

# Assignment3

## DBSCAN

### 1. Algorithm summary

DBSCAN has two parameters,  $\epsilon$  (dense region radius) and  $\text{minPts}$  (minimum number of points to form a dense region). It starts with random starting object that has not been visited. Then retrieve all points that is closer than  $\epsilon$  and if it contains sufficiently many points, a cluster is started and points is included in the cluster. Else, the point is labeled as noise.

From each point in cluster, its neighbor points in dense region are also added in the cluster. This process continues until the density-connected cluster is completely found. Then, a new unvisited point is visited and the algorithm is repeated. The algorithm can be expressed as following pseudocode (source: Wikipedia).

```
DBSCAN(D,  $\epsilon$ , MinPts) {  
    C = 0  
    for each point P in dataset D {  
        if P is visited  
            continue next point  
        mark P as visited  
        NeighborPts = regionQuery(P,  $\epsilon$ )  
        if sizeof(NeighborPts) < MinPts  
            mark P as NOISE  
        else {  
            C = next cluster  
            expandCluster(P, NeighborPts, C,  $\epsilon$ , MinPts)  
        }  
    }  
}  
  
expandCluster(P, NeighborPts, C,  $\epsilon$ , MinPts) {  
    add P to cluster C  
    for each point P' in NeighborPts {  
        if P' is not visited {  
            mark P' as visited  
            NeighborPts' = regionQuery(P',  $\epsilon$ )  
            if sizeof(NeighborPts') >= MinPts  
                NeighborPts = NeighborPts joined with NeighborPts'  
        }  
        if P' is not yet member of any cluster  
            add P' to cluster C  
    }  
}  
  
regionQuery(P,  $\epsilon$ )  
    return all points within P's  $\epsilon$ -neighborhood (including P)
```

## 2. Function

### a) Point class

- region\_query(self, data\_set, eps)

: Find all objects within eps from self instance and return objects in array.

### b) Cluster class

- point\_append(self, point)

: Connect point and cluster. The point is added to self cluster and the point's cluster is set as self cluster.

- expand(self, neighbor\_point, data\_set, eps, minPts)

: Expand cluster from each object in neighbor\_point.

### c) db\_scan module

- db\_scan(data\_set, eps, minPts)

: Proceed DBScan algorithm mentioned above.

## 3. Execution

### a) Requirement

- python 3.6
- numpy
- matplotlib

### b) Command line

```
python clustering.py input1.txt 8 15 20
```

(python <execution file> <input file> <cluster\_num> <eps> <minPts>)