10701 Recitation 3-Backpropagation CNN

SVM, Kernel, Backpropagation, CNN

Backpropagation and CNN

- Simple neural network with demo of backpropagation
 - XOR (need to search for it)
- Why is backpropagation helpful in neural networks?
- LeNet implementation
 - What are k, s, p, ... in the convolutional layer and pooling layer
 - Demo of lenet in action

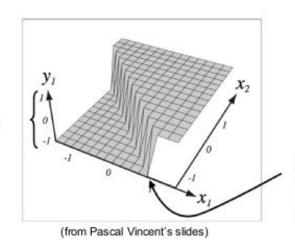
How many layers do you need to construct a neural network that achieves XOR?

Artificial Neuron

Output activation of the neuron:

$$h(\mathbf{x}) = g(a(\mathbf{x})) = g(b + \sum_{i} w_i x_i)$$

Range is determined by $g(\cdot)$



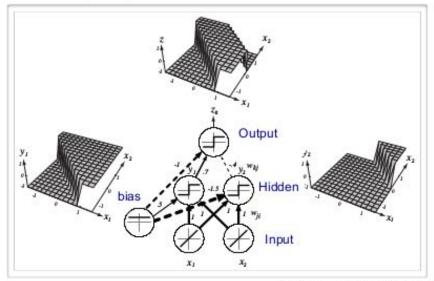
Bias only changes the position of the riff

Backpropagation simple example: XOR

How many layers do you need to construct a neural network that achieves XOR?

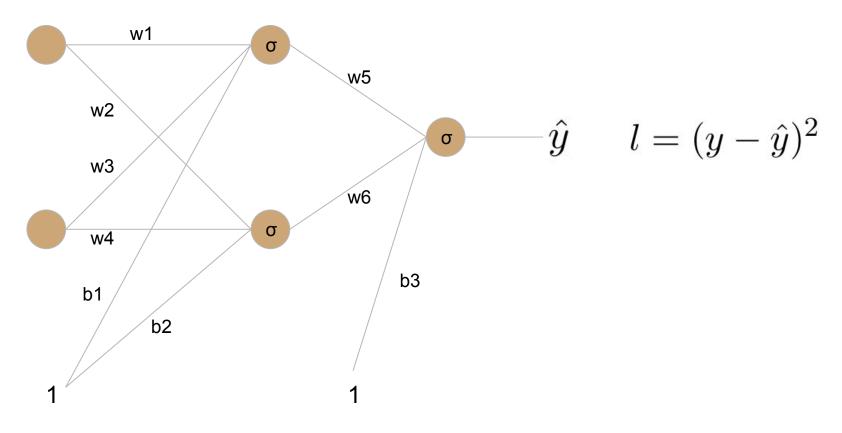
Capacity of Neural Nets

Consider a single layer neural network



(from Pascal Vincent's slides)

Backpropagation simple example: XOR



Backpropagation simple example: XOR

Derivation

Let the loss be $l = (y - \hat{y})^2$

- the special case: $\frac{\partial l}{\partial \hat{y}} = 2(y \hat{y}) \cdot (-1)$
- layer 2 need to compute these terms

$$\frac{\partial l}{\partial w_5} = \frac{\partial l}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial w_5}$$

$$\frac{\partial l}{\partial w_6} = \frac{\partial l}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial w_6}$$

$$\frac{\partial l}{\partial z_1} = \frac{\partial l}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z_1}$$

$$\frac{\partial l}{\partial z_2} = \frac{\partial l}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z_2}$$

Derivation

The first terms in the above equation are carried over from the previous step, and we need to compute the second term.

$$\frac{\partial \hat{y}}{\partial w_5} = \delta'(w_5 z_1 + w_6 z_2 + b_3) \cdot z_1
= \delta(w_5 z_1 + w_6 z_2 + b_3) \cdot (1 - \delta(w_5 z_1 + w_6 z_2 + b_3)) \cdot z_1
= \hat{y} \cdot (1 - \hat{y}) \cdot z_1$$

Similarly

$$\frac{\partial \hat{y}}{\partial w_6} = \hat{y} \cdot (1 - \hat{y}) \cdot z_2$$

$$\frac{\partial \hat{y}}{\partial b} = \hat{y} \cdot (1 - \hat{y})$$

$$\frac{\partial \hat{y}}{\partial z_1} = \hat{y} \cdot (1 - \hat{y}) \cdot w_5$$

$$\frac{\partial \hat{y}}{\partial z_2} = \hat{y} \cdot (1 - \hat{y}) \cdot w_6$$

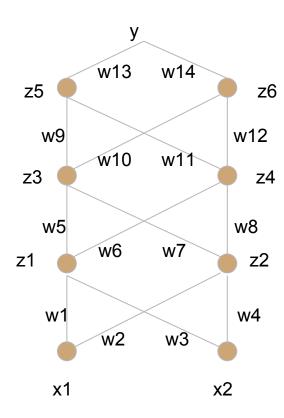
Derivation

- layer 1 we need to compute these terms

$\frac{\partial l}{\partial z_1} = \frac{\partial l}{\partial z_1} = \frac{\partial z_1}{\partial z_2}$	$\frac{\partial z_1}{\partial w_1} = z_1(1-z_1)x_1$
$\frac{\partial w_1}{\partial w_1} - \frac{\partial z_1}{\partial z_1} \cdot \frac{\partial w_1}{\partial w_1}$	∂w_1
$\frac{\partial l}{\partial z} = \frac{\partial l}{\partial z} \cdot \frac{\partial z_2}{\partial z}$	$\frac{\partial z_2}{\partial w_2} = z_2 (1 - z_2) x_1$
$\frac{\partial w_2}{\partial w_2} - \frac{\partial z_2}{\partial z_2} \frac{\partial w_2}{\partial w_2}$	∂w_2
$\frac{\partial l}{\partial z} = \frac{\partial l}{\partial z} \cdot \frac{\partial z_1}{\partial z_1}$	$\frac{\partial z_1}{\partial w_3} = z_1(1-z_1)x_2$
$\frac{\partial w_3}{\partial w_3} - \frac{\partial v_3}{\partial w_3}$	∂w_3
$\frac{\partial l}{\partial z_2}$	$\frac{\partial z_2}{\partial w_4} = z_2(1 - z_2)x_2$
$\partial w_4 \ \partial z_2 \ \partial w_4$	∂w_4
$\frac{\partial l}{\partial z_1} = \frac{\partial l}{\partial z_1} \cdot \frac{\partial z_1}{\partial z_2}$	$\frac{\partial z_1}{\partial b_1} = z_1(1 - z_1)$
$\overline{\partial b_1} = \overline{\partial z_1} \cdot \overline{\partial b_1}$	∂b_1
$\partial l = \partial l \cdot \partial z_2$	$\frac{\partial z_2}{\partial b_2} = z_2(1 - z_2)$
$\frac{\partial b_2}{\partial b_2} - \frac{\partial c_2}{\partial c_2} \cdot \frac{\partial c_2}{\partial b_2}$	$\partial b_2 \stackrel{-\sim_2(1}{\sim} \stackrel{\sim_2)}{\sim}$

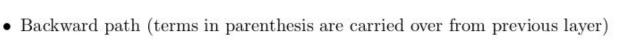
$$l = f_I(w_I, f_{I-1}(w_{I-1}, \dots))$$

Interpretation 1: since the order of differentiation is from the outer function to the inner function. This corresponds to differentiate upper levels first, thus backpropagation



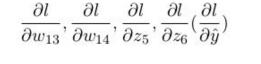
Interpretation 2: We can see from the toy example that the number of terms computed from the backward propagation is linear in the number of nodes (or weights), but roughly quadratic for the forward path

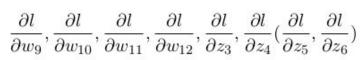
Why backpropagation?

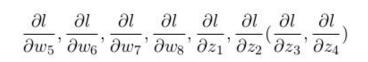


- last layer
- layer 4
- layer 3
- layer 2
- layer 1

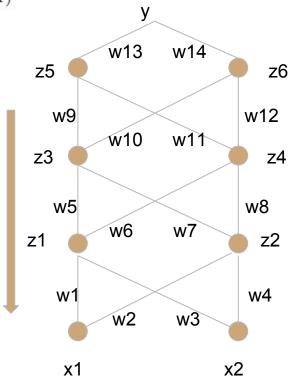








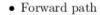
$$\frac{\partial l}{\partial w_1}, \frac{\partial l}{\partial w_2}, \frac{\partial l}{\partial w_3}, \frac{\partial l}{\partial w_4}, (\frac{\partial l}{\partial z_1} \frac{\partial l}{\partial z_2})$$



Loss

Why backpropagation?

Each layer compute some constant number of terms (including carried over terms)



- layer 1 (4)
$$\frac{\partial z_1}{\partial z_1}, \frac{\partial z_2}{\partial z_2}$$

$$\frac{\partial z_1}{\partial w_1}, \frac{\partial z_2}{\partial w_2}, \frac{\partial z_1}{\partial w_3}, \frac{\partial z_2}{\partial w_4}$$

$$\frac{\partial z_3}{\partial w_5}, \frac{\partial z_3}{\partial w_7}, \frac{\partial z_4}{\partial w_6}, \frac{\partial z_4}{\partial w_8}$$

$$\frac{\partial z_3}{\partial w_1}, \frac{\partial z_3}{\partial w_2}, \frac{\partial z_3}{\partial w_3}, \frac{\partial z_3}{\partial w_4}, \frac{\partial z_4}{\partial w_1}, \frac{\partial z_4}{\partial w_2}, \frac{\partial z_4}{\partial w_3}, \frac{\partial z_4}{\partial w_4}$$

$$\frac{\partial z_5}{\partial w_9}, \frac{\partial z_5}{\partial w_{11}}, \frac{\partial z_6}{\partial w_{10}} \frac{\partial z_6}{\partial w_{12}}$$

$$\frac{\partial z_5}{\partial w_1}, \frac{\partial z_5}{\partial w_2}, \frac{\partial z_5}{\partial w_3}, \frac{\partial z_5}{\partial w_4}, \frac{\partial z_5}{\partial w_4}, \frac{\partial z_5}{\partial w_6}, \frac{\partial z_5}{\partial w_6}, \frac{\partial z_5}{\partial w_7}, \frac{\partial z_5}{\partial w_8}, \frac{\partial z_5}{\partial w_9}, \frac{\partial z_5}{\partial w_{10}}, \frac{\partial z_5}{\partial w_{11}} \frac{\partial z_5}{\partial w_{12}}$$

$$\frac{\partial z_6}{\partial w_1}, \frac{\partial z_6}{\partial w_2}, \frac{\partial z_6}{\partial w_3}, \frac{\partial z_6}{\partial w_4}, \frac{\partial z_6}{\partial w_5}, \frac{\partial z_6}{\partial w_6}, \frac{\partial z_6}{\partial w_7}, \frac{\partial z_6}{\partial w_8}, \frac{\partial z_6}{\partial w_9}, \frac{\partial z_6}{\partial w_{10}}, \frac{\partial z_6}{\partial w_{11}}, \frac{\partial z_6}{\partial w_{12}}$$

- laver 4 (14)

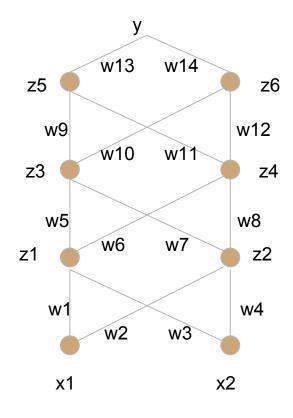
$$\frac{\partial \hat{y}}{\partial w_{13}} \frac{\partial \hat{y}}{\partial w}$$

$$\frac{\partial \hat{y}}{\partial w_1}, \frac{\partial \hat{y}}{\partial w_2}, \frac{\partial \hat{y}}{\partial w_3}, \frac{\partial \hat{y}}{\partial w_4}, \frac{\partial \hat{y}}{\partial w_5}, \frac{\partial \hat{y}}{\partial w_6}, \frac{\partial \hat{y}}{\partial w_7}, \frac{\partial \hat{y}}{\partial w_8}, \frac{\partial \hat{y}}{\partial w_9}, \frac{\partial \hat{y}}{\partial w_{10}}, \frac{\partial \hat{y}}{\partial w_{11}}, \frac{\partial \hat{y}}{\partial w_{12}}$$

- last layer (14)

$$\frac{\partial l}{\partial w_1}, \frac{\partial l}{\partial w_2}, \frac{\partial l}{\partial w_3}, \frac{\partial l}{\partial w_4}, \frac{\partial l}{\partial w_5}, \frac{\partial l}{\partial w_6}, \frac{\partial l}{\partial w_7}, \frac{\partial l}{\partial w_8}, \frac{\partial l}{\partial w_9}, \frac{\partial l}{\partial w_{10}}, \frac{\partial l}{\partial w_{11}}, \frac{\partial l}{\partial w_{12}}, \frac{\partial l}{\partial w_{13}}, \frac{\partial l}{\partial w_{14}}$$





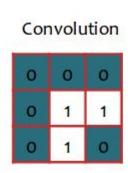
Why backpropagation?

Each layer compute 8 more terms than the previous layer

Demon of convolution operation

Input Image

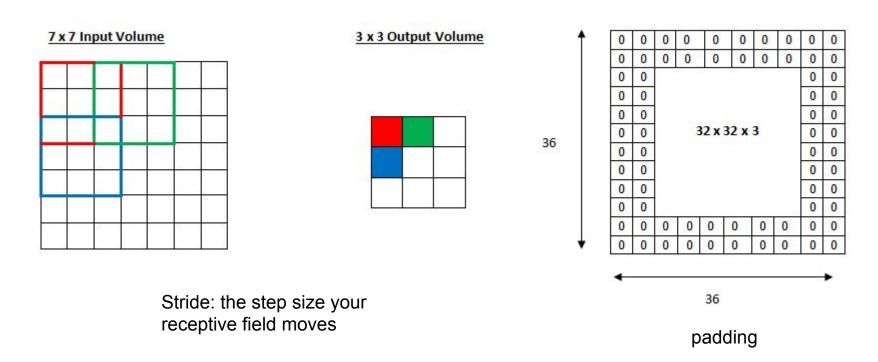
0	0	0	0	0	0	0
0	1	1	1	1	1	0
0	1	0	0	1	0	0
0	1	0	1	0	0	0
0	1	1	0	0	0	0
0	1	0	0	0	0	0
0	0	0	0	0	0	0



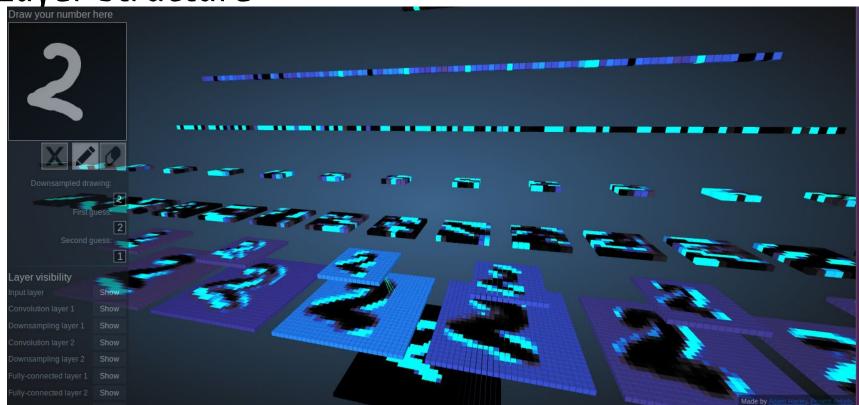
Convolved Image

3	2	2	3	1
2	0	2	1	0
2	2	1	0	0
3	1	0	0	0
1	0	0	0	0

What are the stride, padding, size of the receptive fields



Layer structure



http://scs.ryerson.ca/~aharley/vis/conv/