## SOLITARY-WAVE FAMILIES OF THE GENERALIZED POCHAMMER-CHREE PDE'S

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ABSTRACT. The Generalized Pochammer-Chree Equations Since solitary-wave solutions often play a central role in the long-time evolution of an initial disturbance, we consider such solutions here (via normal form approach) within the framework of reversible systems theory. On isolated curves in the relevant parameter region, the delocalized waves reduce to genuine embedded solitons. Directions for future work are also described.

### 1. Introduction

The nonlinear dispersive equations [2]

$$(1.1a) (u - u_{xx})_{tt} - (a_1u + a_2u^2 + a_3u^3)_{xx} = 0$$

$$(1.1b) (u - u_{xx})_{tt} - (a_1u + a_3u^3 + a_5u^5)_{xx}^{2} = 0$$

are known as the Generalized Pochammer-Chree Equation 1 and 2, respectively.

We use the theory of reversible systems and the method of normal forms to categorize the possible solitary waves of (1.1). As we shall see, several families of solitary waves exist in various regions of parameter space. Our main focus here will be on delineating the possible occurrence and multiplicity of solitary waves in defferent parameter regimes. Certain delicate questions relating to specific waves or wave families will form the basis of future work.

The remainder of this paper is organized as follows. In Section 2, we delineate the possible families of solitary waves in various parameter domains and on certain important curves using the theory of reversible systems. In Section 3 and 4, we next focus on the various transition curves and derive normal forms in their vicinity to confirm the existence of families of regular or delocalized solitary-wave solutions in their vicinity.

### 2. Solitary waves: local bifurcation

Solitary waves of (1.1) of the form  $v(x,t) = \phi(x-ct) = \phi(z)$  satisfy the fourth-order travelling wave ODE

$$\phi_{zzzz} - q\phi_{zz} + p\phi = \mathcal{N}_{1,2}[\phi]$$

where

$$\mathcal{N}_{1} \left[ \phi \right] = -\frac{1}{c^{2}} \left[ 3a_{3} \left( 2\phi\phi_{z}^{2} + \phi^{2}\phi_{zz} \right) + 2a_{2} \left( \phi_{zz}\phi_{z} + \phi_{z}^{2} \right) \right]$$

(2.2b) 
$$\mathcal{N}_{2} \left[ \phi \right] = -\frac{1}{c^{2}} \left[ 3a_{3} \left( 2\phi\phi_{z}^{2} + \phi^{2}\phi_{zz} \right) + 5a_{5} \left( 4\phi^{3}\phi_{z}^{2} + \phi^{4}\phi_{zz} \right) \right]$$

$$(2.3a) z \equiv x - ct$$

$$(2.3b) p \equiv 0$$

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$$(2.3c) q \equiv 1 - \frac{a_1}{c^2}$$

(2.3d)

Equation (2.1) is invariant under the transformation  $z \mapsto -z$  and is thus a reversible system. In this section we shall use the theory of reversible systems to characterize the homoclinic orbits to the fixed point of (2.1), which correspond to pulses or solitary waves of the Micro-Structure PDE in various regions of the (p,q) plane.

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The linearized system corresponding to (2.1)

$$\phi_{zzzz} - q\phi_{zz} + p\phi = 0$$

has a fixed point

$$\phi = \phi_z = \phi_{zz} = \phi_{zzz} = 0$$

Solutions  $\phi = ke^{\lambda x}$  satisfy the characteristic equation  $\lambda^4 - q\lambda^2 + p = 0$  from which one may deduce that the structure of the eigenvalues is distinct in two regions of (p,q)-space. Since p=0 we have only two possible regions of eigenvalues. We denote  $C_0$  as the positive q axis and  $C_1$  the negative q-axis. First we shall consider the bounding curves  $C_0$  and  $C_1$  and their neighborhoods, then we shall discuss the possible occurrence and multiplicities of homoclinic orbits to (2.5), corresponding to pulse solitary waves of (1.1), in each region:

**Near**  $C_0$ : The eigenvalues have the structure  $\lambda_{1-4} = 0, 0, \pm \lambda, (\lambda \in \mathbb{R})$  and the fixed point (2.5) is a saddle-focus.

**Near**  $C_1$ : Here the eigenvalues have the structure  $\lambda_{1-4}=0,0,\pm i\omega, (\omega\in\mathbb{R})$ . We will show by analysis of a four-dimensional normal form in Section 4 that there exists a  $sech^2$  homoclinic orbit near  $C_1$ .

Having outlined the possible families of orbits homoclinic to the fixed point (2.5) of (2.4), corresponding to pulse solitary waves of (1.1), we now derive normal forms near the transition curves  $C_0$  and  $C_1$  to confirm the existence of regular or delocalized solitary waves in the corresponding regions of (p,q) parameter space.

### 3. Calculations

Using (2.4), the curve  $C_0$ , corresponding to  $\lambda = 0, 0, \pm \tilde{\lambda}$ , is given by

$$(3.1) C_0: p = 0, q > 0$$

Using (2.3c) implies

$$(3.2) stuff > 0$$

Denoting  $\phi$  by  $y_1$ , (2.1) may be written as the system

$$\frac{dy_1}{dz} = y_2$$

$$\frac{dy_2}{dz} = y_3$$

$$\frac{dy_3}{dz} = y_4$$

(3.3a) 
$$\frac{dy_1}{dz} = y_2$$
(3.3b) 
$$\frac{dy_2}{dz} = y_3$$
(3.3c) 
$$\frac{dy_3}{dz} = y_4$$
(3.3d) 
$$\frac{dy_4}{dz} = qy_3 - py_1 - (\Delta_1 y_2^2 + b\Delta_1 y_1 y_3)$$

We wish to rewrite this as a first order reversible system in order to invoke the relevant theory [1]. To that end, defining  $Y = \langle y_1, y_2, y_3, y_4 \rangle^T$  (3.3) may be written

$$\frac{dY}{dz} = L_{pq}Y - F_2(Y,Y)$$

where

(3.5) 
$$L_{pq} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ q/3 & 0 & 1 & 0 \\ 0 & q/3 & 0 & 1 \\ q^2 - p & 0 & q/3 & 0 \end{pmatrix}$$

Since p = 0 for (1.1), we have

(3.6) 
$$\frac{dY}{dz} = L_{0q}Y - F_2(Y,Y)$$

where

(3.7) 
$$F_2(Y,Y) = \langle 0, 0, 0, XXX \rangle^T$$

Next we calculate the normal form of (3.6) near  $C_0$ . The procedure is closely modeled on [1] and many intermediate steps may be found there.

# 3.1. Near $C_0$ . HERE

Here we have

(3.8a) 
$$q = 1 - \frac{a_1}{c^2}$$

$$(3.8b) p = 0$$

We emphasize that p=0 because this corresponds to a 1-D subspace of the (p,q) parameter space in [2]. We denote  $C_0$  as the positive q axis and  $C_1$  the negative q-axis.

Solutions  $\phi = ke^{\lambda x}$  satisfy the characteristic equation  $\lambda^4 - q\lambda^2 + p = 0$ . Since p = 0 for the GPC PDE's we have only two possible regions of eigenvalues. On  $C_0$  the eigenvalues have the structure  $\lambda_{1-4}=0,0,\pm\lambda$ ,  $(\lambda \in \mathbb{R})$  while on  $C_1$  we have  $\lambda_{1-4} = 0, 0, \pm i\omega, (\omega \in \mathbb{R})$ .

We now use the theory of Iooss and Adelmeyer [1] to write the GPC PDE's in reversible form: Let  $Y = \langle y_1, y_2, y_3, y_4 \rangle^T$  where  $\langle y_1, y_2, y_3, y_4 \rangle^T = \langle \phi_z, \phi_{zz}, \phi_{zzz}, \phi_{zzzz} \rangle^T$ We may now write (2.1) as a reversible first-order system

(3.9) 
$$\frac{dY}{dz} = L_{pq}Y - F_{1,2}(Y,Y)$$

where

(3.10) 
$$L_{pq} = \begin{pmatrix} 0 & 1 & 0 & 0 \\ q/3 & 0 & 1 & 0 \\ 0 & q/3 & 0 & 1 \\ q^2 - p & 0 & q/3 & 0 \end{pmatrix}$$

Since p = 0 for the GPC PDE's, we have

(3.11) 
$$\frac{dY}{dz} = L_{0q}Y - F_{1,2}(Y,Y)$$

where

(3.12) 
$$F_{1,2}(Y,Y) = \langle 0, 0, 0, -\mathcal{N}_{1,2} \rangle^T$$

and

(3.13a) 
$$F_1(Y,Y) = \left\langle 0, 0, 0, \frac{1}{c^2} \left[ 3a_3 \left( 2y_1 y_2^2 + y_1^2 y_2 \right) + 2a_2 \left( y_2 y_3 + y_2^2 \right) \right] \right\rangle^T$$

(3.13b) 
$$F_2(Y,Y) = \left\langle 0, 0, 0, \frac{1}{c^2} \left[ 3a_3 \left( 2y_1 y_2^2 + y_1^2 y_2 \right) + 5a_5 \left( 4y_1^3 y_2^2 + y_1^4 y_3 \right) \right] \right\rangle^T$$

3.2. Near  $C_0$ . Near  $C_0$  the dynamics reduce to a 2-D Center Manifold

$$(3.14) Y = A\zeta_0 + B\zeta_1 + \Psi(\epsilon, A, B)$$

with

$$\frac{dA}{dz} = B$$

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$$\frac{dB}{dz} = b\epsilon A + \tilde{c}A^2$$

and the eigenvectors are  $\zeta_0 = \langle 1, 0, -q/3, 0 \rangle^T$ ,  $\zeta_1 = \langle 0, 1, 0, -2q/3 \rangle^T$ ,  $\epsilon$  determines the distance from  $C_0$ . A simple dominant balance argument on the linearized equation yields  $b = -\frac{1}{q}$ .

To determine  $\tilde{c}$  we calculate  $\frac{dY}{dz}$  in two ways and match the  $\mathcal{O}(A^2)$  terms. Expanding  $\Psi(\epsilon,A,B)$  in series

(3.16) 
$$\Psi(\epsilon, A, B) = \epsilon A \Psi_{10}^1 + \epsilon B \Psi_{01}^1 + A^2 \Psi_{20}^0 + A B \Psi_{11}^0 + B^2 \Psi_{02}^0 + \cdots$$

we find

(3.17) 
$$\tilde{c}\zeta_1 = L_{0q}\Psi_{20}^0 - F_{1,2}(\zeta_0, \zeta_0)$$

We find that  $F_1(\zeta_0, \zeta_0) = \langle 0, 0, 0, -\frac{q}{c^2} a_3 \rangle^T$  and  $F_2(\zeta_0, \zeta_0) = \langle 0, 0, 0, -\frac{q}{c^2} \left( a_3 + \frac{5a_5}{3} \right) \rangle^T$  which implies  $\tilde{c} = -\frac{a_3}{c^2}$  for the GPC 1 and  $\tilde{c} = -\frac{1}{c^2} \left( a_3 + \frac{5}{3} a_5 \right)$  for the GPC 2. Therefore, the normal form for the GPC 1 PDE near  $C_0$  is

$$\frac{dA}{dz} = B$$

$$\frac{dA}{dz} = B$$

$$\frac{dB}{dz} = -\frac{\epsilon}{q}A - \frac{a_3}{c^2}A^2$$

and the normal form for the GPC 2 PDE near  $C_0$  is

$$\frac{dA}{dz} = B$$

(3.19b) 
$$\frac{dB}{dz} = -\frac{\epsilon}{q}A - \frac{1}{c^2}\left(a_3 + \frac{5}{3}a_5\right)A^2$$

3.3. Near  $C_1$ . Near  $C_1$  the dynamics reduce to a 4-D Center Manifold

(3.20) 
$$Y = A\zeta_0 + B\zeta_0 + C\zeta_+ + \bar{C}\zeta_- + \Psi(\epsilon, A, B, C, \bar{C})$$

with

$$\frac{dA}{dz} = E$$

(3.21b) 
$$\frac{dB}{dz} = \bar{\nu}A + b_*A^2 + c_*|C|^2$$

$$\begin{array}{cccc} (3.21\mathrm{a}) & & \frac{dA}{dz} & = & B \\ (3.21\mathrm{b}) & & \frac{dB}{dz} & = & \bar{\nu}A + b_*A^2 + c_* \left|C\right|^2 \\ (3.21\mathrm{c}) & & \frac{dC}{dz} & = & id_0C + i\bar{\nu}d_1C + id_2AC \\ \end{array}$$

where  $\zeta_{\pm} = \left\langle 1, \lambda_{\pm}, 2q/3, \frac{\lambda_{\pm}}{3}q \right\rangle^{T}$  where  $\bar{\nu} = -\frac{\epsilon}{q}, b_* = -\frac{b\Delta 1}{3}$  and  $\lambda_{\pm} = \pm i\sqrt{-q}$ . Comparing to the linearized equations gives  $d_0 = \sqrt{-q}$ .

ACTUALLY DO THIS: If we do a dominant balance argument after the change of variable  $\tilde{\epsilon} = \sqrt{-3\mu}$  on the characteristic equation as  $\lambda \to 0$  then we find  $d_1 = \frac{\sqrt{-3\mu}}{18\mu^2}$ . Using  $\mu = q/3$  we find  $d_1 = \frac{\sqrt{-q}}{2q^2}$ To determine  $b_*, c_*$  and  $d_2$  we expand

$$(3.22) \qquad \quad \Psi(\epsilon,A,B,C,\bar{C}) = \epsilon A \Psi^1_{1000} + \epsilon B \Psi^1_{0100} + A^2 \Psi^0_{2000} + AB \Psi^0_{1100} + AC \Psi^0_{1010} + \epsilon C \Psi^1_{0010} + \cdots$$

Now we use (3.21b), (3.21c), (3.21c) in (3.22) when we calculate  $\frac{dY}{dz}$ . Matching coefficients yields

(3.23a) 
$$\mathcal{O}(A^2): \qquad b_*\zeta_1 = L_{0q}\Psi^0_{2000} - F_2(\zeta_0, \zeta_0)$$

(3.23b) 
$$\mathcal{O}(|C|^2): c_*\zeta_1 = L_{0q}\Psi^0_{0011} - 2F_2(\zeta_+, \zeta_-)$$

(3.23b) 
$$\mathcal{O}(|C|^2): \qquad c_*\zeta_1 = L_{0q}\Psi_{0011}^1 - 2F_2(\zeta_+, \zeta_-)$$
(3.23c) 
$$\mathcal{O}(\epsilon C): \quad -\frac{i}{q}\left(d_1\zeta_+ + d_0\Psi_{0010}^1\right) = L_{0q}\Psi_{0010}^1 - F_2(\Psi_{0010}^1, \Psi_{0010}^1)$$

(3.23d) 
$$\mathcal{O}(AC): id_2\zeta_+ + id_0\Psi^0_{1010} = L_{0q}\Psi^0_{1010} - 2F_2(\zeta_0, \zeta_+)$$

(3.23e)

where we have used the fact that  $F_2$  is a symmetric bilinear form. Equation (3.23b) is decoupled and yields  $c_* = 2\Delta_1\left(\frac{1}{q} + \frac{2b}{3}\right)$  The only coefficient left to determine is  $d_2$  which we shall compute now.

Put 
$$\Psi^0_{1010} = \langle x_1, x_2, x_3, x_4 \rangle^T$$
 into (3.23e) implies

$$(3.24a) id_2 + id_0x_1 = x_2$$

$$-d_0 d_2 + i d_0 x_2 = \frac{q}{3} x_1 + x_3$$

(3.24c) 
$$\frac{2iq}{3}d_2 + id_0x_3 = \frac{q}{3}x_2 + x_4$$

$$-\frac{q}{3}d_0d_2 + id_0x_4 = \frac{q}{3}\left(\frac{q}{3}x_1 + x_3\right) - \frac{2bq\Delta_1}{3}$$

Using (3.24a) in (3.24b) , (3.24b) in (3.24d) and using these in (3.24c) yields  $d_2 = \frac{b\Delta_1}{3\sqrt{-q}}$ . Therefore the normal form for the MS PDE near  $C_1$  is

$$\frac{dA}{dz} = B$$

(3.25b) 
$$\frac{dB}{dz} = -\frac{\epsilon}{q}A - \frac{b\Delta_1}{3}A^2 + 2\Delta_1\left(\frac{1}{q} + \frac{2b}{3}\right)|C|^2$$

$$(3.25c) \qquad \frac{dC}{dz} = i\sqrt{-q}C - i\frac{\epsilon\sqrt{-q}}{q^3}C + i\frac{b\Delta_1}{3\sqrt{-q}}AC$$

4. Analysis of Normal Forms

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### References

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