

Analog Circuit

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Abstract

In this lab we work on the physics of an analog circuit, by building a radio demodulator and an amplifier. We understand the physics behind the transmission of radiowaves and signal transmissions, by developing our own circuits using breadboards and analysing signals with an oscilloscope. The design and construction were made in group by the following students: Isaac Domagalski, David Galbraith and Leonardo Sattler. At last, we study sources of noise related to electric circuits and develop Python codes (individually) to enhance its comprehension.

1 Introduction

Radio players deal with several electronic components that, added together on a certain order, will generate different features with huge physical meaning behind them. With the purpose of understanding the theory behind it, we describe separately the working of these components, and simulate their behavior with generated graphs. The plots are a way of picturing what happens inside these circuits.

To play an FM signal is our main goal, but transmission, enhancement and lost of these signals are discussed, so as their impact over the system and how one generally deals with it. This is done with an statistical approach over some of these problems with developed codes in *Python*, and the results are physically interpreted.

2 FM Demodulator

In order to understand what is an analog circuit we built a radio receiver on a breadboard, by using electronic devices provided by the Undergraduate Lab at UC Berkeley. The basic concept of this device is, by the receiving of a radio signal it will, first, translate this signal into audio information and than enhance it by an electrical filter (see Fig.1). The scheme presented was used to reproduce FM (Frequency Modulated) waves from a source located in the lab.

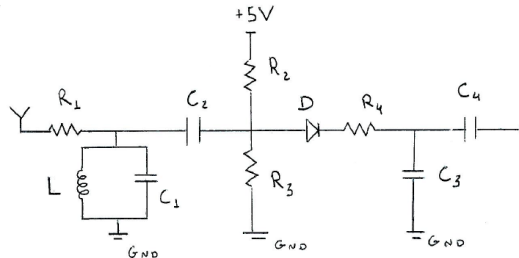


Figure 1: Sketch of the FM demodulator circuit built for this lab.

Electric Component	Value
R_1	33Ω
R_2	150Ω
R_3	150Ω
R_4	150Ω
C_1	$22000 pF$
C_2	$10000 pF$
C_3	$10000 pF$
C_4	$10000 pF$
L	$1 \mu H$

Table 1: Components specifications. The values were calculated by looking at reference tables for Resistors and Capacitors.

The very first part is an antenna that receives the signal from the FM source. The oscilating signal produces a flow of electrons that will run through the circuit as an alternating current AC . The only external power here is the $+5V$ battery providing direct curent DC , that will not be over the whole circuit.

The reason is because the capacitors C_2 and C_4 have their own job of blocking direct current. Made of parallel plates that, once in equilibrium after charged, no flow of electrons will pass by them. From a practical point of view it devides the circuit, and the $+5V$ voltage source won't act on the electrical components after C_2 and C_4 . The other elements act together creating electrical devices that will determine the working of the whole circuit. They are presented and described on the next sections.

2.1 RLC Filter

By using an antenna, it first captures the signal. After passing by R_1 , it reaches a device that will translate the variable frequency wave into an Amplitude Modulated wave, which is a signal with a variable amplitude. It generates an *envelope* over this signal, now called *carrier* (see Fig.2). This device, together with R_1 , is known as RLC filter, and the other components are a *Capacitor* and an *Indutor* (L on Fig.1).

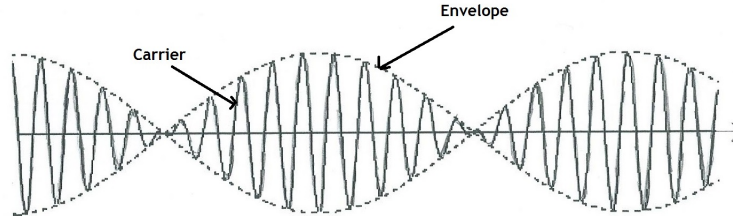


Figure 2: Figure showing the wave after passing by the RLC filter. An envelope over the amplitude modulated signal, the carrier.

Series RLC circuits give minimum impedance at the so called Resonance Frequency. Parallel RLC (also known as 'tank', used here) give maximum *impedance* (technical name for the resistance created by the circuit components) at their resonant frequency. It is used to short the entrance signal based on its frenquency. Our receiving signal is a faked FM station at $1.045 MHz$. The resonant frequency is calculated with the following formula:

$$f_0 = \frac{1}{2\pi\sqrt{LC}}, \quad (1)$$

and by looking at Table 1 we have $f_0 = 1.073 MHz$.

The basic physics behind this device is that Indutor and Capacitor store electromagnetic energy by themselves by the passing of an electric current. They store but also release, and this keep going as an

oscilating pendulum, but the energy fades with time. This will generate a change in amplitude for the signal (recall that $Energy \propto V^2$), and its minimum possible value will be the one closer to f_0 . It is clearly shown by the equation

$$Z(\omega) = -j \frac{1}{C} \frac{\omega}{\omega^2 - \omega_0^2}, \quad (2)$$

where Z is the letter for impedance, $\omega = 2\pi f$ is the incoming frequency and $\omega_0 = 2\pi f_0$ is the natural frequency of oscilation from Eq.1. It is straightforward to realize the growth of Z as $\omega \rightarrow \omega_0$.

Our working FM station produces waves at 1.045 MHz . We built our circuit with R , C and L that could match something close but not at 1.045 MHz , creating high *resistence* for these frequencies and allowing f_0 to survive (almost) alone after the filter. Fig.3 shows the behavior of the impedance due to the LC values chosen, and the maximum impedance happens on the f_{max} specified on the graph, marked with the green dashed line.

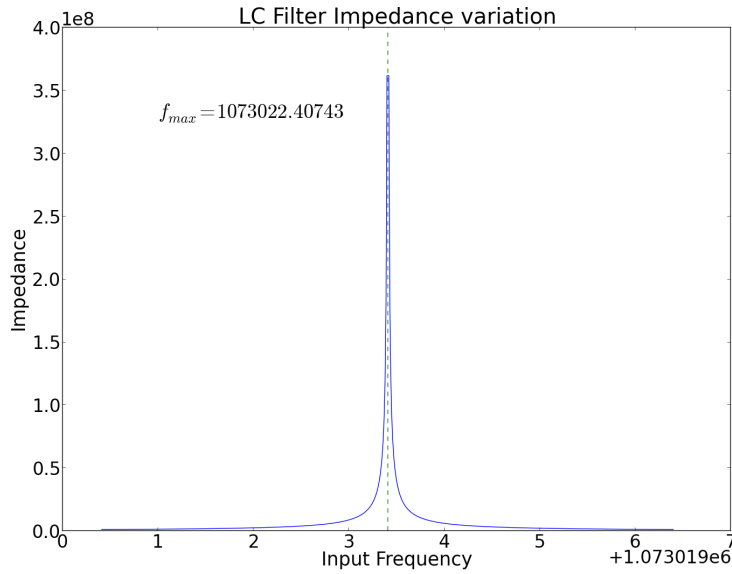


Figure 3: Impedance response to a given frequency input. The value of f_{max} corresponds to the one of maximum impedance, and as expected matches with f_0 .

2.2 Envelope Detector

2.2.1 Biasing and Diode

Once we have a well behaved Amplitude Modulated signal, we use a *Diode* (D on Fig.1) to remove the negative part of the incoming wave, composed by the *carrier* and the *envelope* (see Fig.2). But first we apply a Voltage source ($+5V$) to power up the circuit. It adds a step voltage to the oscilating signal, basing it, and at the same time gives more current flow for the diode. The Resistors R_2 and R_3 act as voltage dividers, lowering its value through the circuit.

The diode works by allowing the current flow through only one direction: positive or negative (in our case positive). Since we have an alternating current on the circuit, the diode will block any backing current and no negative value of the oscilating wave will survive after that. This feature allows the capacitor only to charge, since no signal with opposte value will pass by it. It charges after each oscilation of the carrier wave, never discharging until it reaches its maxima, when it will keep following its peaks. The result is a wave profile as the one of the the envelope but with no negative part and no carrier, taken out by its association with a Resistor, presented next, creating a device that is presented next.

2.2.2 RC Filter

In order to clean the internal waves of the envelope a RC Filter is used with the diode. They together are known as Envelope Detector, since the output will be only the positive part of the envelope originally travelling with a carrier.

The RC configuration used above is called *Low Pass Filter*. It literally allows only small frequencies to survive, hence the disappearing internal waves (with high frequency in contrast to its envelope). As we can see on Fig.4, the so-called cutoff frequency is the one at which the signal is attenuated by $3dB$, happening at

$$\omega_{3dB} = \frac{1}{RC}, \quad (3)$$

defining the bandwidth that survives due to this device. On the graph we see that the bandwidth is composed by frequencies smaller than $\omega_{3dB} = 106103.295$, placed on the left part before the vertical green dashed line.

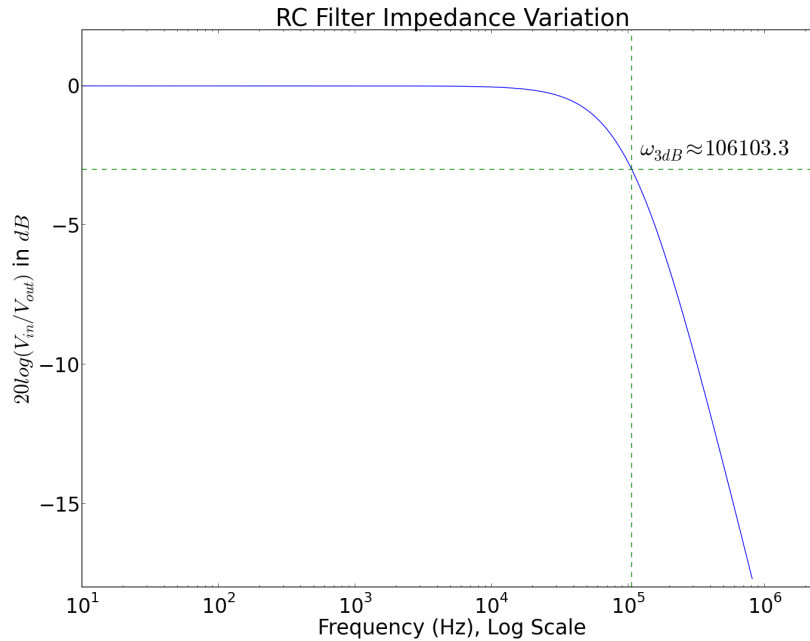


Figure 4: Graph showing the impedance response due to the input frequency. The vertical green dashed line marks the *cutoff frequency*, and the horizontal one the $3dB$ of attenuation on the input signal, corresponding to a 70.7% of lost, defining the bandpass.

The input FM signal, after turned into an AM wave with an amplitude and frequency very well defined, reaches the RC filter for an extraction of what really is the audio signal. Now it is able to be the input of an amplifier before reaching our ears.

3 Amplifier

Amplifiers are devices that enlarge the power of a given input, by a certain ratio called *gain*, basically by the usage of *Transistors* in association with resistors (See Fig.5). The one built here is known as Emitter-Follower.

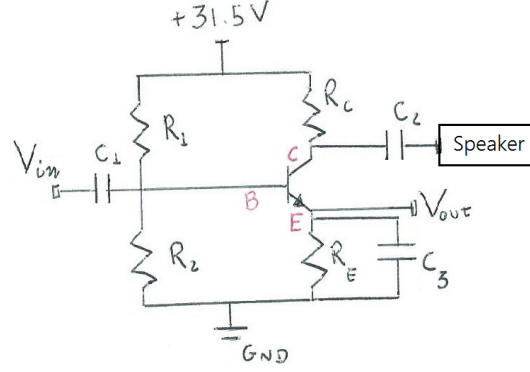


Figure 5: Sketch of the circuit of an Amplifier built for this lab.

Electric Component	Value
C_1	$1 \mu F$
C_2	$1 \mu F$
C_3	$1 \mu F$
R_1	3900Ω
R_2	470Ω
R_C	510Ω
R_E	220Ω

Table 2: Components specifications for the Amplifier circuit.

Again, C_2 is isolating the circuit from the DC current provided by the external source. C_1 also isolates this current from the RM Demodulator of the last section, that will provide the signal to be amplified. C_2 separates the amplifier from the speaker that will be playing the output of this circuit. The other components (including C_1 , that plays another role here) are described in the following sections.

3.1 Transistors

Transistors are composed by 2 diodes that work under certain conditions. On the next diagram, a *BjT* (*Bipolar junction Transistors*) is presented with its terminals, *B*, *C*, and *E*. They are the Base, Collector and Emitter. The voltage difference between base and emitter ($V_{BE} \approx 0.6V$) is constante, so if V_{in} drops, so does V_E , and will rise if V_{in} incrases:

$$V_{out} = V_{in} - V_{BE}. \quad (4)$$

The same between collector and emitter ($V_{CE} \approx 0.2V$). This is guaranteed by the collector, that allows the current to pass given a DC source (+31.5 V). Both collector and emitter will cease the current and stop working if these conditions are not satisfied.

3.1.1 Biasing the Circuit

And how does the amplification work? It is related to the current and the resistance at the terminals of the transistor. Once respected the relation of the previous equation, we have for the currents:

$$I_E = I_C + I_B, \text{ or } I_E = (\beta + 1)I_B, \quad (5)$$

where $\beta = I_C/I_B = 60$, a nominal value of the used transistor. The key understanding is that, with a *biasing source* as the +31.5V used here, the current flow will be respecting the rules of Eq.'s(4) and (5) and won't care for the impedance of the load, in our case a speaker. It means that, even with a small current on the

input I_B , provided by V_{in} , the current I_E at V_{out} will be a lot larger, in such a way that I_B is negligible on Eq.(5).

What does it mean in terms of power? Having a higher current flow means more energy ($Energy \propto I^2$), so this and not a voltage gain is the responsible for amplifying the signal (as one can see from Eq.(4), $V_{in} - V_{out} = V_{BE} = 0.6$ is not a considerable value).

Since, as discussed in the beginning of Section 2.1, transistors only work if V_{BE} is over a threshold, the values of R_1 and R_2 are chosen to be high in order to avoid too much current from the biasing voltage source to flow toward the base terminal, and guarantee its flow through collector and emitter. In addition to that, once specified the value of the biasing voltage source ($+31.5V$) and the impedance value of $Z_C = R_C$, I_C is known from *Ohm's Law* ($V = RI$), and so is I_E (see Eq.(5), and recall that I_B is too small compared to I_C). For a given Z_E it also means a known V_E .

With the quantities calculated above, one can choose the right R_1 and R_2 to work as voltage dividers, and drop the voltage from the biasing source until the desired value for the terminal V_B . This will give the transistor the minimum value $V_{BE} = V_B - V_E$ to satisfy its working conditions, even if there's no voltage input V_{in} .

3.1.2 Gain

To measure how much is the amplification, one can calculate the gain given by this configuration. It is the ratio of the impedance on the collector terminal and of the emitter terminal. The impedance Z_C on the collector is simply R_C . On the emitter, Z_E it is the impedance of a resistor (R_E) in parallel association with a capacitor (C_3). As a result:

$$g = \frac{Z_C}{Z_E} = \frac{R_C}{R_E} \sqrt{1 + R_E^2 \omega^2 C_3^2}, \quad (6)$$

and one can choose R_E , R_C and C_3 in order to achieve a desired value for g (see next graph).

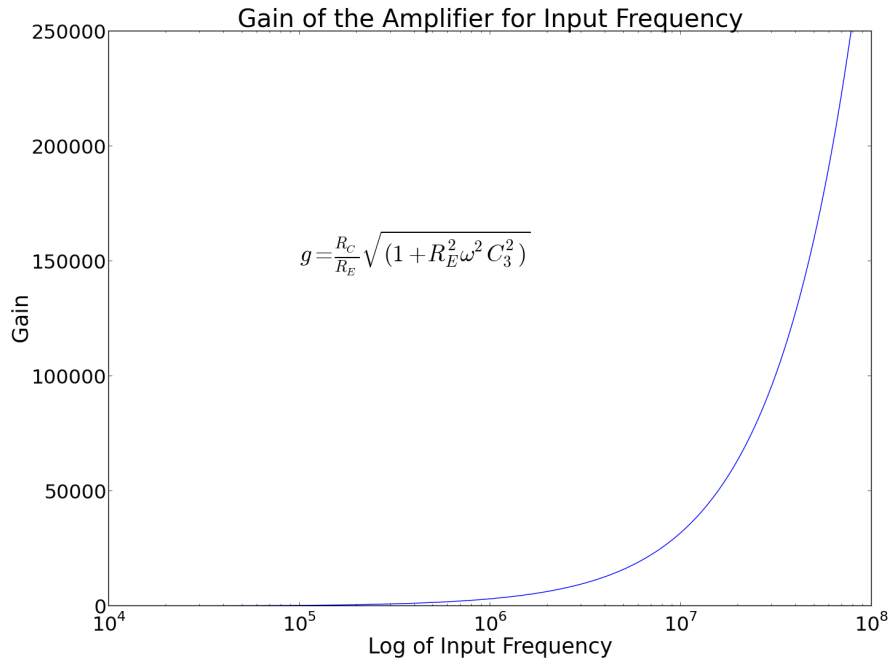


Figure 6: Amplifier response related to the frequency input. The gain is higher for higher frequencies.

As seen on Fig.(6), the gain is higher for higher frequencies. It is like this because the calculus of our gain, which evolves the impedances at the collector and emitter (see Eq.(8)), has to deal with the capacitor

at the emitter's terminal, and it has a variable impedance that depends on the receiving frequency.

3.2 Another RC Filter

This result for the gain is important because, despite all that has been said about R_1 and R_2 so far, together with C_1 they compose what is called a *High Pass Filter*, located at the very beginning of our circuit diagram.

The filter described on Subsection 2.2.2 was a capacitor following a resistor creating a Low Pass. When the opposite is true, and a capacitor comes before the resistance, they work in such a way to have a maximum impedance for low frequencies. The cutoff frequency is again

$$\omega_{3dB} = \frac{1}{RC}, \quad (7)$$

but due to the different configuration the result is as shown in Fig.(7) (it is interesting to compare with Fig.(4)).

This is totally reasonable since we are designing an audio amplifier, so we want it to operate frequencies on the range 20 Hz to 20 kHz . This is, as seen on Fig.(7) (x axis in log scale), what this filter will provide. The bandwidth that survives after it belongs to the range of $\approx 400\text{ Hz}$ to higher than 20000 Hz .

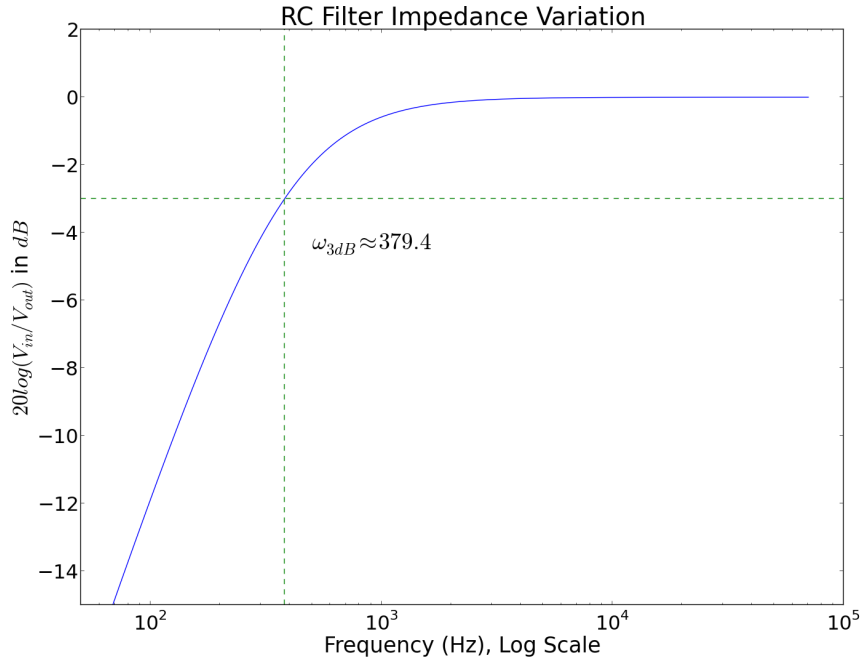


Figure 7: Amplifier response related to the frequency input. The gain is higher for higher frequencies.

3.3 Impedances

In the overall, powering a circuit is a matter of giving more current than the input voltage V_{in} provides, reaching the load with a factor called gain that increases it. Another way to understand this phenomena is realizing that the input has an impedance different from the output. For example, looking into the base one sees an *input impedance* of $Z_{in} = R_{in}\beta$, while looking into the emitter sees an *output impedance* smaller than that, equals to $Z_{out} = R_{out}/\beta$. In this case R_{in} is any impedance connected to the emitter, and R_{out} is whatever impedance connected to the base.

It tells the upcoming signal V_{in} that the circuit has an impedance much larger than the one seen by the load, and that is why even with an small input current the voltage on the output is powered and we see an amplification of the original signal.

But impedances are relevant not only for power gain, but also to avoid its lost. In a *Transmission Line*, a wire that propagates the signal from a source to a load, impedance matching is a key factor. It is true because the signal can reflect either with positive or negative sign when finding a different impedance along its way. The reflection will be positive if there's a load with higher resistance than the one of the cable, and negative if the load has a lower resistance. Reflections are not desired since it causes interference with the upcoming waves, so to avoid this we seek for an impedance matching between source, cable and load.

If we are to transmit the output of the amplifier to a speaker with a wire, we should look for the impedance of both. To calculate the impedance of a transmission line there's the following equation,

$$Z_0 = \sqrt{\frac{L}{C}}, \quad (8)$$

which is interesting since does not depend on the cable's length. The impedance of the speaker, as of other loads, is usually known. The objective is than look for a way to match the impedance of the cable with both source and load. But maximizing power transfer is not the same as maximizing power efficiency (η):

$$\eta = \frac{R_{load}}{R_{source} + R_{load}} = \frac{1}{1 + \frac{R_{source}}{R_{load}}}, \quad (9)$$

showing that when $R_{load} = R_{source}$ we have $\eta = 0.5$.

However, impedance mismatching can lead to excessive power use, distortion and noise problems. The most serious problems occur when the impedance of the load is too low, requiring too much power from the source to drive the load with the signal. So the importance of matching impedances goes beyond just avoiding reflections, but as showed in Eq.(9) it does not mean a transmission of the total power from our amplifier.

4 Noise

Well built audio circuits will provide high audio fidelity. But the sound quality can be compromised by several factors, and the *Noise* is one of them. The Johnson-Nyquist noise is characterized as the thermal noise generated by the random motions of electrons on a resistor. This motion generates a resultant flow that is interpreted as a current by the circuit and a voltage appears.

The equation describing this phenomena is

$$V^2 = 4K_B T B R, \quad (10)$$

where K_B is the Boltzmanns constant, T the temperature of the resistor, B is the frequency bandwidth of the circuit and R is the resistance of the resistor. The Power signal (P_{sig}) generated is easily derived, since $P_{sig} = V^2/R$:

$$P_{sig} = 4K_B T B. \quad (11)$$

This power will propagate through the circuit and be a source of noise for it. This is also known as the *White Noise* of the circuit, and since the random motion of electrons is proportional to the temperature on the resistor, the higher it is more voltage will appear. Besides that, Eq.(13) also tells that larger bandwidth will increase the noise. So a way to reduce it is by either cooling the resistor or working with a smaller bandwidth on our systems.

4.1 Fourier Transform

Fourier Transform is a mathematical tool used to convert any signal from time domain to frequency domain and vice versa. If we analyse the voltage (or current) flowing over time on the resistance generating the noise and apply a Fourier Transformation, we find a cutoff frequency for which this thermal noise will cease (which high, $\approx 50 \text{ Ghz}$). And the power noise as a function of frequency ($P_{sig}(\omega)$) appears to be *flat*, meaning that we usually receive the same amount of noise for a big range of frequency, untill it starts cutting off (around the cutoff frequency).

Since our circuits usually operate under this cutoff frequency, we associate our noise to a determined bandwidth,

$$P_{sig} = K_B T B, \quad (12)$$

and B is the range of frequency determined by our low pass and high pass filters, for example. The drop of the 4 from Eq.(13) is because a source only maximize its power transfer to a load when we have an impedance matching, as discussed on Section 3.3. In order to have this power noise running over the circuit, we can think the resistor generating it as a source, and the impedance of the circuit as a load. From Eq.(9), this impedance matching will provide a factor of 0.5 over the voltage output and hence a factor of 0.25 for P_{sig} .

4.2 Random Electrons

The thermal noise is a source of random error that acts over electrical circuits. But within the time it shows an amplitude distribution that corresponds to a *Gaussian*, what can be illustrated with the *Central Limit Theorem*.

This theorem says that, on the limit of a large quantity of sets of some variables from any random distribution, the ensemble of these sets emerges on a Gaussian distribution. To prove so, a code was developed to apply the Central Limit Theorem to a distribution created with a random range of integers by the usage of the *numpy.random* function in *Python*. The result is shown on Fig.(8).

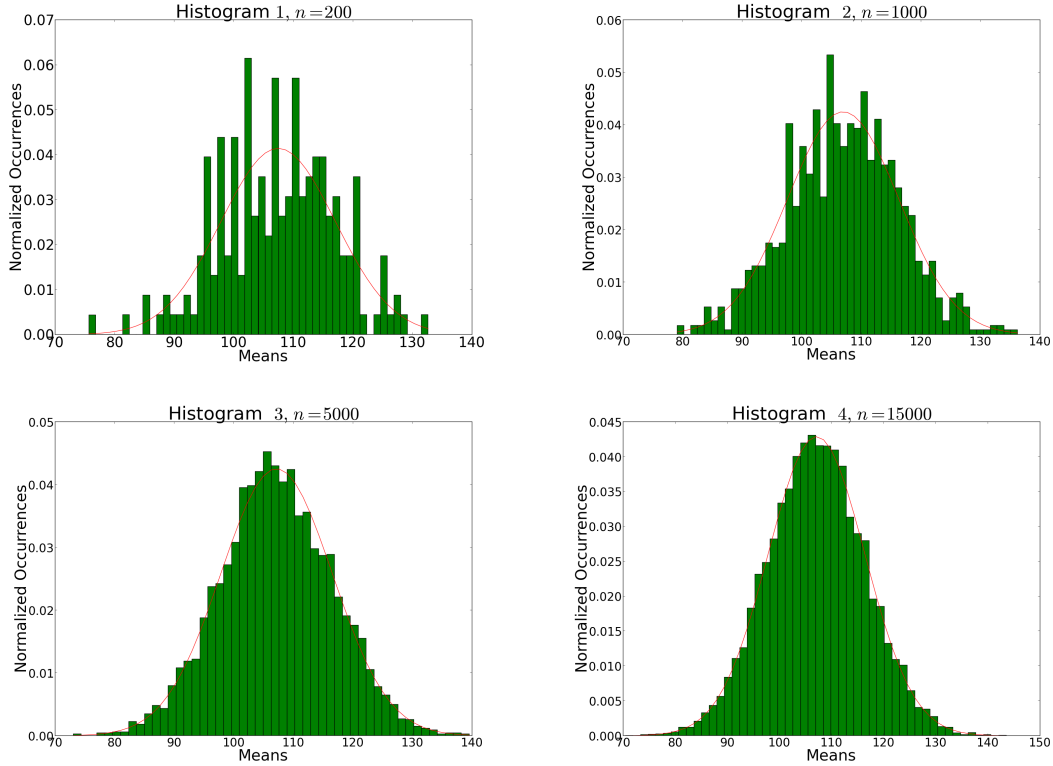


Figure 8: These histograms show how the means of sets with a given sample size, when added over and over n times, will approach a Gaussian Distribution, showing that the Johnson-Nyquist noise will act with a gaussian profile over the system. Histogram 1, with $n = 200$, has a randomic shape that is not much of a gaussian. As n grows, untill $n = 15000$ on Histogram 4, we see the gaussian profile taking form over the mean occurrences.

Also, for any random distribution, a larger number of samples used to calculate the mean will result on a smaller standard deviation for the converged gaussian noise. This is ilustrated by Fig.(9), where a curve of the form

$$\sigma = \frac{1}{\sqrt{N}} \quad (13)$$

was used to fit the data, N being the number of samples and σ the standard deviation of these sample means.

Physically speaking, the averaged velocities of the electrons inside a resistor will add up n times until converge to a resultant value, that is different from zero and will be described by a gaussian. Besides that, the larger is the N number of electrons randomly contributing to this net velocity, smaller will be the standard deviation of this gaussian.

A possible way to experimentally check the Johnson-Nyquist noise is to plug a cable on a resistor, properly heat it and check the noise appearing on an oscilloscope or powermeter. Since this signal is supposed to be small, amplifiers are required to enhance it. However, some points as impedance matching and the signal noise of the own amplifiers must be observed, since it must be significantly small compared to the resistor's noise and a person might want to use more than one to get more gain. Another problem is choosing a filter that will supply the correct bandwidth for the used amplifiers, filtering their signal before reaching the oscilloscope.

If the result is not an increase of the noisy signal as you plug your resistor to end of the cable, something is amiss. Even if following these conditions, one must recall that the *Signal to Noise Ratio* is what comes into play while trying to observe the resistor's noise above the noise generated by your configuration. A deeper study over this can drive more general explanations. For example, the information transmission, on a system of a specified bandwidth in the presence of a gaussian noise, will be the maximum according to the *Shannon-Hartley Theorem*. These are relevant subjects to be understood while conducting this experiment.

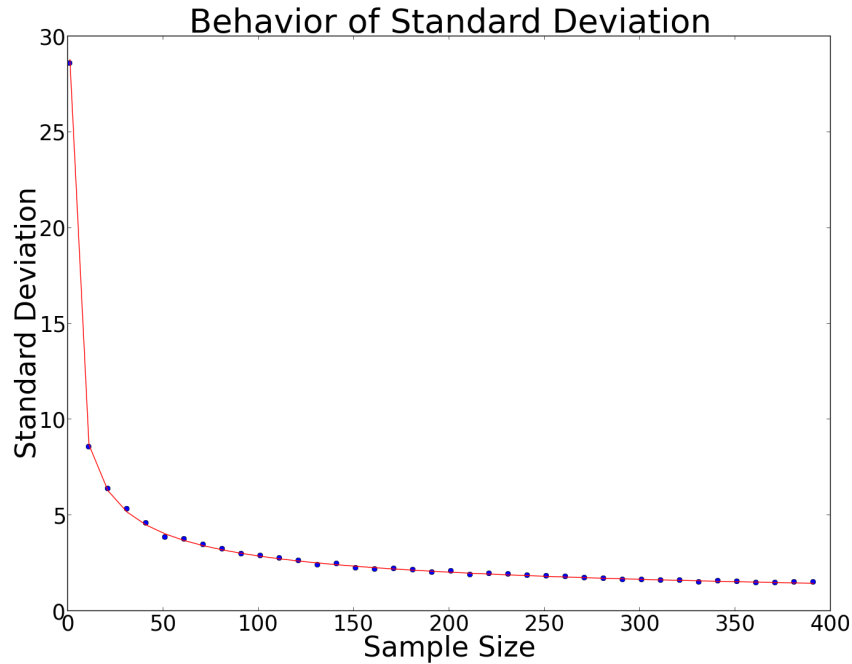


Figure 9: Standard Deviation of the mean of N random samples. Increasing N , the standard deviation drops as describe by the red line: $\sigma \propto 1/\sqrt{N}$.

5 Conclusion

In this lab, the construction of circuits was very important to understand the physical concepts behind electronic equipments, and this was achieved by applying the knowledge of different associations between inductors, capacitors, and resistors, also by understanding the working of a diode and a transistor. As seen

on the Fig.'s (3), (4), (6) and (7), the theoretical plots were consistent with the experimental results read on the oscilloscope, when analysing the difference between input and output signal over the built devices.

We can firmly state that the specified values used on Tables 1 and 2 were properly chosen, since both FM Demodulator and Amplifier were giving the expected output on the oscilloscopes. More than that, they were attached together and plugged into a speaker, tuned to a FM station and the result was as expected: an amplified audio signal (music!). By decoupling the circuit of Fig.(5) from the one of Fig.(1), the volume was lower as expected.

The Johnson-Nyquist noise profile over the circuit was well described by the presented graphs, as a result of the developed code (sent together with this lab report), that provided the physical association between the Central Limit Theory and the thermal noise.

The experimental difficulties related to the proof of this phenomena were presented, and relevant topics about the theory of signal propagation and detection were cited, as starting points to overcome these difficulties.