

LECTURE 5: LINEAR MAPS, MATRICES, RANK-NULITY.

Prof. Piya Pal
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AGENDA

1. Linear Maps

- Definition

- Examples

- $R(T)$ and $N(T)$

2. Linear Maps between FINITE Dimensional
Vector Spaces -

3. Rank-Nullity : Sketch of Proof.
Theorem

LINEAR MAPS

Let U and V be vector spaces over a field \mathbb{F} . A function $f: U \rightarrow V$ is linear if

- (i) $f(u+v) = f(u) + f(v)$, $\forall u, v \in U$.
vector addition in U . vector addition in V .
- (ii) $f(\alpha \cdot u) = \alpha \cdot f(u)$, $\forall u \in U, \alpha \in \mathbb{F}$.
scalar multiplication in U scalar multiplication in V .

Question: What is $f(0)$? $= 0 \in V$.
 $0 \in U$.

$$f(0 \cdot 0) = 0 \cdot f(0) = 0 \in V$$

$0 \in \mathbb{F}$ $0 \in U$ $0 \in \mathbb{F}$

$$\Rightarrow f(0) = 0 \in V.$$

Examples

1 $f: \mathbb{R} \rightarrow \mathbb{R}$

Show f is linear

$$f(x) = \alpha x, \quad \alpha \in \mathbb{R}.$$

$$f(x) = \alpha x + \beta, \quad \alpha, \beta \in \mathbb{R}, \quad \beta \neq 0$$

Not linear ($\because f(0) \neq 0$)

2 $f: \mathbb{R}^n \rightarrow \mathbb{R}^m$

Given $A \in \mathbb{R}^{m \times n}$

SHOW THIS
IS LINEAR

define

$$f(x) = Ax$$

by showing

$$f(x+y) = f(x) + f(y)$$

$$\Delta f(\alpha x) = \alpha f(x)$$

3 $f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$

$$f(X) = \sum_{i=1}^n X_{ii} = \text{Trace}(X)$$

Show that $f(X)$ is linear map

Range & Kernel of Linear Maps

Let $T: \mathcal{U} \rightarrow \mathcal{V}$ be a linear map. Then

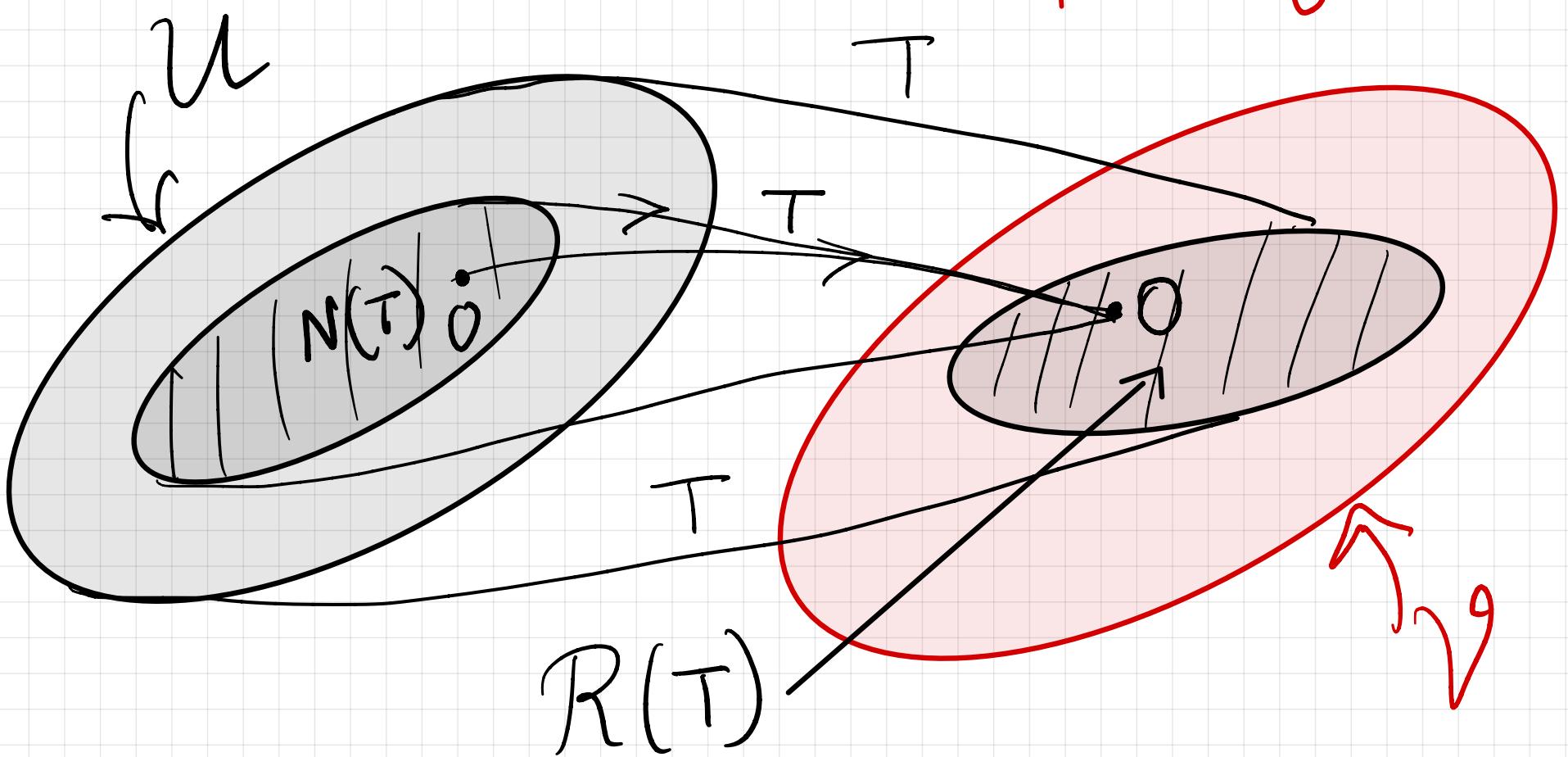
$$R(T) = \{v \in \mathcal{V}, \text{ s.t. } v = T(u) \text{ for some } u \in \mathcal{U}\}$$

$$N(T) = \{u \in \mathcal{U}, \text{ s.t. } T(u) = 0\}$$

(aka kernel)

VERIFY: If T is linear (need not be representable by a matrix since \mathcal{U} or \mathcal{V} can be infinite dimensional)

$R(T)$ is a subspace.
 $N(T)$ is a subspace.] Verify using basic definition of linearity of T .



LINEAR MAPS BETWEEN FINITE DIMENSIONAL VECTOR SPACES

Let U, V be finite dimensional vector spaces over a field \mathbb{F} .

Say, $\dim(U) = n, \dim(V) = m$.

Consider a linear map $T: U \rightarrow V$.

We will show that T can be represented by a matrix.

Consider a basis $\{v_1, v_2, \dots, v_n\}$ of U .

Similarly, let $\{v_1, \dots, v_m\}$ be a basis of V .

Let u be any vector in U .

and $v = T(u)$

Notice that u can be represented as

$$u = \sum_{i=1}^n \alpha_i v_i$$

Since $\{v_1, \dots, v_n\}$ is a basis, $\{\alpha_1, \dots, \alpha_n\}$ are unique for a given u .

Similarly, v can be represented as

$$v = \sum_{i=1}^m \beta_i v_i$$

Since $\{v_1, \dots, v_m\}$ is a basis of \mathcal{V} , $\{\beta_1, \dots, \beta_m\}$ are unique for a given v .

We will show that

$$\beta = \begin{bmatrix} \beta_1 \\ \vdots \\ \beta_m \end{bmatrix}$$

$$\text{and } \alpha = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$$

are related

by a matrix $C \in \mathbb{F}^{m \times n}$

ie $\boxed{\beta = C \alpha \dots}$

Note that β uniquely defines v and
 α uniquely defines u

Proof:

$$\begin{aligned} v &= T(u) = T\left(\sum_{i=1}^n \alpha_i u_i\right) \xrightarrow{\text{linearity of } T} \\ &= \sum_{i=1}^n \alpha_i T(u_i) \end{aligned}$$

Now $T(u_1), T(u_2), \dots, T(u_n) \in \mathcal{V}$

Since $\{v_1, \dots, v_m\}$ is a basis of V

we must have

$$T(v_1) = \sum_{j=1}^m y_{1j} v_j \quad \text{--- } ②$$

$$T(u_2) = \sum_{j=1}^m y_{2j} v_j \quad \text{--- } ③$$

⋮

$$T(u_n) = \sum_{j=1}^m y_{nj} v_j \quad \text{--- } n+1$$

Substituting $②, ③, \dots, n+1$ into $①$

We get

$$\begin{aligned} V &= \sum_{i=1}^n \alpha_i T(u_i) = \sum_{i=1}^n \alpha_i \sum_{j=1}^m y_{ij} v_j \\ &= \sum_{j=1}^m \left(\sum_{i=1}^n \alpha_i y_{ij} \right) v_j \end{aligned}$$

However

$$v = \sum_{j=1}^m \beta_j v_j$$

Since basis expansion coefficients are unique,

we have

$$\beta_j = \sum_{i=1}^n \alpha_i \gamma_{ij}, \quad j = 1, 2, \dots, m$$

\Rightarrow

$$\begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_m \end{bmatrix} = \begin{bmatrix} \sum_{i=1}^n \gamma_{i1} \alpha_i \\ \sum_{i=1}^n \gamma_{i2} \alpha_i \\ \vdots \\ \sum_{i=1}^n \gamma_{im} \alpha_i \end{bmatrix} \in \mathbb{F}^m$$
$$= \begin{bmatrix} \gamma_{11} & \gamma_{21} & \cdots & \gamma_{n1} \\ \gamma_{12} & \gamma_{22} & \cdots & \gamma_{n2} \\ \vdots & \ddots & \ddots & \vdots \\ \gamma_{1m} & \gamma_{2m} & \cdots & \gamma_{nm} \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix} \in \mathbb{F}^n$$

$$\Rightarrow \boxed{\beta = C\alpha}$$

Call this C

Hence $T: U \rightarrow V$ is represented by
an $m \times n$ matrix $C \in \mathbb{F}^{m \times n}$, where

$$\dim(U) = n, \quad \dim(V) = m.$$

This means that if you need to compute $T(u)$ for any u in U , you can equivalently do so using "matrix vector multiplication" with C , as follows:-

① Obtain the basis expansion coefficients $\alpha_1, \alpha_2, \dots, \alpha_n$ for u , with respect to the basis $\{u_1, u_2, \dots, u_n\}$.

Note $\alpha_1, \dots, \alpha_n$ uniquely identifies " u ".

② Apply the matrix C on $\alpha = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix}$ to obtain $\beta \in \mathbb{F}^m$ as follows:-

$$\beta = C\alpha.$$

③ Using $\beta_1, \beta_2, \dots, \beta_m$ construct (or Synthesize) v as:

$$v = \sum_{i=1}^m \beta_i v_i, \quad \{v_1, v_2, \dots, v_m\} \text{ is the basis of } V.$$

④ v is the desired $T(u)$.

RANK-NULLITY THEOREM

Let U, V be vector spaces over a field \mathbb{F} . Let $T: U \rightarrow V$ be a linear map. Suppose U is finite dimensional. Then.

$$\dim(R(T)) + \dim(N(T)) = \dim(U).$$

Proof:

$$R(T) = \{v \in V, \text{ s.t. } v = T(u) \text{ for some } u \in U\}$$

$$N(T) = \{u \in U, \text{ s.t. } T(u) = 0\}$$

$N(T) \subseteq U$. Let $\dim(U) = n$ (n is a finite integer)

$$\dim(N(T)) \leq n.$$

Let $k = \dim(N(T)) \leq n$.

Let $\{u_1, u_2, u_3, \dots, u_k\}$ be a basis for $N(T)$

$\Rightarrow \{u_1, u_2, \dots, u_k\}$ is a linearly independent set in U .

\Rightarrow Recall: Any linearly independent set in a vector space is contained in some basis

of the vector space -

\Rightarrow There exist vectors $u_{k+1}, u_{k+2}, \dots, u_n \in U$ s.t.
 $\{u_1, u_2, \dots, u_k, u_{k+1}, \dots, u_n\}$ is a basis for
 U .

Consider the vectors

$$T(u_{k+1}) = v_1$$

$$T(u_{k+2}) = v_2$$

⋮

$$T(u_n) = v_{n-k}$$

Of course $v_1, v_2, \dots, v_{n-k} \in R(T)$,

If we can show that v_1, v_2, \dots, v_{n-k}
is a "basis" for $R(T)$, then we will

have

$$\dim(R(T)) = n-k$$

$$\Rightarrow \dim(R(T)) + k = n$$

$$\dim(U)$$

$$\Rightarrow \dim(R(T)) + \dim(N(T)) = n.$$

[We will establish this in next lecture...]