Introduction to Data Processing and representation

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HW3

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Theory

1. Circulant Matrices

a. Considering the matrix $J = \begin{pmatrix} 0 & \cdots & \cdots & 0 & 1 \\ 1 & 0 & \ddots & \ddots & 0 \\ 0 & 1 & 0 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 1 & 0 \end{pmatrix} \in \mathbb{R}^{n \times n}$, we want to compute J^k ,

for $k \in \mathbb{N}$:

Let's check the behavior of I^k for k=2

$$J^{2} = J^{1} \cdot J = \begin{pmatrix} 0 & \cdots & \cdots & 0 & 1 \\ 1 & 0 & \ddots & \ddots & 0 \\ 0 & 1 & 0 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & \cdots & \cdots & 0 & 1 \\ 1 & 0 & \ddots & \ddots & 0 \\ 0 & 1 & 0 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & \cdots & \cdots & 1 & 0 \\ 0 & 0 & \ddots & \ddots & 1 \\ 1 & 0 & 0 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 1 & 0 & 0 \end{pmatrix}$$

As can be seen from the outcome above, we got matrix J with one cyclic shift of the rows downward or n-1 cyclic shifts of the rows upward. Thus for $k \in \mathbb{N}$ we get $J^k = j^{k-1}J$, meaning the result is matrix J with k-1 cyclic shifts of the rows downward. For k=n we get $J^n=j^{n-1}J$, meaning the result is matrix J with n-1 cyclic shifts of the rows downward or one cyclic shift of the rows upwards. The first row of J would be the n^{th} row of the outcome matrix now, after shifting all the rows we get

$$J^{n} = \begin{pmatrix} 1 & \cdots & \cdots & 0 & 0 \\ 0 & 1 & \ddots & \ddots & 0 \\ 0 & 0 & 1 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & 1 \end{pmatrix} = I_{n \times n}$$

This means, for k=n the result is the identity matrix of order n. J is called permutation matrix which means a square binary matrix that has exactly one entry of 1 in each row and each column and 0s elsewhere.

b. We want to compute the eigenvalues of J Using the definition, if there is a vector $V \in \mathbb{R}^n \neq 0$ such that $JV = \lambda V$

For some scalar λ , then λ is called the eigenvalues of J with corresponding eigenvector V.

This is equivalent to $(J - \lambda I)V = 0$, and nontrivial solution is available iff the determinant vanishes, so the solutions of $(J - \lambda I)V = 0$ are given by

$$\det(J - \lambda I) = 0$$

By applying the determinant of upper or lower triangular matrix is the product of all the diagonal elements of the matrix, we get

$$\det(I - \lambda I) = 0$$

$$\det(J - \lambda I) = \det\begin{pmatrix} -\lambda & \cdots & \cdots & 0 & 1\\ 1 & -\lambda & \ddots & \ddots & 0\\ 0 & 1 & -\lambda & \ddots & 0\\ \vdots & \ddots & \ddots & \ddots & \vdots\\ 0 & \cdots & 0 & 1 & -\lambda \end{pmatrix}$$

$$= -\lambda \cdot \det\begin{pmatrix} -\lambda & \cdots & 0 & 0\\ 1 & -\lambda & \ddots & 0\\ \vdots & \ddots & \ddots & \vdots\\ 0 & 0 & 1 & -\lambda \end{pmatrix} + (-1)^{n+1} \cdot 1 \cdot \det\begin{pmatrix} 1 & -\lambda & \cdots & 0\\ 0 & 1 & -\lambda & 0\\ \vdots & \ddots & \ddots & \vdots\\ 0 & \cdots & 0 & 1 \end{pmatrix}$$

$$= (-\lambda)^n + (-1)^{n+1}$$

$$\Rightarrow (-\lambda)^n + (-1)^{n+1} = 0$$

$$\Rightarrow \lambda^n = -(-1) = 1$$

Using the polar form, we denote λ by $\lambda = re^{i\theta}$, then we get

$$r^n e^{in\theta} = 1e^{i0}$$

$$r^n = 1 \Rightarrow r = 1$$

$$n\theta = 0 + 2\pi k \text{ for } k = 0,1,2,...,n-1$$

$$\theta = +\frac{2\pi k}{n} \text{ for } k = 0,1,2,...,n-1$$

 $\lambda^n = 1e^{i0}$

Since every $n \times n$ matrix has exactly n complex eigenvalues, we get that the n eigenvalues of J are given by:

$$\lambda_k = e^{i\frac{2\pi k}{n}}$$
 for $k = 0, 1, 2, ..., n - 1$

 To complete the eigendecomposition of J, we need to compute the corresponding eigenvectors of the previously computed eigenvalues in (b):
 We get

$$(J - \lambda_r I)V_r = 0$$
 for $r = 0, ..., n - 1$

$$\begin{pmatrix} -\lambda_r & \cdots & \cdots & 0 & 1\\ 1 & -\lambda_r & \ddots & \ddots & 0\\ 0 & 1 & -\lambda_r & \ddots & 0\\ \vdots & \ddots & \ddots & \ddots & \vdots\\ 0 & \cdots & 0 & 1 & -\lambda_r \end{pmatrix} \begin{pmatrix} v_{r_1}\\ v_{r_2}\\ v_{r_3}\\ \vdots\\ v_{r_n} \end{pmatrix} = 0$$

$$\begin{pmatrix} -\lambda_r v_{r_1} + v_{r_n} \\ -\lambda_r v_{r_2} + v_{r_1} \\ -\lambda_r v_{r_3} + v_{r_2} \\ \vdots \\ -\lambda_r v_{r_n} + v_{r_{n-1}} \end{pmatrix} = 0$$

For $v_{r_1}=1=\lambda_r^0$ (since eigenvectors are up to multiplication by a scalar), we get

$$\begin{cases} v_{r_1} = 1 \\ v_{r_2} = \lambda_r^{-1} \\ v_{r_3} = \lambda_r^{-2} \\ \vdots \\ v_{r_n} = \lambda_r^{-(n-1)} = \lambda_r^1 \end{cases}$$

Thus, we get

$$V_{1} = \begin{pmatrix} 1 \\ 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}, V_{2} = \begin{pmatrix} 1 \\ e^{-i\frac{2\pi}{n}} \\ e^{-i\frac{2\pi \cdot 2}{n}} \\ \vdots \\ e^{-i\frac{2\pi(n-1)}{n}} \end{pmatrix}, \dots, V_{n} = \begin{pmatrix} 1 \\ e^{-i\frac{2\pi(n-1)}{n}} \\ e^{-i\frac{2\pi(n-1) \cdot 2}{n}} \\ \vdots \\ e^{-i\frac{2\pi(n-1) \cdot (n-1)}{n}} \end{pmatrix}$$

Therefore, J is diagonalizable and can be decomposed to the form $I = PDP^{-1}$

Where P is a matrix composed of the eigenvectors of J, D is the diagonal matrix constructed from the corresponding eigenvalues and P^{-1} is the matrix inverse of P.

Thus, P is of the form

$$P = \begin{pmatrix} | & | & \dots & | \\ V_1 & V_2 & \dots & V_n \\ | & | & \dots & | \end{pmatrix}$$

And D is of the form

$$D = \begin{pmatrix} \lambda_0 & \cdots & \cdots & 0 & 0 \\ 0 & \lambda_1 & \ddots & \ddots & 0 \\ 0 & 0 & \lambda_2 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & \lambda_{n-1} \end{pmatrix}$$

We can diagonalize J in a unitary basis, since we can get U by normalizing the matrix P such that $U = \frac{1}{\sqrt{n}} P$ (eigenvectors are up to multiplication by a scalar), U is symmetric and unitary since its rows and columns obey

$$\sum_{l=0}^{n-1} U^{kl} (U^{rl})^* = \sum_{l=0}^{n-1} U^{(k-r)l} = \frac{1}{n} \sum_{l=0}^{n-1} e^{-\frac{i2\pi}{n}(k-r)l} = \begin{cases} 1 & k=r \\ 0 & k \neq r \end{cases}$$

and which makes the following statement true

$$U^*JU = \begin{pmatrix} \lambda_0 & \cdots & \cdots & 0 & 0 \\ 0 & \lambda_1 & \ddots & \ddots & 0 \\ 0 & 0 & \lambda_2 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 0 & \lambda_{n-1} \end{pmatrix}$$

d. Considering the general circulant matrix $H = \begin{pmatrix} n_0 & n_{n-1} & n_{n-2} & \cdots & n_1 \\ h_1 & h_0 & h_{n-1} & \ddots & h_2 \\ h_2 & h_1 & h_0 & \ddots & h_3 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ h_{n-1} & h_{n-2} & h_{n-3} & \cdots & h_0 \end{pmatrix}$.

And recalling that
$$J$$
 is given by $J=\begin{pmatrix} 0 & \cdots & \cdots & 0 & 1 \\ 1 & 0 & \ddots & \ddots & 0 \\ 0 & 1 & 0 & \ddots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & 1 & 0 \end{pmatrix} \in \mathbb{R}^{n\times n}.$

Using the results of (a) we get:

$$H = h_1 J + h_2 J^2 + \dots + h_{n-1} J^{n-1} + h_0 J^n = h_0 I_n + h_1 J + h_2 J^2 + \dots + h_{n-1} J^{n-1}$$

Thus, the polynomial P on matrix I is given by

$$P(J) = h_0 I_n + h_1 J + h_2 J^2 + \dots + h_{n-1} J^{n-1}$$

Therefore, H = P(J)

e. We got that H = P(J), by applying this we get that for all eigenvalue of matrix J, λ_k when k = 1, ..., n, $P(\lambda_k)$ is an eigenvalue of H with the same eigenvector. To see that we first show that if λ is an eigenvalue of matrix A then λ^k is the eigenvalue of the matrix A^k , since λ is the eigenvalue of A then $AV = \lambda V$ as V is the corresponding eigenvector. The eigenvalue of A^k is computed by

$$A^{k}V = A^{k-1}(AV) = A^{k-1}(\lambda V) = \lambda A^{k-1}V = \lambda A^{k-2}(AV) = \lambda^{2}A^{k-2}V = \dots = \lambda^{k}V$$

This result indicates that λ^k is the eigenvalue of A^k with the same eigenvector of the eigenvalue λ of A.

Now, let's compute the eigenvalues of H

$$HV_r = \left(\sum_{k=0}^{n-1} h_k J^k\right) V_r = \sum_{k=0}^{n-1} h_k (J^k V_r)$$

Using the results above, we get

$$\begin{split} HV_r &= \left(\sum_{k=0}^{n-1} h_k J^k\right) V_r = \sum_{k=0}^{n-1} h_k \big(J^k V_r\big) = \sum_{k=0}^{n-1} h_k \big(\lambda_r^k V_r\big) = \left(\sum_{k=0}^{n-1} h_k \lambda_r^k\right) V_r = P(\lambda_r) V_r \\ &= \lambda_{H_r} V_r \end{split}$$

Therefore, the eigenvalue λ_{H_r} of H with V_r as corresponding eigenvector is given by

$$\lambda_{H_r} = P(\lambda_r) = P\left(e^{i\frac{2\pi(r-1)}{n}}\right) = h_1 e^{i\frac{2\pi r}{n}} + h_2 e^{i\frac{2\pi r \cdot 2}{n}} + \dots + h_{n-1} e^{i\frac{2\pi r(n-1)}{n}} + h_0 \quad \text{for } r$$

$$= 0.1.2. \dots n-1$$

H is diagonalizable by the same unitary matrix $U=\frac{1}{\sqrt{n}}\begin{pmatrix} |&|&...&|\\V_1&V_2&...&V_n\\|&|&...&| \end{pmatrix}$ with the eigenvalues computed above, meaning it is diagonalizable in a unitary basis.

f. We want to show that the diagonalization basis matrix B can be chosen as the DFT^* matrix:

We saw earlier that H is diagonalizable in unitary basis using the basis matrix U. Since U is symmetric and each one of its elements is given by $W^{*kr} =$

 $e^{-rac{i2\pi}{n}kr}$ for $k,r=0,\ldots,n-1$, therefore its conjugate is the conjugate of the Discrete Fourier Transform matrix, given that H is diagonalizable using U and since U=DFT, we get

$$H = B\Lambda B^*$$

$$H = \overline{DFT^*\Lambda DFT} = \overline{DFT^*\Lambda DFT} = DFT\overline{\Lambda}DFT$$

$$H is real DFT is symmetric DFT is symmetric$$

In short, both the DFT and its complex conjugate can be chosen as the diagonalization basis matrix and it's up to the choice of the eigenvalues (we can choose them to be $\lambda_k = e^{-i\frac{2\pi k}{n}}$ for $k=0,1,2,\ldots,n-1$ or $\lambda_k = e^{i\frac{2\pi k}{n}}$ for $k=0,1,2,\ldots,n-1$).

g. Let B be the diagonalization basis matrix and let's denote $\sqrt{n}B=U$, then we get $U^*HU=\Lambda$

By applying matrix transpose operation on both sides and considering the symmetry of U and U^* and the fact that Λ is diagonal matrix, we get

$$(U^*HU)^T = \Lambda^T$$

$$\Rightarrow UH^TU^* = \Lambda$$

After multiplying both side by U from the right, we get

$$UH^{T} = \Lambda U$$

$$U\begin{pmatrix} h_{0} & h_{1} & h_{2} & \cdots & h_{n-1} \\ h_{n-1} & h_{0} & h_{1} & \cdots & h_{n-2} \\ h_{n-2} & h_{n-1} & h_{0} & \cdots & h_{n-3} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ h_{1} & h_{2} & h_{3} & \cdots & h_{0} \end{pmatrix}$$

$$=\begin{pmatrix} \lambda_0 & 0 & 0 & \cdots & 0 \\ 0 & \lambda_1 & 0 & \cdots & 0 \\ 0 & 0 & \lambda_3 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_{n-1} \end{pmatrix} \begin{pmatrix} 1 & 1 & 1 & \cdots & 1 \\ 1 & \lambda_1 & \lambda_2 & \cdots & \lambda_n \\ 1 & \lambda_1^2 & \lambda_2^2 & \cdots & \lambda_n^2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \lambda_1^{n-1} & \lambda_2^{n-1} & \cdots & \lambda_n^{n-1} \end{pmatrix}$$

Since both sides are equal, we get

$$\sqrt{n}B\begin{pmatrix}h_{0}\\h_{n-1}\\h_{n-2}\\\vdots\\h_{1}\end{pmatrix}=\begin{pmatrix}\lambda_{0} & 0 & 0 & \cdots & 0\\0 & \lambda_{1} & 0 & \cdots & 0\\0 & 0 & \lambda_{3} & \cdots & 0\\\vdots & \vdots & \vdots & \ddots & \vdots\\0 & 0 & 0 & \cdots & \lambda_{n-1}\end{pmatrix}\begin{pmatrix}1\\1\\1\\\vdots\\1\end{pmatrix}=\begin{pmatrix}\lambda_{0}\\\lambda_{1}\\\lambda_{2}\\\vdots\\\lambda_{n-1}\end{pmatrix}$$

Therefore, we get

$$\begin{pmatrix} \lambda_0 \\ \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_{n-1} \end{pmatrix} = \sqrt{n} B \begin{pmatrix} h_0 \\ h_{n-1} \\ h_{n-2} \\ \vdots \\ h_1 \end{pmatrix}$$

h. We want to show that given the two circulant matrices $H_1, H_2 \in \mathbb{R}^{n \times n}$, H_1 and H_2 commute, meaning $H_1H_2 = H_2H_1$:

Let B be the diagonalization basis matrix and let's denote $\sqrt{n}B = U$, hence $U^*HU = \Lambda$.

Let's assume the following

$$H_1 = U\Lambda_1 U^*$$

$$H_2 = U\Lambda_2 U^*$$

Then we get

$$H_1H_2 = U\Lambda_1U^*U\Lambda_2U^*$$

Since U is unitary matrix, we get $U^*U = I$, therefore

$$H_1 H_2 = U \Lambda_1 U^* U \Lambda_2 U^* = U \Lambda_1 \Lambda_2 U^*$$

Considering that Λ_1 and Λ_2 are diagonal matrices meaning they commute, we get

$$H_1H_2 = U\Lambda_1\Lambda_2U^* = U\Lambda_2\Lambda_1U^*$$

By using the fact $U^*U = I$ again we get

$$H_1H_2 = U\Lambda_2\Lambda_1U^* = U\Lambda_2U^*U\Lambda_1W^* = H_2H_1$$

Therefore, H_1 and H_2 commute.

 H_1H_2 is a circulant matrix, we show this using the results of section (d). We saw that H_1 and H_2 are given by polynomial expression of the matrix J, meaning

$$H_1 = P_1(J)$$

$$H_2 = P_2(J)$$

Hence,

$$H_1 H_2 = P_1(J) P_2(J) = \sum_{k=0}^{n-1} h_{1_k} J^k \sum_{r=0}^{n-1} h_{2_r} J^r = \sum_{k=0}^{n-1} \sum_{r=0}^{n-1} h_{1_k} h_{2_r} J^{k+r}$$

As we saw earlier, J^{k+r} is a circulant matrix, thus $h_{1_k}h_{2_r}J^{k+r}$ is a circulant matrix two, and since the outcome of adding two circulant matrices is also a circulant matrix we get that H_1H_2 is a circulant matrix too.

i. We want to compute DFT^k for $k \in \mathbb{N}$: Let's first check the behavior of DFT^k for k = 2, we get

$$DFT^{2} = \frac{1}{\sqrt{n}} \begin{pmatrix} w^{*0 \cdot 0} & w^{*1 \cdot 0} & w^{*2 \cdot 0} & \cdots & w^{*(n-1) \cdot 0} \\ w^{*0 \cdot 1} & w^{*1 \cdot 1} & w^{*2 \cdot 1} & \cdots & w^{*(n-1) \cdot 1} \\ w^{*0 \cdot 2} & w^{*2 \cdot 1} & w^{*2 \cdot 2} & \cdots & w^{*(n-1) \cdot 2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ w^{*0 \cdot (n-1)} & w^{*1 \cdot (n-1)} & w^{*2 \cdot (n-1)} & \cdots & w^{*(n-1) \cdot (n-1)} \end{pmatrix}$$

$$\cdot \frac{1}{\sqrt{n}} \begin{pmatrix} w^{*0 \cdot 0} & w^{*1 \cdot 0} & w^{*2 \cdot 0} & \cdots & w^{*(n-1) \cdot 0} \\ w^{*0 \cdot 1} & w^{*1 \cdot 1} & w^{*2 \cdot 1} & \cdots & w^{*(n-1) \cdot 1} \\ w^{*0 \cdot 2} & w^{*2 \cdot 1} & w^{*2 \cdot 2} & \cdots & w^{*(n-1) \cdot 2} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ w^{*0 \cdot (n-1)} & w^{*1 \cdot (n-1)} & w^{*2 \cdot (n-1)} & \cdots & w^{*(n-1) \cdot (n-1)} \end{pmatrix}$$

Hence,

$$DFT_{kr}^{2} = \frac{1}{n} \sum_{l=0}^{n-1} w^{*lk} w^{*rl} = \frac{1}{n} \sum_{l=0}^{n-1} e^{-\frac{i2\pi lk}{n}} e^{-\frac{i2\pi lr}{n}} = \frac{1}{n} \sum_{l=0}^{n-1} e^{-\frac{i2\pi l(k+r)}{n}} = \begin{cases} 1 & (k+r) \mod n = 0 \\ 0 & else \end{cases}$$

And we get

$$DFT^{2} = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & \vdots & \ddots & 1 \\ 0 & \vdots & 0 & \ddots & 0 \\ \vdots & 0 & 1 & \ddots & 0 \\ 0 & 1 & 0 & \cdots & 0 \end{pmatrix}$$

We notice that this is the vertically flipped form of J, let's denote it by FJ. Now for k=4 we get

$$DFT^{4} = DFT^{2} + DFT^{2} = \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & \vdots & \ddots & 1 \\ 0 & \vdots & 0 & \ddots & 0 \\ \vdots & 0 & 1 & \ddots & 0 \\ 0 & 1 & 0 & \cdots & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 0 & \vdots & \ddots & 1 \\ 0 & \vdots & 0 & \ddots & 0 \\ \vdots & 0 & 1 & \ddots & 0 \\ 0 & 1 & 0 & \cdots & 0 \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 0 & 0 & \cdots & 0 \\ 0 & 1 & 0 & \cdots & 0 \\ 0 & 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & 1 \end{pmatrix} = I_{n \times n}$$

To calculate DFT^3 we rely on the fact that $DFT \cdot DFT^* = I$, thus for k = 3 we get

$$DFT^3 = DFT^3 \cdot I = DFT^3 \cdot DFT \cdot DFT^* = DFT^4 \cdot DFT^* = I \cdot DFT^*$$

Relying on the results we got above, we can conclude that for $k \in \mathbb{N}$ DFT^k is given by:

$$DFT^{k} = \begin{cases} I_{n \times n} & k \bmod 4 = 0 \\ DFT & k \bmod 4 = 1 \\ FJ & k \bmod 4 = 2 \\ DFT^{*} & k \bmod 4 = 3 \end{cases}$$

j. We want to prove that a convolution of n-dimensional signals can be computed by point-wise multiplication of the signals in the Fourier domain, up to a normalization.

The convolution of x and y can be computed using a circulant matrix X built from x (the same as H by with the elements of x) then multiplying by y as follows

$$z = x \otimes y = Xy$$

We get

$$(DFT)z = (DFT)Xy$$

Considering $(DFT^*)(DFT) = I$ we get

$$(DFT)z = (DFT)Xy = (DFT)X(DFT^*)(DFT)y$$

Considering that $(DFT)X(DFT^*)$ is a diagonal matrix and hence symmetric, we get

$$(DFT)z = (DFT)Xy = (DFT)X(DFT^*)(DFT)y = (DFT^*)X(DFT) \cdot (DFT)y$$

Relying on the results of (g), we get

$$\sqrt{n}(DFT)y = \begin{pmatrix} \lambda_0^y \\ \lambda_1^y \\ \lambda_2^y \\ \vdots \\ \lambda_{n-1}^y \end{pmatrix}$$

$$(DFT)y = \frac{1}{\sqrt{n}} \begin{pmatrix} \lambda_0^y \\ \lambda_1^y \\ \lambda_2^y \\ \vdots \\ \lambda_{n-1}^y \end{pmatrix}$$

Therefore, we get

$$(DFT)z = (DFT^*)X(DFT)(DFT)y = \begin{pmatrix} \lambda_0^x & 0 & 0 & \cdots & 0 \\ 0 & \lambda_1^x & 0 & \cdots & 0 \\ 0 & 0 & \lambda_2^x & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_{n-1}^x \end{pmatrix} \begin{pmatrix} \lambda_0^y \\ \lambda_1^y \\ \lambda_2^y \\ \vdots \\ \lambda_{n-1}^y \end{pmatrix} =$$

$$\sqrt{n} \begin{pmatrix} \lambda_0^x \\ \lambda_1^x \\ \lambda_2^x \\ \vdots \\ \lambda_{n-1}^x \end{pmatrix} \odot \begin{pmatrix} \lambda_0^y \\ \lambda_1^y \\ \lambda_2^y \\ \vdots \\ \lambda_{n-1}^y \end{pmatrix} = \sqrt{n}(DFT)x \odot (DFT)y$$

2. Fourier Transform

a. f(t) and g(t) are two given functions, with convolution denoted by h(t) and given by

$$h(t) = f(t) * g(t)$$

We want to find f(t-1) * g(t+1) in terms of h(t)

We start by denoting $f(t-1) = \tilde{f}(t)$ and $g(t+1) = \tilde{g}(t)$, then we get

$$f(t-1) * g(t+1) = \tilde{f}(t) * \tilde{g}(t) = \int_{-\infty}^{\infty} \tilde{f}(\tilde{\tau}) \tilde{g}(t-\tilde{\tau}) d\tilde{\tau}$$
$$= \int_{-\infty}^{\infty} f(\tilde{\tau}-1) g(t-\tilde{\tau}+1) d\tilde{\tau} = \int_{-\infty}^{\infty} f(\tilde{\tau}-1) g(t-(\tilde{\tau}-1)) d\tilde{\tau}$$

By changing the integral variable $\tilde{\tau}$ by denoting $\tilde{\tau} - 1 = \tau$ and hence $d\tilde{\tau} = d\tau$, we get

$$f(t-1) * g(t+1) = \int_{-\infty}^{\infty} f(\tilde{\tau} - 1)g(t - (\tilde{\tau} - 1)) d\tilde{\tau} = \int_{-\infty}^{\infty} f(\tau)g(t - \tau) d\tau$$
$$= f(t) * g(t) = h(t)$$

b. f(t) and g(t) are two given functions, we want to show that the following condition holds

$$\int_{-\infty}^{\infty} f(t)g(-t) dt = \int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u) du$$

Where $\mathcal{F}(u)$ and $\mathcal{G}(u)$ are the Fourier transform of f(t) and g(t) respectively. We get

$$\int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u) du = \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} f(\tau)e^{-i2\pi u\tau} d\tau \int_{-\infty}^{\infty} g(\eta)e^{-i2\pi u\eta} d\eta \right) du$$

$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\tau) e^{-i2\pi u \tau} g(\eta) e^{-i2\pi u \eta} d\tau d\eta \right) du$$

$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\tau) g(\eta) e^{-i2\pi u (\tau + \eta)} d\tau d\eta \right) du$$

By changing the variables and denoting $\eta + \tau = t$, hence $\eta = t - \tau$ and $d\eta = dt$. We get

$$\int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u) du = \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\tau)g(\eta)e^{-i2\pi u(\tau+\eta)} d\tau d\eta \right) du$$

$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(\tau)g(t-\tau)e^{-i2\pi ut} d\tau dt \right) du$$

$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} e^{-i2\pi ut} dt \int_{-\infty}^{\infty} f(\tau)g(t-\tau) d\tau \right) du$$

 $\int_{-\infty}^{\infty} f(\tau)g(t-\tau)d\tau$ is the definition of convolution of the two functions f(t) and g(t), meaning

$$h(t) = f(t) * g(t) = \int_{-\infty}^{\infty} f(\tau)g(t - \tau)d\tau$$

Now we get

$$\int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u) du = \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} e^{-i2\pi u t} dt \int_{-\infty}^{\infty} f(\tau)g(t-\tau)d\tau \right) du$$
$$= \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} h(t)e^{-i2\pi u t} dt \right) du$$

 $\int_{-\infty}^{\infty} h(t)e^{-i2\pi ut}dt = H(u)$ is the Fourier transform of h(t), therefore we get

$$\int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u) du = \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} h(t)e^{-i2\pi ut} dt \right) du = \int_{-\infty}^{\infty} H(u) du = \int_{-\infty}^{\infty} H(u) e^{2\pi i u \cdot 0} du$$

 $\int_{-\infty}^{\infty} H(u) \, e^{2\pi i u \cdot 0} du$ is the projection of h(t=0) to the Fourier family, as seen in the lecture, or the inverse Fourier transform, also $h(t) = f(t) * g(t) = \int_{-\infty}^{\infty} f(\tau) g(t-\tau) d\tau$

Thus,
$$h(0) = \int_{-\infty}^{\infty} f(\tau)g(-\tau)d\tau = \int_{-\infty}^{\infty} f(t)g(-t)dt$$

$$\int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u)\,du = \int_{-\infty}^{\infty} H(u)\,e^{2\pi i u \cdot 0}du = h(0) = \int_{-\infty}^{\infty} f(t)g(-t)\,dt$$
 We got $\int_{-\infty}^{\infty} \mathcal{F}(u)\mathcal{G}(u)\,du = \int_{-\infty}^{\infty} f(t)g(-t)\,dt$ as required.

Question 3

a.
$$\phi^{F} = \sqrt{2N} \begin{bmatrix} \sum_{k=0}^{2N-1} W^{*k\cdot 0} \cdot \phi(k) \\ \sum_{k=0}^{2N-1} W^{*k\cdot 1} \cdot \phi(k) \\ \sum_{k=0}^{2N-1} W^{*k\cdot 2} \cdot \phi(k) \\ \vdots \\ \sum_{k=0}^{2N-1} W^{*k\cdot (2N-1)} \cdot \phi(k) \end{bmatrix} =$$

$$\sqrt{2N} \begin{bmatrix} W^{*0\cdot0} + \frac{W^{*0}}{2} + \frac{W^{*(2N-1)\cdot0}}{2} \\ W^{*0\cdot1} + \frac{W^{*1}}{2} + \frac{W^{*(2N-1)\cdot1}}{2} \\ W^{*0\cdot2} + \frac{W^{*2}}{2} + \frac{W^{*(2N-1)\cdot2}}{2} \\ \vdots \\ W^{*0\cdot(2N-1)} + \frac{W^{*(2N-1)}}{2} + \frac{W^{*(2N-1)\cdot(2N-1)}}{2} \end{bmatrix} =$$

$$\sqrt{2N} \begin{bmatrix} 1 + \frac{W^{*0}}{2} + \frac{W^{0}}{2} \\ 1 + \frac{W^{*1}}{2} + \frac{W^{1}}{2} \\ 1 + \frac{W^{*2}}{2} + \frac{W^{2}}{2} \\ \vdots \\ 1 + \frac{W^{*(2N-1)}}{2} + \frac{W^{(2N-1)}}{2} \end{bmatrix}$$

b. For $k \in [0, ..., 2N - 1]$:

$$\gamma^{F}(k) = \frac{1}{\sqrt{2N}} \cdot \sum_{n=0}^{2N-1} W_{2N}^{*n \cdot k} \cdot \gamma_{n} = \frac{1}{\sqrt{2N}} \cdot \sum_{n=0}^{N-1} W_{2N}^{*(2n) \cdot k} \cdot \psi_{n} = \frac{1}{\sqrt{2N}} \cdot \sum_{n=0}^{N-1} W_{N}^{*n \cdot k} \cdot \psi_{n} = \frac{1}{\sqrt{2}} \cdot \psi^{F}(k \pmod{N})$$

So:

$$\gamma^F = \frac{1}{\sqrt{2}} \cdot [\psi_0^F, \psi_1^F, \dots, \psi_{N-1}^F, \psi_0^F, \psi_1^F, \dots, \psi_{N-1}^F]^T$$

c. For $k \in [0, ..., 2N - 1]$:

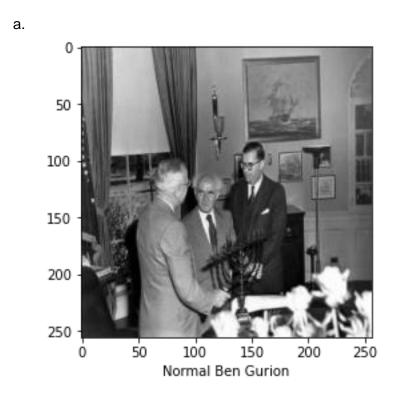
$$(\gamma * \phi)(k) = \sum_{m=0}^{2N-1} \phi(m) \cdot \gamma(k-m) = \sum_{m=0}^{2N-1} \phi(m) \cdot \gamma(k-m) = \phi(0) \cdot \gamma(k-0) + \phi(1) \cdot \gamma(k-1) + \phi(2N-1) \cdot \gamma(k-2N+1) = \gamma(k) + \frac{\gamma(k-1)}{2} + \frac{\gamma(k-1)}{2} + \frac{\gamma(k-2N+1)}{2} = \begin{cases} \psi\left(\frac{k}{2}\right), & k \text{ is even} \\ \frac{\psi\left(\frac{k-1}{2}\right)}{2} + \frac{\psi\left(\frac{k+1}{2}\right)}{2}, & k \text{ is odd} \end{cases}$$

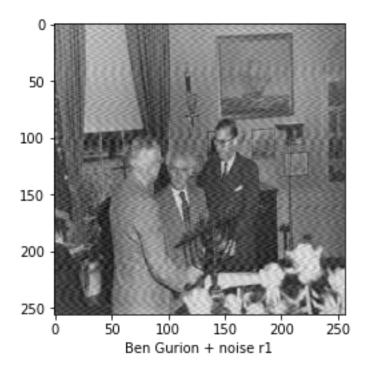
d. For $k \in [0, ..., 2N - 1]$:

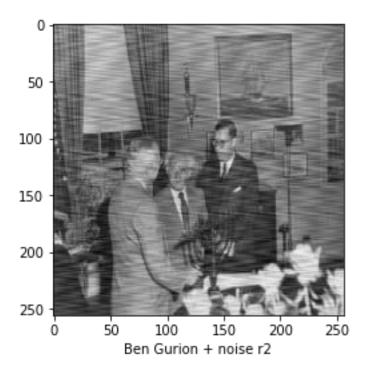
$$h^{F}(k) = \frac{1}{\sqrt{2N}} \cdot \sum_{n=0}^{2N-1} W_{2N}^{*n \cdot k} \cdot h_{n} = \frac{1}{\sqrt{2N}} \cdot \sum_{n=0}^{N-1} W_{2N}^{*(2n) \cdot k} \cdot \psi_{n} + \frac{1}{\sqrt{2N}} \cdot \sum_{n=0}^{N-1} W_{2N}^{*(2n+1) \cdot k} \cdot \frac{\psi_{n} + \psi_{n+1}}{2} = \frac{1}{\sqrt{2}} \cdot \psi^{F}(k \pmod{N}) + \frac{1}{\sqrt{8N}} \cdot \left(\sum_{n=0}^{N-1} W_{2N}^{*(2n+1) \cdot k} \cdot \psi_{n} + \cdot \sum_{n=0}^{N-1} W_{2N}^{*(2n+1) \cdot k} \cdot \psi_{n+1} \right) = \frac{1}{\sqrt{2}} \cdot \psi^{F}(k \pmod{N}) + \frac{1}{\sqrt{8N}} \cdot \left(W_{2N}^{*k} \sum_{n=0}^{N-1} W_{2N}^{*(2n) \cdot k} \cdot \psi_{n} + \frac{1}{W_{2N}^{*k}} \sum_{n=0}^{N-1} W_{2N}^{*(2n) \cdot k} \cdot \psi_{n} \right) = \frac{1}{\sqrt{2}} \cdot \psi^{F}(k \pmod{N}) + \frac{W_{2N}^{*k} + \frac{1}{W_{2N}^{*k}}}{\sqrt{8}} \cdot \left(\frac{1}{\sqrt{N}} \sum_{n=0}^{N-1} W_{2N}^{*(2n) \cdot k} \cdot \psi_{n} \right) = \frac{W_{2N}^{*k} + W_{2N}^{k} + 2}{\sqrt{8}} \cdot \psi^{F}(k \pmod{N})$$

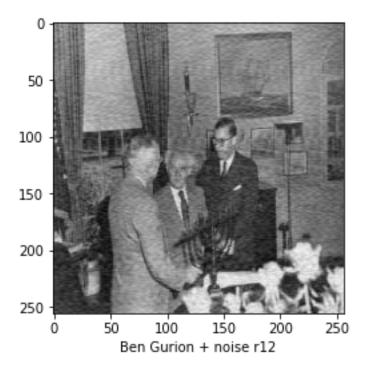


Implementation









b. We use the index t instead of i, so as not to confuse with the imaginary number i. We will define: $u = f \cdot n$.

$$\begin{split} \phi_{I_{t,j}^{noisy}}^{F} &= \phi_{I_{t}^{noisy}}^{F}(j) = \frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot I_{t}^{noisy}(k) = \\ &\frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot (I_{t}(k) + A_{t} \cdot \cos(2\pi f k + \varphi_{t})) = \\ &\frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot I_{t}(k) + \frac{1}{2\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot A_{t} \cdot \left(e^{\frac{i2\pi}{n} u k + i \varphi_{t}} + e^{-\frac{i2\pi}{n} u k - i \varphi_{t}} \right) = \\ &\frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot I_{t}(k) + \frac{1}{2\sqrt{n}} \sum_{k=0}^{n-1} A_{t} \cdot W^{*j \cdot k} \cdot \left(W^{u \cdot k} \cdot e^{i\varphi_{t}} + W^{-u \cdot k} \cdot e^{-i\varphi_{t}} \right) = \\ &\frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot I_{t}(k) + \frac{A_{t} e^{i\varphi_{t}}}{2\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{u \cdot k} + \frac{A_{t} e^{-i\varphi_{t}}}{2\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{-u \cdot k} \end{split}$$

For
$$\sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{u \cdot k}$$
:
If $u = j$:
 $\sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{u \cdot k} = \sum_{k=0}^{n-1} W^0 = n$

$$\sum_{k=0}^{n-1} W^{*J \cdot k} \cdot W^{u \cdot k} = \sum_{k=0}^{n-1} W^0 = n$$

$$\sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{u \cdot k} = \sum_{k=0}^{n-1} \left(W^{*j-u} \right)^k = \frac{\left(W^{*j-u} \right)^{n-1}}{\left(W^{*j-u} \right) - 1} = \frac{\left(W^{*n} \right)^{j-u} - 1}{\left(W^{*j-u} \right) - 1} = \frac{(1)^{j-u} - 1}{\left(W^{*j-u} \right) - 1} = 0$$

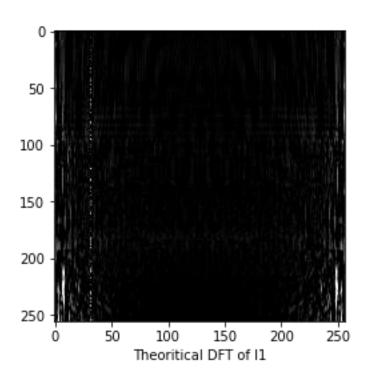
For
$$\sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{-u \cdot k}$$
:
If $u = -j$:

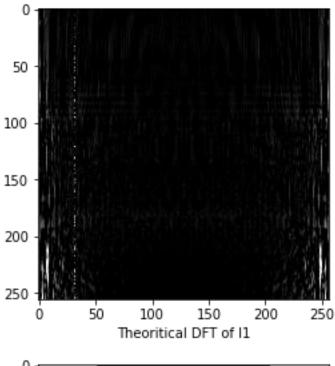
$$\begin{split} & \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{-u \cdot k} = \sum_{k=0}^{n-1} W^0 = n \\ & \text{Else:} \\ & \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot W^{-u \cdot k} = \sum_{k=0}^{n-1} \left(W^{*-j-u} \right)^k = \frac{\left(W^{*-j-u} \right)^{n} - 1}{\left(W^{*-j-u} \right) - 1} = \frac{(1)^{-j-u} - 1}{\left(W^{*-j-u} \right) - 1} = 0 \end{split}$$
 So:
$$& \phi_{I_{t,j}}^F = \\ & \frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot I_t(k) + \frac{A_t e^{i\phi_t \sqrt{n}}}{2} \cdot \delta_{j,f \cdot n} + \frac{A_t e^{-i\phi_t \sqrt{n}}}{2} \cdot \delta_{j,-f \cdot n} \end{split}$$

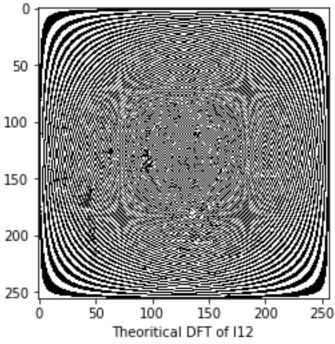
c. The weight of noise 1: w_1 ; The weight of noise 2: w_2

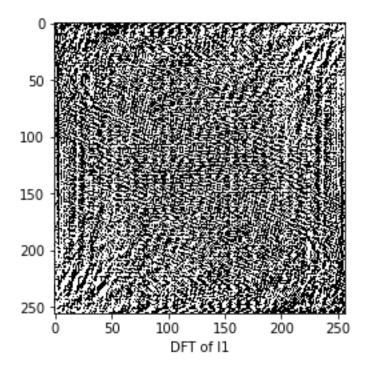
$$\begin{split} \phi^F_{I^{noisy}_{t,j}} &= \\ &\frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot \left(I_t(k) + \frac{w_1 \cdot A_t^{(1)} \cdot \cos\left(2\pi f^{(1)} k + \varphi_t^{(1)}\right)}{w_1 + w_2} + \frac{w_2 \cdot A_t^{(2)} \cdot \cos\left(2\pi f^{(2)} k + \varphi_t^{(2)}\right)}{w_1 + w_2} \right) = \\ &\frac{1}{\sqrt{n}} \sum_{k=0}^{n-1} W^{*j \cdot k} \cdot I_t(k) + \frac{w_1 A_t^{(1)} e^{i\varphi_t^{(1)}} \sqrt{n}}{2(w_1 + w_2)} \cdot \delta_{j,f^{(1)} \cdot n} + \frac{w_2 A_t^{(2)} e^{i\varphi_t^{(2)}} \sqrt{n}}{2(w_1 + w_2)} \cdot \delta_{j,f^{(2)} \cdot n} + \frac{w_1 A_t^{(1)} e^{-i\varphi_t^{(1)}} \sqrt{n}}{2(w_1 + w_2)} \cdot \delta_{j,-f^{(2)} \cdot n} \\ &\delta_{j,-f^{(1)} \cdot n} + \frac{w_2 A_t^{(2)} e^{-i\varphi_t^{(2)}} \sqrt{n}}{2(w_1 + w_2)} \cdot \delta_{j,-f^{(2)} \cdot n} \end{split}$$

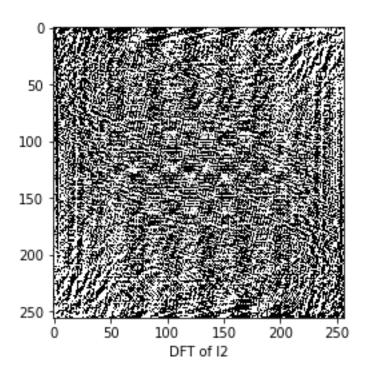
d.

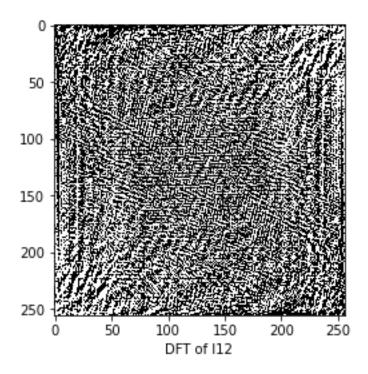












e.

MSE of I1 is: 2.7109850297764546 MSE of I2 is: 2.7002239091778053 MSE of I12 is: 359.91252877302543

