Assessing Covid-19 Situation in Vietnam Using a Data-Driven Epidemiological Compartmental Model

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Outline

- Introduction
- 2 Literature review
- Methodologies
- 4 Results
- Discussion
- **6** Conclusion

Outline for Introduction

Introduction

The Covid-19 disease

- Health impacts (WHO)
 - 230 million global infections
 - 4.7 million global deaths

The Covid-19 disease

- Health impacts (WHO)
 - 230 million global infections
 - 4.7 million global deaths
- Economic impacts
 - Delayed shipments
 - Increased transaction cost

Why do we need a Covid-19 model?

 Lack of research on the impacts of Non-Pharmaceutical Intervention (NPI) in Vietnam

Why do we need a Covid-19 model?

- Lack of research on the impacts of Non-Pharmaceutical Intervention (NPI) in Vietnam
- Need of a simple tool for assessing the disease current and future progression

Goals

• A model that works with the data availability in Vietnam

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- An explainable model that can be used by experts

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- A model that works with the data availability in Vietnam
- An explainable model that can be used by experts
- Assess the effectiveness of mobility data in predicting future cases

Outline for Literature review

- 2 Literature review
 - Mathematical models
 - Data-driven models
 - Novel compartmental models

Compartmental models

Susceptible-Exposed-Infective-Removed (SEIR) model [1]

$$S' = -\beta(N)SI$$

$$E' = \beta(N)SI - \kappa E$$

$$I' = \kappa E - \alpha I$$

$$R' = f\alpha I$$

$$N' = -(1 - f)\alpha I$$

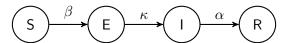


Figure: States graph for the SEIR model

Agent-based models

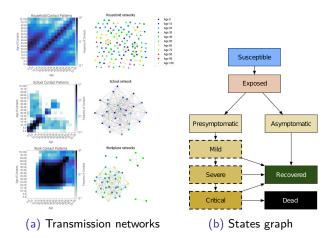


Figure: Covasim model [2]

Mathematical models

Pros & cons

Pros

- Explainable
- Based on many years of research
- Easy to understand and implement

Mathematical models

Pros & cons

Pros

- Explainable
- Based on many years of research
- Easy to understand and implement

Cons

- Low representational capabilities
- The represented dynamics are stationary
- Unrealistic assumptions about real-world scenarios

Data-driven models

Examples

Autoregressive Integrated Moving Average (ARIMA) models
 [3]–[5]

Data-driven models

Examples

- Autoregressive Integrated Moving Average (ARIMA) models
 [3]–[5]
- Explainable Artificial Neural Network (ANN) encoder [6]

Examples

- Autoregressive Integrated Moving Average (ARIMA) models
 [3]–[5]
- Explainable Artificial Neural Network (ANN) encoder [6]
- Recurrent Neural Network (RNN) [7], [8]
 - Long Short Term Memory (LSTM)
 - Bidirectional Long Short Term Memory (Bi-LSTM)
 - Gated Recurrent Unit (GRU)

Data-driven models

Pros & cons

Pros

- High prediction accuracy
- Allow for modeling without needing domain knowledge

Data-driven models

Pros & cons

Pros

- High prediction accuracy
- Allow for modeling without needing domain knowledge

Cons

- Unexplainable
- Relied on large amount of data
- Inability to capture the true disease dynamics

Incorporating mobility data

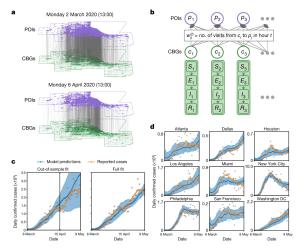


Figure: SEIR model informed with mobility data [9]

Incorporating artificial neural networks

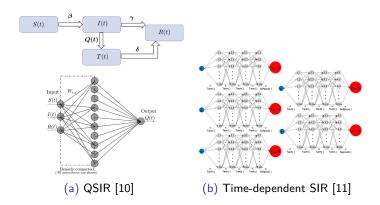


Figure: Predict the parameters of compartmental models with Artificial Neural Networks (ANNs)

Outline for Methodologies

- Methodologies
 - Model definition
 - Datasets
 - Parameters estimation
 - Experiments

Model definition

Universal differential equation

Universal Differential Equation (UDE) [12] is a neural network architecture based on Neural Ordinary Differential Equation (NeuralODE) [13]

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Generalized NeuralODE

$$u' = U_{\theta}(u, t)$$

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Generalized NeuralODE

$$u' = U_{\theta}(u, t)$$

Generalized UDE

$$u' = f(u, t, U_{\theta}(u, t))$$

System of ODEs

Definition

$$S' = -\frac{\beta(t)SI}{N}$$

$$E' = \frac{\beta(t)SI}{N} - \gamma E$$

$$I' = \gamma E - \lambda I$$

$$R' = (1 - \alpha(t))\lambda I$$

$$D' = \alpha(t)\lambda I$$

$$N' = -\alpha\lambda I$$

$$C' = -C + \gamma E$$

$$T' = \gamma E$$

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Reproduction number

$$\mathcal{R}^* = \frac{\beta(t)}{\gamma}$$

Model definition

States graph

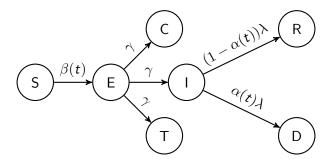


Figure: States graph for the proposed model

Box constraints for time-independent parameters

$$\gamma = \gamma_L + (\gamma_U - \gamma_L) * \sigma(\gamma')$$
$$\lambda = \lambda_L + (\lambda_U - \lambda_L) * \sigma(\lambda')$$

System parameters

Box constraints for time-independent parameters

$$\gamma = \gamma_L + (\gamma_U - \gamma_L) * \sigma(\gamma')$$
$$\lambda = \lambda_L + (\lambda_U - \lambda_L) * \sigma(\lambda')$$

Neural networks for time-dependent parameters

$$\begin{split} \beta(t) &= \mathcal{NN}_{\theta_1}(\mathcal{F}) \\ \alpha(t) &= \mathcal{NN}_{\theta_2}(\frac{t}{t_{\text{max}}}, \frac{\textit{I}(t-1)}{\textit{N}(t-1)}, \frac{\textit{R}(t-1)}{\textit{N}(t-1)}, \frac{\textit{D}(t-1)}{\textit{N}(t-1)}) \end{split}$$

- Hidden layers activation: mish [14]
- Output layer activation $\nu_i = \nu_{i,L} + (\nu_{i,U} \nu_{i,L}) * \sigma(z_i)$

Model definition

Neural network input features

1st. set of input features

$$\mathcal{F}_1(t) = \left\{ \frac{t}{t_{\mathsf{max}}}, \frac{\mathcal{S}(t-1)}{\mathcal{N}(t-1)}, \frac{\mathcal{E}(t-1)}{\mathcal{N}(t-1)}, \frac{\mathcal{I}(t-1)}{\mathcal{N}(t-1)} \right\}$$

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2nd. set of input features

$$\mathcal{F}_2(t) = \mathcal{F}_1(t) \cup \{\mathsf{MovementRange}(t)\}$$

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2nd. set of input features

$$\mathcal{F}_2(t) = \mathcal{F}_1(t) \cup \{\mathsf{MovementRange}(t)\}$$

3rd. set of input features

$$\mathcal{F}_3(t) = \mathcal{F}_2(t) \cup \{ SocialProximityToCases(t) \}$$

Covid-19 cases time series

| date | infective | confirmed | recoveries | deaths |
|---------|-----------|-----------|------------|--------|
| 1/22/20 | 0 | 0 | 0 | 0 |
| 1/23/20 | 2 | 2 | 0 | 0 |
| 1/24/20 | 2 | 2 | 0 | 0 |
| • • • | | | | |

Table: Structure of the processed Covid-19 time series datasets

- John Hopkins University (JHU) Covid-19 public datasets
- VNExpress Covid-19 public dashboard
- VnCDC Covid-19 public dashboard



Datasets

Facebook's movement range maps dataset

| ds | country | polygon | rel. change | stay put ratio |
|------------|---------|------------|-------------|----------------|
| • • • | | • • • | | • • • |
| 2021-01-01 | VNM | VNM.1.10_1 | 0.125 | 0.270 |
| 2021-01-02 | VNM | VNM.1.10_1 | 0.052 | 0.259 |
| 2021-01-03 | VNM | VNM.1.10_1 | 0.185 | 0.269 |
| | | | | |

Table: Structure of Facebook's Movement Range Maps (MRMs) dataset.

Datasets

Facebook's social connectedness index

Social Connectedness Index (SCI)

$$\mathsf{SCI}_{i,j} = \frac{\mathsf{FB} \; \mathsf{connections}_{i,j}}{\mathsf{FB} \; \mathsf{users}_i * \mathsf{FB} \; \mathsf{users}_j},$$

Datasets

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Social Connectedness Index (SCI)

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Social Proximity to Cases (SPC) index [15]

$$\mathsf{SPC}_{i,t} = \sum_{j}^{C} \mathsf{Cases} \ \mathsf{per} \ \mathsf{10k}_{j,t} \frac{\mathsf{SCI}_{i,j}}{\sum_{h}^{C} \mathsf{SCI}_{i,h}},$$

Datasets

Population data

| ID_1 | NAME_1 | AVGPOPULATION |
|---------|----------------------|---------------|
| 3 | Ha Noi | 8.2466e6 |
| 62 | Vinh Phuc | 1.1712e6 |
| • • • | • • • | ••• |
| 1001.0 | Autauga, Alabama, US | 55869 |
| 1003.0 | Baldwin, Alabama, US | 223234 |
| • • • • | • • • | • • • |

Table: Structure of the processed average population datasets

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- Vietnam General Statistics Office (GSO)
- JHU Covid-19 datasets



Loss function

Regularized Mean Squared Error (MSE) with scaled outputs

$$\begin{split} \mathcal{L}(\hat{y}, y) &= \frac{1}{T} \sum_{i=1}^{N} \sum_{t=0}^{T-1} \left[e^{\zeta t} \left(\frac{\hat{y}_{i,t} - y_{i,t}}{\max(y_i) - \min(y_i)} \right)^2 \right] \\ &+ \frac{\lambda}{2T} (\|\theta_1\|_2^2 + \|\theta_2\|_2^2) \end{split}$$

Parameters estimation

Training process

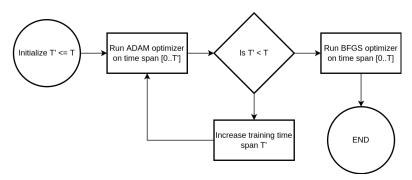


Figure: Model training procedure

Experiments

Data preprocessing

- Applied 7-day moving average to all datasets
- Applied min-max scaling on the Movement Range Map (MRM) dataset and Social Proximity to Cases (SPC) index

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 - United States: 1st July 2021

Experiments

Data preprocessing

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- Applied min-max scaling on the Movement Range Map (MRM) dataset and Social Proximity to Cases (SPC) index
- Training period: 48 days
 - Vietnam: First date when the total confirmed cases passed 500
 - United States: 1st July 2021
- Testing period: 28 days

- Tsit5 solver (Tsitouras Runge-Kutta 5/4 method [16])
- InterpolatingAdjoint technique for approximating gradients in NeuralODE [17]

Experiments

Initial conditions

| Location | S (0) | E(0) | <i>I</i> (0) | R(0) |
|-------------------------|--------------|-------|--------------|--------|
| Vietnam | 9.75e7 | 25 | 5 | 2817 |
| Ho Chi Minh city | 9.22e6 | 173.5 | 34.7 | 360.1 |
| Binh Duong | 2.58e6 | 206.4 | 41.2 | 314.7 |
| Dong Nai | 3.17e6 | 295 | 59 | 194.8 |
| Long An | 1.71e6 | 217.8 | 43.5 | 300.5 |
| United States | 2.99e8 | 71890 | 14378 | 3.31e7 |
| Los Angeles, California | 8.78e6 | 2500 | 500 | 1.22e6 |
| Cook, Illinois | 4.59e6 | 615 | 123 | 546508 |
| Harris, Texas | 4.30e6 | 930 | 186 | 396430 |
| Maricopa, Arizona | 3.92e6 | 1325 | 265 | 549899 |

Table: Initial conditions for the system of Ordinary Differential Equations (ODEs)

| Parameter | Value | Lower bound | Upper bound |
|------------|---------------|-------------|-------------|
| β | N/A | 0.05 | 1.67 |
| γ | 1/4 | 1/4 | 1/4 |
| λ | 1/14 | 1/14 | 1/14 |
| α | N/A | 0.005 | 0.05 |
| θ_1 | glorot_normal | N/A | N/A |
| θ_2 | glorot_normal | N/A | N/A |

Table: Initial parameters for the system of ODEs

Outline for Results



- Model's outputs for Vietnam and the United States
- Model's outputs for counties in the United States
- Model's outputs for provinces in Vietnam

Evaluation metric

Mean absolute percentage error

$$MAPE = \frac{100}{n} \sum_{i=1}^{n} \left| \frac{\hat{y}_i - y_i}{y_i} \right|$$

Model's outputs for Vietnam and the United States

MAPE: Country-level data

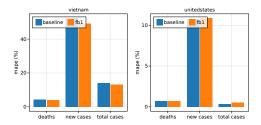


Figure: MAPE for 28-day forecast horizon

Model's outputs for Vietnam and the United States

Forecasts: Country-level data

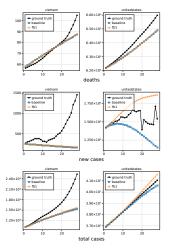


Figure: Forecasts made by different versions of the model

Model's outputs for counties in the United States

MAPE: Counties in the United States

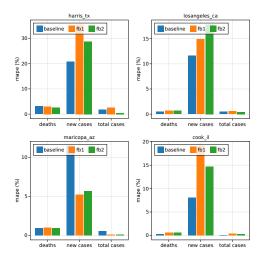


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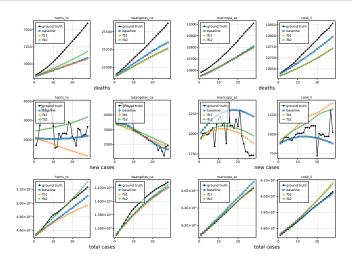


Figure: Forecasts made by different versions of the model



MAPE: Provinces in Vietnam

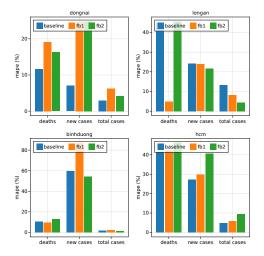


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Forecasts: Provinces in Vietnam

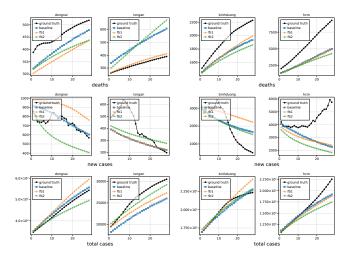


Figure: Forecasts made by different versions of the model

Outline for Discussion

- Discussion
 - Model's convergence and generalizability
 - Model's limitations

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- Accuracy get lower as we extrapolated further into the future
- Bad fit and low forecast accuracy when applied to data with high fluctuation
- No improvement in the forecast accuracy when mobility data was incorporated

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- The model could get stuck in bad local minima, due to
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- The model was separately trained at each location and only capable of making forecast for the location that it was trained with
- Forecast can only be made for a short period after the training period

Model's limitations

Issues with ground truth data

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- Covariates bias
- The changing dynamics of Covid-19
- Neural network interpretability

Outline for Conclusion

6 Conclusion

What has been done?

Goals: An explainable Covid-19 model that can work with the low data availability in Vietnam

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• Collect and process Covid-19 related data for various locations

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Goals: An explainable Covid-19 model that can work with the low data availability in Vietnam

- Collect and process Covid-19 related data for various locations
- Implement a model an explainable Covid-19 model using UDE
 - Progression of all compartments can be given by the model
 - Metric about the disease, e.g. \mathcal{R}_0 , can be derived

What has been done?

Goals: An explainable Covid-19 model that can work with the low data availability in Vietnam

- Collect and process Covid-19 related data for various locations
- Implement a model an explainable Covid-19 model using UDE
 - Progression of all compartments can be given by the model
 - Metric about the disease, e.g. \mathcal{R}_0 , can be derived
- Add mobility data to the model and show that ineffectiveness of the approach

 Increase the model complexity with additional compartments and parameters

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- Include additional time-varying covariates
- Implement better methods and algorithms for training UDE
- Use methods such as Sparse Identification of Nonlinear Dynamical System (SINDy) to find a governing equation and improve the model interpretability

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Outline for Mathematical models

Mathematical models

Changes made to classical models for infectious disease [18]–[22]:

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- Inclusion of compartments that represent government interventions
- Inclusion of compartments that specifically represent the behavior of SARS-NCOV-2
- Separation of the infectious compartment into multiple compartments representing the severity of the patients

Outline for MLPs



Multi-layer perceptron: Graph representation

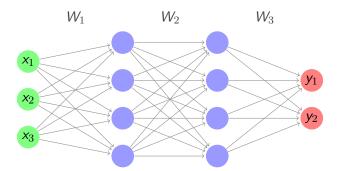


Figure: A Multi-Layer Perceptron (MLP) with four layers

Multi-layer perceptron: Mathematical representation

Definition

$$g(X) = \phi_n(W_n \phi_{n-1}(\cdots (W_2 \phi_1(W_1 X + b_1) + b_2) + \cdots) + b_n)$$

Multi-layer perceptron: Mathematical representation

Definition

$$g(X) = \phi_n(W_n\phi_{n-1}(\cdots(W_2\phi_1(W_1X + b_1) + b_2) + \cdots) + b_n)$$

Theorem

Given appropriate weights, ANNs can approximate any arbitrary function $f: \mathbb{R}^M \to \mathbb{R}^N$ [23]–[25]

Training neural networks: Back-propagation

MSE

$$\mathcal{L} = \frac{1}{N} \sum_{i=1}^{N} (g(X_i) - Y_i)^2$$

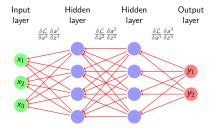


Figure: Graph representation of the back-propagation algorithm

Outline for PINNs



Physics-informed neural networks

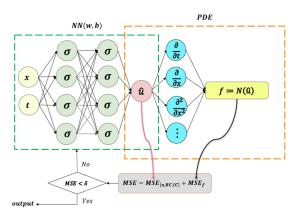


Figure: The schematic of Physics-Informed Neural Networks (PINNs) for solving Partial Differential Equations (PDEs) [26].

Outline for NeuralODEs

10 NeuralODEs

Neural ordinary differential equations: Idea

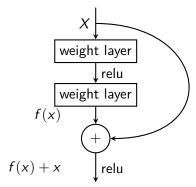


Figure: Skip connection

Neural ordinary differential equations: Idea

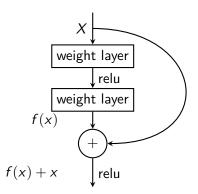


Figure: Skip connection

Observation

$$h_{t+1} = h_t + f(h_t, \theta_t)$$

$$\Leftrightarrow \frac{dh(t)}{dt} = f(h(t), t, \theta)$$

$$z(t_1) = z(t_0) + \int_{t_0}^{t_1} f(z(t), t, \theta) dt$$

Neural Ordinary Differential Equation (NeuralODE) output

$$z(t_1) = z(t_0) + \int_{t_0}^{t_1} f(z(t), t, \theta) dt$$

Memory efficiency

$$z(t_1) = z(t_0) + \int_{t_0}^{t_1} f(z(t), t, \theta) dt$$

- Memory efficiency
- Adaptive computation

$$z(t_1) = z(t_0) + \int_{t_0}^{t_1} f(z(t), t, \theta) dt$$

- Memory efficiency
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- Scalable and invertible normalizing flows

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- Memory efficiency
- Adaptive computation
- Scalable and invertible normalizing flows
- Continuous time series models

Neural ordinary differential equations: Outputs

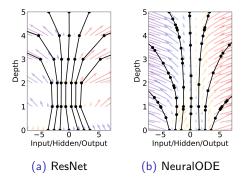


Figure: Comparison between ResNet's discrete state transformations and NeuralODE continuous state transformations

Neural ordinary differential equations: Gradients

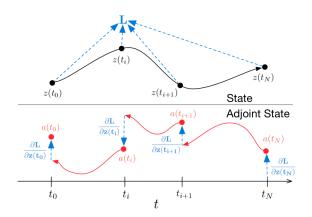


Figure: Reverse-mode differentiation of an ODE solution. [13]

Outline for Software and hardware

Software and hardware

Software and hardware

Julia programming language

- DifferentialEquations package
- DiffEqFlux package

Linux systems

- Google Cloud Compute n2-standard-8 instance
- Personal laptop with 2-core Intel(R) Core(TM) i5-4260U CPU 1.40GHz, and 4Gb of memory.

Julia example

```
function SEIRD!(du, u, p, t)
     @inbounds begin
          S, E, I, \_, \_, N, C, \_ = u
          \beta, \vee, \lambda, \alpha = p
          du[1] = -\beta * S * I / N
          du[2] = \beta * S * I / N - y * E
          du[3] = \vee * E - \lambda * I
          du[4] = (1 - \alpha) * \lambda * I
          du[5] = \alpha * \lambda * I
          du[6] = -\alpha * \lambda * I
          du[7] = -C + \vee * E
          du[8] = y * E
     end
     return nothing
end
```

Figure: Implementation of the system of ODEs in Julia

Outline for Hyperparameters

- Initial time span of 4 days
- Time span increment of 4 days

- Initial time span of 4 days
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- \bullet Time weighting parameter $\zeta=-0.001$

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- Time span increment of 4 days
- Time weighting parameter $\zeta = -0.001$
- ADAM optimizer
 - Learning rate 0.05
 - decay rate 0.5
 - decay step 1000
 - decay limit 0.00001
 - 1000 iterations on each time span

- Initial time span of 4 days
- Time span increment of 4 days
- Time weighting parameter $\zeta = -0.001$
- ADAM optimizer
 - Learning rate 0.05
 - decay rate 0.5
 - decay step 1000
 - decay limit 0.00001
 - 1000 iterations on each time span
- BFGS optimizer
 - Initial stepnorm 0.01
 - 1000 iterations on the full time span



Outline for R_0 and fatality rate

 \bigcirc R_0 and fatality rate

R_0 and fatality rate: Country-level data

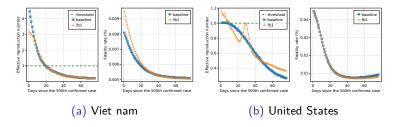


Figure: Disease metrics learned by different versions of the model

R_0 and fatality rate: Counties in the United States

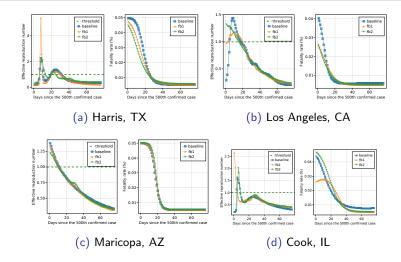


Figure: Disease metrics learned by different versions of the model



R_0 and fatality rate: Provinces in Vietnam

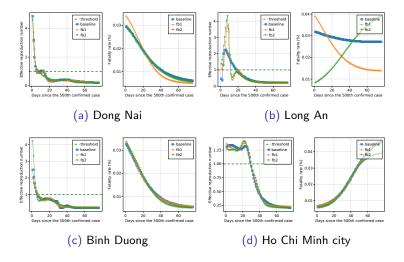


Figure: Disease metrics learned by different versions of the model

