Tuyen P. Le | Resume

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"In the End, we will remember not the words of our enemies, but the silence of our friends." Martin Luther King, Jr.

Education

Kyung Hee University

South Korea Master and PhD. 4.14/5.0

Research Topics: Deep Reinforcement Learning, Machine Learning, Robotics

Bach Khoa University

Bachelor, 8.46/10.0 Honor program

Luong Van Chanh Gifted High School

Diploma, 9+/10

Subjects taken: Mathematics, Physics, Chemistry, English . . .

Ho Chi Minh City

2008-2013

Phu Yen province

2005-2008

2014-2019

PhD dissertation

Title: Deep Hierarchical Reinforcement Learning Algorithm in Partially Observable Markov Decision

Processes

Supervisors: TaeChoong Chung

Abstract: In recent years, reinforcement learning has achieved many remarkable successes due to the growing adoption of deep learning techniques and the rapid growth in computing power. Nevertheless, it is well-known that flat reinforcement learning algorithms are often not able to learn well and data-efficient in tasks having hierarchical structures, e.g. consisting of multiple subtasks. Hierarchical reinforcement learning is a principled approach that is able to tackle these challenging tasks. On the other hand, many real-world tasks usually have only partial observability in which state measurements are often imperfect and partially observable. The problems of RL in such settings can be formulated as a partially observable Markov decision process (POMDP). In this paper, we study hierarchical RL in POMDP in which the tasks have only partial observability and possess hierarchical properties. We propose a hierarchical deep reinforcement learning approach for learning in hierarchical POMDP. The deep hierarchical RL algorithm is proposed to apply to both MDP and POMDP learning. We evaluate the proposed algorithm on various challenging hierarchical POMDP.

Key words: Hierarchical Deep Reinforcement Learning, Partially Observable MDP (POMDP), Semi-MDP, Partially Observable Semi-MDP (POSMDP)

Experience

Professional.....

Software Engineer at KMS Technology Vietnam

Ho Chi Minh City

2013-2014

Ranked: Top 26 best work places in Vietnam **Website**: https://www.kms-technology.com/

Description: Develop some mobile applications (iOS and Android).

Miscellaneous.....

Internship at Recobell

Seoul City

2015-2016

Website: http://www.recobell.com/rb/

Description: Develop mobile applications (iOS and Android).

Internship at Polliwog Corp.

Seongnam City

2014-2015

Website: http://www.polliwogeda.com/xe_new/

Description: Develop algorithm (C++) to find a shortest path in a Printed Circuit Board (PCB).

Internship at VNG Corp.

Ho Chi Minh City

2012-2013

Website: https://vng.com.vn/

Description: Work in a group to develop a website using state-of-the-art technologies.

Languages

Korean: Intermediate level

Read, Write, Speak (simple form)

English: Influence

Second language

Vietnamese: Influence

Mother language

Computer skills

Programming Languages: C++, Java, Python, **Tools**: Visual Studio, Matlab, Pycharm, Eclipse,

Objective-C, Swift, Matlab, Latex

XCode, Texmaker

Libraries: Cocoa, OpenCV, Tensorflow, Mat- Miscellaneous: Adobe Photoshop, Adobe Lightplotlib, ROS, Gym Al

room. ...

References

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Publications

[1] Jin Seok Kim Md. Abu Layek Tuyen P. Le Marlith Jaramillo Tae Choong Chung Chol Jin Jong, Seung-yoon Choi. Study of Sound Location Tracking Mobile Robot Using Lego Mindstorms. volume, pages 1028–1029. KOREA INFORMATION SCIENCE SOCIETY, 2016.

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[5] Tuyen P. Le and T. Chung. Controlling bicycle using deep deterministic policy gradient algorithm. In 2017 14th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI), pages 413–417, June 2017.

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[8] Tuyen P. Le, Vien Anh Ngo, P Marlith Jaramillo, and TaeChoong Chung. Importance sampling policy gradient algorithms in reproducing kernel hilbert space. *Artificial Intelligence Review*, pages 1–21.

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- [12] Tuyen P. Le Marlith Jaramillo JinSeok Kim Jeong cheol jin Eui-Nam Huh TaeChoong Chung Md. Abu Layek, Seung-yoon Choi. Compression Efficiency Of Text Images In Hangul And Other Languages. volume, pages 777–779. KOREA INFORMATION SCIENCE SOCIETY, 2016.
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- [14] Tuyen P. Le Cheoljin Jeong Jinseok Kim Marlith Jaramillo TaeChoong Chung Seung-yoon Choi, Md. Abu Layek. A Study of Sequential Workspace Management Approach for Autonomous Mobile Robot in Path Planning Problem. volume, pages 1036–1038. KOREA INFORMATION SCIENCE SOCIETY, 2016.
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