

This means that the model is not a gauge invariant theory.

The gauge symmetry inside the model will be disclosed via a new gauge-invariant formalism that does not require more than one WZ field. The fundamental concept behind the symplectic gauge-invariant formalism dwells in the extension of the original phase space with the introduction of two arbitrary function $\Psi(\phi, \pi_\phi, A_0, A_1, \pi_1, \theta)$ and $G(\phi, \pi_\phi, A_0, A_1, \pi_1, \theta)$, depending on both the orig-

inal phase space variables and the WZ variable θ , into the first-order Lagrangian, right on the kinetic and symplectic potential sector, respectively. In this way, the first-order Lagrangian that governs the dynamics of the bosonized CSM, given in Eq. (5.2), is rewritten as

$$\tilde{L}^{(0)} = \pi_\phi \dot{\phi} + \pi_1 \dot{A}_1 + \dot{\theta} \Psi - \tilde{U}^{(0)}, \quad (5.13)$$

where

$$\begin{aligned} \tilde{U}^{(0)} = & \frac{1}{2}(\pi_1^2 + \pi_\phi^2 + \phi'^2) - A_0[\pi_1' + \frac{1}{2}q^2(a-1)A_0 + q^2A_1 + q\pi_\phi + q\phi'] \\ & - A_1[-q\pi_\phi - \frac{1}{2}q^2(a+1)A_1 - q\phi'] + G(\phi, \pi_\phi, A_0, A_1, \pi_1, \theta). \end{aligned} \quad (5.14)$$

The gauge-invariant formulation encompasses two steps: one is dedicated to the computation of Ψ while the other is addressed to the calculation of G .

The enlarged symplectic variables are now $\tilde{\xi}_\alpha^{(0)} = (\phi, \pi_\phi, A_0, A_1, \pi_1, \theta)$ with the following one-form canonical momenta

$$\begin{aligned} \tilde{A}_\phi^{(0)} &= \pi_\phi, \\ \tilde{A}_{A_1}^{(0)} &= \pi_1, \\ \tilde{A}_{A_0}^{(0)} &= \tilde{A}_{\pi_\phi}^{(0)} = \tilde{A}_{\pi_1}^{(0)} = 0, \\ \tilde{A}_\theta^{(0)} &= \Psi. \end{aligned} \quad (5.15)$$

The corresponding symplectic matrix $\tilde{f}^{(0)}$ reads

$$\tilde{f}^{(0)} = \begin{pmatrix} 0 & -1 & 0 & 0 & 0 & \frac{\partial \Psi^y}{\partial \phi^x} \\ 1 & 0 & 0 & 0 & 0 & \frac{\partial \Psi^y}{\partial \pi^x} \\ 0 & 0 & 0 & 0 & 0 & \frac{\partial \Psi^y}{\partial \phi^y} \\ 0 & 0 & 0 & 0 & -1 & \frac{\partial \Psi^y}{\partial A_0^x} \\ 0 & 0 & 0 & 1 & 0 & \frac{\partial \Psi^y}{\partial A_1^x} \\ -\frac{\partial \Psi^x}{\partial \phi^y} & -\frac{\partial \Psi^x}{\partial \pi^y} & -\frac{\partial \Psi^x}{\partial A_0^y} & -\frac{\partial \Psi^x}{\partial A_1^y} & -\frac{\partial \Psi^x}{\partial \pi_1^y} & f_{\theta_x \theta_y} \end{pmatrix} \delta(x-y), \quad (5.16)$$

where

$$f_{\theta_x \theta_y} = \frac{\partial \Psi_y}{\partial \theta_x} - \frac{\partial \Psi_x}{\partial \theta_y}, \quad (5.17)$$

with $\theta_x \equiv \theta(x)$, $\theta_y \equiv \theta(y)$, $\Psi_x \equiv \Psi(x)$ and $\Psi_y \equiv \Psi(y)$. Note that this matrix is singular since $\frac{\partial \Psi^x}{\partial A_0^y} = 0$. Due to this, we conclude that $\Psi \equiv \Psi(\phi, \pi_\phi, A_1, \pi_1, \theta)$.

To unveil the gauge symmetry hidden inside the model, we assume that this singular matrix has a zero-mode ($\nu^{(0)}$) that satisfies the following relation,

$$\int \nu_\alpha^{(0)}(x) \tilde{f}_{\alpha\beta}^{(0)}(x-y) dy = 0. \quad (5.18)$$

From this relation a set of equations will be obtained and consequently, the arbitrary function Ψ can be determined. We will now investigate the symmetry related to the following zero-mode,

$$\bar{\nu}^{(0)} = (q \quad -q\partial_x \quad 1 \quad \partial_x \quad -q^2 \quad -1), \quad (5.19)$$

with bar representing a transpose matrix.

To start, we multiply the zero-mode (5.19) by the symplectic matrix (5.16), as shown in equation (5.18). Due to this, some equations arise and after an integration Ψ is determined as

$$\Psi = \pi' + q\phi' + q\pi_\phi + q^2A_1. \quad (5.20)$$