University of California at Berkeley Department of Electrical Engineering and Computer Sciences Computer Science Division

Autumn 2006 Jonathan Shewchuk

CS 61B: Midterm Exam II

This is an open book, open notes exam. Electronic devices are forbidden on your person, including cell phones, iPods, headphones, laptops, and PDAs. Turn your cell phone off and leave it and all electronics at the front of the room, or risk getting a zero on the exam. **Do not open your exam until you are told to!**

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Problem #	Possible	Score		
1. Miscellaneous	8			
2. Binary Trees	8			
3. Directed Graphs	9			
Total	25			

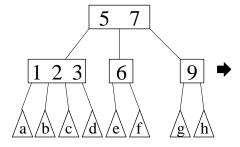
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Problem 1. (8 points) A Miscellany.

a. (2 points) Suppose you implement a binary search method, and it takes 10 microseconds to search a 1,000,000-int array for a number that turns out not to be in the array. How long do you estimate it would take for your implementation to search a 1,000,000,000,000-int array for a number that's not in the array?

b. (2 points) Explain why $\frac{1}{n-100} \in O(n)$. Don't just reiterate the definition of big-Oh; give specific values of c and N that support the claim. (No need for a complete proof, though.)

c. (2 points) When we remove an item from a 2-3-4 tree, sometimes a node tries to "steal" a key from a sibling by performing a rotation. However, the remove algorithm we learned in class only allows a node to steal from an *adjacent* sibling. But there's no fundamental reason why a node couldn't steal a key from a nonadjacent sibling, except that we wanted to keep the algorithm as simple as possible. Show how we could modify the 2-3-4 tree below so that the "9" node has one more key, the "1 2 3" node has one fewer key, every other node has the same number of keys it had before, and the tree is still a valid 2-3-4 tree containing the same keys it had before. The triangles at the bottom are subtrees, which you cannot restructure (but you can change their parents).



d. (2 points) Fill in the blank. The worst-case running time of the following method, expressed as a function of the input parameter n, is in $\Theta(\underline{\hspace{1cm}})$. Note that the loop does not use "i--"!

(It's not quite like the running time of any other algorithm you've seen. An explanation of your reasoning might help you get part marks if your answer is wrong.)

Problem 2. (8 points) **Binary Trees.**

a. (2 points) Draw a tree that is *both* a binary search tree and a complete binary tree, and whose keys are the integers 1 through 9 (each appearing once).

b. (2 points) If you perform the operation remove (5) on a binary search tree, it will obviously delete 5 from the preorder traversal of the tree. For example, if the preorder traversal was 5 2 1 3 4 before the deletion, then it is 2 1 3 4 after the deletion. But can the operation remove (5) ever change the *order* of keys in a preorder traversal? If "yes," give an example. If "no," explain why.

c. (4 points) Show the sequence of swaps by which the method bottomUpHeap converts the following array into a heap. Redraw the array once for each swap (in the boxes provided).

(Note: We've provided room for up to seven swaps, the maximum number possible for eight items. That doesn't necessarily mean that this particular example takes seven swaps.)

7	2	5	9	3	4	1	8

d. (0 points) If you could choose to be a tree, What kind of tree would you choose to be?

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Problem 3. (9 points) **Directed Graphs.**

a. **First**, read the instructions on the next page; then come back here. You may tear the next page off your exam.

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Check here if your answer | | | | is continued on the back. |___|
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For the following questions, give the simplest, smallest bounds possible in terms of the number $s=\mathtt{size}$ of vertices and the number e of edges. Make sure your bounds are correct even when e is much less or much greater than s. (If you skipped part a., assume you have the fastest possible implementation.)

- b. The worst-case running time of your contract method is in Θ ().
- c. If you were to reimplement your Set class so it stores the set in a resizable hash table (with the hash table's size proportional to the size of the set) instead of a list, the worst-case running time of your contract method would be in $\Theta(\underline{})$. Assume no hash table chain gets longer than $\mathcal{O}(1)$, and don't count the time for hash table resizing.

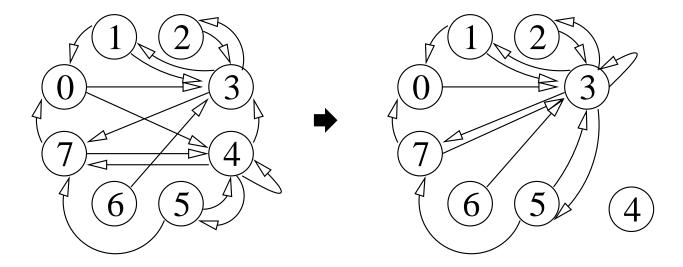
Hint: if your implementation runs as fast as it should, the answers to parts b-d are all different.

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Suppose you implement a directed graph class, DiGraph, using an adjacency list. The vertices are the integers $0 \dots \text{size} - 1$. DiGraph represents the adjacency list as an array of Sets from Homework 5. Recall that your Set implementation stores numbers in a sorted linked list. Sets support the following methods.

Recall that neither union nor intersect change s. Note that we've added a new method remove. If the integer i is in the Set, remove removes i from the Set and returns true. Otherwise, it returns false (without changing the Set). You may access Sets only through these methods.

Write a method to *contract* an edge with vertices x and y—in other words, to combine the two vertices into one vertex x. After an edge contraction, all the edges that pointed into or out of vertex y now point into or out of vertex x instead, and no edge is incident on y. This figure illustrates contracting the vertices 3 and 4, so that 4 becomes disconnected from the rest of the graph.



If an edge contraction creates multiple copies of an edge, only one is stored. (Your Set class will handle this for you automatically, since a set can't contain two copies of the same item.) If the graph had one (or more) of the edges (x, y), (y, x), or the self-edge (y, y) before the contraction, then vertex x gains a self-edge after, as the figure shows.

You will be judged on the speed of your code, as well as its correctness.