## 1 Week 2 Reading

1. (Page 21) How does the equality (given  $S_0 = x$ )

$$F(x) = [1 - \mathbb{P}^x(S_T = N)]F(0) + \mathbb{P}^x(S_T = N)F(N)$$

result in  $\mathbb{P}^x(S_T = N) = \mathbb{P}(S_T = N \mid S_0 = x) = \frac{x}{N}$ 

(Added later: Derivation in continuous setting, page 73)

(NTS: Have to use the mean condition?)

2. (Page 27) (Clarification) The first expression, given the initial conditions, that

$$p_n(y) = \mathbb{P}(S_{n \wedge T_A} = y \mid S_0 = x)$$

From which expression is this equality derived from? I assume that this is not derived from the equation from the last section, where conditions are placed on the boundary  $\partial A$  and values are then projected into the interior A. In this case there are just initial conditions placed on points in A.

I want to write

$$p_n(y) = \sum_{z \in A} \mathbb{P}(S_{n \wedge T_A} = y \mid S_0 = z) p_0(z) = \mathbb{P}(S_{n \wedge T_A} = y \mid S_0 = x) p_0(x) = \mathbb{P}(S_{n \wedge T_A} = y \mid S_0 = x)$$

(the sum simplifies because  $p_0(z) = 0 \ \forall \ z \neq x$ ), but that seems unrigorous to me, though it does make intuitive sense (The heat after n steps only came from within the system and therefore from the initial conditions).

In fact, I think the above equation comes readily from the following paragraph, about how  $\{p_n(x): x \in A\}$  is the vector  $\mathbf{Q}^n f$ .

Perhaps I'm having trouble because the only expression that I have right now is that

$$\partial_n p_n(x) = \mathcal{L}p_n(x)$$

$$\Leftrightarrow p_{n+1}(x) = \mathbf{Q}p_n(x)$$

$$= \mathbb{E}[p_n(S_1) \mid S_0 = x]$$

$$= \sum_{|y-x|=1} p_n(y) \mathbb{P}(S_1 = y \mid S_0 = x)$$

$$= \sum_{y \in A} p_n(y) \mathbb{P}(S_1 = y \mid S_0 = x)$$

(more generically this way, since the other probabilities = 0)

But perhaps this can be done repeatedly to get back down to  $p_0$ , which would turn out to be

$$= \sum_{y \in A} p_0(y) \mathbb{P}(S_{n \wedge T_A} = y \mid S_0 = x)$$

$$= \sum_{y \in A} p_0(y) \mathbb{P}(S_{n \wedge T_A} = x \mid S_0 = y) \text{ (can switch around...?!)}$$

3. (page 35) (Clarification, not sure if my understanding is correct)

Since if

$$f(x) = |x|^2 = x_1^2 + x_2^2 + \dots + x_d^2$$

then  $\mathcal{L}f(x) = 1$ ; for  $n < T_A (\Rightarrow n \land T_A = n, (n+1) \land T_A = n+1)$  we have

$$\mathbb{E}[f(S_{(n+1)\wedge T_A}) \mid S_0, S_1, \dots, S_n] - f(S_{n\wedge T_A}) = 1$$

$$\Rightarrow \mathbb{E}[|S_{(n+1)\wedge T_A}|^2 \mid S_0, S_1, \dots, S_n] = |S_{n\wedge T_A}|^2 + 1$$

$$\Rightarrow \mathbb{E}[|S_{(n+1)\wedge T_A}|^2 \mid S_0, S_1, \dots, S_n] - (n+1) \wedge T_A = |S_{n\wedge T_A}|^2 - n \wedge T_A$$

$$\Rightarrow \mathbb{E}(M_{n+1} \mid S_0, S_1, \dots, S_n) = M_n \quad \Box$$

else if  $n \ge T_A \Rightarrow n \land T_A = (n+1) \land T_A = T_A$  it's trivial that the above equality holds.

4. (Page 36) (Clarification, not sure if my understanding is correct)

We want to show  $\mathcal{L}f(y) = -1$ :

$$\mathcal{L}f(y) = \mathbb{E}[f(S_1) \mid S_0 = y] - f(y)$$

$$= \mathbb{E}[G_A(S_1, y) \mid S_0 = y] - G_A(y, y)$$

$$= \mathbb{E}[G_A(S_1, y) \mid S_0 = y] - \mathbb{E}(V_y \mid S_0 = y)$$

$$= \mathbb{E}[G_A(S_1, y) \mid S_0 = y] - (1 + \mathbb{E}[G_A(S_1, y) \mid S_0 = y])$$

$$= -1$$

- 5. (Page 36 38, Green's Function) I understand the construction and derivations but would like to get a more intuitive explanation of what the Green's Function represents.
- 6. (Page 40, 41) I understood the motivation and computation until the end of page 39, yet I find the following section in page 40 and 41 unmotivated. I guess one can say that they're made to lead up to Theorem 1.14 and 1.15, but I don't really understand the bigger picture.

(skipped 1.5.1. Exterior Dirichlet Problem and 1.6. Exercises)

7. (Page 61) I don't fully understand the implications of Proposition 2.4.

## 1.1 Additional Questions

1. (Page 14) Note that this also implies that if the random walker starts at  $x \neq 0$ , then the probability that it will get to the origin is one.

**Answer:** Can just take expected value of visits of y from x, and realize that the probability is one.

2. (Page 18, 25) "It is not hard to see that with probability one  $T < \infty$  i.e. eventually the walker will reach 0 or N and then stop." "We have shown in the previous section that with probability one  $T < \infty$ ". (Apparently, the statement works for both finite and infinite discrete state space with interior and boundary  $A, \partial A \subset \mathbb{Z}^d$ ). Continuous state space also implies  $T_U < \infty$  too, page 72. Lawler: If there's a positive probability, if keep trying then will get there.

**Answer:**  $\mathbb{E}[T] < \infty$ 

3. (Page 32) Parity issues: Shouldn't this have been accounted for in the transition matrix already?

Answer: Apparently nonsense

4. (Page 66 - 69) **Theorem 2.8** 

**Answer:** Similar to the discrete analogue!

- 5. (Page 73) Show that construction of Brownian motion does satisfy: *continuity* and *MVP*Answer: Direct computation, which shouldn't be too hard.
- 6. (Page 71-75) Why do we take the limits as  $r \to 0, R \to \infty$  to check point recurrence/neighborhood recurrence?

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