# Tuyen P. Le | Resume

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#### **Education**

Coursera [Link] Online Professional Certificate 2022/08-2022/12

Google Project Management

Kyung Hee University [Link] South Korea

Master and Ph.D. 2014/03-2019/02

Dissertation: Deep Hierarchical Reinforcement Learning Algorithms in Partially Observable Markov Decision

HoChiMinh City University of Technology [Link]

Ho Chi Minh City Bachelor 2008-2013

Honor program

**Luong Van Chanh Gifted High School** 

Phu Yen province Diploma 2005-2008

Subjects taken: Mathematics, Physics, Chemistry, English . . .

#### Research Interest

I'm interested in applying various machine learning techniques (especially reinforcement learning) to real-world problems such as finance, logistics, robotics and manufacturing.

#### **Experience**

Professional...

AgileSoDA [Link] Seoul City Position: Senior Researcher (Team Leader), R&D Department 2019-Present

KMS Technology Vietnam [Link] Ho Chi Minh City

Position: Software Engineer, R&D Department 2013-2014

Miscellaneous.....

Recobell (acquired by Yello Mobile) [Link] Seoul City

Position: Intern, IT department 2015-2016

Polliwog Corp (acquired by Altair). [Link] **Seongnam City** 

Position: Intern, IT department 2014-2015

VNG Corporation. [Link] Ho Chi Minh City

Position: Intern, Web development devision 2012-2012

Global CyberSoft (acquired by Hitachi). [Link] Ho Chi Minh City

Position: Intern, R&D Department 2012-2012

Ho Chi Minh City

Position: Intern, Solution Division 2011–2011

#### **Honors and Awards**

- o 2022: Top-10 finalist Golden Globe Science and Technology Award 2022 (Link)
- o 2020: Third prize DACON competition related to manufacturing optimization (Link)
- o 2008-2013: Talented engineer program (a.k.a. honor program) at HCMUT.
- o 2008-2019: University scholarship from HCMUT and KHU.

#### **Talks**

o 2019: Asian Tech Summit (Link)

## **Scientific Community Service**

Here is the list of conferences and journals, which I have served as a reviewer:

- o IEEE Robotics and Automation Letters (RA-L)
- International Conference on Artificial Intelligence and Statistics (AISTATS)
- IEEE Access
- IEEE Conference on Systems, Man, and Cybernetics (IEEE SMC)
- International Conference on Ubiquitous Robots (UR)
- o International Conference on Future Data and Security Engineering (FDSE)

### **Computer skills**

**Programming Languages**: Python, Java, C++, **Tools**: Pycharm, Visual Studio, Eclipse, Visual C#, Matlab, Javascript, Git Code, Docker, MySQL **Libraries**: Deep Learning (Tensorflow, Pytorch), **Platforms**: Window, Mac, Ubuntu, AWS, iOS,

Jupyter, OpenCV, Anaconda

#### **Publications**

# 2022

Android

- [1] **[IP] 르 팜 투옌**, 민예린, 김준호, 윤도균, and 최규원. Apparatus and method for reinforcement learning based on user learning environment in semiconductor design. KR(10-2413005), Jun 2022.
- [2] **[IP] 르 팜 투옌**, 민예린, 김준호, 윤도균, and 최규원. Reinforcement learning apparatus and method for optimizing position of object based on semiconductor design data. KR(10-2416931), Jun 2022.
- [3] **[IP] 르 팜 투옌** and 윤도균. System and method for designing integrated circuits based on deep reinforcement learning using partitioning. KR(10-2454202), Oct 2022.
- [4] **[IP]** 노철균, 민예린, 이성령, **르 팜 투옌**, and 이동현. Apparatus and method for controlling ambient air vaporizer using reinforcement learning. KR(10-2474995), Dec 2022.
- [5] **[IP]** 이성령, **르 팜 투옌**, and 김동석. Reinforcement learning apparatus and method for multiple classification. KR(10-2458103), Oct 2022.

[6] **[IP]** 이성령, **르 팜 투옌**, and 이승준. Reinforcement learning device and method for establishing path based on multiple agents. KR(10-2458105), Oct 2022.

2021

- [7] **[Conf] Tuyen P. Le**, DongHyun Lee, and DaeWoo Choi. A deep reinforcement learning-based application framework for conveyor belt-based pick-and-place systems using 6-axis manipulators under uncertainty and real-time constraints. In *2021 18th International Conference on Ubiquitous Robots (UR)*, pages 464–470, 2021.
- [8] **[IP] 르 팜 투옌**, 노철균, 이성령, and 민예린. Hierarchical decision agent. KR(10-2169876), Jun 2021.
- [9] **[IP] 르 팜 투옌**, 노철균, 이성령, 민예린, 이동수, and 정석규. Apparatus and method for generating decision agent. KR(10-2257082), May 2021.
- [10] **[IP] 르 팜 투옌** and 이동현. Deep reinforcement learning apparatus and method for pick and place system. KR(10-2416931), Dec 2021.
- [11] **[SCI] Tuyen P. Le**, Cheolkyun Rho, Yelin Min, Sungreong Lee, and Daewoo Choi. A2gan: A deep reinforcement-based learning algorithm for risk-aware in finance. *IEEE Access* (*IF:3.367*), 9:137165–137175, 2021.

2020

- [12] **[IP] 투옌**, 노철균, and 민예린. System and method for classifying base on generative adversarial network using labeled data. KR(10-2093079), Mar 2020.
- [13] **[IP] 투옌**, 노철균, and 민예린. System and method for classifying base on generative adversarial network using labeled data and unlabled data. KR(10-2093080), Mar 2020.
- [14] **[IP]** 노철균, 민예린, and **투옌**. System and method for classifying fraudulent loans based on reinforcement learning. KR(10-2148880), Aug 2020.
- [15] **[IP]** 노철균, 민예린, and **투옌**. System and method for classifying payments based on reinforcement learning. KR(10-2105276), Oct 2020.
- [16] **[IP]** 노철균, 이성령, 민예린, and **르 팜 투옌**. Apparatus and method for performing reinforcement learning using conditional episode composition. KR(10-2169876), Oct 2020.
- [17] **[SCI]** Hoang Huu Viet, Le Hong Trang, **Tuyen P. Le**, and Taechoong Chung. A shortlist-based bidirectional local search for the stable marriage problem. *Journal of Experimental & Theoretical Artificial Intelligence*(**IF:2.340**), 32(1):147–163, 2020.

2019

- [18] **[Conf]** Quang Dang Nguyen, Luan N. T. Huynh, **Tuyen P. Le**, and TaeChoong Chung. Ontology-based recommender system for sport events. In Sukhan Lee, Roslan Ismail, and Hyunseung Choo, editors, *Proceedings of the 13th International Conference on Ubiquitous Information Management and Communication (IMCOM) 2019*, pages 870–885, Cham, 2019. Springer International Publishing.
- [19] **[Conf]** Quang Dang Nguyen, Ngo Anh Vien, **Tuyen P. Le**, SeungYoon Choi, A. F. M. Shahab Uddin, and TaeChoong Chung. Optimization to Task Bundle Processing for Multi-Access Edge Computing Systems. *Korea Computer Science Conference*, :255–257, 2019.

- [20] [SCI] Md Layek, AFM Uddin, Tuyen P. Le, TaeChoong Chung, Eui-Nam Huh, et al. Center-emphasized visual saliency and a contrast-based full reference image quality index. *Symmetry* (*IF:2.713*), 11(3):296, 2019.
- [21] **[SCI]** SeungYoon Choi, **Tuyen P. Le**, Quang D Nguyen, Md Abu Layek, SeungGwan Lee, and TaeChoong Chung. Toward self-driving bicycles using state-of-the-art deep reinforcement learning algorithms. *Symmetry* (*IF:2.713*), 11(2):290, 2019.
- [22] **[Workshop] Tuyen P. Le**, Cheolkyun Rho, Yelin Min, Yong Cha, and Daewoo Choi. A deep decision-making framework for fraud detection. *Workshop on Robust AI in Financial Services: Data, Fairness, Explainability, Trustworthiness, and Privacy, NeurIPS*, 2019.

2018

- [23] **[Conf] Tuyen P. Le**, Nguyen Dang Quang, SeungYoon Choi, and TaeChoong Chung. Learning a self-driving bicycle using deep deterministic policy gradient. In *18th International Conference on Control, Automation and Systems (ICCAS2018*), Oct 2018.
- [24] **[Conf]** Viet-Hung Dang, Ngo Anh Vien, **Tuyen P. Le**, and Taechoong Chung. A functional optimization method for continuous domains. In Yuanfang Chen and Trung Q. Duong, editors, *Industrial Networks and Intelligent Systems*, pages 254–265, Cham, 2018. Springer International Publishing.
- [25] **[KCI]** 최 승 윤, **Tuyen P. Le**, and 정 태 충. Deep deterministic policy gradient 알고리즘을 응용한 자전거의 자율 주행 제어. *Convergence Security Journal*, 18(3), 2018.
- [26] [SCI] Tuyen P. Le, N. A. Vien, and T. Chung. A deep hierarchical reinforcement learning algorithm in partially observable markov decision processes. *IEEE Access* (*IF:3.367*), 6:49089– 49102, 7 2018.

2017

- [27] **[Conf]** M. A. Layek, N. Q. Thai, M. A. Hossain, N. T. Thu, **Tuyen P. Le**, A. Talukder, T. Chung, and E. N. Huh. Performance analysis of h.264, h.265, vp9 and av1 video encoders. In *2017 19th Asia-Pacific Network Operations and Management Symposium* (*APNOMS2017*), pages 322–325, Sept 2017.
- [28] **[Conf]** Md Abu Layek, Ngo Quang Thai, Md Alamgir Hossain, Ngo Thien Thu, **Tuyen P. Le**, Ashis Talukder, TaeChoong Chung, and Eui-Nam Huh. Analysis of the Effects of Timing Presets on the Performance of H.264/AVC and H.265/HEVC Video Encoders. volume, pages 442–443. Korea Institute Of Communication Sciences, 2017.
- [29] [Conf] Md Abu Layek, Ngo Quang Thai, Md Alamgir Hossain, Ngo Thien Thu, Tuyen P. Le, Ashis Talukder, TaeChoong Chung, and Eui-Nam Huh. Performance Analysis of AV1 for Video Coding in Very Low Bit Rates. volume, pages 118–120. KOREA INFORMATION SCIENCE SOCIETY, 2017.
- [30] **[Conf]** Minh N. H. Nguyen, **Tuyen P. Le**, Nguyen H. Tran, and Choong Seon Hong. Deep Reinforcement Learning based Smart Building Energy Management. volume, pages 871–873. KOREA INFORMATION SCIENCE SOCIETY, 2017.
- [31] **[Conf]** Tae Choong Chung and **Tuyen P. Le**. Pleasure of Learning. *ICCC International Digital Design Invitation Exhibition*, :131–131, 2017.

- [32] **[Conf]** TaeChoong Chung and **Tuyen P. Le**. RLVisualizer: An application for Visualizing Trajectories of Reinforcement Learning Problem. volume , pages 13–14. The Korea Contents Society, 2017.
- [33] **[Conf] Tuyen P. Le** and T. Chung. Controlling bicycle using deep deterministic policy gradient algorithm. In 2017 14th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI2017), pages 413–417, June 2017.
- [34] **[Conf] Tuyen P. Le**, A. Layek, N. A. Vien, and T. Chung. Deep reinforcement learning algorithms for steering an underactuated ship. In 2017 IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI2017), pages 602–607, Nov 2017.
- [35] **[Conf] Tuyen P. Le**, Abu Layek, Seung yoon Choi, and TaeChoong Chung. Gathering Objects in Four-rooms Domain under Partially Observability. volume, pages 865–867. KOREA INFORMATION SCIENCE SOCIETY, 2017.
- [36] **[Conf] Tuyen P. Le**, Md. Abu Layek, CholJin Jong, Seung yoon Choi, JinSeok Kim, and TaeChoong Chung. Reinforcement Learning of Vehicle Agent and Art work Trial using the Learning Trajectories. volume, pages 719–721. KOREA INFORMATION SCIENCE SOCIETY, 2017.
- [37] **[SCI] Tuyen P. Le**, Vien Anh Ngo, P. Marlith Jaramillo, and TaeChoong Chung. Importance sampling policy gradient algorithms in reproducing kernel hilbert space. *Artificial Intelligence Review (IF:8.139)*, Oct 2017.
- [38] **[SCI] Tuyen P. Le**, Hoang Huu Viet, Sang Hyeok An, Seung Gwan Lee, Dong-Han Kim, and Tae Choong Chung. Univector field method-based multi-agent navigation for pursuit problem in obstacle environments. *Journal of Central South University* (*IF:1.716*), 24(4):1002–1012, Apr 2017.

2016

- [39] **[Conf]** CholJin Jong, Seung yoon Choi, JinSeok Kim, Md. Abu Layek, **Tuyen P. Le**, Marlith Jaramillo, and TaeChoong Chung. Study of Sound Location Tracking Mobile Robot Using Lego Mindstorms. volume, pages 1028–1029. KOREA INFORMATION SCIENCE SOCIETY, 2016.
- [40] **[Conf]** JinSeok Kim, Seung yoon Choi, CholJin Jong, Md. Abu Layek, **Tuyen P. Le**, Marlith Jaramillo, and TaeChoong Chung. Selected wireless mesh network model and architecture for a communication interruption in the fixed wireless environment. volume, pages 1265–1267. KOREA INFORMATION SCIENCE SOCIETY, 2016.
- [41] **[Conf]** Md. Abu Layek, Seung yoon Choi, **Tuyen P. Le**, Marlith Jaramillo, JinSeok Kim, Jeong cheol jin, Eui-Nam Huh, and TaeChoong Chung. Compression Efficiency Of Text Images In Hangul And Other Languages. volume, pages 777–779. KOREA INFORMATION SCIENCE SOCIETY, 2016.
- [42] **[Conf]** Seung-yoon Choi, Md. Abu Layek, **Tuyen P. Le**, Cheoljin Jeong, Jinseok Kim, Marlith Jaramillo, and TaeChoong Chung. A Study of Sequential Workspace Management Approach for Autonomous Mobile Robot in Path Planning Problem. volume, pages 1036–1038. KOREA INFORMATION SCIENCE SOCIETY, 2016.
- [43] **[Conf] Tuyen P. Le**, Md. Abu Layek, Marlith Jaramillo, CholJin Jong, Seung yoon Choi, JinSeok Kim, and TaeChoong Chung. A Non-parametric policy based Algorithm in Reproducing

 $\label{thm:condition} \mbox{Kernel Hilbert Space. volume , pages 892-893. KOREA INFORMATION SCIENCE SOCIETY, 2016.}$