# Tuyen P. Le | Resume

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"In the End, we will remember not the words of our enemies, but the silence of our friends." **Martin Luther King, Jr.** 

## **Education**

Kyung Hee UniversitySouth KoreaMaster and PhD, 4.14/5.02014–2019

Research Topics: Deep Reinforcement Learning, Machine Learning, Robotics

Bach Khoa University
Bachelor. 8.46/10.0
Ho Chi Minh City
2008–2013

Bachelor, 8.46/10.0 Honor program

A CL I C'G III I C I

**Luong Van Chanh Gifted High School** *Diploma, 9+/10*Phu Yen province

2005–2008

Subjects taken: Mathematics, Physics, Chemistry, English . . .

### PhD dissertation

**Title**: Deep Hierarchical Reinforcement Learning Algorithm in Partially Observable Markov Decision Processes

**Supervisors**: TaeChoong Chung

Abstract: In recent years, reinforcement learning has achieved many remarkable successes due to the growing adoption of deep learning techniques and the rapid growth in computing power. Nevertheless, it is well-known that flat reinforcement learning algorithms are often not able to learn well and data-efficient in tasks having hierarchical structures, e.g. consisting of multiple subtasks. Hierarchical reinforcement learning is a principled approach that is able to tackle these challenging tasks. On the other hand, many real-world tasks usually have only partial observability in which state measurements are often imperfect and partially observable. The problems of RL in such settings can be formulated as a partially observable Markov decision process (POMDP). In this paper, we study hierarchical RL in POMDP in which the tasks have only partial observability and possess hierarchical properties. We propose a hierarchical deep reinforcement learning approach for learning in hierarchical POMDP. The deep hierarchical RL algorithm is proposed to apply to both MDP and POMDP learning. We evaluate the proposed algorithm on various challenging hierarchical POMDP.

**Key words**: Hierarchical Deep Reinforcement Learning, Partially Observable MDP (POMDP), Semi-MDP, Partially Observable Semi-MDP (POSMDP)

# **Experience**

Professional....

## Software Engineer at KMS Technology Vietnam

Ho Chi Minh City

2013-2014

**Ranked**: Top 26 best work places in Vietnam **Website**: https://www.kms-technology.com/

**Description**: Develop some mobile applications (iOS and Android).

Miscellaneous.....

**Seoul City** 2015–2016

Internship at Recobell

//www.recohell.com/rh/

*Website*: http://www.recobell.com/rb/

**Description**: Develop mobile applications (iOS and Android).

Internship at polliwog Corp.

**Seongnam City** 

2014-2015

Website: http://www.polliwogeda.com/xe\_new/

**Description**: Develop algorithm (C++) to find a shortest path in a Printed Circuit Board (PCB).

Internship at VNG Corp.

Ho Chi Minh City

2012-2013

Website: https://vng.com.vn/

**Description**: Work in a group to develop a website using state-of-the-art technologies.

# Languages

**Korean**: Intermediate level Read, Write, Speak (simple form)

English:InfluenceSecond languageVietnamese:InfluenceMother language

**Computer skills** 

Programming Languages: C++, Java, Python, Tools: Visual Studio, Matlab, Pycharm, Eclipse,

Objective-C, Swift, Matlab, Latex XCode, Texmaker

Libraries: Cocoa, OpenCV, Tensorflow, Mat- Miscellaneous: Adobe Photoshop, Adobe Light-

plotlib, ROS, Gym Al room. ...

## References

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Professor

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## **Publications**

[1] JinSeok Kim Md. Abu Layek Tuyen P. Le Marlith Jaramillo TaeChoong Chung CholJin Jong, Seung-yoon Choi. Study of Sound Location Tracking Mobile Robot Using Lego Mindstorms. volume, pages 1028–1029. KOREA INFORMATION SCIENCE SOCIETY, 2016.

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- [5] Tuyen P. Le and T. Chung. Controlling bicycle using deep deterministic policy gradient algorithm. In 2017 14th International Conference on Ubiquitous Robots and Ambient Intelligence (URAI), pages 413–417, June 2017.
- [6] Tuyen P. Le, A. Layek, N. A. Vien, and T. Chung. Deep reinforcement learning algorithms for steering an underactuated ship. In 2017 IEEE International Conference on Multisensor Fusion and Integration for Intelligent Systems (MFI), pages 602–607, Nov 2017.
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- [8] Tuyen P. Le, Vien Anh Ngo, P Marlith Jaramillo, and TaeChoong Chung. Importance sampling policy gradient algorithms in reproducing kernel hilbert space. *Artificial Intelligence Review*, pages 1–21.
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