MATH 20700: Honors Analysis in Rn I Problem Set 1

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Textbook: Pugh's Real Mathematical Analysis

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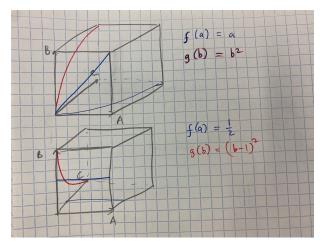
Problem 1.1 (1.21)

Let $f: A \to B$. The **graph** of f is the set S of all pairs $(a, b) \in A \times B$ such that b = f(a).

- (a) Given subset $S \subset A \times B$, how can you tell if it's the graph of some function?
- (b) Let $g: B \to C$ be a second function, consider composed $g \circ f: A \to C$. Assume A = B = C = [0, 1], draw $A \times B \times C$ as the unit cube in 3-space, and try to relate the graph of f, g and $g \circ f$ in the cube.

Solution

- (a) There must be a bijection $g: A \to S, a \mapsto (a, f(a))$. Consequently |A| = |S|.
- (b) The graph $g \circ f$ can be found by taking the intersection of the blue surface (f graph extended throughout C-axis) and red surface (g graph extended throughout A-axis), then projecting this intersection back onto AC plane.



Problem 1.2 (1.22)

A fixed-point of $f: A \to A$ is $a \in A$ such that f(a) = a. The diagonal of $A \times A$ is set of all pairs (a, a) in $A \times A$.

(a) Show that $f: A \to A$ has a fixed point iff graph of f intersects the diagonal.

- (b) Prove that every continuous $f:[0,1]\to[0,1]$ has at least 1 fixed point.
- (c) Is the same true for continuous $f:(0,1)\to(0,1)$?
- (d) Is the same true for discontiuous functions?

Solution

- (a) Let S be the graph of f and D be the diagonal of $A \times A$. Then f has a fixed point $\Leftrightarrow \exists a \in A \text{ such that } f(a) = a \Leftrightarrow (a, a) \in S \Leftrightarrow S \cap D \neq \emptyset$.
- (b) Consider g(x) := f(x) x defined on [0, 1]. f(x) and x are continuous so g is also continuous.

We first consider cases when f(0) = 0 or f(1) = 1. Then we are done because there exists at least 1 fixed point among 0 and 1.

We are left with when 0 < f(0), f(1) < 1. This implies

$$g(0) = f(0) - 0 > 0, g(1) = f(1) - 1 < 0$$

so g(1) < 0 < g(0).

Since g is continuous on [0,1], by IVT, $\exists c \in [0,1]$ such that $g(c) = 0 \Leftrightarrow f(c) = c$. We have found a fixed point c.

- (c) No. Counter example: $f(x) = \frac{x+1}{2}$ on (0,1). Then $f((0,1)) = (1/2,1) \subset (0,1)$, and $f(x') = x' \Rightarrow x' = 1 \notin (0,1)$.
- (d) No. Counter example: $f(x) = \begin{cases} 0 & \text{if } x = 1 \\ 1 & \text{otherwise} \end{cases}$

Problem 1.3 (1.30)

 $f:(a,b)\to\mathbb{R}$ is a **convex function** if for all $x,y\in(a,b)$ and all $s,t\in[0,1]$ with s+t=1 we have

$$f(sx + ty) \le sf(x) + tf(y)$$

- (a) Prove f is convex iff set $S = \{(x,y) : f(x) \le y\}$ of points above its graph is convex in \mathbb{R}^2 .
- (b) Prove that every convex function is continuous.
- (c) Suppose that f is convex and a < x < u < b. Slope σ of the line through (x, f(x)) and (u, f(u)) depends on x and u, say $\sigma = \sigma(x, u)$. Prove that σ increases when x increases, and σ increases when u increases.
- (d) Suppose that f is second-order differentiable. Prove that f is convex iff $f''(x) \ge 0$ for all $x \in (a, b)$.
- (e) Formulate a definition of convexity for $f: M \to \mathbb{R}$ where $M \subset \mathbb{R}^m$ is a convex set [Hint: Start with m = 2].

Solution

(a) \implies f is convex.

Take any $(x_0, y_0), (x_1, y_1) \in S$. We want to show $(sx_0 + tx_1, sy_0 + ty_1) \in S$ for all $s, t \in [0, 1]$ with s + t = 1.

Indeed, since f is convex,

$$f(sx_0 + tx_1) \le sf(x_0) + tf(x_1) \le sy_0 + ty_1$$

so $(sx_0 + tx_1, sy_0 + ty_1) \in S$

 \subseteq S is convex.

Then for all $x, y \in (a, b), (x, f(x)), (y, f(y)) \in S$ trivially. Since S is convex, for all $s, t \in [0, 1]$ with $s + t = 1, (sx + ty, sf(x) + tf(y)) \in S$ too. This implies

$$f(sx + ty) \le sf(x) + tf(y)$$

so f is convex.

(b) Fix $x_0 \in (a, b)$, then choose $p = \frac{a+x_0}{2}$, $q = \frac{b+x_0}{2}$ so that a .

We first prove that f is right-continuous at x_0 . Let $x \in (x_0, q)$. Then using the convex conditions for $p < x_0 < x$ and $x_0 < x < q$, we have:

$$f(x_0) \le \frac{x_0 - p}{x - p} f(x) + \frac{x - x_0}{x - p} f(p)$$

$$\Rightarrow \frac{x - x_0}{x - p} (f(x_0) - f(p)) \le \frac{x_0 - p}{x - p} (f(x) - f(x_0))$$

$$\Rightarrow f(x) - f(x_0) \ge \frac{x - x_0}{x_0 - p} (f(x_0) - f(p))$$

and

$$f(x) \le \frac{x - x_0}{q - x_0} f(q) + \frac{q - x}{q - x_0} f(x_0)$$

$$\Rightarrow f(x) - f(x_0) \le \frac{x - x_0}{q - x_0} (f(q) - f(x_0))$$

Therefore:

$$\frac{x - x_0}{x_0 - p}(f(x_0) - f(p)) \le f(x) - f(x_0) \le \frac{x - x_0}{q - x_0}(f(q) - f(x_0))$$

so
$$|f(x) - f(x_0)| \le (x - x_0) \max \left\{ \left| \frac{f(x_0) - f(p)}{x_0 - p} \right|, \left| \frac{f(q) - f(x_0)}{q - x_0} \right| \right\} \le (x - x_0) M$$

Thus for all $x_0 < x < x_0 + \frac{\varepsilon}{M}$, $|f(x) - f(x_0)| < \varepsilon$ so f is right-continuous at x_0 .

The proof for left continuity is similar. Since f is left- and right-continuous at x_0 , f is continuous at x_0 , for all $x_0 \in (a, b)$. So f is continuous on (a, b).

(c) Take x', u' such that x < x' < u < u' < b, we now prove that $\sigma(x, u) < \sigma(x', u)$ and $\sigma(x, u) < \sigma(x, u')$.

Since f is convex,

$$f(x') \le \frac{u - x'}{u - x} f(x) + \frac{x' - x}{u - x} f(u)$$

$$\Rightarrow \frac{u - x'}{u - x} (f(u) - f(x)) \le f(u) - f(x')$$

$$\Rightarrow \frac{f(u) - f(x)}{u - x} \le \frac{f(u) - f(x')}{u - x'}$$

$$\Rightarrow \sigma(u, x) \le \sigma(u, x')$$

and

$$f(u) \le \frac{u - x}{u' - x} f(u') + \frac{u' - u}{u' - x} f(x)$$

$$\Rightarrow f(u) - f(x) \le \frac{u - x}{u' - x} (f(u') - f(x))$$

$$\Rightarrow \frac{f(u) - f(x)}{u - x} \le \frac{f(u') - f(x)}{u' - x}$$

$$\Rightarrow \sigma(u, x) \le \sigma(u', x) \quad \Box$$

(d) \Rightarrow f is convex.

From (c), we see that for all a ,

$$f'(p) = \lim_{h \to 0} \sigma(p, p+h) \le \lim_{h \to 0} \sigma(q, q+h) = f'(q)$$

Therefore, with p = x and q = x + h,

$$f''(x) = \lim_{h \to 0+} \frac{f'(x+h) - f'(x)}{h} \ge 0 \quad \Box$$

 $f''(x) \ge 0 \ \forall \ x \in (a, b).$

Since $f''(x) \ge 0 \ \forall \ x \in (a,b), \ f'$ is an increasing function in (a,b).

We want to show that for all $x, y \in (a, b)$ and $s, t \in [0, 1]$ such that s + t = 1 then

$$f(sx + ty) \le sf(x) + tf(y)$$

WLOG, suppose x < y and let p = sx + ty. Since f' is differentiable on (a, b), it is integrable. Applying FTC:

$$f(p) - f(x) = \int_{x}^{p} f'(z)dz \le (p - x)f'(p)$$

and

$$f(y) - f(p) = \int_{p}^{y} f'(z)dz \ge (y - p)f'(p)$$

so

$$\frac{f(p) - f(x)}{p - x} \le f'(p) \le \frac{f(y) - f(p)}{y - p}$$

$$f(p)(y - x) \le f(x)(y - p) + f(y)(p - x)$$

$$f(p) \le f(x)\frac{y - p}{y - x} + f(y)\frac{p - x}{y - x}$$

$$f(p) \le sf(x) + tf(y) \quad \Box$$

(e) $f: M \to \mathbb{R}$ is convex iff for all $x, y \in M$ and for all $s, t \in [0, 1]$ such that s + t = 1, we have

$$f(sx + ty) < sf(x) + t(y)$$

Such a notion is well-defined, because since M is convex, $\forall x, y \in M, sx + ty \in M$.

Problem 1.4 (1.31*)

Suppose that $f:[a,b]\to\mathbb{R}$ is monotone nondecreasing. That is, $x_1\leq x_2\Rightarrow f(x_1)\leq f(x_2)$.

- (a) Prove that f is continuous except at a countable set of points. [Hint: Show that at each $x \in (a,b)$, f has **right limit** f(x+) and a **left limit** f(x-), which are limits of f(x+h) as $h \to 0$ through positive and negative values respectively. The **jump** of f at x is f(x+) f(x-). Show that f is continuous at x iff it has zero jump at x. At how many points can f have jump ≥ 1 ? At how many points can the jump be between 1/2 and 1? Between 1/3 and 1/2?
- (b) Is the same assertion true for a monotone function defined on all of \mathbb{R} ?

Solution

(a) Take $x \in (a, b)$. Then for any $h > 0, f(x) \le f(x + h)$ so f(x) is a lower bound for $R = \{f(x + h) \mid h > 0\}$.

R is non-empty, so there exists an infimum inf $R =: f(x+) \ge f(x)$.

We prove that in fact $f(x+h) \xrightarrow{h\to 0+} f(x+)$.

For all $\varepsilon > 0$, since $f(x+) = \inf R$, there exists $\delta = \delta(\varepsilon) > 0$ such that

$$f(x+) \le f(x+\delta) < f(x+) + \varepsilon$$

Then since f(x+h) decreases as h decreases, for all $h < \delta$ we have

$$f(x+) \le f(x+h) \le f(x+\delta) < f(x+) + \varepsilon$$

which implies

$$\lim_{h \to 0+} f(x+h) = f(x+)$$

Similarly, there exists $\sup\{f(x+h)\mid h<0\}=:f(x-)\leq f(x)$ so that $\lim_{h\to 0-}f(x+h)=f(x-)$.

Define j(x) = f(x+) - f(x-). When j(x) = 0, i.e. f(x+) = f(x-), the inequality $f(x-) \le f(x) \le f(x+)$ implies that f(x-) = f(x) = f(x+), so f is continuous at x.

We therefore consider points x where j(x) > 0.

Since f is monotone nondecreasing, the sum of all j(x) of points $x \in (a,b)$ is at most f(b)-f(a). Therefore there are at most f(b)-f(a) points with $j(x) \geq 1$, at most $\frac{f(b)-f(a)}{1/2} = 2(f(b)-f(a))$ points with $1 \geq j(x) \geq 1/2, \ldots, (n+1)(f(b)-f(a))$ points with $1/n \geq j(x) \geq 1/(n+1) \ \forall \ n \in \mathbb{N}$.

The set of points at which j(x) > 0 is the union of the set of points at which $1/n \ge j(x) \ge 1/(n+1)$ over all $n \in \mathbb{N}$, which is a countable union of countable sets, and is therefore countable.

(b) Yes, it is true. Let D_A be the set of discontinuity points in set A. Then since

$$\mathbb{R} = \bigcup_{n \in \mathbb{N}} [-n, n]$$

we have

$$D_{\mathbb{R}} = \bigcup_{n \in \mathbb{N}} D_{[-n,n]}$$

 $D_{[-n,n]}$ is countable, so $D_{\mathbb{R}}$ is also countable.

Problem 1.5 (1.32*)

Suppose that E is a convex region in the plane bounded by a curve C.

- (a) Show that C has a tangent line except at a countable number of points. [For example, a circle has a tangent line at all its points. The triangle has a tangent line except at three points, and so on.]
- (b) Similarly, show that a convex function has a derivative except at a countable set of points. Solution
- (a) We shall use part (b) to prove this.

Case 1: E is unbounded.

Then we assert that we can pick a set of axes such that there exists a function f whose domain is the set of x-coordinates in C, and takes its value as corresponding y-coordinate of points on C, except at x-coordinates at which there are vertical lines. In which case, we define f piecewise, and note that for a x-coordinate to have such a vertical line, it must be either the minimum value or the maximum value of the domain of f, therefore adding only a finite number of points without a tangent line.

Using (b), the epigraph of (piecewise) f is then convex, making it a convex function and thus only have a countable number of points without derivatives, and therefore tangent lines.

Case 2: E is bounded.

Then C is a closed curve.

Let $D = \{x \in \mathbb{R} \mid \exists (x,y) \in C\}$, then there exists $x_{min} = \min D, x_{max} = \max D$ that has corresponding y_{min}, y_{max} . It does not matter which y we choose, if there are multiple points on the curve of x-coordinate x_{min} .

Draw a line connecting (x_{min}, y_{min}) to (x_{max}, y_{max}) , which partitions E into convex sets E_1 below the line and E_2 above the line.

Using the current set of axes, we can then define $f:[x_{min},x_{max}]$ that has E_1 as its epigraph, and reverse the direction of the y-axis to similarly define g that has E_2 as its epigraph.

Points that have vertical line can only be either x_{min} or x_{max} , at which we can define f and g piecewise, only gaining a finite number of points without derivatives.

Having convex epigraphs, f and g are therefore convex. Using (b), they have a countable number of points without derivatives. Combining them, there's still only a countable number of points without tangent lines.

(b) Recall that $f:(a,b)\to\mathbb{R}$ is a convex function if for all $x,y\in(a,b)$ and for all $s,t\in[0,1]$ with s+t=1, we have

$$f(sx + ty) \le sf(x) + tf(y)$$

We have previously derived that for $u, v \in (a, b)$,

$$\sigma(v,u) := \frac{f(u) - f(v)}{u - v}$$

increases as v increases, and also increases as u increases.

Consider a point $x_0 \in (a, b)$. We can select $p = \frac{x_0 + a}{2}, q = \frac{x_0 + b}{2}$, so that a .

Then we know that

$$\sigma(p, x_0) < \sigma(x_0, x_0 + h) \ \forall \ h > 0$$

so $\sigma(p,x_0)$ is a lower bound of $\{\sigma(x_0,x_0+h)\mid h>0\}$. The set is non-empty, so there exists

$$f'(x_0+) := \inf\{\sigma(x_0, x_0+h) \mid h > 0\}$$

We shall easily prove that $\sigma(x_0, x_0 + h) \xrightarrow{h \to 0+} f'(x_0+)$.

Since $f'(x_0+)$ is the infimum, for all $\varepsilon > 0$, there exists $\delta = \delta(\varepsilon) > 0$ such that $f'(x_0+) \le \sigma(x_0, x_0 + \delta) < f'(x_0+) + \varepsilon$. But $\sigma(x_0, x_0 + h)$ decreases as h decreases, so $\forall 0 < h < \delta$, we have

$$f'(x_0+) \le \sigma(x_0, x_0+h) \le \sigma(x_0, x_0+\delta) < f'(x_0+) + \varepsilon$$

which suggests

$$f'(x_0+) = \lim_{h \to 0+} \sigma(x_0, x_0 + h)$$

is indeed the right limit of f' at x_0 .

Similarly, there exists a left limit $f'(x_0-)$.

It is trivial that $f'(x_0-) \leq f'(x_0+)$ based on the property of σ . So we are concerned with the number of points at which $f'(x_0-) < f'(x_0+)$ because when $f'(x_0-) = f'(x_0+)$, the derivative is defined at x_0 .

Let D be the set of such points, then all intervals (f'(d-), f'(d+)) of $d \in D$ are pairwise disjoint. Then for each interval, we are able to select a rational $Q(d) \in (f'(d-), f'(d+))$. Then $Q: D \to \mathbb{Q}$ is injective, and since \mathbb{Q} is countable, D must be also be countable. \square

Problem 1.6 (1.48)

The trefoil cannot be unknotted in 3-space. How can you unknot the trefoil in 4-space?

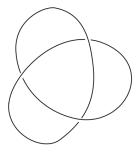
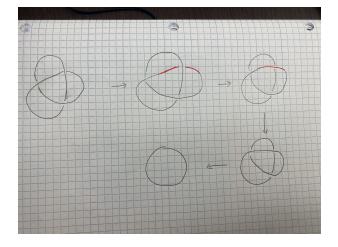


Figure 25 An overhand knot in 3-space

Solution



Problem 1.7 (1.49*)

Prove that there exists no continuous three dimensional motion de-linking the two circles shown below, which keeps both circles flat at all times.

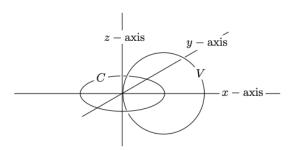
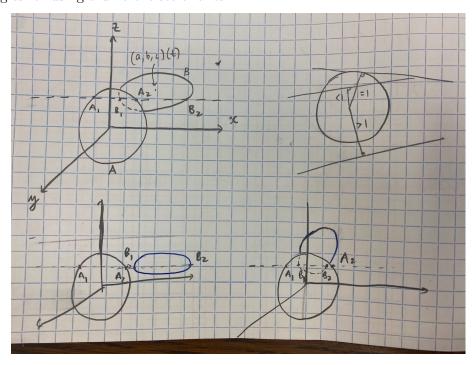


Figure 22 C and V are linked circles.

Solution

My apologies for using a different set of axes.



WLOG, we assume that A is a fixed unit circle on the xz-plane, centered at (0, 0, 0), and B is a mobile unit circle whose movement always keeps it on a plane parallel to the xy-plane. WLOG, assume that when t = 0, B is centered at (1, 0, 0).

Suppose there exists a continuous motion that delinks the 2 loops. Then if we parameterize the position of the center of B as a function of time, (a(t),b(t),c(t)) as $t \in [0,1]$, then $a,b,c: \mathbb{R} \to \mathbb{R}$ must also be continuous.

Then the equation for points on A is

$$x^2 + z^2 = 1, y = 0$$

and for points on B at time t is

$$(x - a(t))^2 + (z - c(t))^2 = 1, y = b(t)$$

If the disc bounded by A intersects the disc bounded by B, these points of intersection must lie on the line at which their 2 planes intersect, i.e. y = 0 and z = c(t) respectively. Call this line l.

Then at t = 0, l intersects with circle A at 2 points, A_1, A_2 and circle B at 2 points, B_1, B_2 with the x-coordinate of lower-indexed points being smaller. We shall track the x-coordinate of these 4 points via time-dependent functions $A_1(t), A_2(t), B_1(t), B_2(t)$ until either the end of the motion, or until any of them ceases to exist (there's no longer any intersection). Since the motion is continuous, these functions shall also be continuous.

At
$$t = 0, A_1(0) < B_1(0) < A_2(0) < B_2(0)$$
.

As long as the 2 loops are linked, the 4 points still exist and the 4 functions still conform to this ordering, that is B_1 is between A_1 and A_2 , and A_2 is between B_1 and B_2 .

When the 2 loops are de-linked, either one of the following 2 cases must happen.

Case 1: There is a swapping of the aforementioned "ABAB" order. For example, managing to pull out B in the positive x- direction would yield "AABB" order, while squeezing B's "right" half into A would yield "ABBA" order. Either way, a swapping of A_i and B_j must have happened.

Define $f(t) := A_i(t) - B_j(t)$, then f is continuous. But since A_i and B_j have swapped, either f(0) > 0 > f(1) or f(1) > 0 > f(0). Either case, using IVT, there exists time $t = \tau$ where $f(\tau) = 0$, A_i and B_j have "merged" into 1 point. $\Rightarrow \Leftarrow$

Case 2: If the order is never switched, then by the end of the motion, line l as defined no longer intersects either circle A or circle B at any point. For example, l would no longer intersect A if one manages to "lift" B up via the positive z-direction, after which line l: y = 0, z = c(1) > 1 no longer intersects A. l would no longer intersect B if one manages to "push" B away via the negative y-direction, after which line l: y = 0 >> b(1), z = c(1) no longer intersects B.

Assume that it is the first case, where l stops intersecting A when t = 1. Let r(t) = |c(t)|, essentially the distance from the center of A (the origin) to line l. It is trivial that r is continuous. Here we calculate $A_1(t)$ and $A_2(t)$ in detail:

$$A_1(t) = -\sqrt{1 - r(t)^2}, A_2(t) = \sqrt{1 - r(t)^2}$$

At t = 0, r(t) = 0. When t = 1, r(t) > 1, since l no longer intersects A. By IVT, there exists time $t = \tau$ such that $r(\tau) = 1$. Then, $A_1(\tau) = A_2(\tau) = 0$. But $A_1(\tau) \leq B_1(\tau) \leq A_2(\tau)$, so it must be the case that

$$A_1(\tau) = B_1(\tau) = A_2(\tau)$$

effectively meaning that A_1, B_1 and A_2 have "merged" into 1 point.

This is the same for when l stops intersecting $B. \Rightarrow \Leftarrow$

Therefore, by contradiction, there exists no continuous motion that delinks the 2 circles. \Box

Problem 1.8 (2.20)

What function (given by a formula) is a homeomorphism from (-1,1) to \mathbb{R} ? Is every open interval homeomorphic to (0,1)? Why or why not?

Solution

$$f:(0,1)\to \mathbb{R}, f(x)=\frac{x}{\sqrt{1-x^2}}$$

is clearly continuous and bijective. Meanwhile,

$$f^{-1}(y) = \frac{y}{\sqrt{y^2 + 1}}$$

is continuous too. So it is a homeomorphism from (-1,1) to \mathbb{R} .

Yes, every open interval (a,b) is homeomorphic to (0,1). For example, we can define $g:(0,1)\to(a,b)$ to map

$$g(x) = a + (b - a)x$$

that is clearly continuous and bijective, with inverse

$$g^{-1}(y) = \frac{y-a}{b-a}$$

is also continuous. So g is a homeomorphism.

Problem 1.9 (2.21)

Is the plane minus four points on the x-axis homeomorphic to the plane minus four points in an arbitrary configuration?

Solution

Let P_1 be the plane minus 4 points in an arbitrary configuration. Via some linear transformation (rotation), we can select a xy- coordinate system that has these 4 points at pairwise different x-coordinates. Let their coordinates be $\{(x_i,y_i)\}_{1\leq i\leq 4}$.

Let

$$f(x) = y_1 \frac{(x - x_2)(x - x_3)(x - x_4)}{(x_1 - x_2)(x_1 - x_3)(x_1 - x_4)} + y_2 \frac{(x - x_1)(x - x_3)(x - x_4)}{(x_2 - x_1)(x_2 - x_3)(x_2 - x_4)} + y_3 \frac{(x - x_1)(x - x_2)(x - x_4)}{(x_3 - x_1)(x_3 - x_2)(x_3 - x_4)} + y_4 \frac{(x - x_1)(x - x_2)(x - x_3)}{(x_4 - x_1)(x_4 - x_2)(x_4 - x_3)}$$

so that $f(x_i) = y_i$ for $1 \le i \le 4$. Then we can transform $(x, y) \in P_1$ as follows:

$$T(x,y) = (x, y - f(x))$$

It is easy to see that T is a bijection, there exists an inverse map that satisfies $T \circ T^{-1} = id$, $T^{-1} \circ T = id$, namely

$$T^{-1}(x,y) = (x, y + f(x))$$

We freely use the fact (Prof. Wilkinson) that T and T^{-1} are continuous. T is therefore a homeomorphism. Then indeed we have $T(x_i, y_i) = (x_i, 0)$ for $1 \le i \le 4$, sending our 4 original arbitrary points to 4 points on the x-axis.

Problem 1.10 (2.28)

A map $f: M \to N$ is **open** if for each open set $U \subset M$, the image set f(U) is open in N.

- (a) If f is open, is it continuous?
- (b) If f is a homeomorphism, is it open?
- (c) If f is an open, continuous bijection, is it a homeomorphism?
- (d) If $f: \mathbb{R} \to \mathbb{R}$ is a continuous surjection, must it be open?
- (e) If $f: \mathbb{R} \to \mathbb{R}$ is a continuous, open surjection, must it be a homeomorphism?
- (f) What happens in (e) if \mathbb{R} is replaced by the unit circle S^1 ?

Solution

- (a) No. Counter example: $f: (\mathbb{R}, d_{\mathbb{R}}) \to (\mathbb{R}, d_{discrete})$, sending $x \in [0, 1]$ to 0 and $x \in \mathbb{R} \setminus [0, 1]$ to 1. The topology induced by $d_{discrete}$ is the discrete topology, so for all open $U \subset M$, f(U) is open.
- (b) Yes. Since f is a homeomorphism, it bijects open sets in M to open sets in N. Thus it sends open U to open f(U), so f is open.
- (c) Yes, it is a homeomorphism. f is already a continuous bijection, so we only need to show f^{-1} is also continuous.

i.e., $(f^{-1})^{Pre}(U)$ of open $U \subset M$ is open. Since f is bijective, $(f^{-1})^{Pre}(U) = f(U)$, which is open for U open because f is open.

(d) No. Counter example:

$$f(x) = \begin{cases} x & \text{for } x \le 1\\ 2 - x & \text{for } 1 \le x \le 2\\ x - 2 & \text{for } x \ge 2 \end{cases}$$

then f is trivially continuous, while the image set of (0, 2) is (0, 1], which is not open, so f is not continuous.

(e) Yes. We want to show that f is injective.

Assume there exists $x_1 \neq x_2$ such that $f(x_1) = f(x_2)$.

Consider the image set of $[x_1, x_2]$, which by EVT and IVT, is a closed set [m, M] where $m = \min_{[x_1, x_2]} f$, $M = \max_{[x_1, x_2]} f$. We consider 3 possible cases:

Case 1: m = M, which implies that $f \equiv m$ on $[x_1, x_2]$. However this implies that the image set of (x_1, x_2) , an open set, is $\{m\}$, a closed set. $\Rightarrow \Leftarrow$

Case 2: $m \neq M$, but f achieves either maximum or minimum at x_1 and x_2 . WLOG, assume that $f(x_1) = f(x_2) = M$. This means that $\exists x_3 \in (x_1, x_2)$ such that $f(x_3) = m$. Then the image set of $(\frac{x_3+x_1}{2}, \frac{x_3+x_2}{2})$ will be a half-closed interval [m, K) for some $K \in \mathbb{R}$. $\Rightarrow \Leftarrow$

Case 3: $m \neq M$ and $f(x_1) = f(x_2) \notin \{m, M\}$. This means that there exists some $x_3, x_4 \in (x_1, x_2)$ such that $f(x_3) = m, f(x_4) = M$. WLOG assume $x_1 < x_3 < x_4 < x_2$, then by IVT the image set of the open interval $\left(\frac{x_1+x_3}{2}, \frac{x_4+x_2}{2}\right)$ is the closed interval [m, M]. $\Rightarrow \Leftarrow$

Therefore, by contradiction, f is injective. f is therefore a continuous bijection, making it a homeomorphism.

(f) No. Parameterize points on S^1 as $S^1=\{(\cos\theta,\sin\theta)\mid\theta\in[0,2\pi)\}$. Then define $f:S^1\to S^1$ as

$$f((\cos \theta, \sin \theta)) = (\cos 2\theta, \sin 2\theta)$$

then f is clearly continuous (we travel around S^1 twice as fast). f is also open, and surjective $(f((\cos \theta/2, \sin \theta/2)) = (\cos \theta, \sin \theta)$ for all $\theta \in [0, 2\pi)$), but f is not injective $(f((\cos 0, \sin 0)) = f((\cos \pi, \sin \pi)) = (1, 0))$ so it can't be a homeomorphism.