vices include:

a cup attachment device that attaches a cup to a lens surface of the eyeglass lens; and
a lens processing device that mounts the eyeglass lens with mounting a chuck shaft on the cup attached to the eyeglass lens by the cup attachment device, and processes a peripheral edge of the mounted eyeglass lens.

12. The eyeglass lens peripheral edge processing system according to claim 11,
wherein the controller

acquires information of a cup position on the lens surface where the cup is attached by the cup attachment device, and
moves the eyeglass lens to the installation position where the chuck shaft of the lens processing device and the cup position coincide with each other, based on the information of the cup position, when the eyeglass lens is moved to the installation position of the lens processing device.

13. The eyeglass lens peripheral edge processing system according to claim 11 or 12,
wherein the controller

acquires information of an attachment angle at which the cup attached to the eyeglass lens by the cup attachment device is attached to the eyeglass lens, and
sets an angle at the installation position of the eyeglass lens to which the cup is attached, based on the information of the attachment angle, when the eyeglass lens is moved to the installation position of the lens processing device.

14. An eyeglass lens peripheral edge processing program executed in an eyeglass lens peripheral edge processing system that processes a peripheral edge of an eyeglass lens,
wherein the eyeglass lens peripheral edge processing system includes:

a plurality of eyeglass manufacturing devices that performs mutually different steps out of a plurality of steps for processing the eyeglass lens, and that include mutually different housings;
a robot arm that includes an arm unit having a plurality of joint portions, and a holding unit provided in the arm unit to hold and release an object, and that rotates the arm unit via the joint portion to move the object held by the holding unit; and
a controller,

the eyeglass lens peripheral edge processing program being executed by the controller of the eyeglass lens peripheral edge processing system to cause the eyeglass lens peripheral edge processing system to perform:

a position storing process of storing installation position information indicating an installation position where the eyeglass lens is installed and unloaded for each of the plurality of eyeglass manufacturing devices, in a memory device; and
a movement process of controlling an operation of the robot arm based on the installation position information stored in the memory device, to move the eyeglass lens from the installation position of one device out of the plurality of eyeglass manufacturing devices to the installation position of another device out of the plurality of eyeglass manufacturing devices.