

A Dynamic Spatial Knowledge Economy

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Introduction

- Micro estimates: Workers learn more in big cities

[Glaeser and Maré (2001), Baum-Snow and Pavan (2012), Wang (2016), De la Roca and Puga (2017)]

*"[W]e find that workers in **bigger cities** . . . obtain an immediate static [earnings] premium and accumulate **more valuable experience**. The additional value of experience in bigger cities **persists** after leaving and is **stronger** for those with higher initial ability."* (De la Roca and Puga, 2017)

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- We think learning drives growth → How does the spatial dist. matter for growth?
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[Lucas (2009), Lucas and Moll (2014), Buera and Lucas (2018), Gabriel and Lucas (2019)]
- If space matters → Spatial policy must weigh long-run growth/welfare response
[static: Hsieh and Moretti (2019), Fajgelbaum and Gaubert (2020), Rossi-Hansberg, Sarte, and Schwartzman (2021)]

This paper: Three contributions

1. Theory: Local human capital externalities → Agglomeration & Growth

- system of cities
- heterogeneous workers **learn & migrate** over the life cycle
- human capital process drives **both** agglomeration and growth
 - learn from others in your city, more if bigger or more skilled (*local externalities*)
 - learning → human capital dist. shifts right → output grows
- **characterize “cities drive growth”:** growth rate = $f(\text{spatial distribution})$

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Solves the **hard problem of regional econ** (Breinlich, Ottaviano, and Temple, 2014)

- “How to model growth and agglomeration as outcomes of a joint process”
- Agents must know *distribution* of economic activity over *time & space* → high-dimensional
- *how?* **Equilibrium is a mean field game** (Achdou et al., 2022) → can track distribution

This paper: Three contributions

2. Quantitative: Using U.S. data, jointly rationalize ...

- ... urban cross-section:
 - match city size distribution
 - big cities more productive, more expensive, more skilled on avg. (Glaeser, 2008)
- ... worker panels:
 - life-cycle of human capital investment (Ben-Porath, 1967; Huggett, Ventura, and Yaron, 2006)
 - migration driven by expected income; young & edu. move more (Kennan and Walker, 2011)
 - city size wage premium = higher wage level + faster wage growth w/ permanent value (Glaeser and Maré, 2001; Baum-Snow and Pavan, 2012; Duranton and Puga, 2022)
- ... aggregate growth: 2% per year on BGP

3. Long-run effects of place-based policy

- policy: relax LURs in **NY** and **SF** to U.S. median
- outcome: aggregate growth **increases by 13bp**
- **through what channel?**
 - *not* siphoning skill from elsewhere
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Spatial **policy** → Δ spatial **distribution** → Δ **growth** in two (complementary) ways:

- by *attracting* more skilled workers to particular cities (e.g., push *skilled* to **NY**)
- by *producing* more skilled workers for the economy overall (e.g., push *young* to **NY**)

Outline for today

1. **Model:** setup, equilibrium, BGP, main result
2. **Quantitative analysis:** calibration/estimation, predictions
3. **Counterfactual place-based policy**
4. **Conclusion**

Model

Environment

- continuous time $t \in [0, \infty)$, discrete cities $n = 1, \dots, N$
- mass L of workers with **human capital** $z \in \mathbb{R}_{++}$ and **age** $a \in [0, A]$
 - discount at rate ρ
 - hand-to-mouth
 - consume traded good c (numeraire) and land (**strict necessity**), benefit from amenity B_n

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- two **choices** at each t :
 - **raw labor**: learn (s) and work $(1 - s) \rightarrow$ income tomorrow vs. today
 - **migration**: city n s.t. opportunity $\stackrel{iid}{\sim} \text{Poisson}(\lambda)$ & taste $b_n^\omega \stackrel{iid}{\sim} \text{T2EV}(\epsilon)$ & cost τ_{in} 

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- expected flow utility:

$$U_n(s; z, t) = \underbrace{B_n}_{\text{Amenity}} \underbrace{[y_n(s; z, t) - P_n(z, t)]}_{\text{Consumption flow}} \underbrace{\left[\frac{\text{Income}}{P_n(z, t)} - \frac{\text{Urban cost}}{P_n(z, t)} \right]}_{\text{Expected Flow Utility}}$$

City characteristics: Congestion vs. Agglomeration

Endogenous city populations: $L_n(t) = L \iint g_n(a, z, t) dz da$

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Congestion through land

- pay heterogeneous flow cost $zP_n(t)$ for accommodation in city n , where

$$P_n(t) = p_n \textcolor{orange}{L_n(t)^{\theta_n}}$$

- *microfoundation*: monocentric city with commuting cost as forgone income 

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Agglomeration through static & dynamic channels

- Through **income**: $y_n(s; z, t) = T_n L_n(t)^\alpha (1-s)z$

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Agglomeration through static & dynamic channels

- Through **income**: $y_n(s; z, t) = T_n \mathbf{L}_n(\mathbf{t})^\alpha (1-s)z$
- Define the **vibrancy** of city n as

$$\begin{aligned} Z_n(t) &= \left(L \iint z^\zeta g_n(a, z, t) dz da \right)^{\frac{1}{\zeta}} \\ &\equiv \mathbf{L}_n(\mathbf{t})^{\frac{1}{\zeta}} \bar{z}_{n,\zeta}(t) \end{aligned}$$

- Through **learning**: law of motion for skill

$$\frac{dz}{dt} = \kappa(s) z^\beta Z_n(t)^{1-\beta}$$

Some notes on learning

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- $\kappa(0) = 0, \kappa' > 0, \kappa'' < 0$

What to notice:

- **agglomeration: anyone can learn from anyone...**
- supermodularity
- classical form
- returns to scale

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- **supermodularity**: ... but more if/from highly-skilled
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What to notice:

- agglomeration
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- **classical form: Ben-Porath (1967), Rosen (1976), Heckman (1976)**
- returns to scale

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What to notice:

- agglomeration
- supermodularity
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- **returns to scale:** DRS in time, CRS in tuple (z, Z_n)

Worker's problem

- Given city sizes $\mathbf{L}(t) \equiv \{L_1(t), \dots, L_N(t)\}$ and vibrancies $\mathbf{Z}(t) \equiv \{Z_1(t), \dots, Z_N(t)\}$
- Hamilton-Jacobi-Bellman equation:** after expectations over T2EV preferences . . .

$$\begin{aligned}\rho V_n(a, z, t) = \max_{s \in [0, 1]} & \left\{ \underbrace{B_n[T_n L_n(t)^\alpha(1-s) - P_n(t)]z + \partial_z V_n(a, z, t) \underbrace{[\kappa(s)z^\beta Z_n(t)^{1-\beta}]}_{\text{skill gains}}}_{\text{flow utility}} \right\} \\ & + \underbrace{\lambda \sum_i m_{ni}(a, z, t) [\xi_{ni}(a, z, t)V_i(a, z, t) - V_n(a, z, t)]}_{\text{expected migration gains}} \\ & + \partial_a V_n(a, z, t) + \partial_t V_n(a, z, t)\end{aligned}$$

with **optimal migration shares** and **selection effect**:

$$m_{ni}(a, z, t) = \frac{\tau_{ni}^{-\epsilon} V_i(a, z, t)^\epsilon}{\sum_k \tau_{nk}^{-\epsilon} V_k(a, z, t)^\epsilon} \quad \xi_{ni}(a, z, t) = \frac{1}{N \tau_{ni}} m_{ni}(a, z, t)^{-\frac{1+\epsilon}{\epsilon}}$$

- Terminal condition:** $V_n(A, z, t) = 0$ for all (n, z, t)

How do city characteristics evolve?

- **Recall:** $\{\mathbf{L}, \mathbf{Z}\}$ are entirely determined by the **distribution** of (a, z) across n
- **Demographics:** uniform marginal age distribution, entrants $\sim \underline{g}_n(z, t)$ replace exiters
- **Kolmogorov forward equation:**

$$\begin{aligned} \partial_t g_n(a, z, t) = & -\underbrace{\partial_z [h_n(a, z, t)g_n(a, z, t)]}_{\text{skill accum.}} - \underbrace{\lambda[1 - m_{nn}(a, z, t)]g_n(a, z, t)}_{\text{outflow: migration}} \\ & + \underbrace{\lambda \sum_{i \neq n} m_{in}(a, z, t)g_i(a, z, t)}_{\text{inflow: migration}} - \underbrace{\partial_a g_n(a, z, t)}_{\text{aging}} \end{aligned}$$

with initial condition $g_n(0, z, t) = \frac{1}{A} \underline{g}_n(z, t)$ and **optimal skill accumulation**:

$$h_n(a, z, t) = \kappa[s_n(a, z, t)]z^\beta Z_n(t)^{1-\beta}$$

Look for a balanced growth path

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$$V_n(a, z, t) = e^{\gamma t} v_n(a, x)$$

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and (V, s, m, g) is an equilibrium with initial condition $g_n(a, z, 0) = \phi_n(a, z)$, where

$x \equiv ze^{-\gamma t}$ is **relative human capital**.

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- **Needs:** I.b. and quantiles of \underline{g} grow with those of $g \rightarrow$ **entrants getting better**
- **Implies:** **constant** city size, **same** productivity growth (*in progress: solving transitions*)

The detrended BGP: number γ and functions (v, σ, μ, ϕ)

- workers solve a **detrended HJB equation**

$$(\rho - \gamma)v_n(a, x) = B_n(T_n L_n^\alpha [1 - \sigma_n(a, x)] - p_n L_n^{\theta_n})x + \partial_x v_n(a, x)[h_n(a, x) - \gamma x] \\ + \partial_a v_n(a, x) + \lambda \sum_i \mu_{ni}(a, x)[\xi_{ni}(a, x)v_i(a, x) - v_n(a, x)]$$

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- the detrended distribution evolves according to a **Kolmogorov forward equation**

$$0 = -\partial_x\{[h_n(a, x) - \gamma x]\phi_n(a, x)\} - \partial_a \phi_n(a, x) \\ - \lambda[1 - \mu_{nn}(a, x)]\phi_n(a, x) + \lambda \sum_{i \neq n} \mu_{in}(a, x)\phi_i(a, x)$$

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- aggregates are **feasible**:

$$X_n = \left(L \iint x^\zeta \phi_n(a, x) dx da \right)^{\frac{1}{\zeta}} \quad L_n = L \iint \phi_n(a, x) dx da$$

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- an expression relating the **growth rate** to the **decision rules & distribution**

Main theoretical result: Endogenous growth rate $\gamma(\sigma, \phi)$

Add up KF over all (n, a, x) , noting **no net migration** and **uniform age density**:

$$\gamma(\sigma, \phi) = \frac{\sum_n \int \kappa[\sigma_n(a, x)] x^\beta X_n^{1-\beta} \phi_n(a, x) da}{\sum_n \int x \phi_n(a, x) da}, \quad \forall x \in \text{supp}(\phi)$$

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Intuition by building on **Uzawa (1965)**:

$$\max_s \quad \int_0^\infty e^{-\rho t} c dt \quad \text{s.t.} \quad \begin{aligned} c &= (1-s)z \\ \dot{z} &= \kappa(s)z \end{aligned} \implies \gamma = \kappa(s^*)$$

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Intuition by building on **Uzawa (1965)**: reintroduce externality . . .

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Intuition by building on Uzawa (1965): ... then reintroduce death (random at rate δ)

$$\max_s \int_0^\infty e^{-(\rho+\delta)t} c dt \quad \text{s.t.} \quad \begin{aligned} c &= (1-s)z \\ \dot{z} &= \kappa(s) z^\beta Z^{1-\beta} \end{aligned} \implies \gamma = \kappa(s_2^*) < \kappa(s_1^*)$$

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Intuition by building on Uzawa (1965): ... then reintroduce worker heterogeneity (a, x)

$$\gamma = \frac{\int_0^A \kappa[\sigma(a, x)] x^\beta X^{1-\beta} \phi(a, x) da}{\int_0^A x \phi(a, x) da}, \quad \forall x \in \text{supp}(\phi) \text{ with } X = \left(L \iint x^\zeta \phi(a, x) dx da \right)^{\frac{1}{\zeta}}$$

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- growth rate = weighted avg. of returns to investment, $\kappa(\sigma)$
- more weight to investment in **larger, more skilled places**
- **spatial distribution of human capital matters for growth**

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When every idea must be in somebody's brain, it matters where those brains are.

Recap: How it solves the “hard problem”

Key idea: Economy is summarized by density $g_n(a, z, t)$, which we can track!

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▶ well-posedness

1. **HJB**: how workers w/ states (n, a, z) learn and migrate given (moments of) distribution
2. **Kolmogorov forward**: how distribution evolves in response to workers' decisions
3. **endogenous growth**: restriction on distribution relating cross-sectional **shape** to **speed**

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3. **endogenous growth**: restriction on distribution relating cross-sectional **shape** to **speed**

$$\text{growth rate} = f(\text{spatial distribution})$$

Spatial **policy** $\rightarrow \Delta$ spatial **distribution** $\rightarrow \Delta$ **growth** in two (complementary) ways:

- by *attracting* more skilled workers to particular cities (e.g., send higher x to raise X_n)
- by *producing* more skilled workers throughout (e.g., send higher σ_n to already-high X_n)

Quantitative analysis

Four steps to rationalize patterns in U.S. data

Select cities: 

- 378 MSAs → **30 biggest + 4 groups**
- congestion elasticity from (**Saiz, 2010**)

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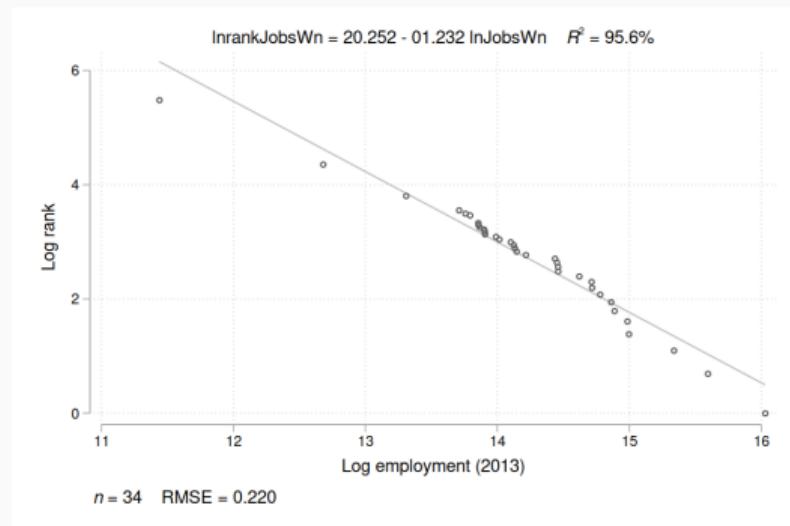
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 - * (computational and data constraints prevent folding #2 into #3 for now)
3. Local fundamentals and elasticities: MDE to match data, prior lit.
 - B_n, T_n, p_n : city size, income; budget shares
 - $\alpha, \zeta, x_{\text{scale}}$: **Duranton and Puga (2022)** wage regression on NLSY panel w/ city groups

Using U.S. data, the model can jointly rationalize...

...urban cross-section:

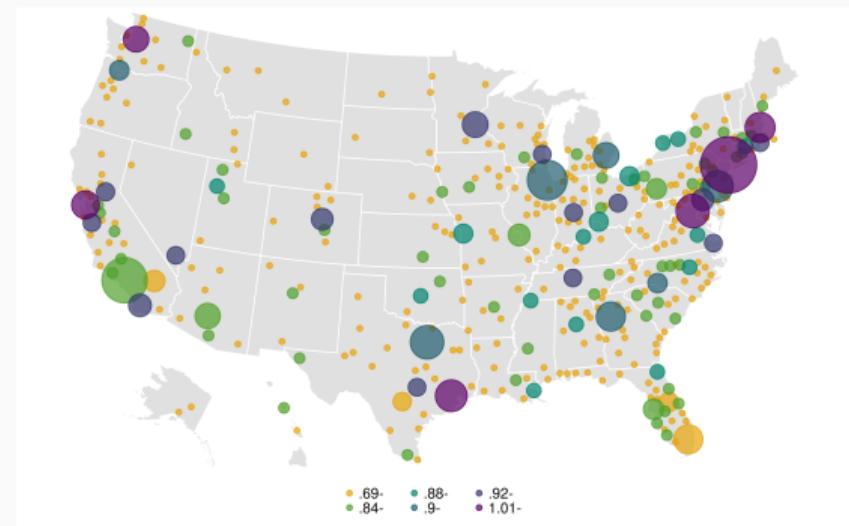
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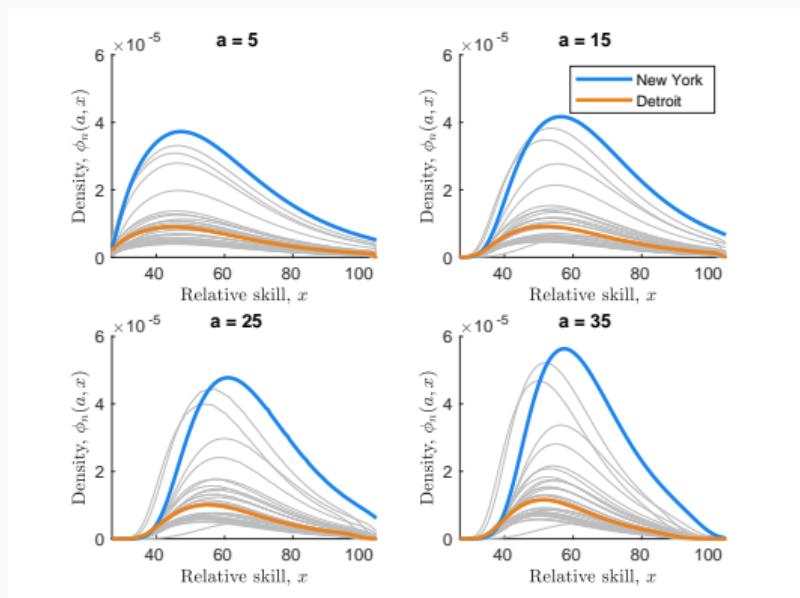
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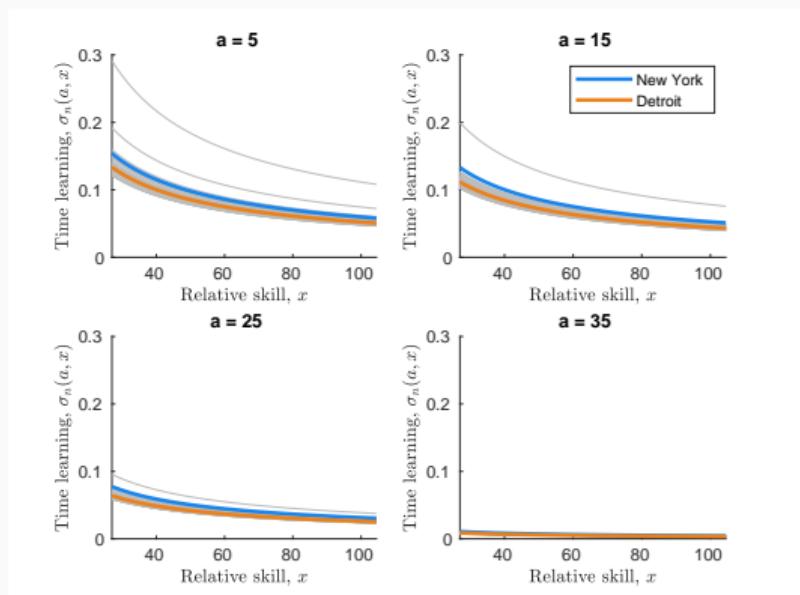
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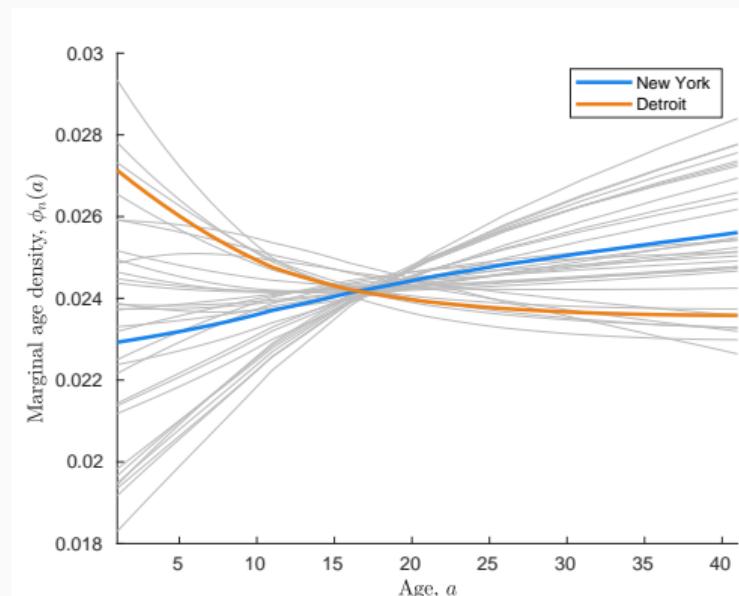
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(Ben-Porath, 1967; Huggett, Ventura, and Yaron, 2006)
- migration driven by expected income; young & educated move more (Kennan and Walker, 2011)
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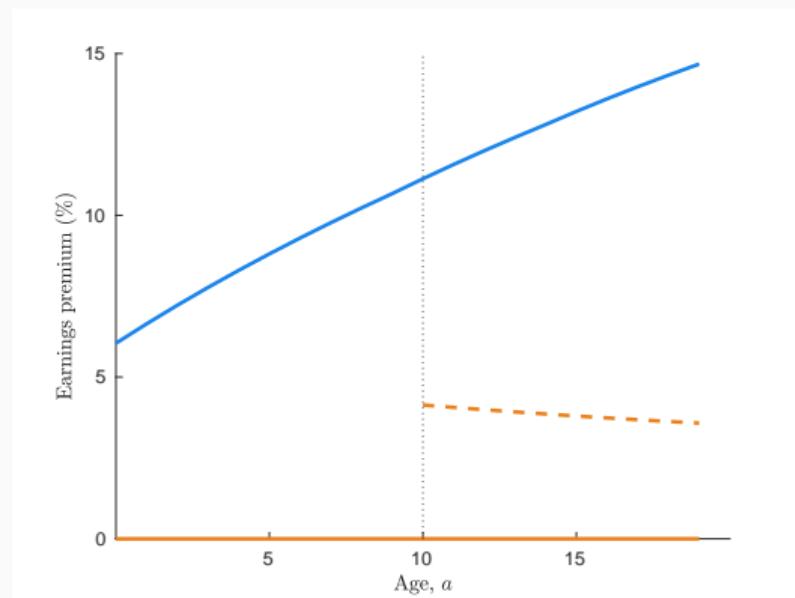
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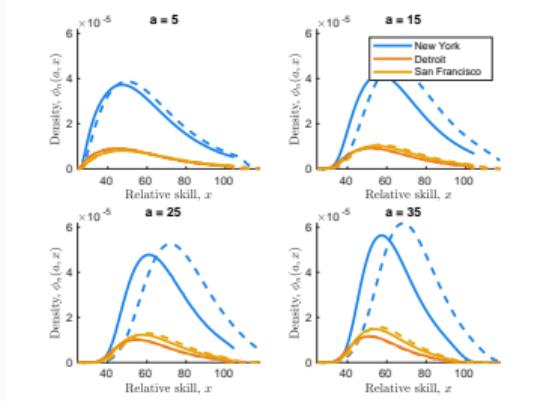
Using U.S. data, the model can jointly rationalize . . .

. . . aggregate growth: 2% per year on BGP

Policy counterfactual

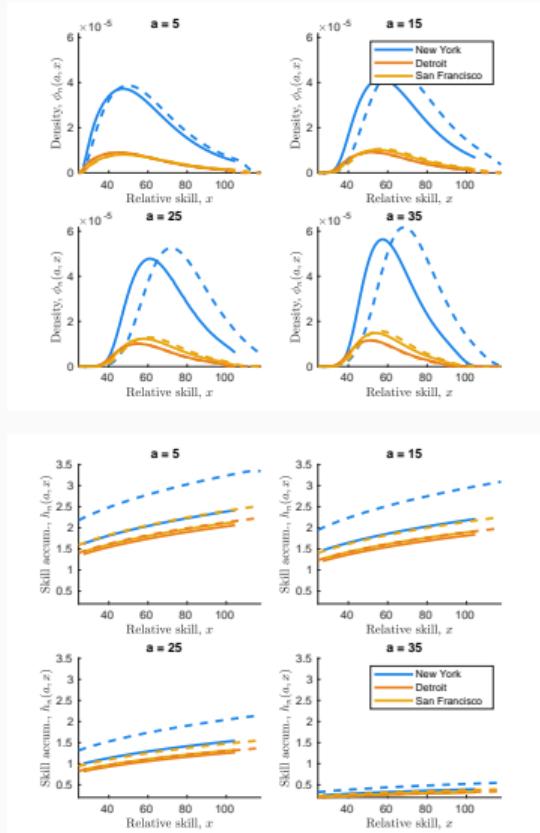
Counterfactual: Relaxing LURs in NY and SF

- Relax land use regulations in **NY** and **SF** to median level ($\downarrow \theta_n$)
- On new BGP, both cities would have lower urban costs at old pop. levels
 - **direct:** lower costs attract workers
 - **indirect:** static & dynamic agglomeration amplify attraction
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 - **direct:** lower costs attract workers
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 - **result:** both *bigger, more skilled*
- **Through what channel?**
 - *not* siphoning skill from elsewhere
 - instead, stronger dynamic spillover → **faster human capital accumulation**
- Overall, **growth $\uparrow 13\text{bp}$** b/c policy **produces** more skilled workers



Recap: The “hard problem” of regional economics

- A classic hypothesis (Jacobs, 1969; Lucas, 1988; Glaeser, 2011) ...

human capital spillovers	→ agglomeration (cities!)
+ human capital accumulation	→ growth
human capital accumulation s.t. local spillovers	→ “ cities drive growth ”

... but no models → no testing, no counterfactuals, no optimal policy

- Why not? forward-looking dynamics + can't average across space → *high-dimensional*
- This paper: **Tackle hard problem with new tools** + apply to U.S. data & policy
 1. characterize “cities drive growth”: growth rate = $f(\text{spatial distribution})$
 2. rationalize patterns in U.S. data: worker panels, city cross-section, aggregate BGP trend
 3. policy counterfactual: relax LURs in **NY** and **SF** → aggregate growth increases by 13bp

Appendix

Formal definition of location history



Key: taste shocks and migrations costs for chosen cities are *multiplicative* and *permanent*
(Desmet, Nagy, and Rossi-Hansberg, 2018; Caliendo, Dvorkin, and Parro, 2019)

- birth location n_0^ω
- count of opportunities $I^\omega(t)$, a Poisson process with arrival rate λ
- each opportunity ι , draw idiosyncratic taste shocks $\{b_n^{\omega,\iota}\}_n \stackrel{iid}{\sim} \text{T2EV}(\epsilon)$
- bilateral migration costs τ_{ni}
- **define ...**
 - $n_\iota^\omega :=$ her location choice at opportunity ι
 - $\hat{b}_\iota^\omega := b_{n_\iota^\omega}^{\omega,\iota}$, the realization of her taste shock for her location choice
 - $\hat{\tau}_\iota^\omega := \tau_{n_{\iota-1}^\omega, n_\iota^\omega}$, the bilateral cost to move to her location choice
- **then we have ...**

$$U^\omega(t) = \Omega^\omega(t) U_n(s; z, t) \text{ with } \Omega^\omega(t) := \prod_{\iota=1}^{I^\omega(t)} \frac{\hat{b}_\iota^\omega}{\hat{\tau}_\iota^\omega}$$

City structure and urban costs: Setup

- canonical rent gradient model: trade off commuting cost vs. rents, utility equalizes
- **here:** heterogeneous agents \implies assignment problem
- a city is a line with...
 - all production at single point ("CBD")
 - identical residences of unit length
- **commuting takes time:** forgo $(T_n z) \vartheta_n \ell^\theta$ of income to commute from distance ℓ
- **equilibrium:** a rent gradient $r_n(\ell, t)$ and an assignment function $\mathcal{L}_n(z, t)$ s.t.
 - (i) individual optimality holds (Alonso-Muth condition):

$$\theta(T_n z) \vartheta_n \mathcal{L}_n(z, t)^\theta = -\partial_\ell r_n(\mathcal{L}_n(z, t), t)$$

- (ii) all workers are allocated to a residence

City structure and urban costs: Solving for equilibrium

- “supply = demand” + sorting: **allocate by skill quantile**

$$-\frac{\partial \mathcal{L}_n(z, t)}{\partial z} = \frac{1}{2} g_n(z, t) \implies \mathcal{L}_n(z, t) = \frac{L_n(t)}{2} [1 - G_n(z, t)]$$

where $g_n(z, t)$ is the marginal density of skill (integrated over age)

- **rents:** integrate Alonso-Muth condition given assignment function

$$r_n(\ell, t) = \theta \vartheta_n T_n \int_{\ell}^{L_n(t)/2} G_n^{-1} \left(1 - \frac{2l}{L_n(t)}, t \right) l^{\theta-1} dl.$$

- urban cost grows at the same rate as income \implies **consumption grows at constant rate**
- would need to guess G each iteration \implies let local government collect & redistribute rents to simplify urban cost to $zP_n(t) = \theta \vartheta_n T_n z L_n(t)^{\theta}$



Equilibrium = Mean Field Game (MFG)



A tuple of functions $\{V, s, m, g\}$ on $\mathcal{N} \times \mathbb{R}_{++} \times [0, A] \times \mathbb{R}_+$ and a tuple of functions $\{\mathbf{L}, \mathbf{P}, \mathbf{Z}\}$ on $\mathcal{N} \times \mathbb{R}_+$ such that

1. workers solve the **Hamilton-Jacobi-Bellman equation** for $n = 1, \dots, N$, taking paths of vibrancies \mathbf{Z} and city sizes \mathbf{L} (thus, also urban costs \mathbf{P}) as given;
2. density $g_n(a, z, t)$ evolves according to the **Kolmogorov forward equation** for $n = 1, \dots, N$, taking workers' optimal policy functions as given;
3. vibrancies and urban costs **satisfy their definitions** given $g_n(a, z, t)$:

$$Z_n(t) = \left(L \iint z^\zeta g_n(a, z, t) dz da \right)^{\frac{1}{\zeta}}, \quad P_n(t) = p_n \left(L \iint g_n(a, z, t) dz da \right)^{\theta_n};$$

4. local population shares **sum to one** for all t :

$$1 = \sum_{n=1}^N \frac{L_n(t)}{L} = \sum_{n=1}^N \iint g_n(a, z, t) dz da.$$

Loose end: Well-posedness of a BGP?

- Main result: “if BGP $\{v, \sigma, \mu, \phi, \gamma\}$ exists, it must be that $\gamma = f(\sigma, \phi)$ ”

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- Main result: "if BGP $\{v, \sigma, \mu, \phi, \gamma\}$ exists, it must be that $\gamma = f(\sigma, \phi)$ "
- **But does a BGP exist?** **no proofs** of existence & uniqueness for this class of MFGs (first-order, smoothing, non-separable Hamiltonian w/ boundaries)
- take **three steps** to ensure sensible results:
 1. impose $\beta\bar{\kappa} < \rho\eta$, necessary for E&U in Uzawa model with externality
 2. show **existence & local stability of (discretized) BGP by construction**
→ look for one that matches data
 3. in counterfactual, select closest BGP (**Ahlfeldt et al., 2015**)

Overview of algorithm

Adapt the usual **HACT algorithm** (Achdou et al., 2022)

0. Begin with guess $\{\gamma^0, \mathbf{X}^0, \mathbf{L}^0\}$. Denote iterations by $\iota = 0, 1, 2, \dots$
1. Given $\{\gamma^\iota, \mathbf{X}^\iota, \mathbf{L}^\iota\}$, solve detrended HJB w/ finite difference method + calculate policy functions $\sigma_n^\iota(a, x)$ and $\mu_{ni}^\iota(a, x)$.
2. Given $\sigma_n^\iota(a, x)$ and $\mu_{ni}^\iota(a, x)$, solve KF for $\phi_n^\iota(a, x)$ w/ finite difference method.
3. Given $\phi_n^\iota(a, x)$, compute vibrancies, populations, and growth rate:

$$\tilde{X}_n^\iota = \left(L \iint x^\zeta \phi_n^\iota(a, x) dx da \right)^{\frac{1}{\zeta}}, \quad \tilde{L}_n^\iota = L \iint \phi_n^\iota(a, x) dx da.$$

$$\tilde{\gamma}^\iota = \frac{\sum_n \int_0^A \kappa[\sigma_n^\iota(a, x)] x^\beta (\tilde{X}_n^\iota)^{1-\beta} \phi_n^\iota(a, x) da}{\sum_n \int_0^A x \phi_n^\iota(a, x) da}, \quad x \in \text{supp}(\phi^\iota)$$

4. If $\{\tilde{\gamma}^\iota, \tilde{\mathbf{X}}^\iota, \tilde{\mathbf{L}}^\iota\}$ close enough to $\{\gamma^\iota, \mathbf{X}^\iota, \mathbf{L}^\iota\}$, **stop**. Else, construct $\{\gamma^{\iota+1}, \mathbf{X}^{\iota+1}, \mathbf{L}^{\iota+1}\}$ as a linear combination of previous guess and computed values, then return to step 1.

One-slide summary of steps 1 & 2

- Will discretize and solve using a **finite difference method** to approx. derivatives
- Discretization → HJB non-linear in \mathbf{v} , KF linear in ϕ , solved iteratively over age index j

$$(\rho - \gamma)\mathbf{v}^j = \mathbf{u}(\mathbf{v}^{j+1}) + \boldsymbol{\Pi}(\mathbf{v}^{j+1})\mathbf{v}^j \quad (\text{HJB})$$

$$\mathbf{0} = (\boldsymbol{\Pi}^j)^T \boldsymbol{\phi}^j - \frac{\boldsymbol{\phi}^{j+1} - \boldsymbol{\phi}^j}{\Delta a} \quad (\text{KF})$$

where each $\boldsymbol{\Pi}^j$ is a **sparse** transition matrix (rows sum to one)

Finite difference approximations to $v'_n(x_i)$

- Approximate $v_n(a, x)$ at $I \times J$ discrete points in the state space, x_i , $i = 1, \dots, I$, and a_j , $j = 1, \dots, J$ with distance Δx and Δa between points, resp.
- Shorthand notation: $v_{i,n}^j := v_n(a_j, x_i)$
- Need to approximate $\partial_x v_n(a_j, x_i)$ and $\partial_a v_n(a_j, x_i)$
- **Three different possibilities:** written for x , analogous for a

$$\partial_x^F v_{i,n}^j := \frac{v_{i+1,n}^j - v_{i,n}^j}{\Delta x} \quad \text{forward difference}$$

$$\partial_x^B v_{i,n}^j := \frac{v_{i,n}^j - v_{i-1,n}^j}{\Delta x} \quad \text{backward difference}$$

$$\partial_x^C v_{i,n}^j := \frac{v_{i+1,n}^j - v_{i-1,n}^j}{2\Delta x} \quad \text{central difference}$$

Which to use? Always upwind!

- Best solution: **upwind scheme**

- **forward** difference whenever drift of state variable is **positive**
- **backward** difference whenever drift of state variable is **negative**

- Upwind version of HJB:

$$(\rho - \gamma)v_{i,n}^j = u_{i,n}^j + \partial_x^F v_{i,n}^j [h_{i,n}^j - \gamma x_i]^+ + \partial_x^B v_{i,n}^j [h_{i,n}^j - \gamma x_i]^- + \partial_a^F v_{i,n}^j + \lambda \sum_k \mu_{i,nk}^j [v_{i,k}^j - v_{i,n}^j]$$

with $y^+ = \max\{y, 0\}$ and $y^- = \min\{y, 0\}$ for any y

- **Complication:** drift $d_{i,n}^j \equiv h_{i,n}^j - \gamma x_i$ itself depends on which approx. is used

$$h_{i,n}^j = \kappa(\sigma_{i,n}^j) x_i^\beta X_n^{1-\beta}, \quad \text{where } \sigma_{i,n}^j \text{ is a function of } \partial_x v_{i,n}^j$$

- **Solution:** use $\sigma_{i,n}^{F,j}$ and $h_{i,n}^{F,j}$ when drift is positive; use $\sigma_{i,n}^{B,j}$ and $h_{i,n}^{B,j}$ when negative

Constructing the transition matrix Π^j

- Stack the discretized age- a_j value functions into a column vector of length NI

$$\mathbf{v}^j = [v_{1,1}^j, \dots, v_{I,1}^j, v_{1,2}^j, \dots, v_{I,2}^j, \dots, v_{1,N}^j, \dots, v_{I,N}^j]'$$

- Define the matrix entries

$$\pi_{i,n}^{B,j} = -\frac{(h_{i,n}^{B,j} - \gamma x_i)^-}{\Delta x}$$

$$\pi_{i,n}^{F,j} = \frac{(h_{i,n}^{F,j} - \gamma x_i)^+}{\Delta x}$$

$$\tilde{\pi}_{i,n}^j = -\pi_{i,n}^{F,j} + \pi_{i,n}^{B,j} - \lambda[1 - \mu_{i,n}^j \xi_{i,n}^j]$$

- Will be $NI \times NI$, block tri-diagonal, rows sum to one, very sparse

$$\tilde{\Pi}^j = \begin{bmatrix} \tilde{\pi}_1^j & \tilde{\mathbf{M}}_2^j & \tilde{\mathbf{M}}_3^j & \cdots & \tilde{\mathbf{M}}_N^j \\ \tilde{\mathbf{M}}_1^j & \tilde{\pi}_2^j & \tilde{\mathbf{M}}_3^j & \cdots & \tilde{\mathbf{M}}_N^j \\ \vdots & \tilde{\mathbf{M}}_2^j & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ \tilde{\mathbf{M}}_1^j & \tilde{\mathbf{M}}_2^j & \cdots & \tilde{\mathbf{M}}_{N-1}^j & \tilde{\pi}_N^j \end{bmatrix}$$

$$\mathbf{M}_n^j = \begin{bmatrix} \lambda\mu_{1,n}^j \xi_{1,n}^j & 0 & \cdots & \cdots & \cdots & 0 \\ 0 & \lambda\mu_{2,n}^j \xi_{2,n}^j & 0 & \ddots & \ddots & \vdots \\ \vdots & 0 & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & \cdots & \cdots & 0 & \lambda\mu_{I,n}^j \xi_{I,n}^j \end{bmatrix}$$

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Implicit method for HJB

- Solve HJB **iteratively** backwards from terminal condition $\mathbf{v}^J = \mathbf{0}$.
- Want to solve

$$(\rho - \gamma)\mathbf{v}^j = \mathbf{u}^{j+1} + \tilde{\boldsymbol{\Pi}}^{j+1}\mathbf{v}^j + \frac{\mathbf{v}^{j+1} - \mathbf{v}^j}{\Delta a} \text{ for } j = 1, \dots, J.$$

- **Implicit method:** the HJB can be written as

$$\begin{aligned} \mathbf{B}^{j+1}\mathbf{v}^j &= \mathbf{b}^{j+1}, \quad \text{where} \quad \mathbf{B}^{j+1} = \left(\frac{1}{\Delta a} + \rho - \gamma \right) \mathbf{I} - \tilde{\boldsymbol{\Pi}}^{j+1} \\ \mathbf{b}^{j+1} &= \mathbf{u}^{j+1} + \frac{1}{\Delta a} \mathbf{v}^{j+1}. \end{aligned}$$

which can be solved efficiently for \mathbf{v}^j with sparse matrix routines

Solving the KF equation

- Define Π^j as $\tilde{\Pi}^j$ without the correction terms (i.e., $\xi \equiv 1$)
- Recall the discretized, stacked KF equation + adding up for population:

$$\begin{aligned}\phi^{j+1} &= \left(\mathbf{I} - \Delta a (\Pi^j)' \right)^{-1} \phi^j \\ \frac{1}{A} &= \sum_i \phi_{i,1}^j \Delta x + \sum_i \phi_{i,2}^j \Delta x\end{aligned}$$

- We've already computed $\tilde{\Pi}^j$ to get the HJB, just need to correct and transpose
- Just solve directly for ϕ^{j+1} at **almost no extra cost!**
 - Iterate forward from $\phi^1 = \underline{\phi}$
- Renormalize ϕ^j if needed to ensure it adds to $1/A$

Reminder of algorithm (we just did steps 1 & 2 in depth)

- **Outer loop:** Guess growth rate γ , solve inner loop, update guess $\gamma(\sigma, \phi)$, repeat.
- **Inner loop:** Given γ , adapt the usual **HACT algorithm** (Achdou et al., 2022)
 0. Begin with guess $\{\mathbf{X}^0, \mathbf{p}^0\}$. Denote iterations by $\ell = 0, 1, 2, \dots$
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 3. Given $\phi_n^\ell(a, x)$, compute vibrancies and housing prices:

$$\tilde{X}_n^\ell = \iint x \phi_n^\ell(a, x) dx da, \quad \tilde{p}_n^\ell = p_n \left(\iint \phi_n^\ell(a, x) dx da \right)^\theta.$$

4. If $\{\tilde{\mathbf{X}}^\ell, \tilde{\mathbf{p}}^\ell\}$ close enough to $\{\mathbf{X}^\ell, \mathbf{p}^\ell\}$, **stop**. Else, construct $\{\mathbf{X}^{\ell+1}, \mathbf{p}^{\ell+1}\}$ as a linear combination of previous guess and computed values, then return to step 1.



Spatial scope: 378 MSAs, but smaller are grouped together

- all with 2010 Census pop. $> 2\text{mil}$ represented individually \rightarrow **30 MSAs**
(New York, Los Angeles, Chicago, ..., Cleveland, Kansas City)
- below, group by 500K \rightarrow **4 additional groups** (*finer partition in progress*)
- groups contain **copies** \rightarrow correct geography & pop. scale, miss within-group variation
- **why?** accord with later regressions from **Duranton and Puga (2022)**



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Congestion elasticity mapped to housing supply (**Saiz, 2010**)

- housing supply elasticity $= f(\text{land availability, land use regulations})$
- for groups: use pop.-weighted mean

Quantification: Determine migration params., $\{\lambda, \epsilon, \tau_{ni}\}$, using ACS data

2011–15 ACS Migration files count moves within/across MSAs cross-tabbed by age

- 5-year average of 1-year migration events, where we can see...
 1. % that didn't move, $1 - \lambda(a)$
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So, do the following:

- set $\lambda(a)$ to **match fraction that move by age group**
(decreasing from 26.6% \searrow 7.9% because marriage, family size, home ownership)
- set $\epsilon = 3$ from **Diamond (2016)** [w.r.t. real wages at decadal frequency]
- invert bilateral costs from flows using **Head-Ries index**:

$$\mu_{ni}(a, x) = \frac{\tau_{ni}^{-\epsilon} V_i(a, x)^\epsilon}{\sum_k \tau_{nk}^{-\epsilon} V_k(a, x)^\epsilon} \implies \frac{\bar{\mu}_{ni} \bar{\mu}_{in}}{\bar{\mu}_{nn} \bar{\mu}_{ii}} = \frac{\tau_{ni}^{-\epsilon} \tau_{in}^{-\epsilon}}{\tau_{nn}^{-\epsilon} \tau_{ii}^{-\epsilon}}$$

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- invert bilateral costs from flows using **Head-Ries index**:

$$\mu_{ni}(a, x) = \frac{\tau_{ni}^{-\epsilon} V_i(a, x)^\epsilon}{\sum_k \tau_{nk}^{-\epsilon} V_k(a, x)^\epsilon} \implies \frac{\bar{\mu}_{ni} \bar{\mu}_{in}}{\bar{\mu}_{nn} \bar{\mu}_{ii}} = \frac{\tau_{ni}^{-\epsilon} \tau_{in}^{-\epsilon}}{\tau_{nn}^{-\epsilon} \tau_{ii}^{-\epsilon}}$$

Targeting **mobility by age and avg. bilateral flows**, not $\mu_{ni}(a, x)$

Quantification: Set human capital investment params., $\{A, \rho, \beta, \eta, \underline{\phi}_n\}$



Key idea: Worker's investment problem nests Ben-Porath (1967) model

→ **calibrate to previous structural estimates** that used U.S. data

(Heckman, Lochner, and Taber, 1998; Browning, Hansen, and Heckman, 1999; Huggett, Ventura, and Yaron, 2006)

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Patterns matched:

- concentrate skill acquisition when young; steeper earnings profile if more schooling
- concavity of the cross-sectional earnings distribution across ages
- trends in mean earnings and earnings dispersion & skewness as the typical cohort ages

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Calibration:

- worker's horizon: $A=40$ (age 20–59) and $\rho=0.10$ (discount & IES)
- investment elasticities: $\beta=0.8$ and $\eta=0.7$
- initial human capital distribution, $\underline{\phi}_n$
 - *shape*: log-normal with coefficient of variation 0.468
 - *mean*: varies by HS ($x \approx 10$) vs. COL ($x \approx 13$) → weight by 2011–15 ACS college share
 - *mass*: match share of 15–19 year olds in 2010 ACS 1-year sample



Identify $\{\alpha, \zeta, x_{\text{scale}}\}$ by matching **wage panel regressions** from Duranton and Puga (2022)

$$\ln y_{nt}^j = \textcolor{brown}{a_n} + a_j + a_t + \sum_n \textcolor{brown}{b_n} e_{nt}^j + \mathbf{C}_t^j \mathbf{b} + \varepsilon_{nt}^j$$

Find that \hat{a}_n and \hat{b}_n are generally **increasing** in city size

Quantification: Minimum distance estimator, $\{\alpha, \zeta, x_{\text{scale}}, B_n, T_n, p_n, \bar{\kappa}\}$

Identify $\{\alpha, \zeta, x_{\text{scale}}\}$ by matching **wage panel regressions** from Duranton and Puga (2022)

$$\ln y_{nt}^j = \textcolor{brown}{a_n} + a_j + a_t + \sum_n \textcolor{brown}{b_n} e_{nt}^j + \mathbf{C}_t^j \mathbf{b} + \varepsilon_{nt}^j$$

Find that \hat{a}_n and \hat{b}_n are generally **increasing** in city size

1. Differential value of experience: pin down ζ

$$1.0114 = \frac{\hat{b}_{5\text{mil}}}{\hat{b}_{2\text{mil}}} = \underbrace{\left(\frac{X_{5\text{mil}}}{X_{2\text{mil}}} \right)^{1-\beta}}_{\text{model}} = \left(\frac{L_{5\text{mil}}^{\frac{1}{\zeta}} \bar{x}_{5\text{mil}, \zeta}}{L_{2\text{mil}}^{\frac{1}{\zeta}} \bar{x}_{2\text{mil}, \zeta}} \right)^{1-\beta}$$

2. IV of static city FE on city size: pin down α (can match directly without MDE)

$$\hat{a}_n = \alpha \ln L_n + \varepsilon_n$$

3. IV of medium-run city effect on city size: pin down x_{scale}

$$\hat{a}_n + \hat{b}_n \bar{e} = (\alpha + \zeta) \ln L_n + \varepsilon_n$$

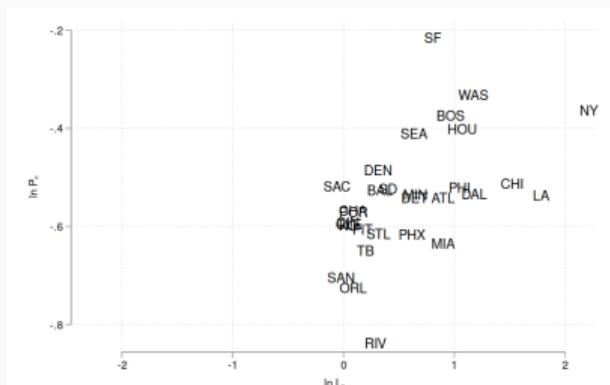
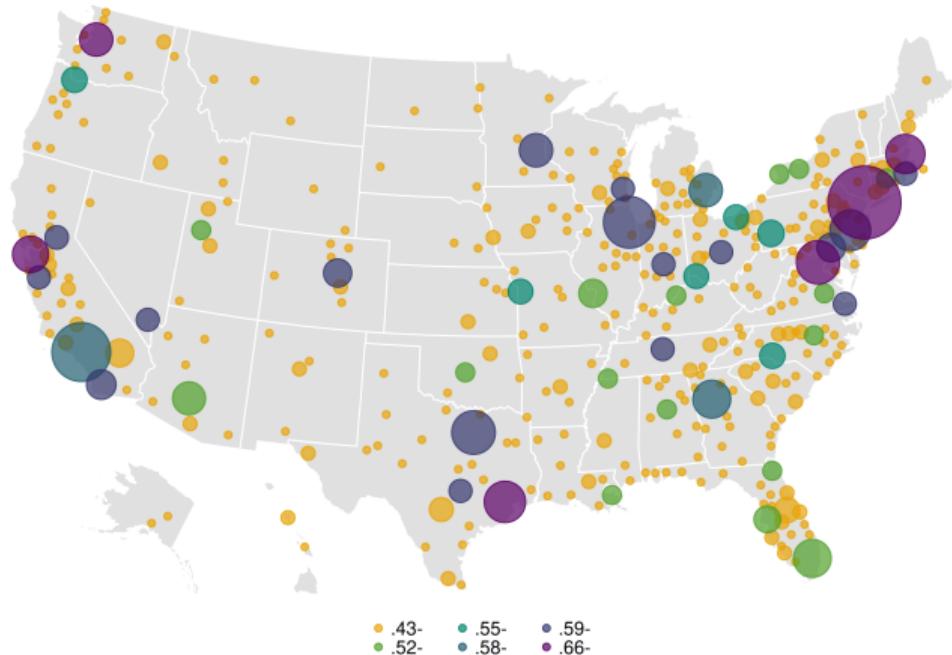


Remaining scales $\{B_n, T_n, p_n, \bar{\kappa}\}$ estimated to minimize distance between model and data for:

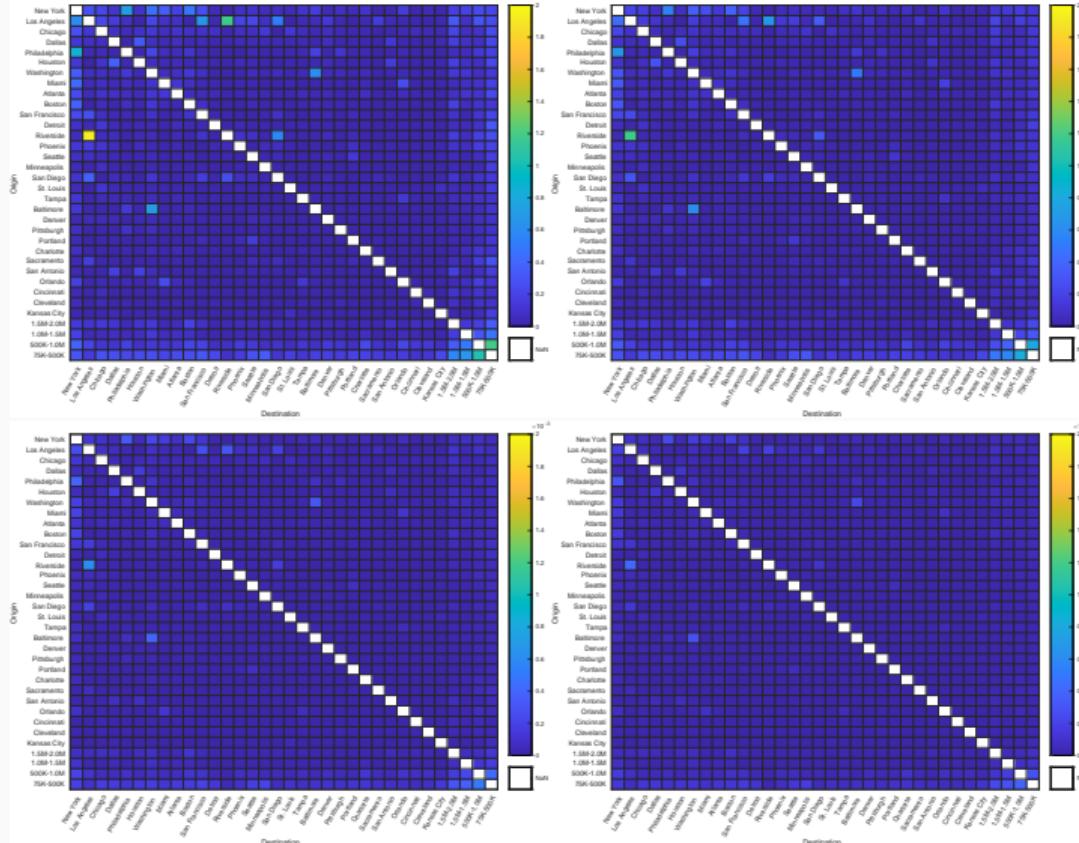
- total **employment** in each city per the 2013 BEA Regional Accounts
- the total **wage bill** in each city per the 2013 BEA Regional Accounts
- **constant local expenditure shares** across all cities ([Diamond, 2016](#))
- a **2%** annual growth rate

Able to **match exactly** even though cannot invert the model (solving ϕ nonparametrically)

City-level aggregates: Urban cost, $P_n = p_n L_n^{\theta_n}$



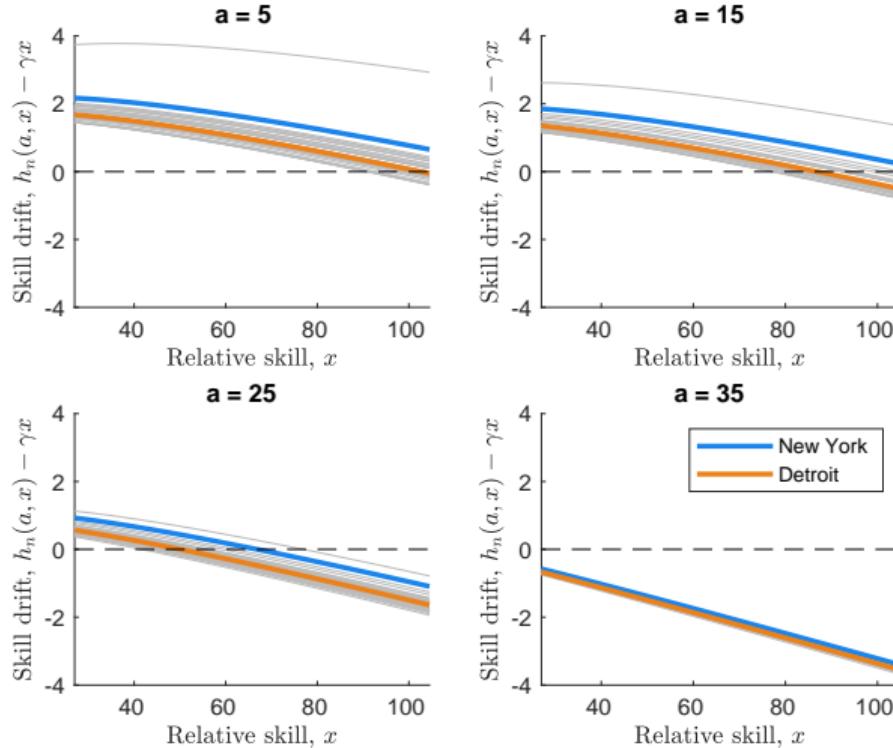
Optimal annual flows, $\lambda(a)\mu_{ni}(a, x)L_n(a)$



$$\mu_{ni}(a, x) = \frac{\tau_{ni}^{-\epsilon} v_i(a, x)^\epsilon}{\sum_k \tau_{nk}^{-\epsilon} v_k(a, x)^\epsilon}$$

- x (not shown): slight lean to **most vibrant cities**
 - supermodularity \rightarrow PAM (high x with high X_n)
- a : less mobility over time
 - always strong home bias (whited out)
 - when old, stop learning
 - just trade-off income vs. urban cost, both vs. τ_{ni}

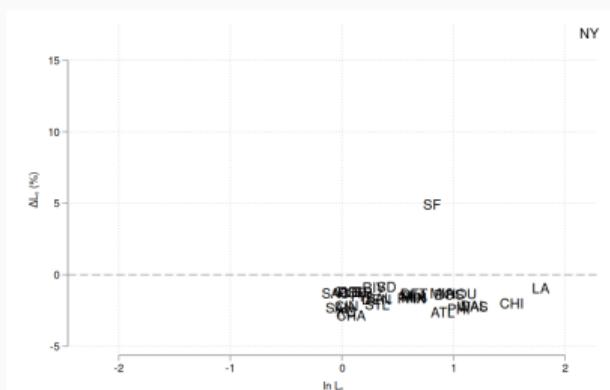
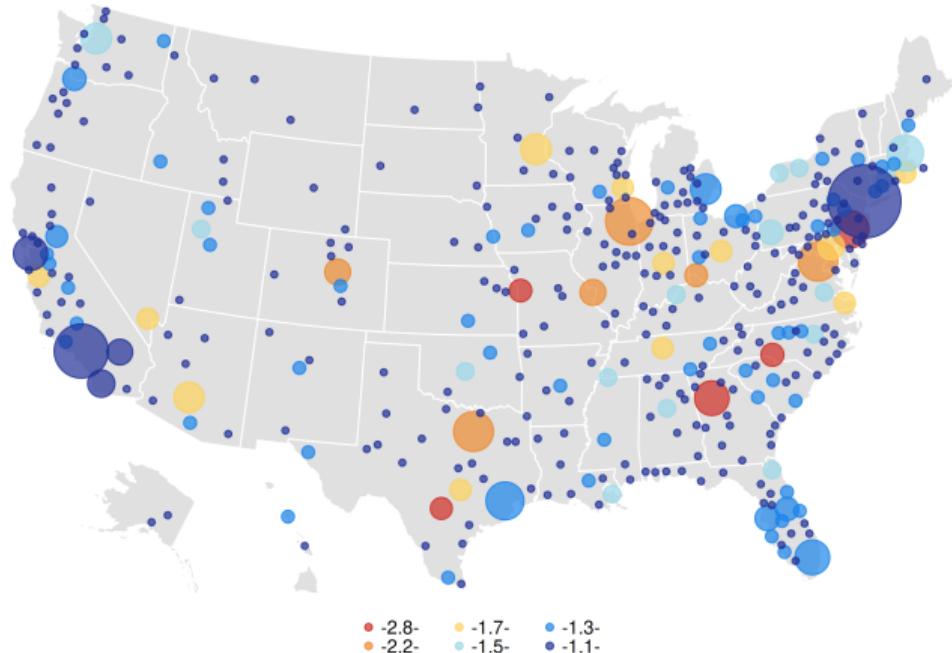
Optimal skill *drift*, $h_n(a, x) - \gamma x$



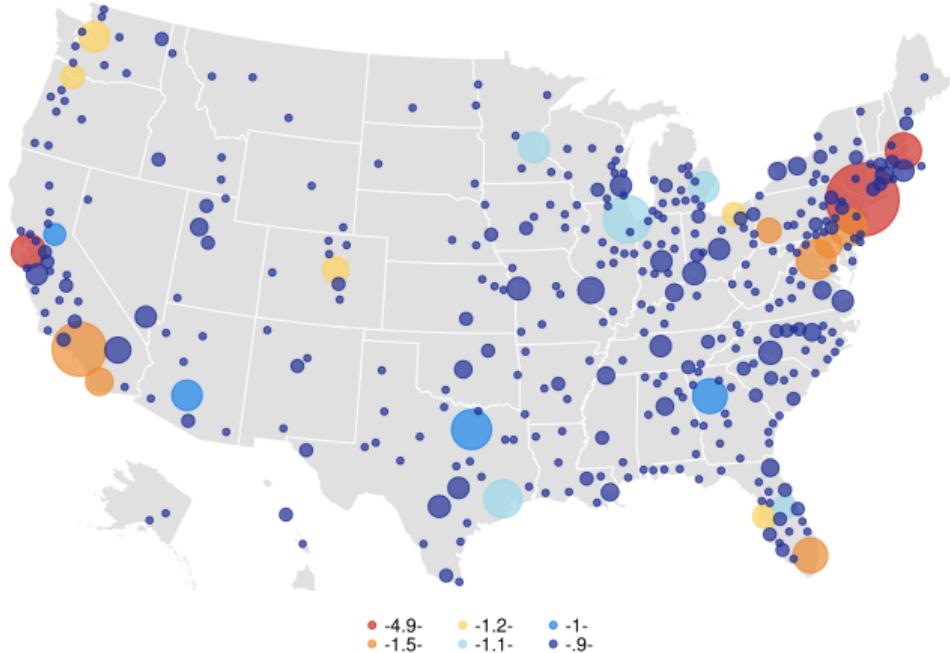
$$d_n(a, x) \equiv \kappa[\sigma_n(a, x)]x^\beta X_n^{1-\beta} - \gamma x$$

- x : decline w/ relative skill
 - a : decline w/ age (zero at A)
 - n : inherits from h_n
-
- $\arg_x d_n(a, x) = 0$ is a **sink**
 - density $\phi_n(a, x)$ has finite support if $d_n(a, x)$ has **single-crossing property** of zero in x for all n
→ don't need fat tail

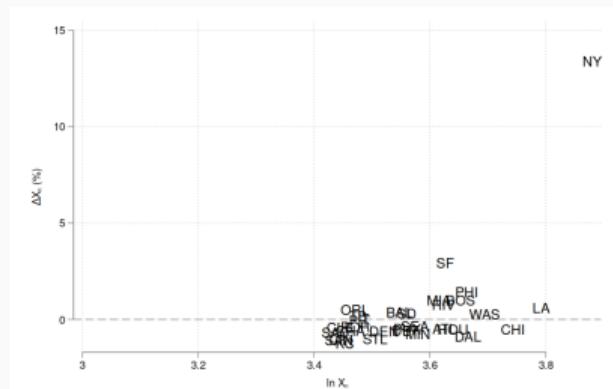
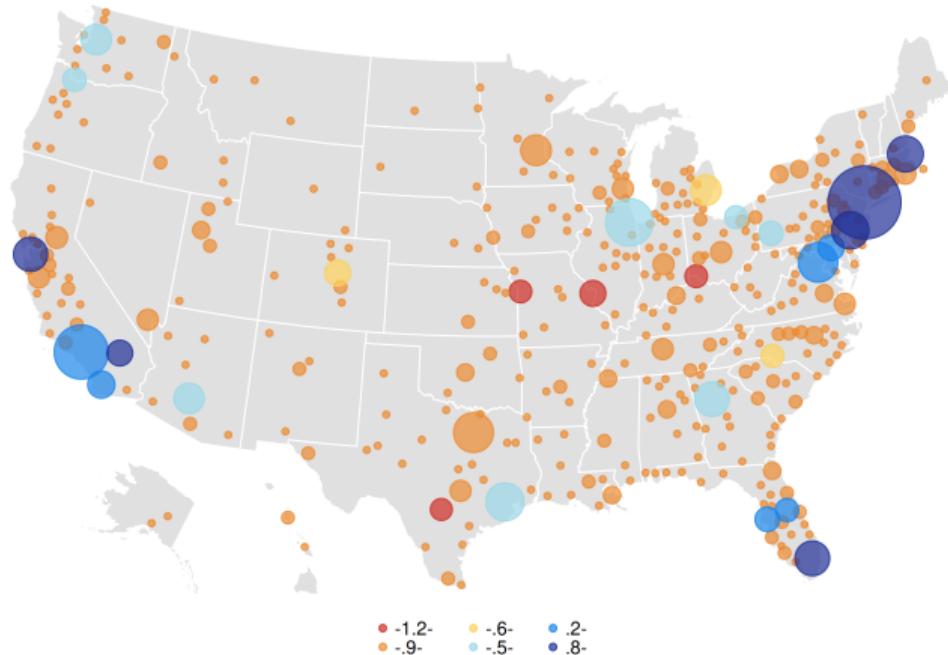
City-level aggregates: ΔL_n (%)



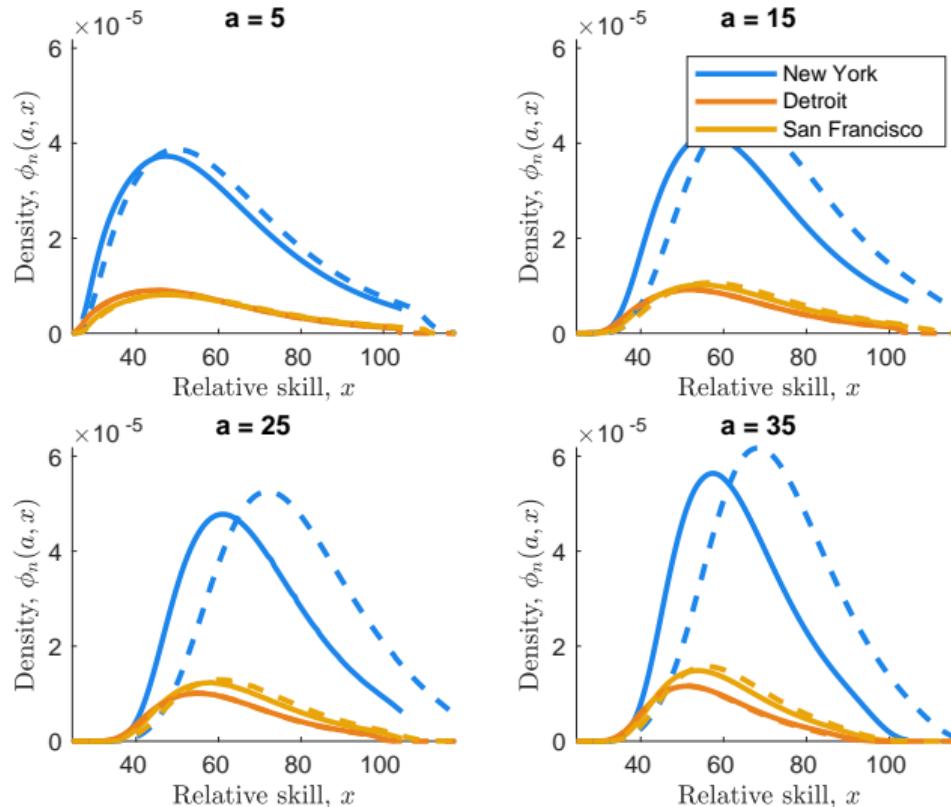
City-level aggregates: ΔP_n (%)



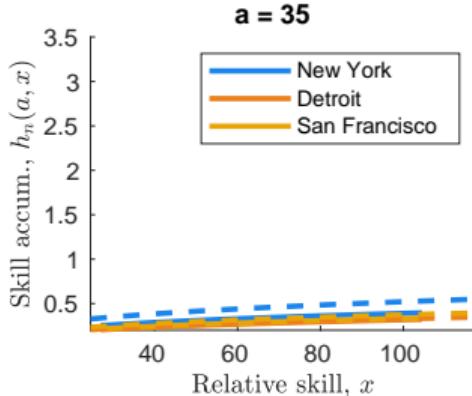
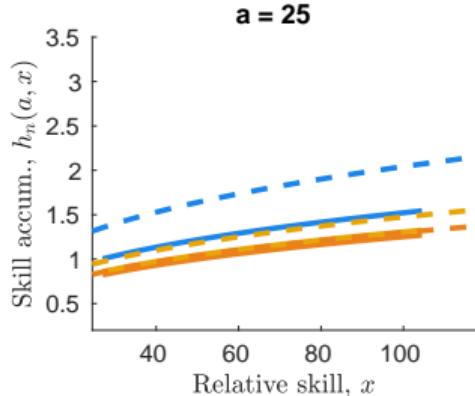
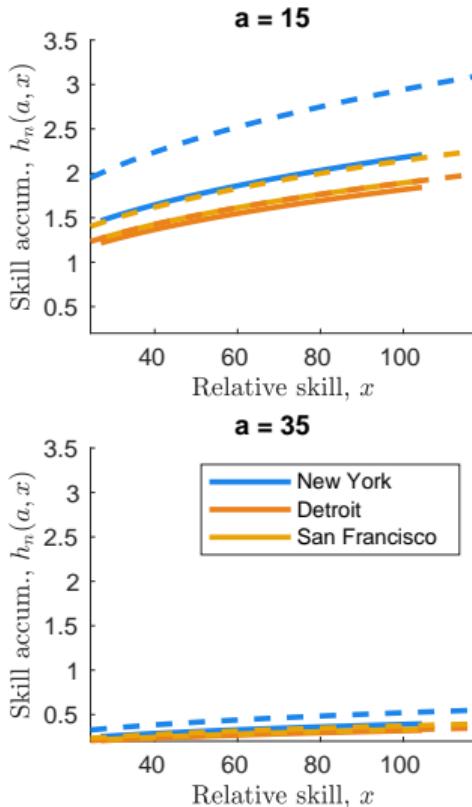
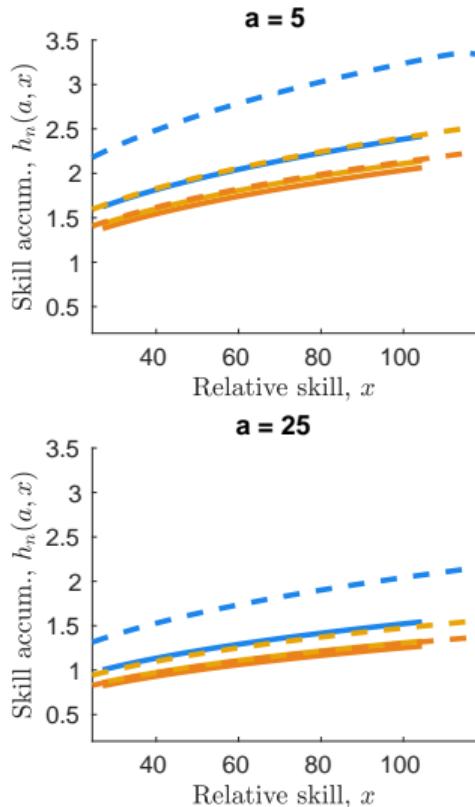
City-level aggregates: ΔX_n (%)



City-level distributions: NY and SF get more skilled, others change little



A new channel for spatial policy: *Produce, not just attract*, skill



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