

# PyUncertainNumber for uncertainty propagation: beyond probability arithmetic

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## Summary

Scientific computations or simulations play a central role in quantifying the performance, reliability, and safety of complex engineered systems. However, these analyses are complicated by the various sources of uncertainties inherent in the computational pipeline. Underestimation may lead to suboptimal performance outside the most common scenarios while overestimation, on the other hand, may lead to over-engineered systems and significant waste of resources. To ensure that complex engineered systems can be operated reliably and robustly, even during rare and extreme environment conditions, a comprehensive analysis is required. The analysis should be comprehensive in two senses: (i) all of the possible sources of uncertainty must be identified and represented using appropriate mathematical constructs; (ii) that rigorously account for mixed or mixture of various types of uncertainties. One of the biggest challenges include xxx, code accessibility, tools to conduct the analysis. By xxx, pyuncertainnumber bla bla.. non-intrusively. We interface with many softwares.

## Statement of need

A comprehensive uncertainty framework for scientific computation involves a mathematical model, through which various input uncertainties are propagated to estimate the uncertainty of an unknown quantity of interest (QoI). In real-world applications, these input uncertainties are commonly manifested as mixed uncertainties, e.g. probability boxes (p-boxes) which effectively represents a set of distributions, combining both the aleatory and epistemic uncertainty in one structure, or a mixture of uncertainties suggesting, for instance, a vector of input parameters of aleatory (e.g. probability distributions), epistemic (e.g. intervals), and mixed nature (e.g. probability boxes).

Probability bounds analysis is one of the expressive frameworks proposed to manage uncertainties in an imprecise setting (Beer et al., 2013). Software packages have been developed to facilitate the calculations of uncertain quantities, such as interval arithmetic (Angelis, 2022) and probability arithmetic (A. Gray et al., 2021; N. Gray et al., 2022). Collectively, they can be referred to as *uncertainty arithmetic* (Chen & Ferson, 2025) which straightforwardly computes the response provided the performance function.

While it has the potential to automatically compile non-deterministic subroutines via uncertain primitives, its usages face several challenges, one significant challenge is that code accessibility is often not guaranteed and hence unable to proceed. This would largely restrict the adoption of mixed uncertainty calculations in engineering practice. Such need has been echoed in the engineering applications and also the NASA challenge.

pyuncertainnumber addresses that by enabling non-intrusive capability. That is, generic black-box models can be propagated with (that fancy word) various types of uncertainty. This

41 capability significantly boost its versatility for scientific computations by interfacing with many  
42 engineering softwares.

### 43 Interval propagation in a non-intrusive manner

44 Interval analysis has the advantages of providing rigorous enclosures of the solutions to problems,  
45 especially for engineering problems subject to epistemic uncertainty, such as modelling system  
46 paramters due to lack-of-knowledge or characterising measurement incertitude. Naive interval  
47 arithmetic typically faces difficulties such as the infamous [interval dependency](#) issue. Though  
48 it may be mitigated through mathematical rearrangements in some simple cases, it will be  
49 challenging for models of most complex systems. The bigger issue remains the accessibility of  
50 code.

51 Generally, the interval propagation problem can be cast as an optimisation problem where the  
52 minimum and maximum are sought via a function mapping. The function, for example  $f$  in  
53 [Equation 1](#), is not necessarily monotonic or linear and may well be a black-box deterministic  
54 model for a generic system.

$$Y = f(I_{x1}, I_{x2}, \dots, I_{xn}) \quad (1)$$

55 where  $\mathbf{I} = [\underline{\mathbf{I}}, \bar{\mathbf{I}}] = [I_{x1}, I_{x2}, \dots, I_{xn}]^T$  represents the vector of interval-valued inputs. For black  
56 box models the optimisation can generally be solved via gradient-free optimisation techniques.

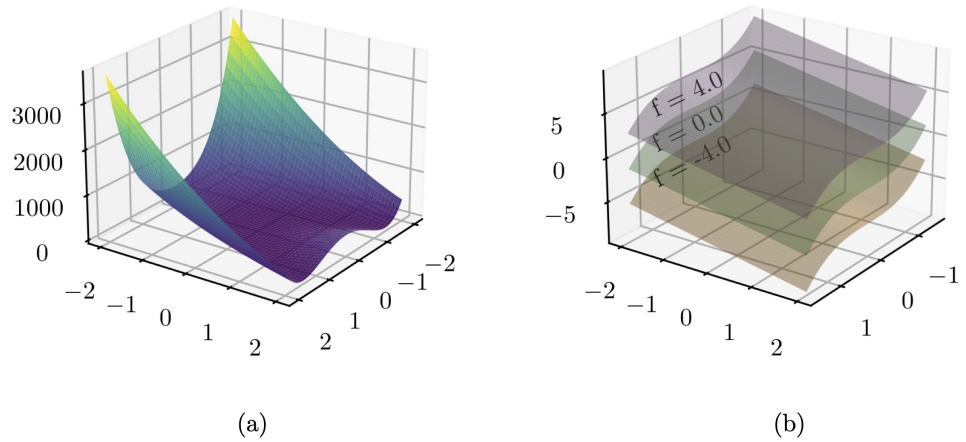
$$\underline{Y} = \min_{\mathbf{I} \in [\underline{\mathbf{I}}, \bar{\mathbf{I}}]} [f(\mathbf{I})]; \quad \bar{Y} = \max_{\mathbf{I} \in [\underline{\mathbf{I}}, \bar{\mathbf{I}}]} [f(\mathbf{I})]$$

57 `pyuncertainnumber` provides a series of non-intrusive methodologies of varying applicability.  
58 It should be noted that there is generally a trade-off between applicability and computational  
59 efficiency. With more knowledge pertaining the characteristics of the underlying function, one  
60 can accordingly dispatch an efficient method. For example, when monotonicity is known one  
61 can use the vertex method which requires  $2^n$  model evaluations. Furthermore, the accuracy  
62 of these methods varies, and a common rule of thumb indicates that increasing the number  
63 of model evaluations generally leads to improved accuracy. A summary of applicability is  
64 tabulated in [Table 1](#), readers can refer to ([Chen & Ferson, 2025](#)) for additional details.

**Table 1:** Several methods for interval propagation

Method	End-points	Subinterval reconstitution	Cauchy-Deviante method	Bayesian optimisation	Genetic algorithm
As-sump-tion	monoto-nicity	monotonicity in subinterlvas	linearity and gradient required	No	No
Exam-ple result	[13.0,148.0]	[13.0,148.0]	[-11.7,100.67]	[13.0,148.0]	[13.0,147.8]

65 To better demonstrate the non-intrusive capability, two numerical examples, shown below,  
66 are provided where they are treated as black-box models. [Table 2](#) lists the response interval for  
67  $f_b([1, 5], [7, 13], [5, 10])$  for associated method.



**Figure 1:** Exemplar functions as black-box models. (a)  $f_a(x, y) = 100(x - y^2)^2 + (1 - x)^2$ ; (b)  $f_b(x, y, z) = x^3 + y + z$

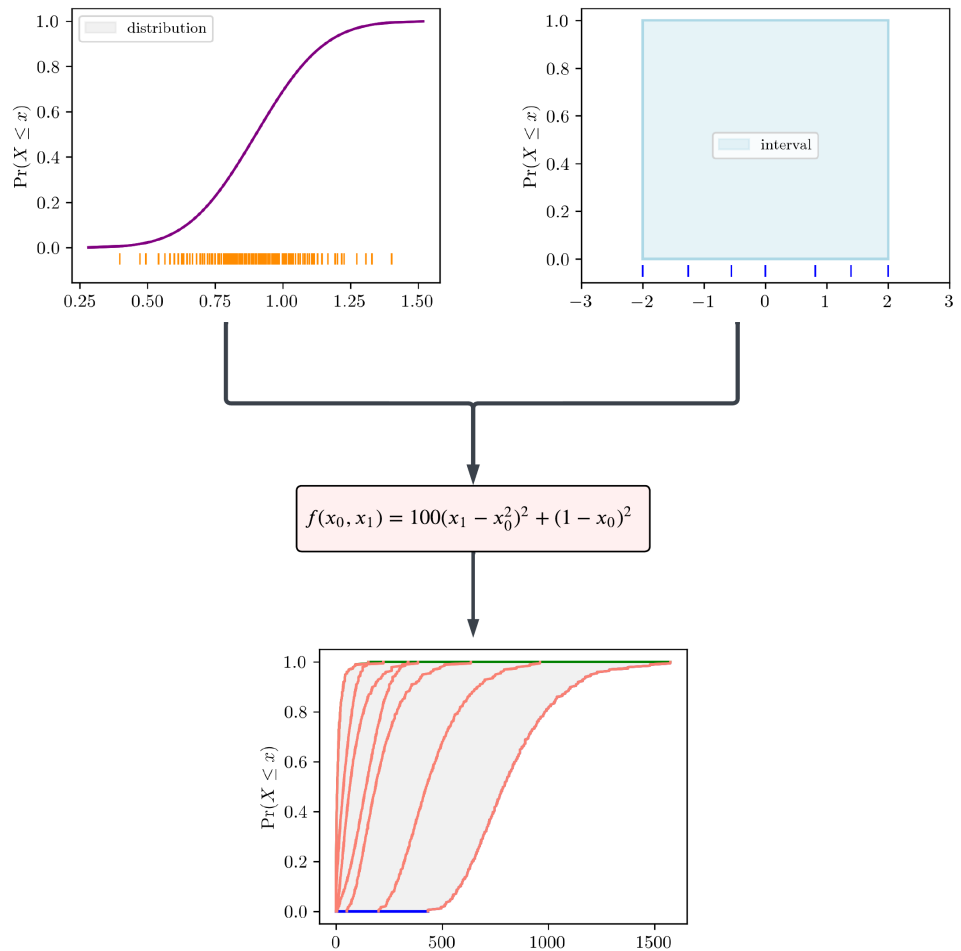
## Mixed uncertainty propagation for black-box models

Real complex systems (physical or engineered) of industrial significance typically involves parameters subject to uncertainties of various nature. It requires faithful characterisation of these uncertainties given the empirical information, and the approach to rigorously propagate them. Due to the fact that empirical information is often sparse or scarce or conflicting, even the uncertainty characterisation for one parameter could be of mixed nature, for example one may be confident about the distributional family but uncertain about its shape parameters, or when there exists multiple expert opinion of different credibility regarding its elicitation. Commonly, real systems expect a high-dimensional input which effectively represents a mixture of aleatory, epistemic, and mixed uncertainties, as symbolified below:

$$Y = f(\mathbf{u}; C) \quad (2)$$

where  $\mathbf{u} \in \mathbb{R}^n$  denotes the collection of  $n$  uncertain inputs and  $C$  denotes intervariable dependency structure.

When both aleatory and epistemic uncertainties are present in  $\mathbf{u}$ , a *nested (double) Monte Carlo* approach can be used for deterministic models without confounding the two distinct types of uncertainty. As illustrated in Figure 2, Latin-hypercube samples are first drawn from the epistemic interval, conditioned on which aleatory samples are drawn from the aleatoric probability distributions. Propagate these samples, which are visually denoted as rug ticks alongside the abscissa, through the computational model results in an ensemble of CDF (cumulative distribution function) of the QoI whereby a final p-box is obtained as the envelope. Each CDF (orange color) corresponds to an epistemic sample.



**Figure 2:** Workflow of the Double Monte Carlo.

88 To scale to a more realistic setting, [Figure 3](#) illustrates the workflow of *interval Monte Carlo*  
 89 method where a mixture of aleatory, epistemic, and mixed uncertainty parameters are present,  
 90 and a certain copula is specified denoting the dependency structure. Correlated samples in the  
 91 uniform space from the copula, visually denoted as rug ticks alongside the probability axis, are  
 92 converted to physical space through alpha-cuts. Interval propagation (see [the last section](#))  
 93 then does the heavy lifting in which scalar values can be considered as degenerate intervals. As  
 94 a result, the response QoI in [Figure 3](#) is then obtained as a p-box shown in gray. In contrast, a  
 95 pinched response, obtained from propagating pinched input variables (e.g. a p-box is pinched  
 96 into a distribution and an interval is pinched into a scalar), is also shown as a comparison.  
 97 Importantly, rigorous bla bla.

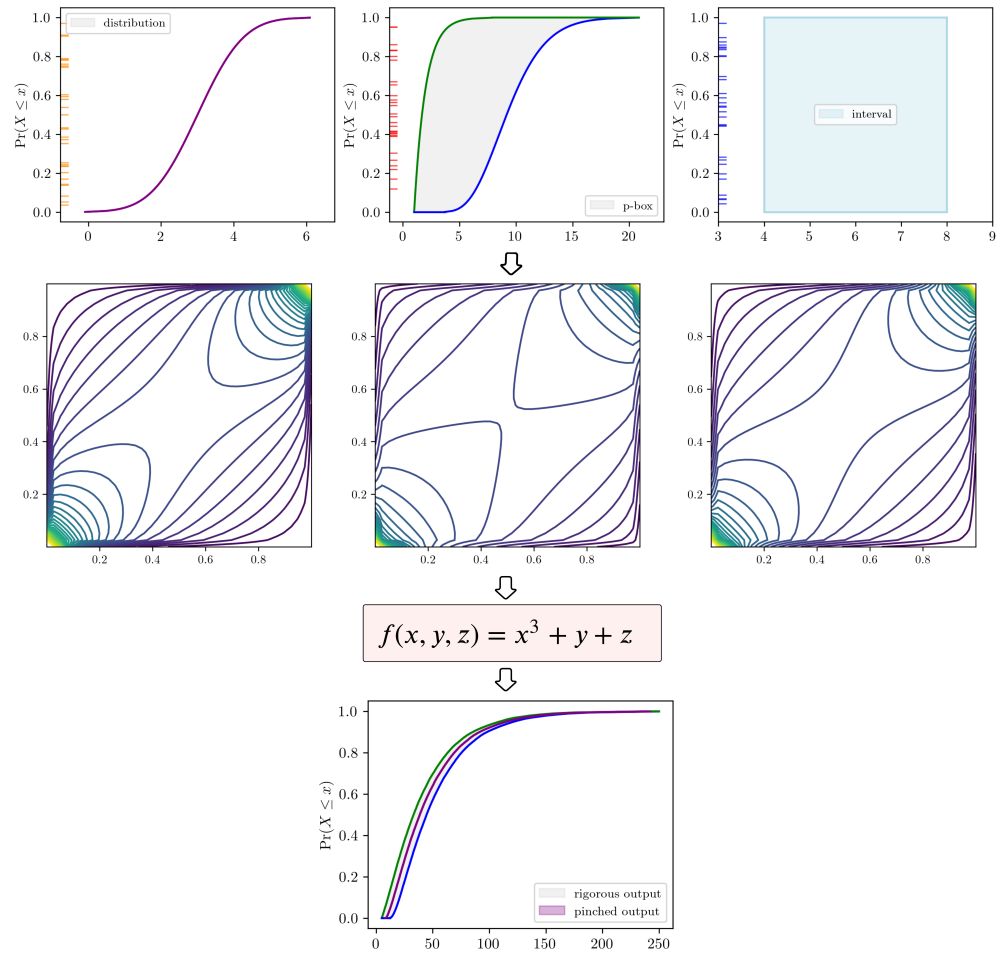


Figure 3: Workflow of the Interval Monte Carlo.

## Conclusion

It is evident that computational tasks requiring complex numerical solutions of intervals are non-intrusive (i.e. the source code is not accessible). `pyuncertainnumber` enables rigorous uncertainty analysis for real-world situations of mixed uncertainties and partial knowledge. Significance: this provides compatability as interfacing with many engineering applications. boost its usage.

Enriched sampling methods bla bla ...

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