# Shengmiao (Samuel) Jin

♠ github.com/leumasnij
♦ leumasnij.github.io
♦ 443-207-6601
Image: Image:

#### EDUCATION

# University of Illinois Urbana-Champaign

Bachelor of Science in Electrical Engineering

• Minor in Computer Science

#### West Nottingham Academy

High School Diploma

• Graduated as Valedictorian

 ${\rm May}\ 2025\ expected$ 

GPA: 3.93/4.0

May 2021

GPA: 4.18/4.33

# SKILLS

Speaking Languages: English, Chinese(Bilingual)

Programming Languages: Python, ROS, C/C++, LATEX, R, Matlab, SystemVerilog

Libraries: TensorFlow, PyTorch, Scikit-Learn, OpenCV, Keras

Relevant courses: Intro to Robotics, Signal Processing, Computational Photography, Control Systems, Deep Learning

for CV, Principle of Safe Autonomy, Artificial Intelligence

# WORK EXPERIENCE

#### **UIUC ECE** | Undegraduate Grader for ECE 210

August 2023 – December 2023

- Graded weekly homework assignments and handle all regrade request for Undergraduate Course Analog Signal Programming
- Helped revise solution manual and grading manual of several homework assignments.

### BGI-Shenzhen Institute of Biointelligence | Intern-Algorithmic Engineer

December 2022 – June 2023

- Implemented a tool to help Biomedical Researchers to perform automatic Image Registration. Was later integrated into Cellbin, a BGI product that enpowered research in Stereo-Seq
- Integrated company's own Segmentation model on a server app via MONAI-based tool for easy access by biomedical researchers
- Tested performance of different segmentation models, helped fine-tuned company's own segmentation models
- Developed an automatic chip analysis tool to facilitate production of biomedical chips.

#### Research Experience

#### UIUC RoboTouch Lab | advisor: Prof. Wenzhen Yuan

September 2023 - present

- Designed and implemented an algorithm that decompose an arbitrary image into robot trajectory. Experimented and designed an algorithm for the robot to be able to handle liquid in a even manner
- Tested and designed a visual-base closed-loop controller to ensure a stable starting position of the robot pourring.
- Wrote and maintaining a manual on how to use the UR5 robots in the lab.

#### Tufts Higher Energy Physics Lab | advisor: Prof. Pierre-Hugo Beauchemin

June 2020 – August 2020

- Implemented an Unfolding Algorithm to clean up data from CERN's Large Hadron Collider using Deep Learning algorithms.
- Examined the performs of different Deep Learning algorithms on the specific dataset and how they improves the data quality
- Presented findings in the form of an academic poster at Tufts Summer Research Experience Symposium

#### Honors and Awards

James Scholar Dean's List Spring 2022 - Present 2021-2022, Fall 2023

# Artwork Style Classification and Tranfer | CS445 Final Project

Fall 2023

• Implemented and trained an EfficientNetV2-based classification model, a VGG-based Neural Style transfer and a CycleGAN-based style generator.

# Reaction Wheel Pendulum | ECE 486 Final Project

Fall 2023

• Implemented a 3-state PD controller with Decoupled Observer and friction compensation that can allows a pendulum to reject disturbance and stay at a unstable equilibrium position with only a rotor

# Tetris On FPGA | ECE 385 Final Project

Summer 2023

• Implemented the classic game Tetris on a Intel MAX10 FPGA, programmed using SystemVerilog for hardware level and C for software level.

# Computer Vision Team Member | Illini Robomaster

Fall 2022

• Part of Illini Robomaster CV Team that implemented object detection and tracking algorithm for competition

# BitCorn | ECE 220 Honors Project

Fall 2022

• Implemented a Bitcoin Price prediction model using LSTM and updated daily result on a website