

where

$$\begin{aligned} d_1(\psi) &= \Delta_y \psi - \Delta_x \psi, \\ d_2(\psi) &= |\nabla_y \psi|^2 - |\nabla_x \psi|^2. \end{aligned}$$

Then, we obtain

$$\begin{aligned} J_1 &= -2s \operatorname{Im} \int_{\Omega} z \partial_t (\nabla_y \varphi) \cdot \nabla_y \bar{z} dx dy dt + 2s \operatorname{Im} \int_{\Omega} z \partial_t (\nabla_x \varphi) \cdot \nabla_x \bar{z} dx dy dt \\ &= -2s \operatorname{Im} \int_{\Omega} (-2\gamma^2 \beta t) z \varphi \nabla_y \psi \cdot \nabla_y \bar{z} dx dy dt \\ &\quad + 2s \operatorname{Im} \int_{\Omega} (-2\gamma^2 \beta t) z \varphi \nabla_x \psi \cdot \nabla_x \bar{z} dx dy dt \end{aligned} \quad (3.22)$$

and

$$\begin{aligned} J_2 &= \sum_{i,j=1}^m \operatorname{Re} \int_{\Omega} 4s \varphi_{y_i y_j} z_{y_j} \bar{z}_{y_i} dx dy dt - \operatorname{Re} \sum_{j=1}^m \sum_{i=1}^n \int_{\Omega} 4s z_{y_i} \bar{z}_{x_j} \varphi_{y_i x_j} dx dy dt \\ &= \sum_{i,j=1}^m \operatorname{Re} \int_{\Omega} 4s \gamma \varphi \left(\psi_{y_i y_j} + \gamma \psi_{y_i} \psi_{y_j} \right) z_{y_j} \bar{z}_{y_i} dx dy dt + \int_{\Omega} 4s \gamma^2 \varphi |\nabla_y \psi \cdot \nabla_y z|^2 dx dy dt \\ &\quad - \sum_{j=1}^m \sum_{i=1}^n \int_{\Omega} 4s \gamma^2 \varphi (\nabla_y \psi \cdot \nabla_y z) (\nabla_x \psi \cdot \nabla_x \bar{z}) dx dy dt. \end{aligned} \quad (3.23)$$

Before estimating J_3 , we can directly verify

$$\begin{aligned} \Delta_y (\varphi d_2(\psi)) &= (\Delta_y \varphi) d_2(\psi) + 2 \nabla_y \varphi \cdot \nabla_y (d_2(\psi)) + \varphi \Delta_y (d_2(\psi)) \\ &= \gamma \varphi (\Delta_y \psi) d_2(\psi) + \gamma^2 \varphi |\nabla_y \psi|^2 d_2 \psi + 2 \gamma \varphi \nabla_y \psi \cdot \nabla_y (d_2(\psi)) \\ &\quad + \varphi \Delta_y (d_2(\psi)), \\ \Delta_y (\varphi d_1(\psi)) &= (\Delta_y \varphi) d_1(\psi) + 2 \nabla_y \varphi \cdot \nabla_y (d_1(\psi)) + \varphi \Delta_y (d_1(\psi)) \\ &= \gamma \varphi (\Delta_y \psi) d_1(\psi) + \gamma^2 \varphi |\nabla_y \psi|^2 d_1 \psi + 2 \gamma \varphi \nabla_y \psi \cdot \nabla_y (d_1(\psi)) \\ &\quad + \varphi \Delta_y (d_1(\psi)). \end{aligned}$$