# TTIC 31020: Introduction to Machine Learning Problem Set 2

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## Problem 2.1 (Problem 1)

(a) Since  $\rho(x, x_i)$  is shift invariant,  $\int_x K(x, x_i) dx$  is the same constant for all  $x_i$ . Let us denote that  $C := \int_x K(x, x_i) dx$ .

In the binary classification context, then, let  $m_+ := |\{i \mid y_i = 1\}|, m_- := |\{i \mid y_i = -1\}| = m - m_+$ . Then

$$1 = \int_{x} \hat{f}(x \mid Y = 1)$$

$$= \int_{x} Z_{1} \sum_{y_{i}=y} K(x, x_{i})$$

$$= Z_{1} \int_{x} \sum_{y_{i}=y} K(x, x_{i})$$

$$= Z_{1} m_{+} C$$

$$\Rightarrow Z_{1} = \frac{1}{m_{+} C}$$

Similarly,  $Z_{-1} = \frac{1}{m_{-}C}$ . Also,  $\hat{p}(y=1) = \frac{m_{+}}{m}$ ,  $\hat{p}(y=-1) = \frac{m_{-}}{m}$ .

It follows that

$$\hat{f}(y = +1 \mid x) = \frac{\hat{f}(x \mid y = +1)\hat{p}(y = +1)}{\hat{f}(x \mid y = +1)\hat{p}(y = +1) + \hat{f}(x \mid y = -1)\hat{p}(y = -1)}$$

$$= \frac{\left(Z_1 \sum_{y_i = 1} K(x, x_i)\right) \frac{m_+}{m}}{\left(Z_1 \sum_{y_i = 1} K(x, x_i)\right) \frac{m_-}{m} + \left(Z_{-1} \sum_{y_i = -1} K(x, x_i)\right) \frac{m_-}{m}}$$

$$= \frac{\sum_{y_i = 1} K(x, x_i)}{\sum_{y_i = 1} K(x, x_i) + \sum_{y_i = -1} K(x, x_i)}$$

Similarly,

$$\hat{f}(y = -1 \mid x) = \frac{\sum_{y_i = -1} K(x, x_i)}{\sum_{y_i = 1} K(x, x_i) + \sum_{y_i = -1} K(x, x_i)}$$

The Parzen Predictor, as the Bayes Optimal Predictor for  $\hat{\mathcal{D}}$ , predicts 1 when the first conditional density is greater than the second, and -1 otherwise. Therefore,

$$h(x) = \operatorname{sign}\left(\sum_{y_i=1}^{m} K(x, x_i) - \sum_{y_i=-1}^{m} K(x, x_i)\right)$$
$$= \operatorname{sign}\left(\sum_{i=1}^{m} y_i K(x, x_i)\right)$$

as required.

(b) In the limit  $\sigma \to \infty$ ,

$$K(x, x') = e^{-\rho(x, x')^2/\sigma^2} \xrightarrow{\sigma \to \infty} 1$$

therefore

$$h(x) = \operatorname{sign}\left(\sum_{i=1}^{m} y_i\right)$$

taking the average of all  $y_i$ .

(c) In the limit  $\sigma \to 0$ , if  $0 \le \rho(x, x_i) \le \rho(x, x_j) - \varepsilon$  then  $K(x, x_i) \gg K(x, x_j)$  as  $\sigma \to 0$ . It follows that as  $\sigma \to 0$ ,

$$h(x) = \operatorname{sign}\left(\sum_{i=1}^{m} y_i K(x, x_i)\right)$$

$$\stackrel{\sigma \to 0}{=} \operatorname{sign}\left(\sum_{x_i \text{ closest to } x} y_i K(x, x_i)\right)$$

$$= \operatorname{sign}\left(\sum_{x_i \text{ closest to } x} y_i\right)$$

(d) The Parzen predictor also predicts the label for x using the labels of the  $x_i's$  that are closets to x, in this case, summing up the labels of  $y_i$ 's. The sign of the sum will therefore take the sign of the sign of the majority of the labels; the Parzen predictor (as  $\sigma \to 0$ ) breaks ties by following the majority of closest points.

### **Problem 2.2** (Problem 2)

(a) We're given

$$\mathbb{P}_{\mathcal{D}}(Y = +1 \mid x) = \begin{cases} 0.8 & \text{if } x \ge 0 \\ 0.2 & \text{if } x < 0 \end{cases}$$

and it follows that the bayes Optimal Predictor is

$$h_{Bayes}(\mathcal{D})(x) = \operatorname{sign}(\eta_{\mathcal{D}}(x) - 0.5) = \begin{cases} 1 & \text{if } x \ge 0 \\ -1 & \text{if } x < 0 \end{cases}$$

The Bayes Error is

$$L_{\mathcal{D}}(h_{Bayes}(\mathcal{D})) = \mathbb{P}_{(x,y)\sim\mathcal{D}}[h_{Bayes}(\mathcal{D})(x) \neq y]$$
$$= \frac{1}{2}0.2 + \frac{1}{2}0.2 = 0.2$$

(b) As  $m \to \infty$ , the nearest neighbor of  $x_{neighbor}$  of most x in S would have the same sign as x. When  $x \ge 0$ ,  $x_{neighbor}$  has the label distribution

$$\mathbb{P}(y_{neighbor} = +1 \mid x \ge 0) = 0.8, \mathbb{P}(y_{neighbor} = -1 \mid x \ge 0) = 0.2$$

and thus corresponding labeling probabilities for the label of x itself. Therefore

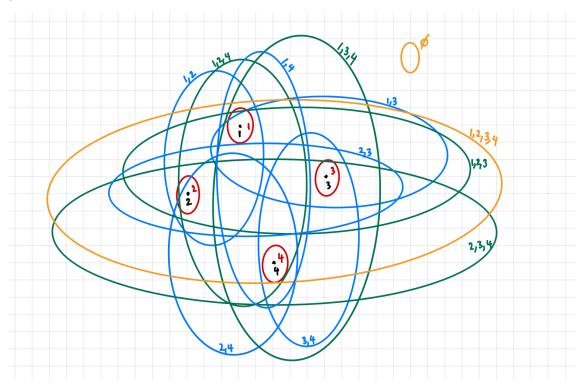
$$L_{x \ge 0, (x,y) \sim \mathcal{D}}(h_m) = \mathbb{P}(y_{neighbor} = +1, y = -1 \mid x \ge 0) + \mathbb{P}(y_{neighbor} = -1, y = +1 \mid x \ge 0)$$
$$= 0.8 \times 0.2 + 0.2 \times 0.8 = 0.32$$

and similarly,  $L_{x<0,(x,y)\sim\mathcal{D}}(h_m)=0.32$ .

It follows that 
$$L_{(x,y)\sim D}(h_m) = 0.32 \times \frac{1}{2} + 0.32 \times \frac{1}{2} = 0.32$$

## Problem 2.3 (Problem 3)

(a)



(b) Using the feature map  $\varphi: \mathbb{R}^2 \to \mathbb{R}^5, (x_1, x_2) \mapsto (x_1^2, x_1, x_2^2, x_2, 1)$  then

$$\mathbb{1}\left[\frac{(x_1-c_1)^2}{a_1^2} + \frac{(x_2-c_2)^2}{a_2^2} \le r\right] = \mathbb{1}\left[\left\langle \varphi(x_1,x_2), \left(\frac{1}{a_1^2}, \frac{-2c_1}{a_1^2}, \frac{1}{a_2^2}, \frac{-2c_2}{a_2^2}, \frac{c_1^2}{a_1^2} + \frac{c_2^2}{a_2^2} - r\right)\right\rangle \le 0\right]$$

Thus

$$\mathcal{H} = \left\{ \mathbb{1} \left[ \langle \varphi(x_1, x_2), \left( \frac{1}{a_1^2}, \frac{-2c_1}{a_1^2}, \frac{1}{a_2^2}, \frac{-2c_2}{a_2^2}, \frac{c_1^2}{a_1^2} + \frac{c_2^2}{a_2^2} - r \right) \rangle \leq 0 \right] : c_1, c_2, a_1, a_2, r \in \mathbb{R}; a_1 \neq a_2 \right\}$$

is a hypothesis class of linear predictors, and therefore a subset of  $H_{\varphi}^{linear}$ , the hypothesis class of all linear predictors in  $\varphi(x_1, x_2)$ :

$$\mathcal{H}_{\omega}^{linear} = \{ \mathbb{1} \left[ \langle \varphi(x_1, x_2), w \rangle \leq 0 \right] : w \in \mathbb{R}^5 \}$$

(c) Since we have represented in (b) that  $\mathcal{H}$  is a subset of  $\mathcal{H}_{\omega}^{linear}$ ,

$$VCDim(\mathcal{H}) \leq VCDim(\mathcal{H}_{\varphi}^{linear}) = 5$$

We have shattered 4 points in (a), which demonstrates that

$$VCDim(\mathcal{H}) \geq 4$$

There is a difference of 5-4=1 between the VCDim bounds. The gap can be explained by that in the linear representation of  $\mathcal{H}$ ,  $w[0] = \frac{1}{a_1^2}$ ,  $w[2] = \frac{1}{a_2^2} > 0$  are forced to be positive; in other words, the predictors with negative values in either w[0] or w[2] are included in  $\mathcal{H}^{linear}_{\wp}$  but are not included in  $\mathcal{H}$ , which potentially decreases the VCDim.

#### Problem 2.4 (Problem 4)

(a) We write out explicitly the definition for  $\mathcal{H}_1$ :

$$\mathcal{H}_1 = \{ y = \text{sign}(\langle w, x \rangle) : w \in \mathbb{R}^d, ||w||_0 = 1 \}$$

 $\|w\|_0=1$  means that w can have 1 non-zero coordinate, say, i-th coordinate. It follows that

$$\mathcal{H}_1 = \{ y = \text{sign}(\alpha x[i]) : i \in [d], \alpha \in \mathbb{R} \setminus \{0\} \}$$

And therefore for a set of points to be classified into the same label, all the points must share at least 1 index i.

We can therefore construct a set of  $\log_2 d$  points, A, in the following manner. Initialize all points to have (-1) as their default coordinate for all coordinates. Within  $[\log_2 d]$  (:=  $\{1,\ldots,\log_2 d\}$ ), there are  $2^{\log_2 d}=d$  subsets of indices. We then iterate through the subsets in some, but fixed, order:

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subsets = all_subsets(A)
for i in range(d):
    subset = subsets[i]
    for point in subset:
        point[i] = 1
```

i.e. assigning 1 to be the value of the *i*-th index of points in the *i*-th subset.

Then, with this A, for any  $(y_1, \ldots, y_{\log_2 d}) \in \{\pm 1\}^{\log_2 d}$ , let

$$B = \{j : y_j = +1\}$$

is a subset of  $[\log_2 d]$ . Let its position, in the fixed order above (0-index), be  $i_B$ .

Then the predictor  $h(x) = \text{sign}(x[i_B])$  would give us  $h(x_i) = y_i \ \forall \ 1 \le i \le |A|$ , since  $x_k[i_B] > 0 \Leftrightarrow x_k \in B \Leftrightarrow y_k = +1$ .

We have thus shattered  $\log_2 d$  points using  $\mathcal{H}_1$ .

(b) We write out  $\mathcal{H}_k$ :

$$\mathcal{H}_k = \{ y = \text{sign}(\langle w, x \rangle) : w \in \mathbb{R}^d, ||w||_0 = k \}$$

If  $k < \log d$  then we have completed this in (a), by using the same method as  $\mathcal{H}_1$  for any index of w and setting the remaining (k-1) non-zero coordinates of w to be infinitesimally small so that their contribution to sign  $(\langle w, x \rangle)$  is negligible, so that same reasoning works.

When  $k \ge \log d$ , then  $\max\{k, \log d\} = k$ . Note that  $k \le d$ , since  $w \in \mathbb{R}^d$ .

Our job now is to shatter k points with  $\mathcal{H}_k$ . Define  $x_j$  to have all (-1) except in the j-th coordinate, and 2d for the j-th coordinate, for  $1 \le j \le k$ .

Then for any  $(y_1, \ldots, y_k) \in \{\pm 1\}^k$ , let

$$B = \{j : y_j = +1\}$$

Then we construct  $\hat{w}$  by assigning 1 in coordinates that are in B, and  $\varepsilon \ll 1$  or 0 everywhere else (fill  $\varepsilon$  in (k-|B|) coordinates to get a total of k non-zero coordinates for  $\hat{w}$  (so that  $\|\hat{w}\|_0 = k$ ), then assign 0 to remaining coordinates; it does not matter which coordinates we choose for  $\varepsilon$  and which for 0).

Then  $\hat{h} = \text{sign}(\langle \hat{w}, x \rangle)$  would give predictions:

$$\langle \hat{w}, x_j \rangle \geq 2d \times 1 + (-1) \times (|B| - 1) + (-1) \times \varepsilon \times (k - |B|) > 0 \text{ (since } |B| \leq d), \text{ for } j \in B$$
  
 $\Rightarrow \hat{h}(x_j) = 1, \text{ for } j \in B$   
 $\langle \hat{w}, x_j \rangle \leq 2d \times \varepsilon + (-1) \times |B| < 0, \text{ for } j \notin B$   
 $\Rightarrow \hat{h}(x_j) = -1, \text{ for } j \notin B$ 

as required.

We have thus shattered  $\max\{k, \log d\}$  points with  $\mathcal{H}_k$ .