Sorting algorithms: how are they affected by memory faults?

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Abstract

Although most people in the world use technology devices for many tasks, they don't know how the devices work and how they deal with faults. When those faults occur in memory, software behavior could be affected. Together with the software-specific algorithms are the sorting algorithms used to solve problems like ordering a list of products by their price. This work presents a discussion about how quicksort, mergesort, insertionsort and bubblesort algorithms are affected by memory faults.

Index Terms

sorting algorithms, memory faults.

I. Introduction

Technology is deeply introduced in people's quotidian supporting a massive number of tasks, for example: searching for a shared car, surfing on the web, sending a message to someone, automating the company's production or using the company's software. Nevertheless, most people don't know that devices are continually dealing with memory failures, faults and errors. These devices were made with large and inexpensive memories, which are also error-prone [1].

Software behavior may be affected by the problems mentioned before, especially those from memory. We have a memory fault when the correct value that should be stored in a memory location gets altered because of a soft failure. In particular, the content of a location can change unexpectedly, i.e., faults may happen at any time: real memory faults are indeed highly dynamic and unpredictable [2].

In the beginning steps of software development, the designer has a general idea of the structure and functions. For each one of these, some algorithms will be produced or used. In the following stages, the outcome software (and its algorithms) will be tested and, then, delivered to the user. Different kinds of algorithms could be written or used in the software, and one of these is the sorting algorithms.

A good algorithm is that which gives satisfactory results for every range of data set. Sorting is a fundamental concept and important for solving other problems like is prerequisite for Binary Search. Sorting is often used in a large variety of critical applications and is a fundamental task that is used by most computers [3].

In this paper, we present a discussion about how these sorting algorithms, particularly Quicksort, Mergesort, Insertion Sort and Bubblesort, are affected by memory faults.

II. BACKGROUND

In this section we describe basic concepts about memory faults and sorting algorithms.

A. Memory Faults

Even the best digital system, with high-quality components and design techniques, may not be infallible to faults. Despite the title of this subsection, when the entire digital system (or software) is considered, there are three terms for computing fault and they have different meanings: failure, fault and error [4].

- *Error*: An error is a manifestation of a fault in a system, in which the logical state of an element differs from its intended value. An error occurs for a particular system state and input when an incorrect next state and/or output results.
- Fault: A fault is an anomalous physical condition. Causes include design errors, manufacturing problems, damage, fatigue, or other deterioration. Faults resulting from design errors and external factors are especially difficult to model and protect against because their occurrences and effects are hard to predict. A fault in a system does not necessarily result in an error;
- Failure: A failure denotes an element's inability to perform its functions because of error in the element itself or its environment, which in turn are caused by various faults;

B. Sorting Algorithms

Sorting algorithms are widely used in many aspects of data processing, information searches, business finance, computer encryption, etc. This work uses four sorting algorithms: quicksort, mergesort, insertionsort, and bubblesort. In the following subsections, we'll give an overview of them.

1) Quicksort: Quicksort algorithm, created by Hoare [5], is considered as one of the fastest and best sorting algorithms [6]. The algorithm is based on the paradigm of divide and conquer.

This algorithm has a execution time of $\theta(n^2)$ in the worst case over n numbers as input. Despite that execution time, quicksort is often the best option for sorting because of its remarkable average efficiency: $\theta(nlgn)$ [7].

The basic steps of this algorithm are [6]:

- Pick an element, which is called a pivot, from the list waiting to be sorted;
- Perform partition operation to realize that all elements in the list with values smaller than the pivot came before the pivot. Otherwise, all elements in the list with values bigger than the pivot come after it (elements which are equal to pivot can go either way). After this partition, the pivot is in the final position of the list;
- Recursively sort the sub-list of smaller elements and the sub-list of the bigger elements.
- 2) Mergesort: Mergesort was invented by John Von Newman and is one of the most elegant algorithms to appear in the sorting literature. It is the first sorting algorithm to have $\theta(nlgn)$ execution time bound. It is important to observe that this algorithm spends a lot of time on data transfer operations. In fact, standard Mergesort incurs about 2n data move operations [8].

Conceptually, Mergesort works as follows [8]:

- Divide the unsorted array into two sub arrays of about half the size;
- Sort each sub array recursively;
- Merge the two sub arrays back into one array.
- 3) Insertionsort: This algorithm sorts the array by shifting the elements one at time. It is efficient in sorting a small number of elements. The overall execution time of this algorithm is $\theta(n^2)$ [7]. The basic sorting steps are:
 - If there are more than one element, pick the next element;
 - Compare with all the elements in sorted sub-list;
 - Shift all the elements in sorted sub-list that is greater than the value to be sorted;

- Insert the value;
- Repeat until list is sorted.
- 4) Bubblesort: The bubble sort is the oldest and simplest sorting method in use. It works by comparing each item in the list with the item next to it, and swapping them if required. The algorithm repeats this process until it makes a pass all the way through the list without swapping any items (in other words, all items are in the correct order) [9].

Table I below shows the time complexity comparison between the sorting algorithms presented. The n is the number of input elements.

TABLE I: Sorting algorithms complexity time comparison [10]

Algorithm	Time Complexity			
Aigurium	Best Case	Average Case	Worst Case	
Bubblesort	$O(n^2)$	$O(n^2)$	$O(n^2)$	
Insertionsort	O(n)	$O(n^2)$	$O(n^2)$	
Quicksort	O(nlgn)	O(nlgn)	$O(n^2)$	
Mergesort	O(nlgn)	O(nlgn)	O(nlgn)	

III. MATERIALS AND METHODS

We first state our problem, then describe our data, showing all its characteristics. Then, we provide our hypothesis, define the setup, and perform the testing. Finally, we collect and perform data analysis.

A. Problem Statement

As introduced in the first section of this paper, sorting is a fundamental concept and essential for solving other problems. The content of memory location can change unexpectedly, i.e., faults may happen at any time. Considering this, the main objective of this work is to design experiments to answer the following question: *How are sorting algorithms affected by memory faults?*

B. Variables

For this experimental study, we assume that the independent and dependent variables are as shown in Table II and Table III below:

TABLE II: Independent variables.

Variable	Description
Probability of failure	Probability of a fault to occur
Array size	Size of the array of integers to be sorted
Sorting algorithm	Algorithm used to sort the array

TABLE III: Dependent variables.

Variable	Description
Largest subarray size Size of the largest sorted subarray produced under the memory fault	
Percentage of largest subarray size Percentage of largest subarray size related to array size independent variable	
Unordered elements quantity Quantity of elements out of position after sorting algorithm execution. Ada	
	k-unordered sequence measure of disorder defined in [11]
Percentage of unordered elements quantity Percentage of unordered elements quantity related to array size independent	

C. Hypothesis

The set of hypothesis defined to test and draw some conclusions about this experiment are listed below. The confidence degree defined for hypothesis testing was 95% ($\alpha = 0.05$ and $\alpha - 1 = 0.95$).

- **Hypothesis 1:** For a given probability of failure and array size, tested algorithms will produce a different percentage of unordered elements quantity.
- **Hypothesis 2:** For a given probability of failure and array size, tested algorithms will produce a different percentage of the largest subarray size.
- **Hypothesis 3:** For each algorithm, the array size and probability of failure have a significative impact on the percentage of unordered elements quantity.
- **Hypothesis 4:** For each algorithm, the array size and probability of failure have a significative impact on the percentage of the largest subarray size.

D. Experimental Setup

To conduct the proposed study, we define the values of the independent variables, as shown in Table IV:

TABLE IV: Values of the independent variables.

Variable	Values	
Probability of failure	1%, 2% and 5%	
Array size 100, 1000 and 10000		
Sorting algorithm Bubblesort, Quicksort, Mergesort and Insertion		

Based on these variables, we ran an existing script *gen.py* to produce input files. We define that our sample was composed by 30 input files for a given combination of the probability of failure and array size. So, considering this, we ran 30 times for each combination of these independent variables, producing 30 inputs, totalizing 270 files. Figure 1 shows an example of produced input files:

0.01 100 9 48	37 6 26 7 24 44 17 50	48 30 49 33 22 13 42 29 39	13 19 13 9 28
34 1 33 27 14	45 48 40 11 17 6 50 9	44 20 16 37 45 23 14 38 29	10 49 44 46 35
45 15 2 22 1	46 40 8 48 23 23 32 35	3 15 8 36 17 24 27 48 28 5	28 50 44 4 25
6 9 1 11 44 2	6 50 44 12 7 20 30 20 3	37 20 6 8 13 15 20 49	

Fig. 1: Example of input file.

The input data shown in the Figure 1 is divided as follows:

- *Probability of Failure*: the first number of the sequence (0.01) is the probability of memory failure when sorting;
- Sequence size: the second number (100) means the size of the integers sequence used by sorting;
- Sequence: the rest of the numbers indicates the sequence itself.

With this input data, we ran, for each one of these, all four algorithms considered in this study. The sorting algorithms used already existed. For example, using all 270 input files, we ran bubblesort, creating 270 output files, and so on for the other algorithms. At the end of executions, we get a total of 1080 output files. An output file look like shown in Figure 2:

Fig. 2: Example of output file.

The output file gives four essential data, as enumerated below:

- [1]: the original sequence of integers contained in the input file;
- [2]: the sequence processed by the sorting algorithm under the memory fault model;
- [3]: the sequence sorted correctly;
- [4]: the size of the largest sorted subsequence in [2]. This number can be interpreted as the quality of sorting. As higher, most successful was the sorting operation.

After generating the dataset, we developed a Python script that reads the 1080 output files and produces a single CSV file (first lines showed in Figure 3 below), containing the following columns:

- algorithm: the algorithm used to sort the array;
- probability_of_failure: the probability of failure used when sorting;
- *size_of_array*: the size of the array to be sorted;
- largest_sorted_subarray: the largest sorted subarray after sorting;
- *k_unordered_sequence*: number of unordered sequence after sorting.
- percentage k unordered: percentage of unordered sequence after sorting related to original array;
- percentage_largest_sorted_subarray: percentage of largest sorted subarray after sorting related to original array.

```
algorithm; probability_of_failure; size_of_array; largest_sorted_subarray; k_unordered_sequence; percentage_k_unordered; percentage_largest_sorted_subarray quick; 0.01; 100; 35; 4; 4.00; 35.00 quick; 0.01; 100; 36; 8; 8.00; 36.00 quick; 0.01; 100; 31; 5; 5.00; 31.00 quick; 0.01; 100; 20; 6; 6.00; 20.00 quick; 0.01; 100; 31; 5; 5.00; 31.00
```

Fig. 3: Example of output CSV file.

We use Python libraries to make data analysis and plot graphs. These libraries were:

- Pandas¹: open source library providing data structures and data analysis tools;
- NumPy²: library for scientific computing with Python;
- SciPy³: ecosystem of open-source software for mathematics, science, and engineering;
- *StatsModels*⁴: module that provides classes and functions for the estimation of many different statistical models, as well as for conducting statistical tests, and statistical data exploration;
- *Matplotlib*⁵: plotting library;
- Seaborn⁶: data visualization library based on matplotlib.

E. Development

We develop Python scripts to generate our dataset. First, we generate all input files through a given script called *gen.py*. This script considers sequence size and the probability of failure to create a sequence of integers. Were produced nine input files like Figure 1, combining the sequence size and probability of failure listed in Table ??.

After that, we developed a script called *main_execution.py* that is responsible for creating output files based on the input files exposed before. At this time, for every input showed in Table ?? we ran 1000 times to minimize any deviation on the quality of sorting indicator (line [4] on Figure 2).

As said before, after the execution of this algorithm, 4000 outputs for each combination of sequence size, and the probability of failure, totalizing 36000 files.

To be continued...

F. Data Analysis

In this section, we describe our data and the statistic tests used to test the hypothesis showed before.

1) Exploratory Data Analysis (EDA): Based on the output files generated before, our starting point was to test if the dataset had a normal distribution. To achieve this, we use Shapiro-Wilk normality test. After we run these tests, only the distribution related to the dependent variable unordered elements size was considered normal. Figure 4 shows an example of this distribution. In these graphs, the red vertical line means the mean, and the blue vertical

¹https://pandas.pydata.org

²https://numpy.org

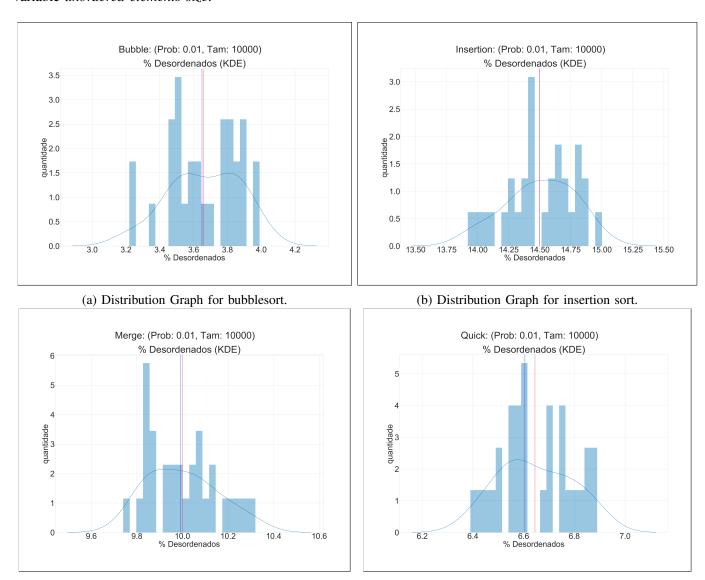
³https://www.scipy.org

⁴https://www.statsmodels.org

⁵https://matplotlib.org

⁶https://seaborn.pydata.org

line means the median. The distributions were normal in all combinations of independent variables for dependent variable *unordered elements size*.



(c) Distribution Graph for mergesort.

(d) Distribution Graph for quicksort.

Fig. 4: Distribution graph for a probability failure of 1% and a sequence size of 10000.

Q-Q plot shows that how much more blue points close to the red line, most normal is the distribution. Figure 5 below presents this graph for a probability failure of 1% and a sequence size of 10000 for considered sorting algorithms.

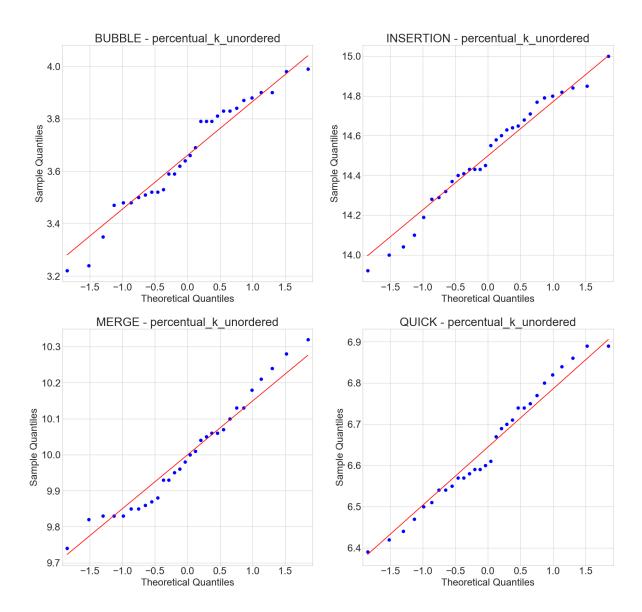


Fig. 5: Q-Q plot showing normal distribution for a probability failure of 1% and a sequence size of 10000.

IV. RESULTS

V. DISCUSSION

VI. CONCLUSION

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- The word "data" is plural, not singular.
- The subscript for the permeability of vacuum μ_0 , and other common scientific constants, is zero with subscript formatting, not a lowercase letter "o".
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TABLE V: Table Type Styles

Table	Table Column Head		
Head	Table column subhead	Subhead	Subhead
copy	More table copy ^a		

^aSample of a Table footnote.

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ACKNOWLEDGMENT

The preferred spelling of the word "acknowledgment" in America is without an "e" after the "g". Avoid the stilted expression "one of us (R. B. G.) thanks . . . ". Instead, try "R. B. G. thanks . . . ". Put sponsor acknowledgments in the unnumbered footnote on the first page.

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