

Leveraging Edge Computing for Earth Observation

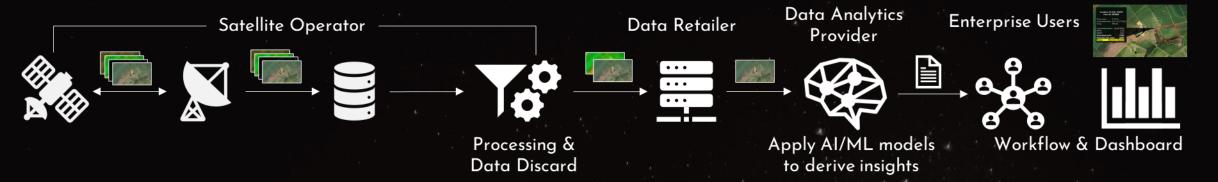
let's talk spatial: Spatial Talks and Network #8

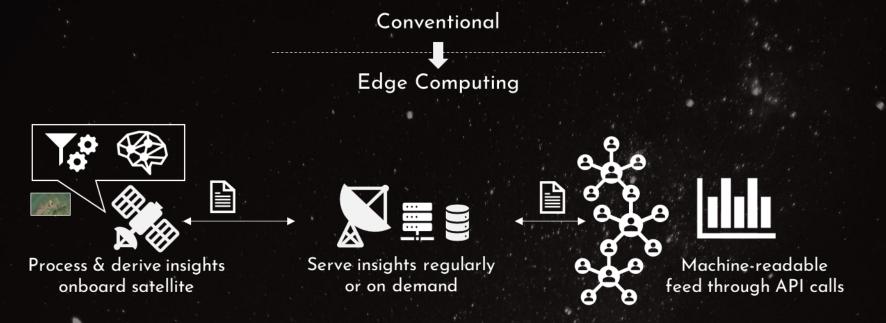
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Changing Paradigm







Data Size at different levels



13km @2m/px

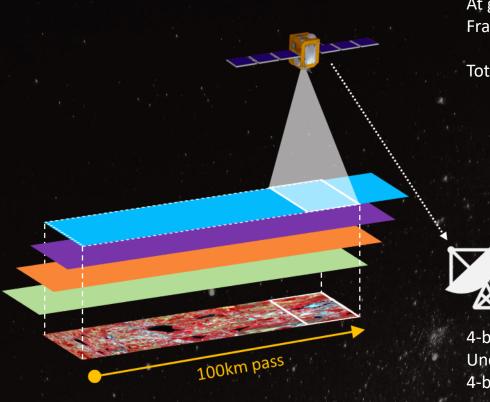
Each band spans 1,125 rows ~ 2.25km

Raw frame

Size = 6500 x 4500 x 12bpp = 351 Mb ~ 43.88 MB

Lossless compression

Size = 43.88 MB / 2.5 = 17.55 MB



At ground speed of 7.85km/s, Frames to capture for pass = at least 45, @5fps

Total compressed data size = $45 \times 17.55 \text{ MB}$ = 789.75 MB

4-band georeferenced scene: Uncompressed raw size = 1.974 GB 4-band registered product = 2.6 GB

Typical tile size: 5km x 5km Tile file size = **50 MB**



Industrial User: Ground-based Processing

Objective: Monitor encroachment along a pipeline installation

Indicators:

- Damage to pipeline
- Vegetation overgrowth
- Encroachment (tents/building)
- Disturbed soil (impending sabotage)

Methodology:

- Acquire satellite images along pipeline once a month
- Apply sequence of change detection & object detection algorithms
- Localize and characterize incidents
- Take corrective action

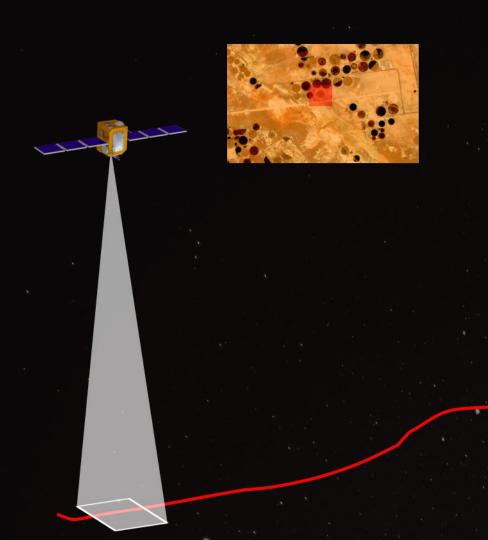
Imagery price @2m resolution = \$P/km2 Over 100km stretch = 100 x P

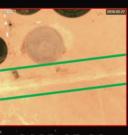
Min. number of attempts to optically image the stretch = 2 (cost passed on to user because of ground-based processing)

Annual image purchase cost to user = $100 \times P \times 12$

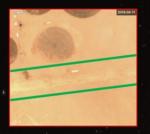


Solution using Edge Processing



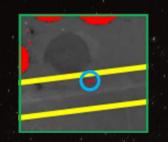


2023-05-23



2023-05-27





```
{
  "type": "Feature",
  "geometry": {
    "type": "Point",
    "coordinates": [125.6391,
10.1037]
  },
  "properties": {
    "class": "Encroachment"
  }
}
```

113 chars = **226 Bytes**

ONLY IF A CHANGE IS DETECTED!



Edge Processing vs. Ground Processing

Info size $\sim \frac{1}{1,000,000}$ of 50MB tile

Considering some unit economics, info price can be at least $\frac{1}{100}$ of P

User spends less for the same monthly cadence

Or can increase the cadence 100x without exceeding the budget

Imagery price @2m resolution = \$P/km2

Over 100km stretch = 100 x P

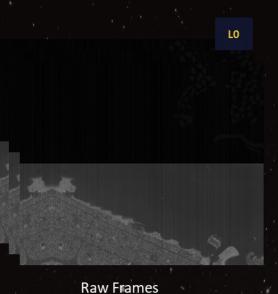
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Edge Processing at SkyServe







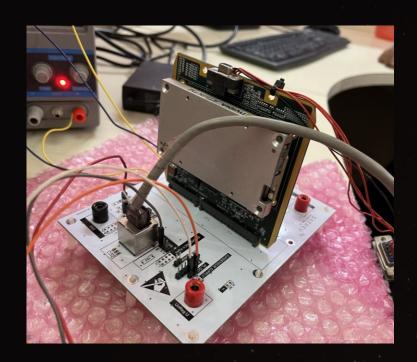


Radiometrically Calibrated Frames

Stitched 4-band Scene



Edge Processing at SkyServe





Haze compensated scene



Scene with Cloud/shadow mask



Geo-referenced scene (in viewer)



Leveraging this capability

- Self-serve submission of classical GIS and AI/ML models
- Automated validation of
 - Input images, metadata
 - Model framework
 - Model output
 - Edge-readiness
- In-app validation on new sensor data
- Ability to continuously improve submissions based on new sensor data, test results and evolving business needs
- Real-time tracking of progress with logging, error drill-down, chat support & resolution workflow

