Velodyne LiDAR®

Velodyne LiDAR Sensors – The Future of Port Automation

Velodyne LiDAR's Puck 3D LiDAR sensors are utilized in automotive vehicles to generate 3D maps/images in real-time traffic environments. These same sensors provide wide area coverage and may be utilized to automate ports to load and unload containers from ships to trucks. Three-dimensional LiDAR sensors provide better, faster measurement data which is easier to model in a more productive way.



Current Solution

Figure 1. Manual operations become more difficult as equipment becomes taller and wider.

Future Solution



Figure 2. 16-channel 3D LiDAR sensor scans a wide spatial area with single sensing technology with the off-the-shelf controller system.

Required Sensor Types	
Data Measurement	

Data Output

Sensor Coverage Area

System Integration 2D LiDAR Scanners

ON/OFF (2D LiDAR)

Several Communication Protocols (Ethernet, RS232, etc.)

Multiple Sensor Technologies Required; Specific Sensors Perform Individual Tasks Over a Limited Area.

Difficult to Implement and Modify for Future Systems

3D LiDAR Sensor

Distance, Calibrated Reflectivity Values, **Rotation Angles and Timestamps**

UDP Packets (with timestamps) via Ethernet Protocol

One 3D LiDAR Sensor Performs Multiple Functions and Covers Greater Spatial Area

Easy Modification and Implementation Process for Future Product Upgrades.



Velodyne LiDAR* Sensor Advantage:

- Lowers Total Cost of Ownership
 - Reduced Sensor Count
 - Shortens/Simplifies Design and Implementation Time
- **Detailed 3D Images for** Vehicle/Object/Container Profiling
 - Full Surround View in both Horizontal and **Vertical Fields**
 - · Fast Identification of Vehicles, Objects and Containers
 - · Object Detection and Identification
 - · Identify Port Workers Wearing Retro-reflective Safety Vests
- > Fast On-site Commissioning Time
- Flexibility in Use of Pure Measurement Data

Real-Time 3D LiDAR Sensors

The Puck $^{\rm IM}$ and HDL-32E provide high definition 3-dimensional information about the surrounding environment.

Parameters	VLP-16	HDL-32E	Benefit
Range	100 m (>300 feet)	100 m (>300 feet)	Detects objects at farther distances.
# of Channels	16	32	Visualize actual scanned objects.
Horizontal Field of View	360°	360°	Detect and maintain visibility continuously.
Horizontal Resolution (Azimuth)	0.1° to 0.4°	0.1° to 0.4°	No laser beam gaps for accurate measurements.
Vertical Field of View	30° (-15° to +15°)	40° (-30.67° to +10.67°)	Follow objects as they move.
Vertical Resolution	2.0°	1.33°	Determine potential hazards before they enter critical scan line.
Rotation Rate	5 Hz to 20 Hz	5 Hz to 20 Hz	Reliable Time-of-Flight Measurement Techniques.
Accuracy	±3.0 cm (±1.2")	±2.0 cm (±0.8")	Measure stationary and moving objects accurately.
Data Output Information	UDP Packets • Distance Measurements • Calibrated Reflectivities • Rotation Angles • Time Stamps (µs resolution)	UDP Packets • Distance Measurements • Calibrated Reflectivities • Rotation Angles • Time Stamps (µs resolution)	Provides a wealth of information to distinguish different types of vehicles and objects.
Data Output	Single Return Mode: 300k points/s Dual Return Mode: 700k points/s	Single Return Mode: 695k points/s Dual Return Mode: 1,390k points/s	More than 4x data output from competing solutions.
Operating Voltage	9 V to 18 V (Directly to Sensor) 9 V to 32 V (Thru Interface Box)	9 V to 18 V (Directly to Sensor) 9 V to 32 V (Thru Interface Box)	Standard operating voltage range.
Power Consumption	8 W	12 W	Low energy consumption, decreases operating expenses.
Enclosure Rating	IP67	IP67	Operates in wet and cold environments.
Operating Temperature	-10°C to +60°C	-10°C to +60°C	Works in hot and cold weather conditions.
Size	Ø103 mm x 72 mm (Ø4.1" x 2.8")	Ø85 mm x 144 mm (Ø3.6" x 5.68")	Smaller size allows for smaller mast size.
Weight	830 g (1.8 lbs)	1 kg (2.2 lbs)	Lower weight decreases need for larger mast.

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