

FALL 2021 Linear Algebra Discussion 5

Before we start, let us recap important definitions.

Definition .1. Given a point $\mathbf{y} \in \mathcal{V}$, and a subspace $\mathcal{S} \subset \mathcal{V}$, a vector $\hat{\mathbf{y}}_{\mathcal{S}}$ is called an orthogonal projection of \mathbf{y} onto \mathcal{S} if

- $\hat{\mathbf{y}}_{\mathcal{S}} \in \mathcal{S}$
- $\langle \mathbf{y} - \hat{\mathbf{y}}_{\mathcal{S}}, \mathbf{v} \rangle = 0 \quad \forall \mathbf{v} \in \mathcal{S}$

Let us define the following quantities. Let $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ be a basis for \mathcal{S} . Then

$$\mathbf{A} = \begin{bmatrix} \langle \mathbf{v}_1, \mathbf{v}_1 \rangle & \langle \mathbf{v}_2, \mathbf{v}_1 \rangle & \dots & \langle \mathbf{v}_k, \mathbf{v}_1 \rangle \\ \langle \mathbf{v}_1, \mathbf{v}_2 \rangle & \langle \mathbf{v}_2, \mathbf{v}_2 \rangle & \dots & \langle \mathbf{v}_k, \mathbf{v}_2 \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{v}_1, \mathbf{v}_k \rangle & \langle \mathbf{v}_2, \mathbf{v}_k \rangle & \dots & \langle \mathbf{v}_k, \mathbf{v}_k \rangle \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} \langle \mathbf{y}, \mathbf{v}_1 \rangle \\ \langle \mathbf{y}, \mathbf{v}_2 \rangle \\ \vdots \\ \langle \mathbf{y}, \mathbf{v}_k \rangle \end{bmatrix} \quad (1)$$

We showed in class that the orthogonal projection exists if and only if the Normal Equation $\mathbf{b} = \mathbf{A}\mathbf{x}$ has a solution. Moreover, the orthogonal projection is given by

$$\hat{\mathbf{y}}_{\mathcal{S}} = \sum_{i=1}^k x_i \mathbf{v}_i$$

Question 1: The Normal Equation $\mathbf{b} = \mathbf{A}\mathbf{x}$ for given $\mathbf{A} \in \mathbb{F}^{k \times k}$ and $\mathbf{b} \in \mathbb{F}^{k \times 1}$ ($\mathbb{F} = \mathbb{C}$ or $\mathbb{F} = \mathbb{R}$) in Eq(1) has always a solution. Hence, the orthogonal projection always exists.

Solution 1: We will show that $\text{rank}(\mathbf{A}) = k$. To do so, we will argue $N(\mathbf{A}) = \{\mathbf{0}\}$. Suppose $\mathbf{z} \in N(\mathbf{A})$. Then $\mathbf{A}\mathbf{z} = \mathbf{0}$, which in turn implies $\mathbf{z}^H \mathbf{A}\mathbf{z} = 0$. Note that $A_{i,j} = \langle \mathbf{v}_j, \mathbf{v}_i \rangle$. Using the properties of the inner product, we can write this product as

$$\begin{aligned} 0 = \mathbf{z}^H \mathbf{A}\mathbf{z} &= \sum_{i=1}^k \sum_{j=1}^k z_i^* A_{ij} z_j = \sum_{i=1}^k \sum_{j=1}^k z_i^* z_j \langle \mathbf{v}_j, \mathbf{v}_i \rangle = \sum_{i=1}^k \sum_{j=1}^k \langle z_j \mathbf{v}_j, z_i \mathbf{v}_i \rangle \\ &= \sum_{i=1}^k \langle \sum_{j=1}^k z_j \mathbf{v}_j, z_i \mathbf{v}_i \rangle = \langle \sum_{j=1}^k z_j \mathbf{v}_j, \sum_{i=1}^k z_i \mathbf{v}_i \rangle = \langle \sum_{i=1}^k z_i \mathbf{v}_i, \sum_{i=1}^k z_i \mathbf{v}_i \rangle \end{aligned}$$

This implies $\sum_{i=1}^k z_i \mathbf{v}_i = \mathbf{0}$. Since vectors $\mathbf{v}_1, \dots, \mathbf{v}_k$ are linearly independent, $\mathbf{z} = \mathbf{0}$. Hence we showed $N(\mathbf{A}) = \{\mathbf{0}\}$. This in turn shows $\text{rank}(\mathbf{A}) = k$, and hence there always exists $\mathbf{x} \in \mathbb{F}^k$ for which $\mathbf{b} = \mathbf{A}\mathbf{x}$.

Question 2: Show that if $\mathbf{Q} \in \mathbb{C}^{m \times n}$, then $\text{rank}(\mathbf{Q}^H \mathbf{Q}) = \text{rank}(\mathbf{Q})$.

Solution 2: We will show $N(\mathbf{Q}) = N(\mathbf{Q}^H \mathbf{Q})$. We will start with $\mathbf{x} \in \mathbf{Q}$.

$$\mathbf{x} \in N(\mathbf{Q}) \implies \mathbf{Q}\mathbf{x} = \mathbf{0} \implies \mathbf{Q}^H \mathbf{Q}\mathbf{x} = \mathbf{0} \implies \mathbf{x} \in N(\mathbf{Q}^H \mathbf{Q})$$

Now we will consider $\mathbf{x} \in \mathbf{Q}^H \mathbf{Q}$.

$$\mathbf{x} \in N(\mathbf{Q}^H \mathbf{Q}) \implies \mathbf{Q}^H \mathbf{Q}\mathbf{x} = \mathbf{0} \implies \mathbf{x}^H \mathbf{Q}^H \mathbf{Q}\mathbf{x} = 0 \implies \|\mathbf{Q}\mathbf{x}\|_2^2 = 0 \implies \mathbf{Q}\mathbf{x} = \mathbf{0} \implies \mathbf{x} \in N(\mathbf{Q})$$

Hence $N(\mathbf{Q}) = N(\mathbf{Q}^H \mathbf{Q})$. Note that $\mathbf{Q}^H \mathbf{Q} \in \mathbb{C}^{m \times m}$. We will use the rank-nullity theorem to see

$$\text{rank}(\mathbf{Q}) = n - \dim(N(\mathbf{Q})) = n - \dim(N(\mathbf{Q}^H \mathbf{Q})) = \text{rank}(\mathbf{Q}^H \mathbf{Q})$$

This completes the proof.

Question 3: Suppose $\mathbf{y} \in \mathbb{C}^m$ and $\mathcal{S} \subset \mathbb{C}^m$ be a subspace. We define the standard inner product in \mathbb{C}^m as $\langle \mathbf{v}_1, \mathbf{v}_2 \rangle = \mathbf{v}_2^H \mathbf{v}_1$. Let $\mathbf{V} = [\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k] \in \mathbb{C}^{m \times k}$ be the matrix of basis vector of \mathcal{S} . Then show that the normal equation is equivalent to

$$\mathbf{V}^H \mathbf{y} = \mathbf{V}^H \mathbf{V} \mathbf{x}$$

Find the projection of \mathbf{y} onto \mathcal{S} .

Solution 3: We will show \mathbf{A} and \mathbf{b} defined in (1) is equal to $\mathbf{V}^H \mathbf{V}$ and $\mathbf{V}^H \mathbf{y}$. First see that $(\mathbf{A})_{i,j} = \langle \mathbf{v}_j, \mathbf{v}_i \rangle = \mathbf{v}_i^H \mathbf{v}_j$. Then $(\mathbf{V}^H \mathbf{V})_{i,j} = \mathbf{v}_j^H \mathbf{v}_i$. Hence this shows

$$\mathbf{A} = \mathbf{V}^H \mathbf{V}.$$

Similarly

$$(\mathbf{b})_i = \langle \mathbf{y}, \mathbf{v}_i \rangle = \mathbf{v}_i^H \mathbf{y} = (\mathbf{V}^H \mathbf{y})_i.$$

Hence $\mathbf{b} = \mathbf{V}^H \mathbf{y}$. This shows the normal equation is equivalent to

$$\mathbf{V}^H \mathbf{y} = \mathbf{V}^H \mathbf{V} \mathbf{x}.$$

Since \mathbf{V} consists of basis vectors, $\text{rank}(\mathbf{V}) = k$. Then $\text{rank}(\mathbf{V}^H \mathbf{V}) = k$. This show $\mathbf{V}^H \mathbf{V}$ is invertible. Hence the solution to the Normal Equation is given as

$$\mathbf{x} = (\mathbf{V}^H \mathbf{V})^{-1} \mathbf{V}^H \mathbf{y}.$$

The projection of \mathbf{y} onto \mathcal{S} is given as

$$\hat{\mathbf{y}}_S = \sum_{i=1}^k x_i \mathbf{v}_i = \mathbf{V} \mathbf{x} = \mathbf{V} (\mathbf{V}^H \mathbf{V})^{-1} \mathbf{V}^H \mathbf{y}$$

Question 4: Let $\mathcal{S} = \{\mathbf{X} \in \mathbb{R}^{m \times m}, X_{i,j} = X_{j,i}\}$ be the set of symmetric matrices. We define the inner product in $\mathbb{R}^{m \times m}$ as $\langle \mathbf{S}_1, \mathbf{S}_2 \rangle = \text{trace}(\mathbf{S}_2^T \mathbf{S}_1)$.

- Show that the orthogonal projection of any matrix $\mathbf{A} \in \mathbb{R}^{m \times m}$ onto \mathcal{S} is

$$\frac{\mathbf{A} + \mathbf{A}^T}{2}$$

Solution 4: Note that in Discussion 2, we showed that \mathcal{S} is a subspace of $\mathbb{R}^{m \times m}$. Hence the orthogonal projection is well defined. Now we can easily show that

$$\left(\frac{\mathbf{A} + \mathbf{A}^T}{2}\right)^T = \frac{\mathbf{A} + \mathbf{A}^T}{2} \implies \frac{\mathbf{A} + \mathbf{A}^T}{2} \in \mathcal{S}$$

In discussion 2, we constructed the basis of \mathcal{S} . Remember we defined the matrix $\mathbf{E}_{i,j}$ for given $1 \leq i, j \leq m$:

$$(\mathbf{E}_{i,j})_{k,l} = \begin{cases} 1 & \text{if } i = k, j = l \text{ or } i = l, j = k \\ 0 & \text{otherwise} \end{cases}$$

Based on this definition, we showed the set

$$\mathcal{A} = \{\mathbf{E}_{i,j} \mid 1 \leq j \leq i \leq m\}$$

is a basis of \mathcal{S} . We need to show

$$\langle \mathbf{A} - \frac{\mathbf{A} + \mathbf{A}^T}{2}, \mathbf{S} \rangle = 0, \quad \forall \mathbf{S} \in \mathcal{S}$$

This condition is equivalent to

$$\langle \mathbf{A} - \frac{\mathbf{A} + \mathbf{A}^T}{2}, \mathbf{E}_{i,j} \rangle = 0, \quad \forall \mathbf{E}_{i,j} \in \mathcal{A}$$

We evaluate the inner product as follows:

$$\begin{aligned} \langle \mathbf{A} - \frac{\mathbf{A} + \mathbf{A}^T}{2}, \mathbf{E}_{i,j} \rangle &= \langle \frac{\mathbf{A} - \mathbf{A}^T}{2}, \mathbf{E}_{i,j} \rangle = \text{trace}(\mathbf{E}_{i,j}^T (\frac{\mathbf{A} - \mathbf{A}^T}{2})) \\ &= \sum_{k=1}^m \sum_{l=1}^m (\mathbf{E}_{i,j})_{k,l} (\frac{\mathbf{A} - \mathbf{A}^T}{2})_{k,l} = (\frac{\mathbf{A} - \mathbf{A}^T}{2})_{i,j} + (\frac{\mathbf{A} - \mathbf{A}^T}{2})_{j,i} \\ &= \frac{\mathbf{A}_{i,j} - \mathbf{A}_{j,i}^T + \mathbf{A}_{j,i} - \mathbf{A}_{i,j}^T}{2} = \frac{\mathbf{A}_{i,j} - \mathbf{A}_{i,j} + \mathbf{A}_{j,i} - \mathbf{A}_{j,i}}{2} = 0 \end{aligned}$$

Hence $\frac{\mathbf{A} + \mathbf{A}^T}{2}$ is the orthogonal projection of \mathbf{A} onto \mathcal{S} .