

BCNF: is there any completely non-trivial FD wh LHS attributes are not superkey?

3NF: BCNF || is there any completely non-trivial where RHS attribute is not a prime attribute?

Prime attribute is the union of all possible keys

Consider R(A,B,C,D,E) with F = {A -> E, AB -> D, CD -> AE, E -> B, E the decomposition of R into the fragments {R1(B,D,E), R2(A,C,E)}.

- a) Is R in BCNF? Explain.
- b) Given the decomposition {R1(B,D,E), R2(A,C,E)} is all fragment in BCNF?
- b) For the projection, we consider either (1) the completely non-trivial fds in the the minimal cover of projection.

- F[R1] = {E -> BD}. Since E is a superkey of R1, then R1 is in BCNF.
- F[R2] = {A -> E, CE -> A}. Consider A -> E in F[R2].
 - 1. A -> E is non-trivial.
 - 2. A is not a superkey of R2.

Consider R(A,B,C,D,E) with F = {AB -> CDE, AC -> BDE, B -> D, C -> B, C -> D, D -> B}

- a) Find a lossless-join valid decomposition of R into BCNF.

- 1. Since B -> DE violates BCNF of R (proof omitted) => Decompose R into R1(B,D,E) and R2(A,B,C).
- 2. Since C -> B violates BCNF of R2 (proof omitted) => Decompose R2 into R3(B,C) and R4(A,C).

Therefore, one possible decomposition is {R1(B,D,E), R3(B,C), R4(A,C)}

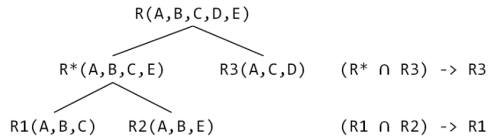
Problem 3 : Decomposition #1

Consider R(A,B,C,D,E) with F = {AB -> C, AC -> D, E -> ABCD}. Consider the decomposition of R into the fragments {R1(A,B,C), R2(A,B,E), R3(A,C,D)}.

- a) Is the decomposition a lossless-join decomposition? Explain.
- b) Is the decomposition a dependency-preserving decomposition? Explain.

Solution Using AC -> D

- a) Yes. The visual proof is as follows:



The more formal proof is as follows:

- 1. Consider R*(A,B,C,E)
- 2. The decomposition of R into {R*, R3} is a lossless-join decomposition because:
 - => (R3 ∩ R*) = AC
 - => AC+ = {ACD}
 - => AC -> ACD
 - => R3 = ACD
 - => (R3 ∩ R*) -> R3
 - => By Theorem 1, the decomposition of R into {R*, R3} is a lossless-join decomposition
- 3. The decomposition of R* into {R1, R2} is a lossless-join decomposition because:
 - => (R1 ∩ R2) = AB
 - => AB+ = {ABC}
 - => AB -> ABC
 - => R1 = ABC
 - => (R1 ∩ R2) -> R1
 - => By Theorem 1, the decomposition of R* into {R1, R2} is a lossless-join decomposition
- 4. By Theorem 2, the decomposition of R into {R1, R2, R3} is a lossless-join decomposition

Is dp

- 1. F[R1] = {AB -> C}
- 2. F[R2] = {E -> AB}
- 3. F[R3] = {AC -> D}
- 4. Let G = F[R1] ∪ F[R2] ∪ F[R3] = {AB -> C, E -> AB, AC -> D}
- 5. G ⊨ F because:
 - => G ⊨ AB -> C (trivial)
 - => G ⊨ E -> AB (trivial)
 - => G ⊨ AC -> D (trivial)
 - => G ⊨ E -> CD (because E+ = ABCDE and hence E -> CD)

Minimum cover

For each attribute on LHS, check if they are redundant and remove them

Consider R(A,B,C,D,E) with F = {AB -> CDE, AC -> BDE, B -> D, C -> B, C -> D, D -> B, B -> E}

G = {B -> D, AB -> C, C -> B, B -> E} Combine same LHS

Is __ in BCNF

- 1. Check if LHS not superkey
- 2. Use armstrong axiom

Is __ in 3NF

- 1. E -> B is non-trivial.
- 2. E is not a superkey of R.
- 3. B is not a prime attribute.

LHS not superkey and RHS not prime attribute

Is all fragment in BCNF

- 1. Calculate projection of decomposed fragments
- 2. Check if it belongs to any of the FD in the not decomposed schema

Problem 1 : Normal Forms #1

Consider R(A,B,C,D,E) with F = {AB -> C, AC -> D, E -> ABCD}. Consider the decomposition of R into the fragments {R1(A,B,C), R2(A,B,E), R3(A,C,D)}.

a) Is R in BCNF? Explain.

b) Given the decomposition {R1(A,B,C), R2(A,B,E), R3(A,C,D)} is all fragment in BCNF? Explain.

c) Is R in 3NF? Explain.

d) Given the decomposition {R1(A,B,C), R2(A,B,E), R3(A,C,D)} is all fragment in 3NF? Explain.

Handwritten notes: R2(ABE), F[R1] = {AB -> C}, F[R2] = {E -> AB}, F[R3] = {AC -> D}, E+ = EABCD, E+ ∩ ABE = ABE, E+ = ABE, E -> AB.

How to get prime attribute

Compute the closure

Common mistake E -> ABCD and E+ = ABCDE

Find a lossless-join dependency-preserving valid decomposition of **R** into 3NF

Use synthesis method

1. Find min cover
2. Combine same LHS
3. Combine into attributes of FD into schemas
4. Add key to schema
5. Remove redundant schemas (subset of other schemas)
 - With B -> DE, R1(B,D,E)
 - With AB -> C, R2(A,B,C)
 - With C -> B, R3(B,C)
 - With key = {A,B}, R4(A,B)

Without the *redundant schema*, the decomposition is {R1(B,D,E) , R2(A,B,C)}.

Another solution is the same as the previous one since if the schema is in BCNF, it is also in 3NF. Since the BCNF decomposition is dependency-preserving, the 3NF decomposition is also dependency-preserving.