delta \rangle A}$ <p>WF-ARG</p>		
$\frac{\Phi \vdash \Sigma \quad \Phi \vdash A}{\Phi \vdash [\Sigma] A}$ <p>WF-RET</p>	$\frac{\Phi \vdash \Sigma}{\Phi \vdash [\Sigma]}$ <p>WF-ABILITY</p>	$\frac{}{\Phi \vdash \emptyset}$ <p>WF-PURE</p>
$\frac{}{\Phi \vdash \mathbf{1}}$ <p>WF-ID</p>		$\frac{\Phi \vdash \Xi \quad (\Phi \vdash R)_i}{\Phi \vdash \Xi, I \bar{R}}$ <p>WF-EXT</p>
$\frac{\Phi \vdash \Theta}{\Phi \vdash \Theta, I (S \rightarrow S')}$ <p>WF-ADAPT</p>		
$\frac{}{\Phi \vdash \cdot}$ <p>WF-EMPTY</p>	$\frac{\Phi \vdash \Gamma \quad \Phi \vdash A}{\Phi \vdash \Gamma, x : A}$ <p>WF-MONO</p>	$\frac{\Phi \vdash \Gamma \quad \Phi \vdash P}{\Phi \vdash \Gamma, f : P}$ <p>WF-POLY</p>
$\frac{\Phi, \Psi \vdash \Gamma}{\Phi \vdash \exists \Psi. \Gamma}$ <p>WF-EXISTENTIAL</p>		$\frac{\Phi \vdash \Omega \quad (\Phi \vdash R)_i}{\Phi \vdash \Omega, x : I \bar{R}}$ <p>WF-INTERFACE</p>

Figure A.2: Well-Formedness Rules



$$\boxed{\Phi \vdash p : A \dashv \Gamma}$$

$$\begin{array}{c}
\text{P-VAR} \\
\hline
\Phi \vdash x : A \dashv x : A
\end{array}
\qquad
\begin{array}{c}
\text{P-DATA} \\
k \bar{A} \in D \bar{R} \quad (\Phi \vdash p_i : A_i \dashv \Gamma)_i \\
\hline
\Phi \vdash k \bar{p} : D \bar{R} \dashv \bar{\Gamma}
\end{array}$$

$$\boxed{\Phi \vdash r : T \dashv [\Sigma] \exists \Psi. \Gamma}$$

$$\begin{array}{c}
\text{P-VALUE} \\
\Sigma \vdash \Delta \dashv \Sigma' \quad \Phi \vdash p : A \dashv \Gamma \\
\hline
\Phi \vdash p : \langle \Delta \rangle A \dashv [\Sigma] \Gamma
\end{array}
\qquad
\begin{array}{c}
\text{P-CATCHALL} \\
\Sigma \vdash \Delta \dashv \Sigma' \\
\hline
\Phi \vdash \langle x \rangle : \langle \Delta \rangle A \dashv [\Sigma] x : \{[\Sigma'] A\}
\end{array}$$

$$\begin{array}{c}
\text{P-COMMAND} \\
\Sigma \vdash \Delta \dashv \Sigma' \quad \Delta = \Theta \mid \Xi \quad c : \forall \bar{Z}. \bar{A} \rightarrow \bar{B} \in \Xi \quad (\Phi, \bar{Z} \vdash p_i : A_i \dashv \Gamma_i)_i \\
\hline
\Phi \vdash \langle c \bar{p} \rightarrow z \rangle : \langle \Delta \rangle B' \dashv [\Sigma] \exists \bar{Z}. \bar{\Gamma}, z : \{\langle \mathbf{1} \mid \mathbf{1} \rangle B \rightarrow [\Sigma'] B'\}
\end{array}$$

Figure A.3: Pattern Matching Typing Rules