view_frames Result
Recorded at time: 1352896612.660
/world
Broadcaster: /map_tfA_pr1012_4987_4442060914350498757
Average rate: 13.321 Hz
Most recent transform: 0.016 sec old
Buffer length: 0.300 sec
/eng2
Broadcaster: /map_tf_pr1012_4987_5359199772344693013
Average rate: 10.214 Hz
Most recent transform: 0.005 sec old
Buffer length: 4.406 sec
Broadcaster: /map_tf_pr1012_4987_6874794973455510992
Average rate: 10.220 Hz
Most recent transform: 0.032 sec old
Buffer length: 4.305 sec
Broadcaster: /map_tf_pr1012_4987_6759559750361062040
Average rate: 10.215 Hz
Most recent transform: -0.046 sec old
Buffer length: 4.405 sec
Broadcaster: /map_tf_pr1012_4987_3963227109738209393
Average rate: 10.221 Hz
Most recent transform: 0.035 sec old
Buffer length: 4.305 sec
/eng2/7f
/eng2/3f
/eng2/8f
/eng2/2f
Broadcaster: /tf_mux
Average rate: 80.779 Hz
Most recent transform: 0.056 sec old
Buffer length: 4.494 sec
Broadcaster: /map_tfB_pr1012_4987_2769321870066104991
Average rate: 10.215 Hz
Most recent transform: 0.032 sec old
Buffer length: 4.405 sec
/map
/eng2/7f/73B2
Broadcaster: /amcl
Average rate: 18.573 Hz
Most recent transform: 0.036 sec old
Buffer length: 4.361 sec
/odom_combined
Broadcaster: /robot_pose_ekf
Average rate: 29.932 Hz
Most recent transform: 0.134 sec old
Buffer length: 4.310 sec
/base_footprint
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
/base_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/base_bellow_link
/base_laser_link
/torso_lift_link
/bl_caster_rotation_link
/br_caster_rotation_link
/fl_caster_rotation_link
/fr_caster_rotation_link
/torso_lift_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
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Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
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Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
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Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/head_pan_link
/imu_link
/l_torso_lift_side_plate_link
/laser_tilt_mount_link
/r_torso_lift_side_plate_link
/l_shoulder_pan_link
/r_shoulder_pan_link
/bl_caster_l_wheel_link
/bl_caster_r_wheel_link
/br_caster_l_wheel_link
/br_caster_r_wheel_link
/fl_caster_l_wheel_link
/fl_caster_r_wheel_link
/fr_caster_l_wheel_link
/fr_caster_r_wheel_link
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/head_tilt_link
/laser_tilt_link
/l_shoulder_lift_link
/r_shoulder_lift_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/head_plate_frame
/l_upper_arm_roll_link
/r_upper_arm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
/kinect_link
/sensor_mount_link
/openni_camera
/projector_wg6802418_frame
/l_upper_arm_link
/r_upper_arm_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/double_stereo_link
/high_def_frame
/openni_depth_frame
/openni_rgb_frame
/projector_wg6802418_child_frame
/l_elbow_flex_link
/r_elbow_flex_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/narrow_stereo_link
/wide_stereo_link
/high_def_optical_frame
/openni_depth_optical_frame
/openni_rgb_optical_frame
/l_forearm_roll_link
/r_forearm_roll_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /roseus_tabletop_object_detector_1352894523791496419
Average rate: 10000.000 Hz
Most recent transform: 3.834 sec old
Buffer length: 0.000 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
/narrow_stereo_gazebo_l_stereo_camera_frame
/narrow_stereo_optical_frame
/wide_stereo_gazebo_l_stereo_camera_frame
/wide_stereo_optical_frame
/table
/l_forearm_cam_frame
/l_forearm_link
/r_forearm_cam_frame
/r_forearm_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/narrow_stereo_gazebo_l_stereo_camera_optical_frame
/narrow_stereo_gazebo_r_stereo_camera_frame
/wide_stereo_gazebo_l_stereo_camera_optical_frame
/wide_stereo_gazebo_r_stereo_camera_frame
/l_forearm_cam_optical_frame
/l_wrist_flex_link
/r_forearm_cam_optical_frame
/r_wrist_flex_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/narrow_stereo_gazebo_r_stereo_camera_optical_frame
/wide_stereo_gazebo_r_stereo_camera_optical_frame
/l_wrist_roll_link
/r_wrist_roll_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
/l_gripper_palm_link
/r_gripper_palm_link
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 21.022 Hz
Most recent transform: 1.309 sec old
Buffer length: 2.521 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/l_gripper_led_frame
/l_gripper_motor_accelerometer_link
/l_gripper_tool_frame
/l_gripper_r_finger_link
/l_gripper_l_finger_link
/l_gripper_motor_slider_link
/r_gripper_led_frame
/r_gripper_motor_accelerometer_link
/r_gripper_tool_frame
/r_gripper_r_finger_link
/r_gripper_l_finger_link
/r_gripper_motor_slider_link
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/l_gripper_r_finger_tip_link
/l_gripper_l_finger_tip_link
/l_gripper_motor_screw_link
/r_gripper_r_finger_tip_link
/r_gripper_l_finger_tip_link
/r_gripper_motor_screw_link
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
Broadcaster: /robot_state_publisher
Average rate: 12.351 Hz
Most recent transform: 1.821 sec old
Buffer length: 2.510 sec
/l_gripper_l_finger_tip_frame
/r_gripper_l_finger_tip_frame