# CS 171: Intro to ML and DM

Christian Shelton

**UC** Riverside

Slide Set 4: Linear Regression, II



#### Slides from CS 171

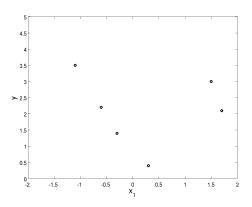
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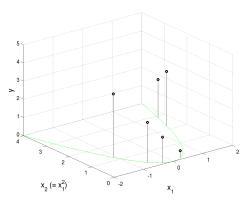
Desired: 
$$f(x) = c + bx + ax^2$$

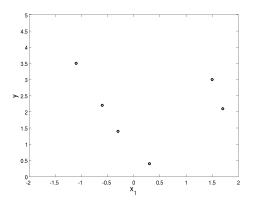
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Can be written as  $f(x) = w_0 \times 1 + w_1 \times x + w_2 \times x^2$ 

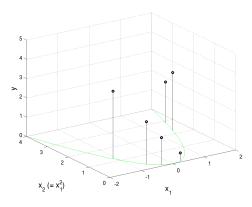
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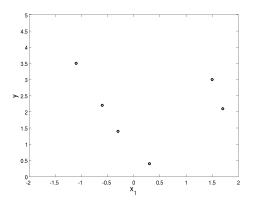
So instead of just adding the "0th" attribute (always 1) also add other attributes that can be calculated from the given attributes.

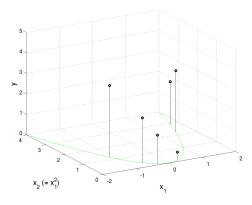


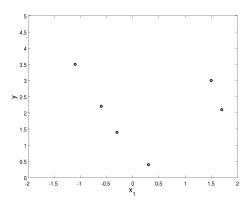


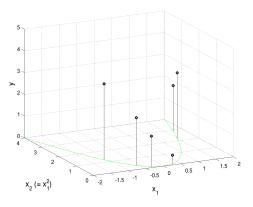


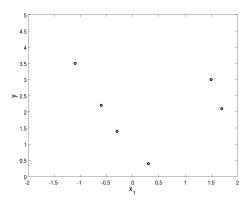


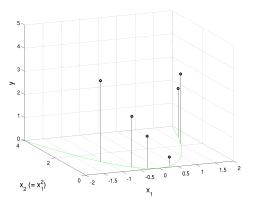


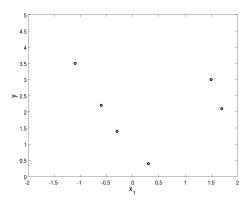


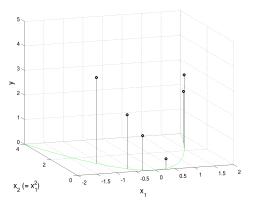


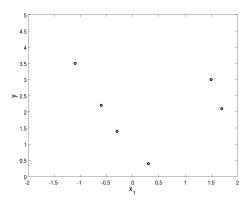


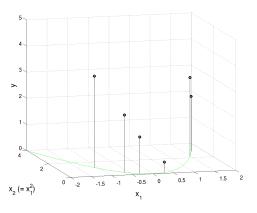


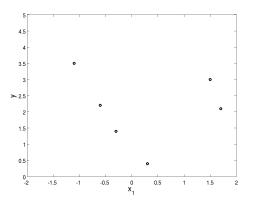


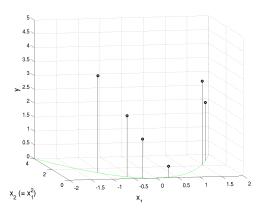


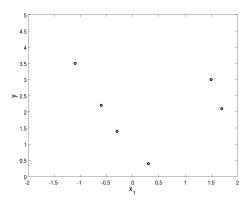


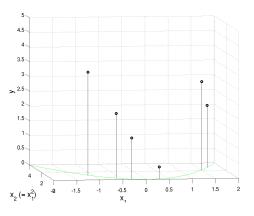


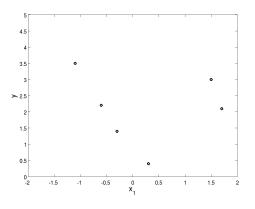


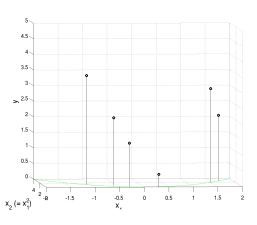


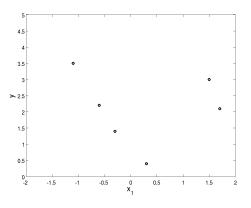


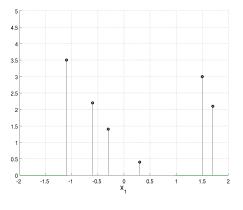


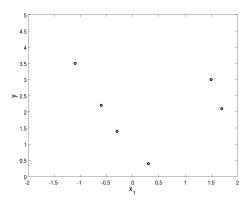


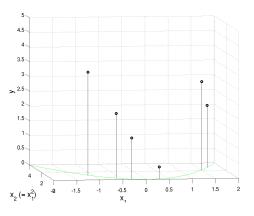


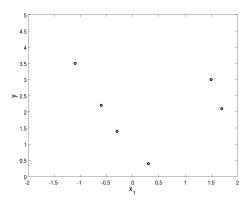


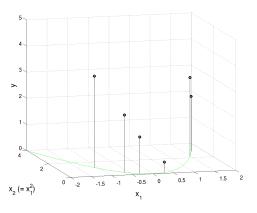


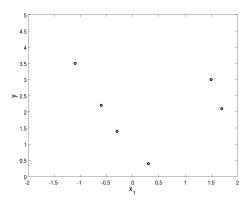


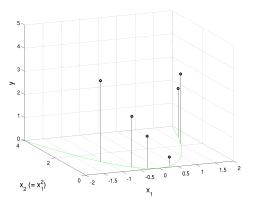


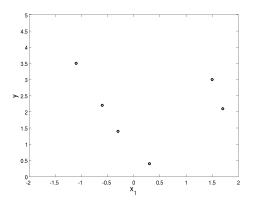


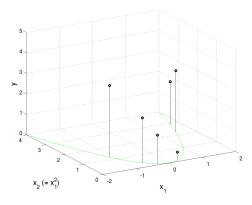


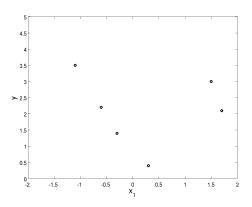


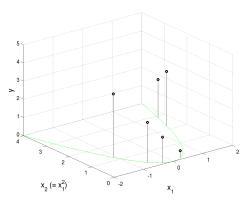


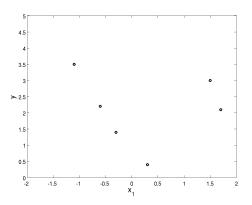


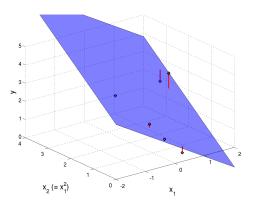


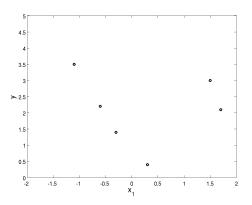


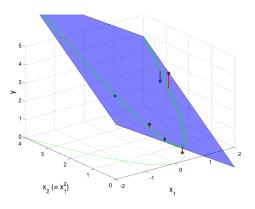


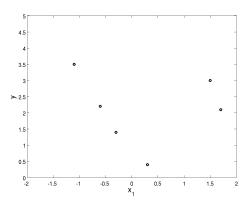


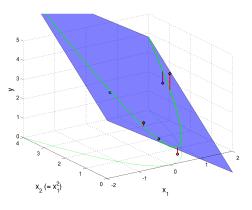


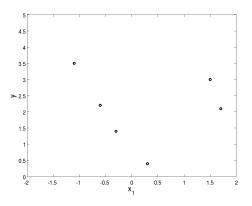


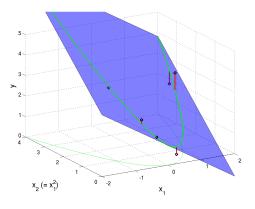


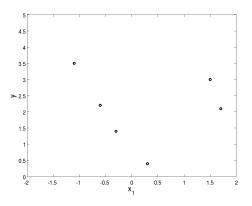


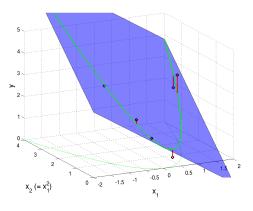


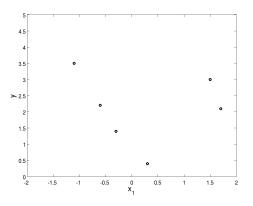


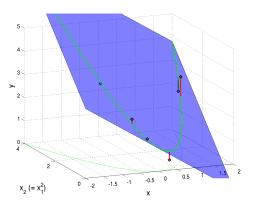


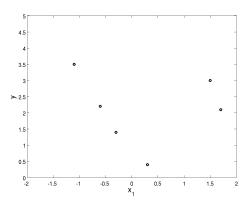


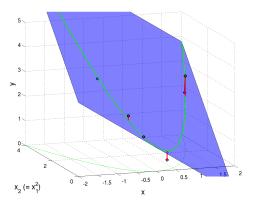


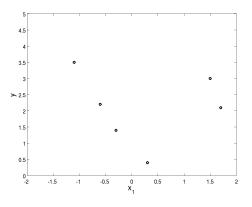


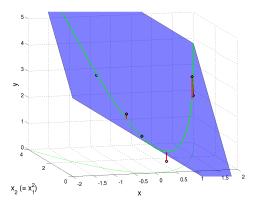


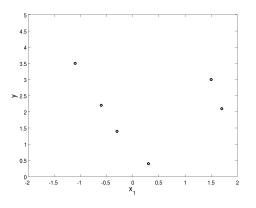


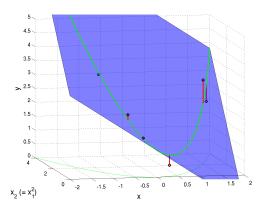


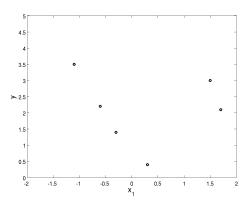


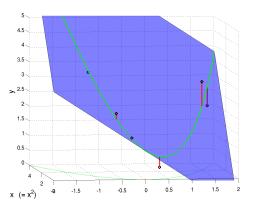


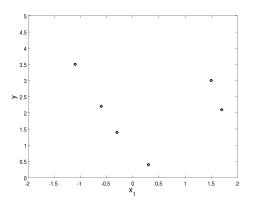


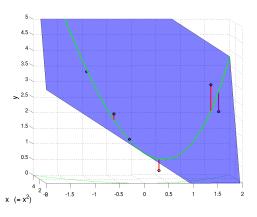


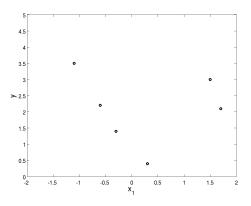


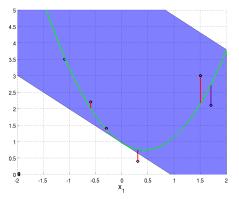


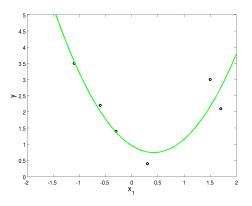


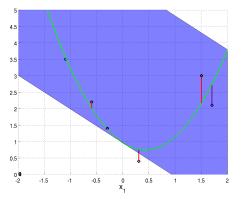


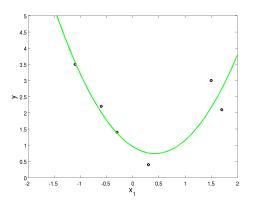


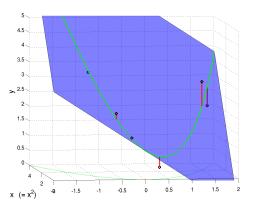


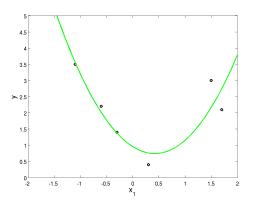


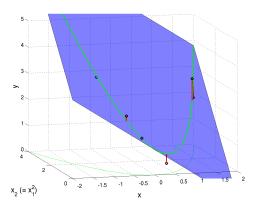


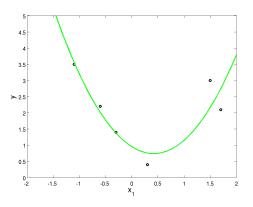


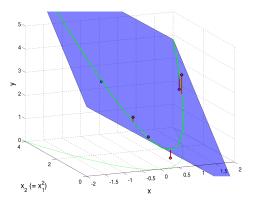


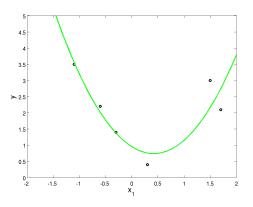


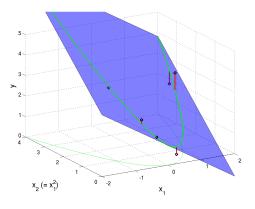


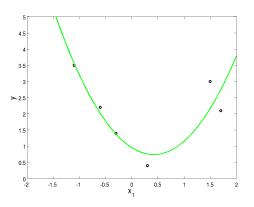


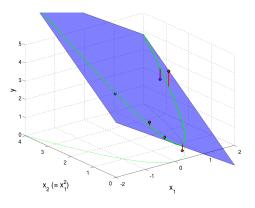


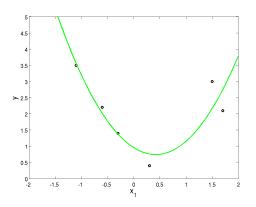


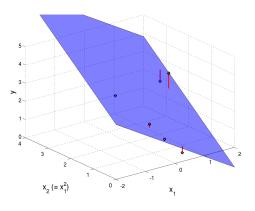












#### Feature Mapping

The function that takes the raw attributes and creates features from them is often written  $\phi(x)$ . For instance

$$\phi(x) = \begin{bmatrix} 1 & x_1 & x_2 \end{bmatrix} \qquad \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & x_1^2 & x_2^2 & x_1 x_2 \end{bmatrix}$$

$$\phi(x) = \begin{bmatrix} 1 & x_1 & x_2^2 \end{bmatrix} \qquad \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & \sin(x_1) & \sin(x_2) \end{bmatrix}$$

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Instead of X, we sometimes call the new matrix  $\Phi$ :

$$X = \begin{bmatrix} -x_1 - \\ -x_2 - \\ \vdots \\ -x_m - \end{bmatrix} \qquad \Phi = \begin{bmatrix} -\phi(x_1) - \\ -\phi(x_2) - \\ \vdots \\ -\phi(x_m) - \end{bmatrix}$$

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$$\begin{array}{llll} \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 \end{bmatrix} & \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & x_1^2 & x_2^2 & x_1 x_2 \end{bmatrix} \\ \phi(x) = \begin{bmatrix} 1 & x_1 & x_1^2 \end{bmatrix} & \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & \sin(x_1) & \sin(x_2) \end{bmatrix} \end{array}$$

Instead of X, we sometimes call the new matrix  $\Phi$ :

$$X = \begin{bmatrix} --x_1 - - \\ --x_2 - - \\ \vdots \\ --x_m - - \end{bmatrix} \qquad \Phi = \begin{bmatrix} --\phi(x_1) - - \\ --\phi(x_2) - - \\ \vdots \\ --\phi(x_m) - - \end{bmatrix}$$

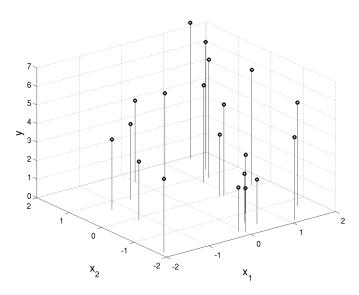
The learning equation correspondingly changes notation:

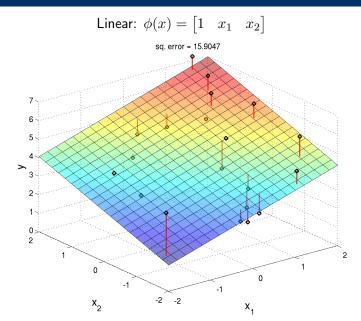
$$\hat{w} = (X^{\top} X)^{-1} (X^{\top} Y)$$
  $\hat{w} = (\Phi^{\top} \Phi)^{-1} (\Phi^{\top} Y)$ 

And of course the resulting function changes equation too:

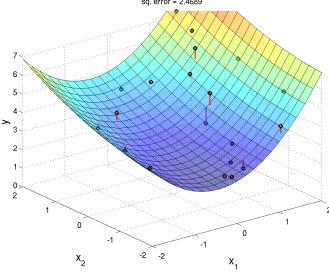
$$f(x) = x^{\top} \hat{w} \qquad \qquad f(x) = \phi(x)^{\top} \hat{w}$$



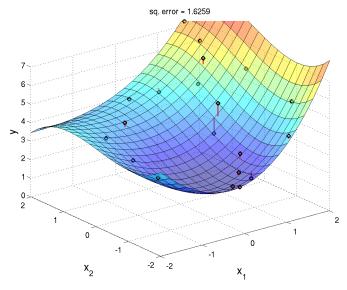




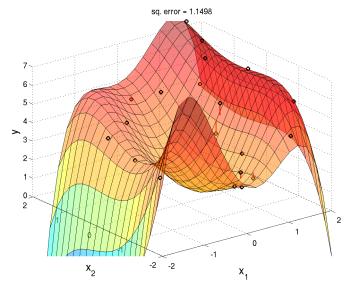
2nd order: 
$$\phi(x)=\begin{bmatrix}1&x_1&x_2&x_1^2&x_1x_2&x_2^2\end{bmatrix}$$
 sq. error = 2.4689



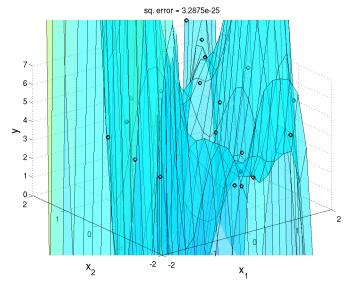
$$\text{3rd order: } \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & x_1^2 & x_1x_2 & x_2^2 & x_1^3 & x_1^2x_2 & x_1x_2^2 & x_2^3 \end{bmatrix}$$



 $\text{4th order: } \phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & x_1^2 & x_1x_2 & x_2^2 & x_1^3 & x_1^2x_2 & x_1x_2^2 & x_2^3 & x_1^4 & x_1^3x_2 & x_1^2x_2^2 & x_1x_2^3 & x_2^4 \end{bmatrix}$ 



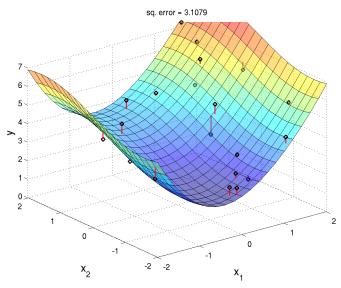
5th order: 
$$\phi(x) = \begin{bmatrix} 1 & x_1 & x_2 & x_1^2 & x_1x_2 & x_2^2 & x_1^3 & x_1^2x_2 & \dots & x_2^5 \end{bmatrix}$$



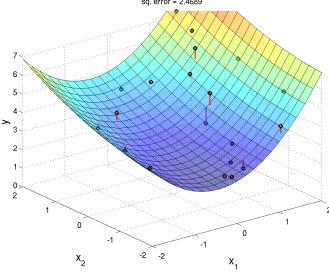
"correct": 
$$\phi(x) = \begin{bmatrix} 1 & \sin(x_1) & \sin(x_2) & x_1^2 \end{bmatrix}$$

sq. error = 2.3717

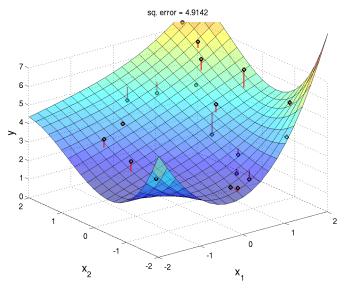
really "correct": 
$$\phi(x) = [3 + \sin(x_1) + \sin(x_2) + x_1^2]$$



2nd order: 
$$\phi(x)=\begin{bmatrix}1&x_1&x_2&x_1^2&x_1x_2&x_2^2\end{bmatrix}$$
 sq. error = 2.4689



some 5th order: 
$$\phi(x)=\begin{bmatrix}1&x_1&x_2&x_1^2x_2&x_1^3x_2^2&x_1^2x_2^2\end{bmatrix}$$



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This is called "ridge regression" or "LLS with  $L_2$  regularization."

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This is called "ridge regression" or "LLS with  $L_2$  regularization." If we have a constant feature, we generally do not include it in the regularization.

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$$w = \left(X^{\top}X\right)^{-1}X^{\top}Y$$

$$L = \sum_{i=1}^{m} \left( y_i - \sum_{j=1}^{n} w_j x_{i,j} \right)^2 + \lambda \sum_{j=1}^{n} w_j^2$$

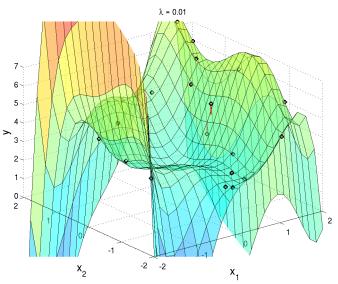
$$w = \left(X^{\top}X + \lambda I\right)^{-1} X^{\top}Y$$

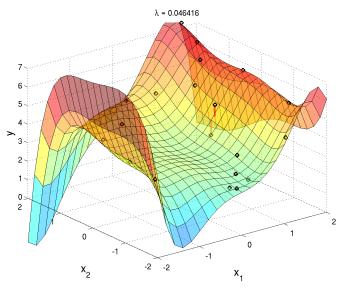
$$L = \sum_{i=1}^{m} \left( y_i - \sum_{j=1}^{n} w_j x_{i,j} \right)^2 + \lambda \sum_{j=1}^{n} w_j^2$$

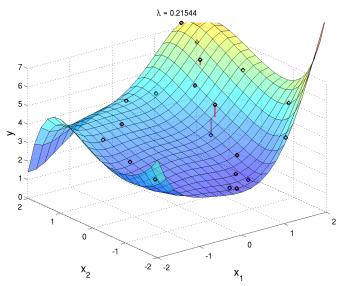
$$w = \begin{pmatrix} X^{\top}X + \lambda \begin{bmatrix} 1 & 0 & & & 0 \\ 0 & 1 & & & 0 \\ & & \ddots & \\ 0 & 0 & & & 1 \end{bmatrix} \end{pmatrix}^{-1} X^{\top}Y$$

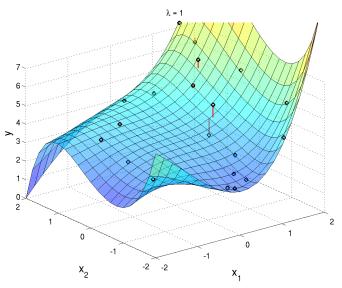
$$L = \sum_{i=1}^{m} \left( y_i - \sum_{j=0}^{n} w_j x_{i,j} \right)^2 + \lambda \sum_{j=1}^{n} w_j^2$$

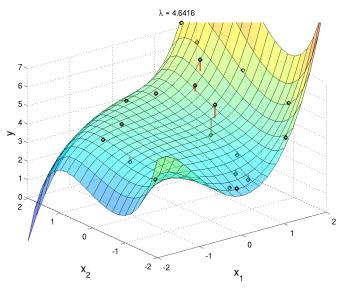
$$w = \begin{pmatrix} X^{\top}X + \lambda \begin{bmatrix} 0 & 0 & & & 0 \\ 0 & 1 & & & 0 \\ & & \ddots & \\ 0 & 0 & & & 1 \end{bmatrix} \end{pmatrix}^{-1} X^{\top}Y$$

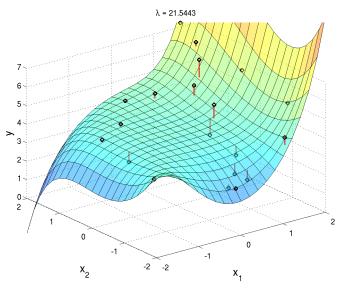


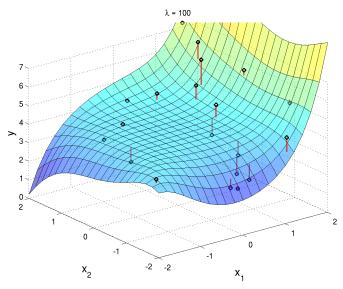


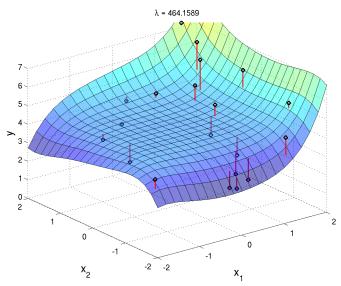






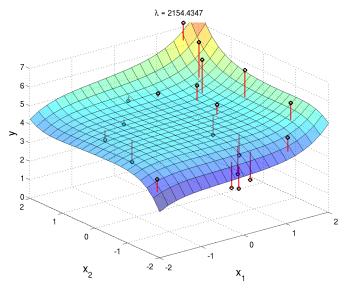






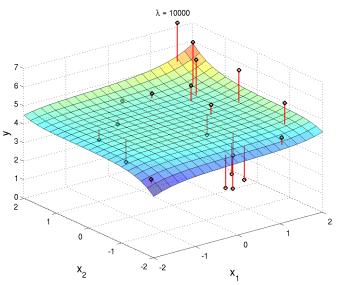
# Regularization

#### 5th order polynomial

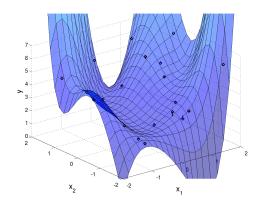


# Regularization

#### 5th order polynomial

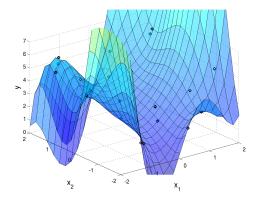


 $\lambda = 0.02$ 





#### $\lambda = 0.02$







#### $\lambda = 0.02$

