

Introduction to Data Processing and representation

236201

HW4

313511602

931190987



Theory

1)

a.

$$H = \begin{bmatrix} -5/2 & 4/3 & -1/12 & 0 & \dots & 0 & -1/12 & 4/3 \\ 4/3 & -5/2 & 4/3 & -1/12 & 0 & \dots & 0 & -1/12 \\ -1/12 & 4/3 & -5/2 & 4/3 & \ddots & 0 & \vdots & 0 \\ 0 & -1/12 & 4/3 & \ddots & \ddots & \ddots & 0 & \vdots \\ \vdots & 0 & \ddots & \ddots & \ddots & \ddots & \ddots & 0 \\ 0 & \vdots & 0 & \ddots & \ddots & \ddots & \ddots & -1/12 \\ -1/12 & 0 & \vdots & 0 & \ddots & \ddots & \ddots & 4/3 \\ 4/3 & -1/12 & 0 & \dots & 0 & -1/12 & 4/3 & -5/2 \end{bmatrix}$$

b.

H is a circulant matrix \rightarrow it is diagonalizable by the DFT matrix

$$H = [DFT]\Lambda[DFT]^*$$

The first row of H

$$H_0 = \begin{bmatrix} -5/2 \\ 4/3 \\ -1/12 \\ 0 \\ \vdots \\ 0 \\ -1/12 \\ 4/3 \end{bmatrix}$$

$$\Lambda = \sqrt{M} [DFT]^* H_0 = \begin{bmatrix} \sum_{l=0}^{M-1} W_M^{0l} H_0 \\ \sum_{l=0}^{M-1} W_M^{1l} H_0 \\ \vdots \\ \sum_{l=0}^{M-1} W_M^{(M-1)l} H_0 \end{bmatrix} = \begin{bmatrix} 0 \\ \sum_{l=0}^{M-1} W_M^{1l} H_0 \\ \vdots \\ \sum_{l=0}^{M-1} W_M^{(M-1)l} H_0 \end{bmatrix}$$

The rank of H is $M - 1$ as Λ_0 is the only zero eigenvalue.
Since H is a symmetric matrix all its eigenvalues are real.

The pseudo – inverse of H :

$$H^\dagger = [DFT] \Lambda^\dagger [DFT]^*$$

$$\text{and } \Lambda^\dagger = \text{diag}(\Lambda^\dagger) = \begin{bmatrix} 0 \\ 1 \\ \hline \sum_{l=0}^{M-1} W_M^{1l} H_0 \\ \vdots \\ 1 \\ \hline \sum_{l=0}^{M-1} W_M^{(M-1)l} H_0 \end{bmatrix}$$

c.

φ cannot perfectly recovered using the previously provided inverse filter because matrix H has a null space which is not invertible. Any signal that contains a component in the null space of H will be unrecoverable.

If we take, for example, a signal which is a scaled version of the eigenvector corresponding to the eigenvalue 0 (the first row of $[DFT]^*$) by a factor of $\alpha \neq 0$

$$\varphi_{\text{unrecoverable}} = \alpha \cdot \begin{bmatrix} W_M^0 \\ W_M^0 \\ \vdots \\ W_M^0 \end{bmatrix} = \begin{bmatrix} \alpha \\ \alpha \\ \vdots \\ \alpha \end{bmatrix}$$

Therefore,

$$H \cdot \varphi_{\text{unrecoverable}} = 0$$

$$\varphi_{\text{unrecoverable}} \neq H^\dagger \cdot H \cdot \varphi_{\text{unrecoverable}} = 0 \quad \forall \alpha \neq 0$$

2)

a.

The expected value of the $i_{th} \leq \frac{N}{2}$ component is :

$$\begin{aligned} E\{\varphi_i\} &= E\{\varphi_i|K=i\}P(K=i) + E\{\varphi_i|K \neq i\}P(K \neq i) = \\ &= E\{M + L_1\}P(K=i) + E\{M\}P(K \neq i) = \\ &= (E\{M\} + E\{L_1\})P(K=i) + E\{M\}P(K \neq i) = 0 \end{aligned}$$

The expected value of the $i_{th} > \frac{N}{2}$ component is :

$$\begin{aligned} E\{\varphi_i\} &= E\{\varphi_i|K=i\}P(K=i) + E\{\varphi_i|K \neq i\}P(K \neq i) = \\ &= E\{M + L_2\}P(K=i) + E\{M\}P(K \neq i) = \\ &= (E\{M\} + E\{L_2\})P(K=i) + E\{M\}P(K \neq i) = 0 \end{aligned}$$

→

The mean signal $E\{\varphi\} = 0$

b.

We will denote $r_{i,j}$ as the i, j element of $R_\varphi = E\{\varphi\varphi^T\}$

For $i \neq j$:

$$\begin{aligned}
r_{i,j} &= E\{\varphi_i, \varphi_j\} = \\
&= E\{\varphi_i, \varphi_j | K = i\}P(K = i) + E\{\varphi_i, \varphi_j | K = j\}P(K = j) + E\{\varphi_i, \varphi_j | K \neq i, j\}P(K \neq i, j) = \\
&= E\{(M + L)M\}P(K = i) + E\{M(M + L)\}P(K = j) + E\{M^2\}P(K \neq i, j)
\end{aligned}$$

$E\{M\} = E\{L\} = 0$ and M, L are independent \rightarrow

$$\begin{aligned}
r_{i,j} &= \left(E\{M^2\} + E\{M\}E\{L\}\right)P(K = i) + \left(E\{M^2\} + E\{M\}E\{L\}\right)P(K = j) + E\{M^2\}P(K \neq i, j) = \\
&= E\{M^2\}(P(K = i) + P(K = j) + P(K \neq i, j)) = \\
&= E\{M^2\} = c
\end{aligned}$$

For $i = j$:

$$\begin{aligned}
r_{i,i} &= \\
&= E\{\varphi_i^2 | K = i\}P(K = i) + E\{\varphi_i^2 | K \neq i\}P(K \neq i) = \\
&= E\{(M + L)^2\}P(K = i) + E\{M^2\}P(K \neq i) = \\
&= \left(E\{M^2\} + 2E\{M\}E\{L\} + E\{L^2\}\right)P(K = i) + E\{M^2\}P(K \neq i)
\end{aligned}$$

Splitting for $i \leq \frac{N}{2}, i > \frac{N}{2}$:

$$r_{i,i} = E\{M^2\} + \frac{E\{L_1^2\}}{N} = c + a \quad \text{for } i \leq \frac{N}{2}$$

$$r_{i,i} = E\{M^2\} + \frac{E\{L_2^2\}}{N} = c + b \quad \text{for } i > \frac{N}{2}$$

c.

For the PCA matrix to be DFT*, R_φ should be diagonalizable by the DFT*.

This will occur if and only if R_ϕ is circulant, and in this case it will happen if $a = b$.
Notably, c can be of any value.

3)

a.

We will denote $r_{i,j}$ as the i, j element of $R_\phi = E\{\phi\phi^T\}$

For $i \neq j, \left(j + \frac{N}{2}\right) \bmod N$:

$$\begin{aligned} r_{i,j} &= E\{\phi_i\phi_j\} = \\ &= E\{\phi_i\phi_j|K=i\}P(K=i) + E\{\phi_i\phi_j|K=j\}P(K=j) + E\{\phi_i\phi_j|K \neq i,j\}P(K \neq i,j) = \\ &= E\{(M+L)M\}P(K=i) + E\{(M+L)M\}P(K=j) + E\{M^2\}P(K \neq i,j) \end{aligned}$$

Since M, L are independent

$$r_{i,j} = \left(E\{M^2\} + E\{M\}E\{L\}\right)P(K=i) + \left(E\{M^2\} + E\{M\}E\{L\}\right)P(K=j) + E\{M^2\}P(K \neq i,j)$$

$$E\{M\} = 0 \quad \text{and} \quad E\{M^2\} = c \rightarrow$$

$$r_{i,j} = E\{M^2\}(P(K=i) + P(K=j) + P(K \neq i,j)) = E\{M^2\} = c$$

For $i = \left(j + \frac{N}{2}\right) \bmod N$:

$$\begin{aligned} r_{i,j} &= E\{\phi_i\phi_j\} = \\ &= E\{\phi_i\phi_j|K=i\}P(K=i) + E\{\phi_i\phi_j|K=j\}P(K=j) + E\{\phi_i\phi_j|K \neq i,j\}P(K \neq i,j) = \\ &= E\{(M+L)^2\}P(K=i) + E\{(M+L)^2\}P(K=j) + E\{M^2\}P(K \neq i,j) = \end{aligned}$$

$$= \left(E\{M^2\} + 2E\{M\}E\{L\} + E\{L^2\} \right) P(K = i) + \left(E\{M^2\} + 2E\{M\}E\{L\} + E\{L^2\} \right) P(K = j) + E\{M^2\} P(K \neq i, j)$$

$$E\{M\} = E\{L\} = 0 \rightarrow$$

$$r_{i,j} = E\{M^2\} + E\{L^2\} (P(K = i) + P(K = j))$$

$$\text{Since } i = \left(j + \frac{N}{2} \right) \bmod N \text{ and } K \sim \text{Uniform over the integers } \left\{ 1, \dots, \frac{N}{2} \right\} \rightarrow$$

$$\text{either } P\left(K = \left(j + \frac{N}{2} \right) \bmod N\right) = 0 \text{ or } P(K = j) = 0 \rightarrow$$

$$(P(K = i) + P(K = j)) = \frac{2}{N} \rightarrow$$

$$r_{i,j} = E\{M^2\} + E\{L^2\} (P(K = i) + P(K = j)) = c + \frac{N}{2}(1-c)\frac{2}{N} = 1$$

$$\text{For } i = j:$$

$$r_{i,j} = E\{\varphi_i \varphi_j\} =$$

$$= E\{\varphi_i^2 | K = i\} P(K = i) + E\{\varphi_i^2 | K \neq i\} P(K \neq i) =$$

$$= E\{(M + L)^2\} P(K = i) + E\{M^2\} P(K \neq i) =$$

$$= \left(E\{M^2\} + 2E\{M\}E\{L\} + E\{L^2\} \right) P(K = i) + E\{M^2\} P(K \neq i) =$$

$$= E\{M^2\} + E\{L^2\} P(K = i) =$$

$$= c + \frac{N}{2}(1-c)\frac{2}{N} = 1$$

$$r_{i,j} = r_{0,(j-i) \bmod N} \implies R_\varphi \text{ is a circulant matrix}$$

b.

R_φ is a symmetric circulant matrix \rightarrow its eigenvalues are real and its eigenvectors are the columns of the DFT.

We will examine the i element of vector v_j (the j -th column of DFT), W_N^{ij}

$$(R_\varphi \cdot v_j)_i = c \sum_{k=0}^{N-1} W^{k,j} - c \left(W^{i,j} + W^{i+\frac{N}{2},j} \right) + 1 \cdot \left(W^{i,j} + W^{i+\frac{N}{2},j} \right) =$$

$$= c \sum_{k=0}^{N-1} W^{k,j} + (1-c) \left(W^{i,j} + W^{i+\frac{N}{2},j} \right)$$

$$\begin{aligned} &= cN + (1-c)(1+1) = 2 + cN - 2c, & j = 0 \\ &0, & j \text{ is odd} \\ &(1-c) \cdot 2W^{i,j}, & j \text{ is even } j \neq 0 \end{aligned}$$

When we multiply the matrix row with the eigenvector, we multiply all entries of the eigenvector by c besides two entries which we multiply by 1.

For $j = 0$, meaning the first row of the DFT (a vector of 1's), we get that each of the output vector is $2 + cN - 2c$, meaning that the eigenvalue is that.

For $j \neq 0$, the sum in the expression evaluates to zero, and we are left with the right part of the expression.

As N is even :

For odd J , $W^{i,j} = -W^{i+\frac{N}{2},j} \rightarrow$ the entire expression is zero

For even J , $W^{i,j} = W^{i+\frac{N}{2},j} \rightarrow$ we get that each entry is $2(1-c)$ times the entry in the eigenvector.
 \implies

The vector has one eigenvalue of $2 + cN - 2c$, $\frac{N}{2}$ zero eigenvalues

and $\left(\frac{N}{2} - 1 \right)$ eigenvalues of $2(1-c)$.

4)

(a)

$$\varphi^* = \mathbf{H}\varphi + n$$

The correletion matrix of φ^*

$$\begin{aligned} R_{\varphi^*} &= E\left\{\varphi^* \varphi^{*T}\right\} = \\ &= E\{(\mathbf{H}\varphi + n)(\mathbf{H}\varphi + n)^T\} = \\ &= E\left\{(\mathbf{H}\varphi + n)(\varphi^T \mathbf{H}^T + n^T)\right\} = \\ &= E\left\{\mathbf{H}\varphi\varphi^T \mathbf{H}^T + \mathbf{H}\varphi n^T + n\varphi^T \mathbf{H}^T + nn^T\right\} = \\ &= \mathbf{H}R_{\varphi} \mathbf{H}^T + \mathbf{H}E\left\{\varphi n^T\right\} + E\left\{n\varphi^T\right\} \mathbf{H}^T + R_n \end{aligned}$$

The noise and random signal are independent \rightarrow

$$E\left\{\varphi n^T\right\} = E\left\{n\varphi^T\right\} = 0 \rightarrow$$

$$\boxed{R_{\varphi^*} = \mathbf{H}R_{\varphi} \mathbf{H}^T + R_n}$$

(b)

$$R_n = \sigma_n^2 I \text{ where } \sigma_n > 0 \rightarrow$$

$$R_{\varphi^*} = \mathbf{H}R_{\varphi} \mathbf{H}^T + R_n = \mathbf{H}R_{\varphi} \mathbf{H}^T + \sigma_n^2 I$$

R_{φ} is positive semi-definite matrix $\rightarrow \mathbf{H}R_{\varphi} \mathbf{H}^T$ is also positive semi-definite matrix

Since $\sigma_n > 0 \rightarrow \sigma_n^2 I$ is positive definite matrix

\rightarrow

R_{φ^*} is positive definite as it the sum of

positive semi-definite matrix $(\mathbf{H}R_\varphi\mathbf{H}^T)$ and positive definite matrix $(\sigma_n^2 I) \rightarrow R_{\varphi^*}$ is invertible matrix

$$W_{filter} R_{\varphi^*} = R_\varphi \mathbf{H}^T$$

$$W_{filter} (\mathbf{H}R_\varphi\mathbf{H}^T + \sigma_n^2 I) = R_\varphi \mathbf{H}^T \rightarrow$$

$$W_{filter} = R_\varphi \mathbf{H}^T (\mathbf{H}R_\varphi\mathbf{H}^T + \sigma_n^2 I)^{-1} = R_\varphi \mathbf{H}^T R_{\varphi^*}^{-1}$$

Ⓒ

$$A = [DFT]\Lambda[DFT]^*$$

$$a_{i,j} = \sum_{k=0}^{N-1} W_N^{-ik} \cdot \lambda_k \cdot W_N^{kj} = \sum_{k=0}^{N-1} \lambda_k \cdot W_N^{k(j-i)}$$

$$\text{By definition } W_N^l = W_N^{(l) \bmod N} \rightarrow$$

$$a_{i,j} = \sum_{k=0}^{N-1} \lambda_k \cdot W_N^{k(j-i)} = \sum_{k=0}^{N-1} W_N^{-0k} \cdot \lambda_k \cdot W_N^{k((j-i) \bmod N)} = a_{0,(j-i) \bmod N} \rightarrow$$

A is a circulant matrix

Ⓓ

A system is shift invariant if and only if the system matrix is a circulant matrix (was shown in class). For example, if we take

$$R_\varphi = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$$

$$\mathbf{H} = I$$

$$\sigma_n = 1$$

$$\begin{aligned}
W_{filter} &= R_\varphi \mathcal{H}^T (\mathcal{H} R_\varphi \mathcal{H}^T + \sigma_n^2 I)^{-1} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot I \cdot \left(I \cdot \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot I + I \right)^{-1} = \\
&= \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot \begin{bmatrix} 2 & 2 \\ 3 & 5 \end{bmatrix}^{-1} = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \cdot \frac{1}{4} \cdot \begin{bmatrix} 5 & -2 \\ -3 & 2 \end{bmatrix} = \frac{1}{4} \begin{bmatrix} -1 & 2 \\ 3 & 2 \end{bmatrix} \rightarrow W_{filter} \text{ is not a circulant matrix}
\end{aligned}$$

⑨

Let A, B be circulant matrices.

if A, B circulant matrices \rightarrow A^* and B^* circulant matrices

$$A^{-1} = ([DFT] \Lambda_A [DFT]^*)^{-1} = [DFT] \Lambda_A^{-1} [DFT]^* \rightarrow \text{ A^{-1} is a circulant matrix}$$

$$AB = [DFT] \Lambda_A [DFT]^* \cdot [DFT] \Lambda_B [DFT]^* = [DFT] \Lambda_A \Lambda_B [DFT]^* \rightarrow \text{ AB is a circulant matrix}$$

$$A + B = [DFT] \Lambda_A [DFT]^* + [DFT] \Lambda_B [DFT]^* = [DFT] (\Lambda_A + \Lambda_B) [DFT]^* \rightarrow \text{ $A + B$ is a circulant matrix}$$

$$\text{ $\sigma_n^2 I$ is a circulant matrix for every constant σ_n } \implies$$

If R_φ and \mathcal{H} are circulant, $W_{filter} = R_\varphi \mathcal{H}^T (\mathcal{H} R_\varphi \mathcal{H}^T + \sigma_n^2 I)^{-1}$ is a circulant as combination of operators preserving circulant property.

Introduction to Data Processing and Representation

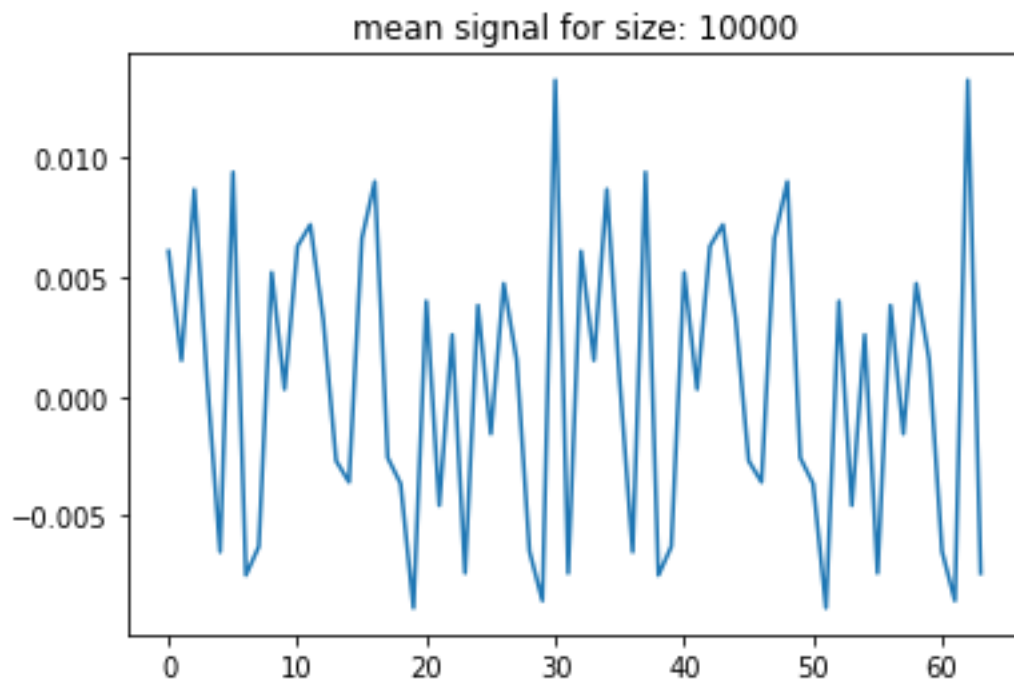
Implementation



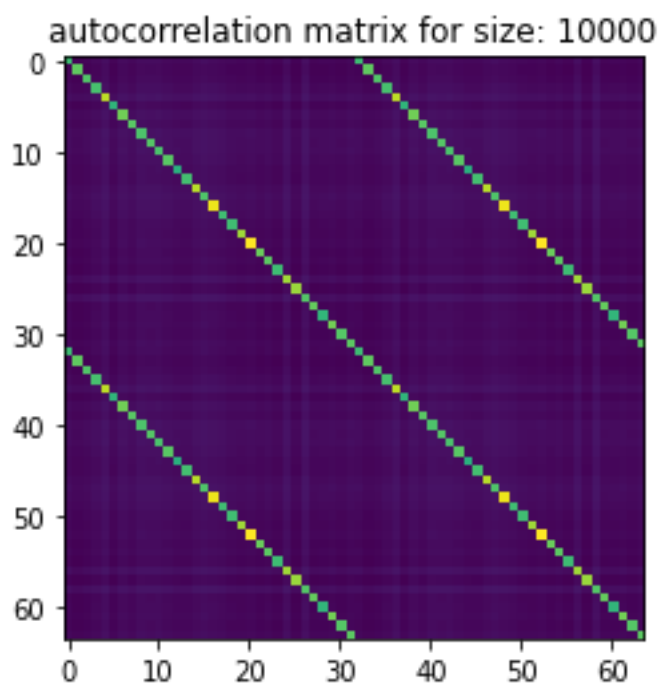
1)

a.

The empirical approximation of the mean signal:



And the empirical autocorrelation matrix is:

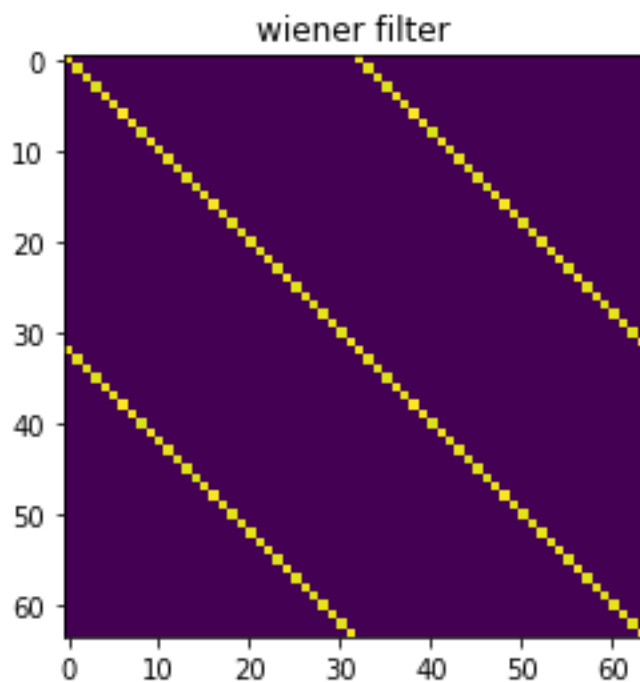


As we can see this sits fine with our solution at the third exercise because we are getting a circulant matrix with all entries equal to $c=0.6$ except for three diagonals which get 1. Moreover the empirical mean signal is very close to 0 as we computed in the third exercise.

The number of realizations we used was 10000, because we managed to approximate the empirical results well with this amount of realizations.

b.

The Wiener Filter matrix we got:



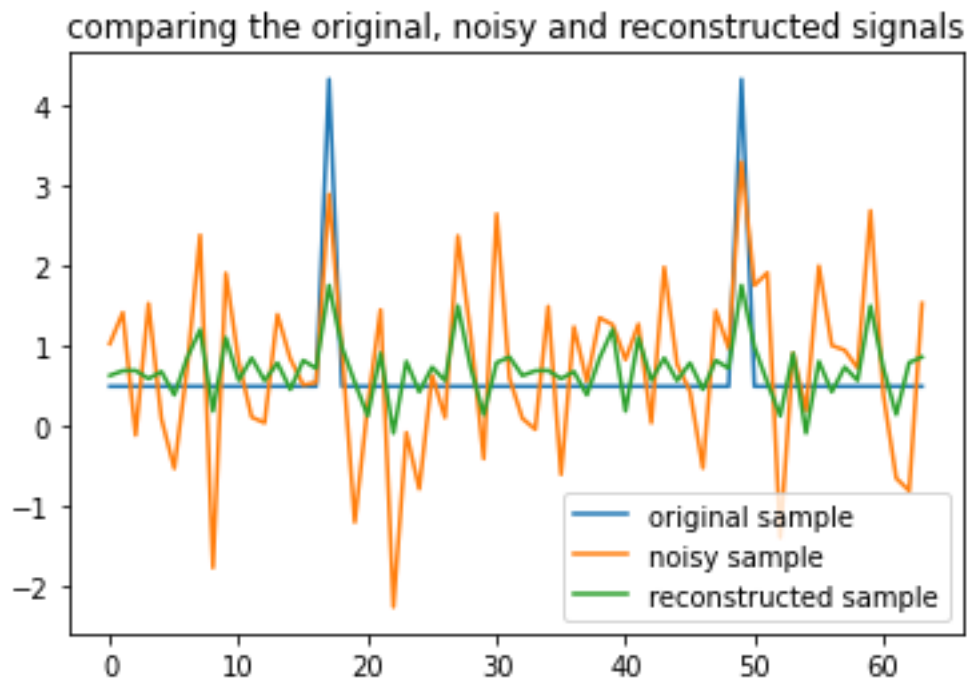
The structure is circulant and like the structure of the autocorrelation matrix as expected. This is from the formulae:

$$W = R_{\phi} H^T (H R_{\phi} H^T + (\sigma_n)^2 I)^{-1}$$

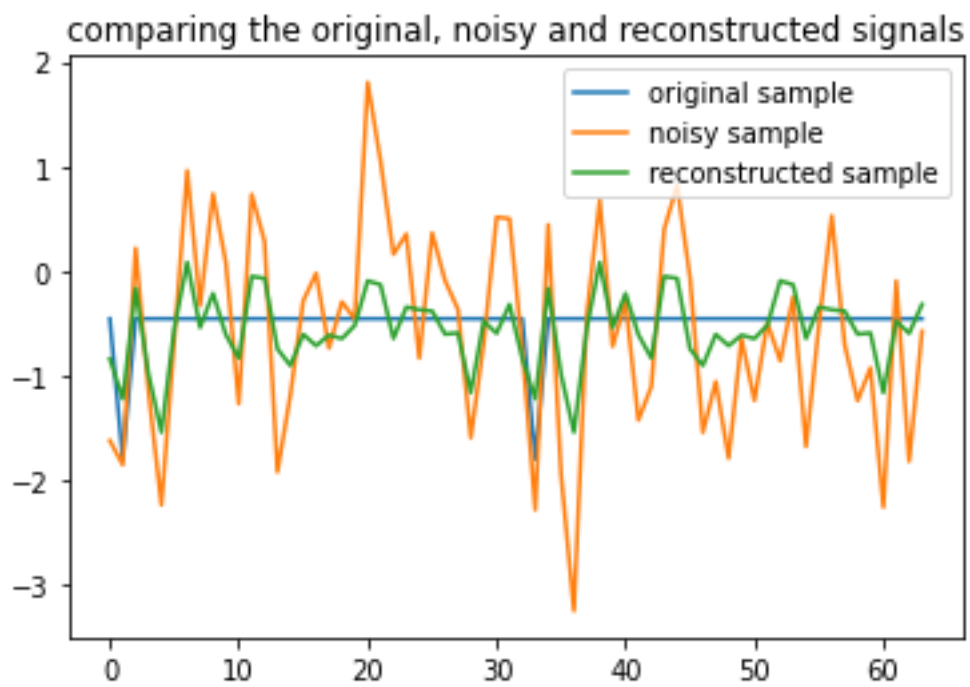
Whereas in our case $H = I$. Because R_{ϕ} and I are circulant we get that W is circulant.

Afterwards we denoised our noisy signals with the Wiener filter.

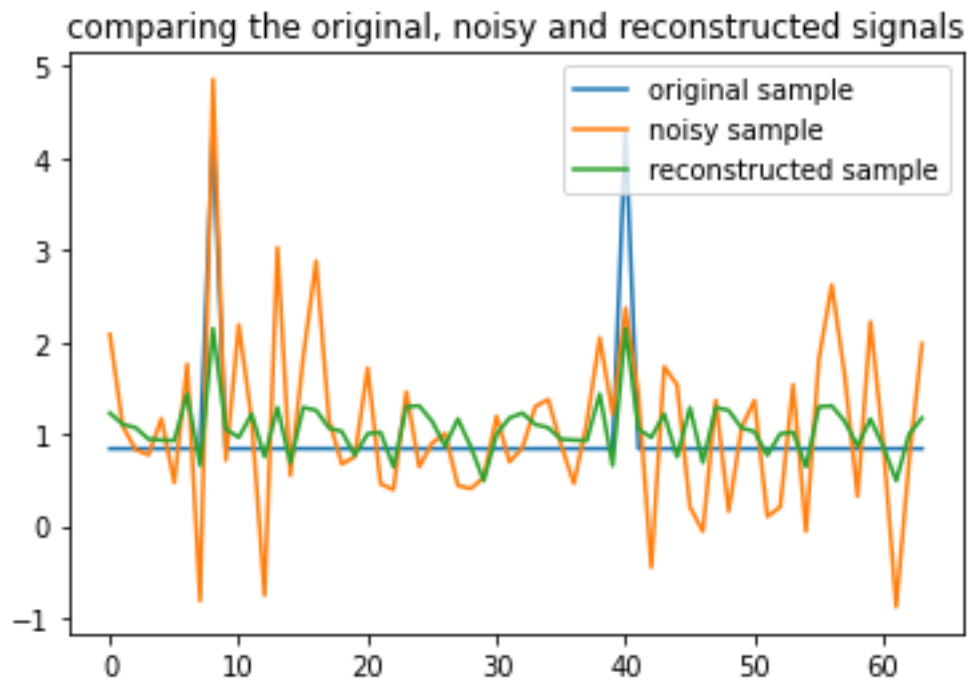
Some of the signals attached:



the mse for sample: 71 is: 0.33402077435404637



the mse for sample: 308 is: 0.1305365394581765

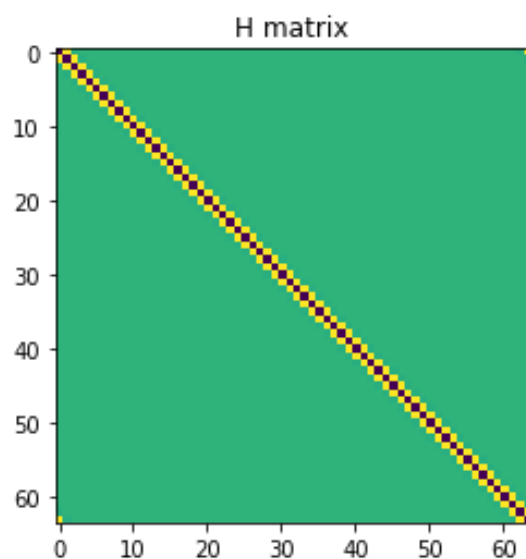


the mse for sample: 4007 is: 0.22276866744094342

As we can see we managed to denoise the signals well, but not to the point of $MSE=0$. For each denoise realization, we computed the MSE with respect to the clean version of the same realization and averaged all the values. The average MSE that we got was 0.22932

c.

Here we present the matrix H:

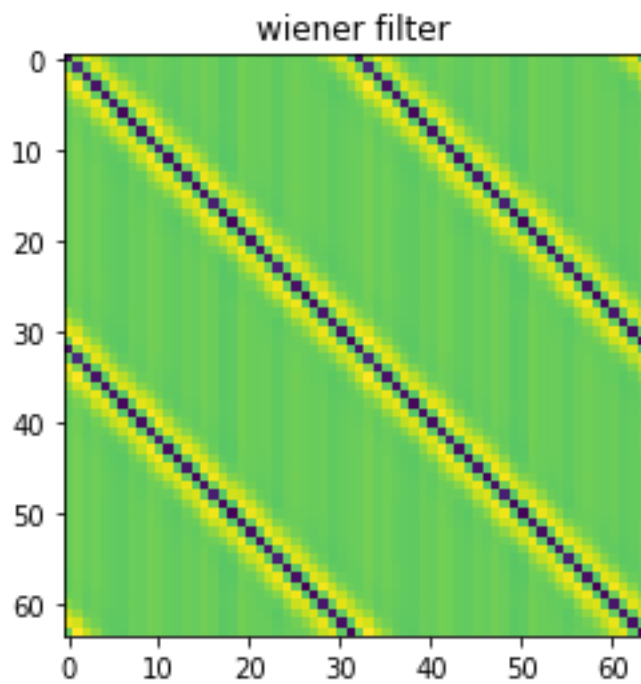


The autocorrelation matrix doesn't change.

The Wiener filter for this problem is again computed by the formulae:

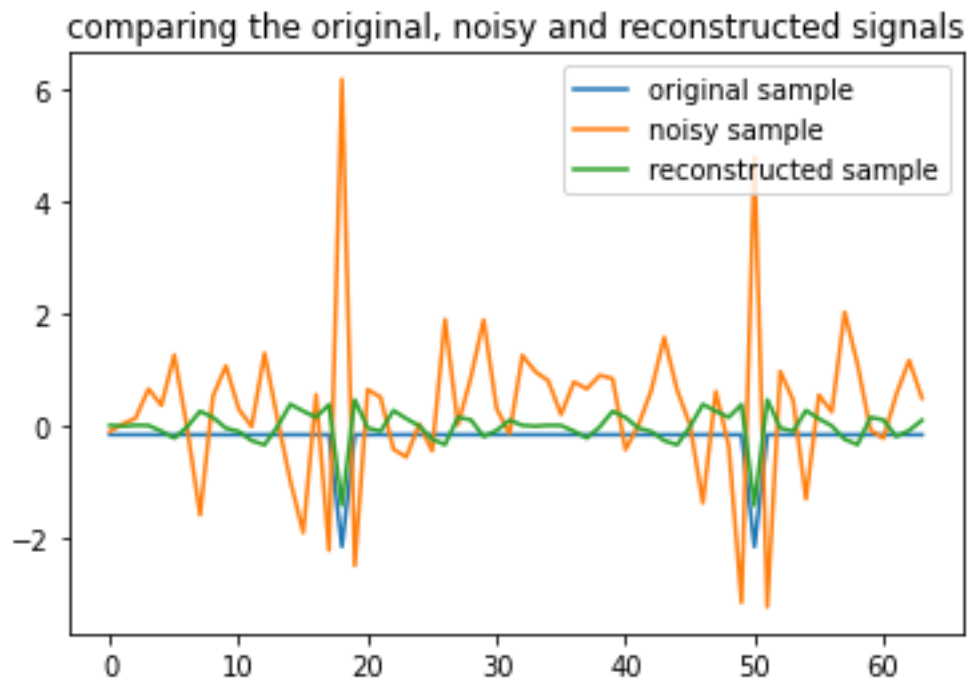
$$W = R_{\phi} H^T (H R_{\phi} H^T + (\sigma_n)^2 I)^{-1}$$

And the matrix itself is:

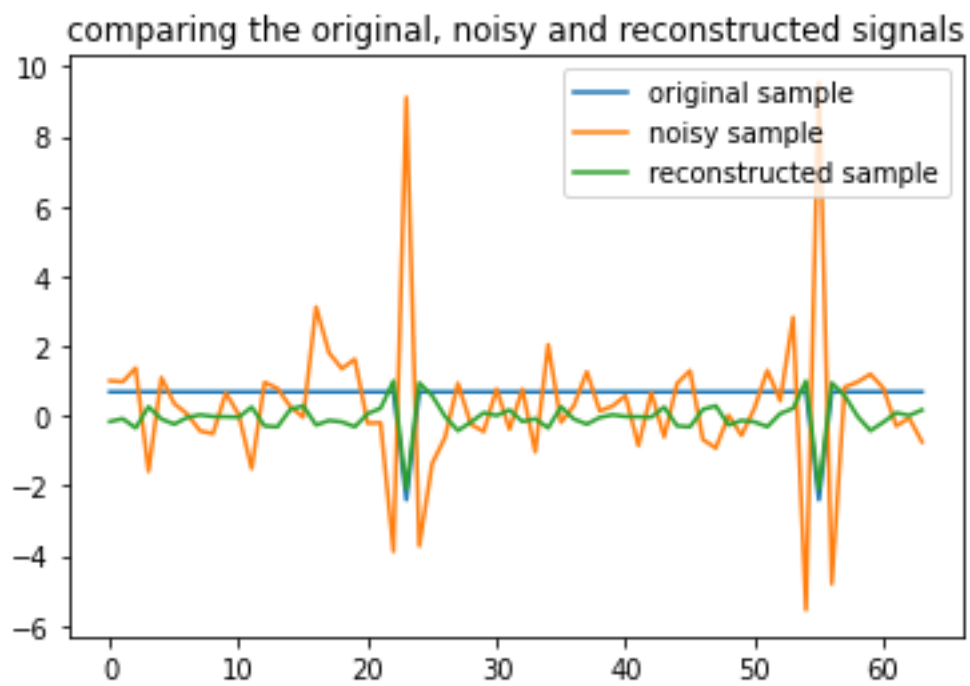


Again, it's a circulant matrix as expected.

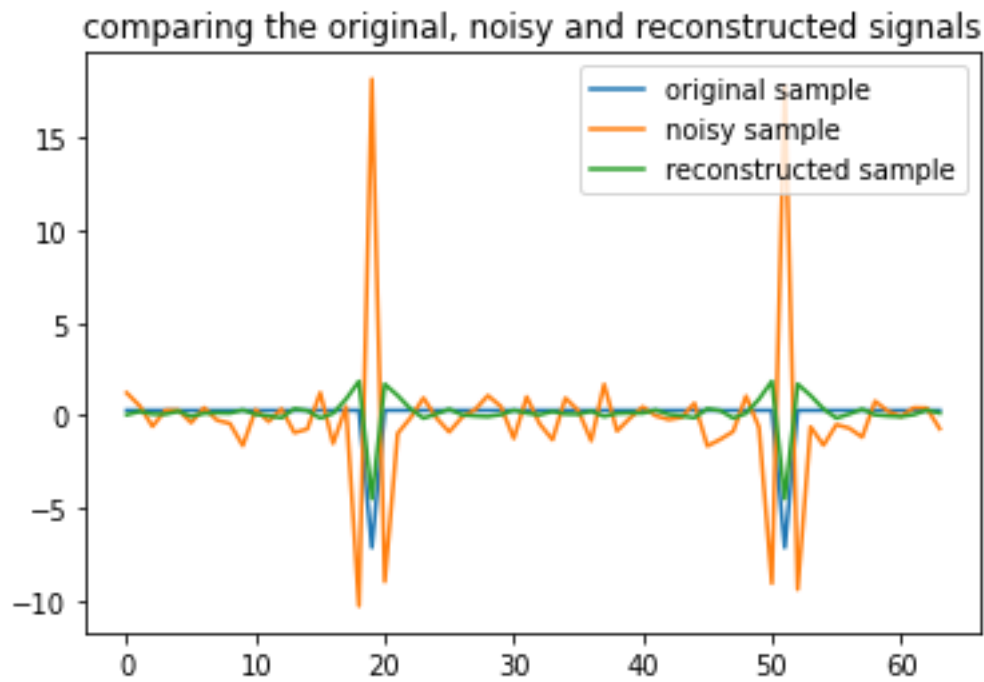
We again examine three samples:



the mse for sample: 71 is: 0.08949026240729514



the mse for sample: 308 is: 0.5271614821295815



the mse for sample: 4007 is: 0.42955218934825595

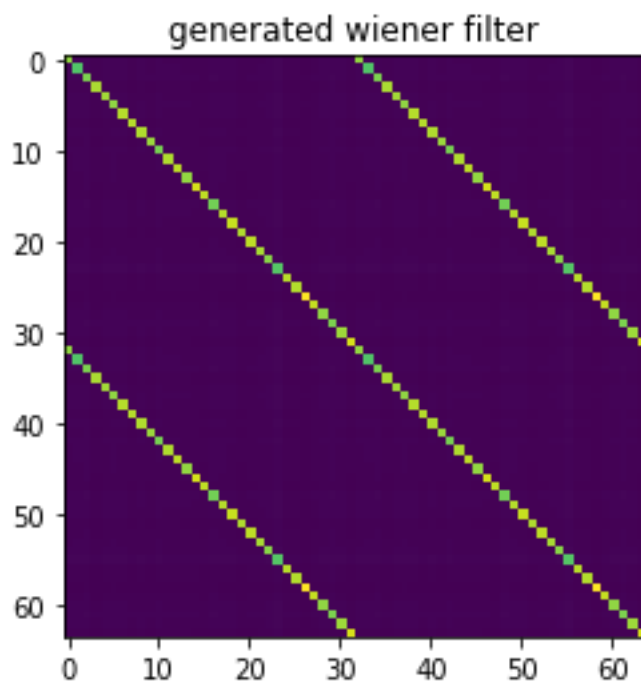
We can see again that the filter worked well approximating all the edges and lowering the signals to a somewhat approximate clean level. The average *MSE* received was:

0.766576647971665

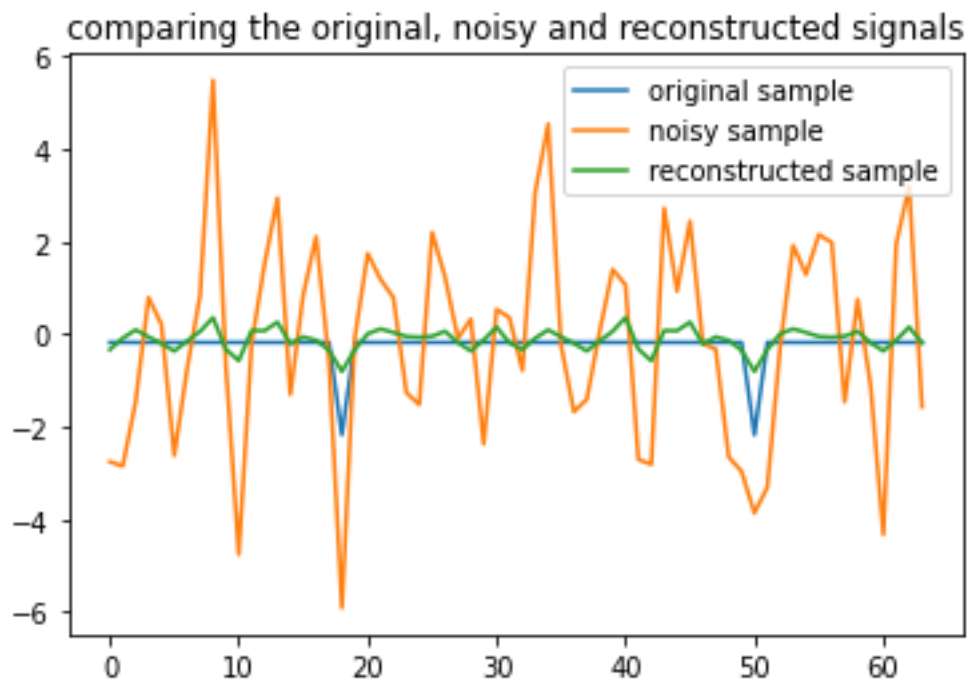
d.

Setting $\sigma_{n2}=5$ we get the following results:

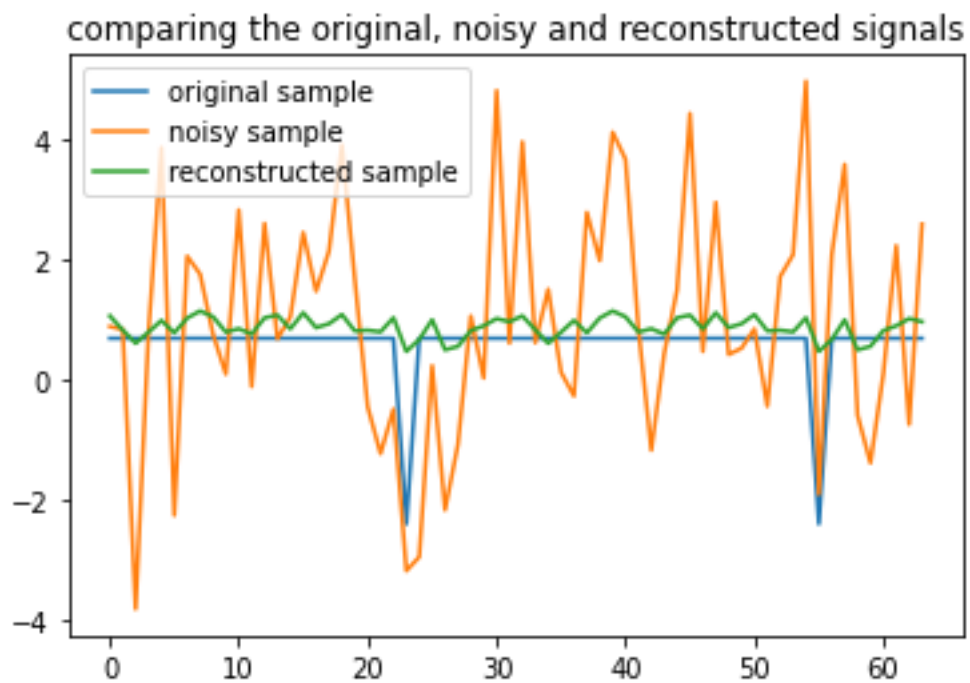
For the first Wiener filter we can see that the values have been decreased:



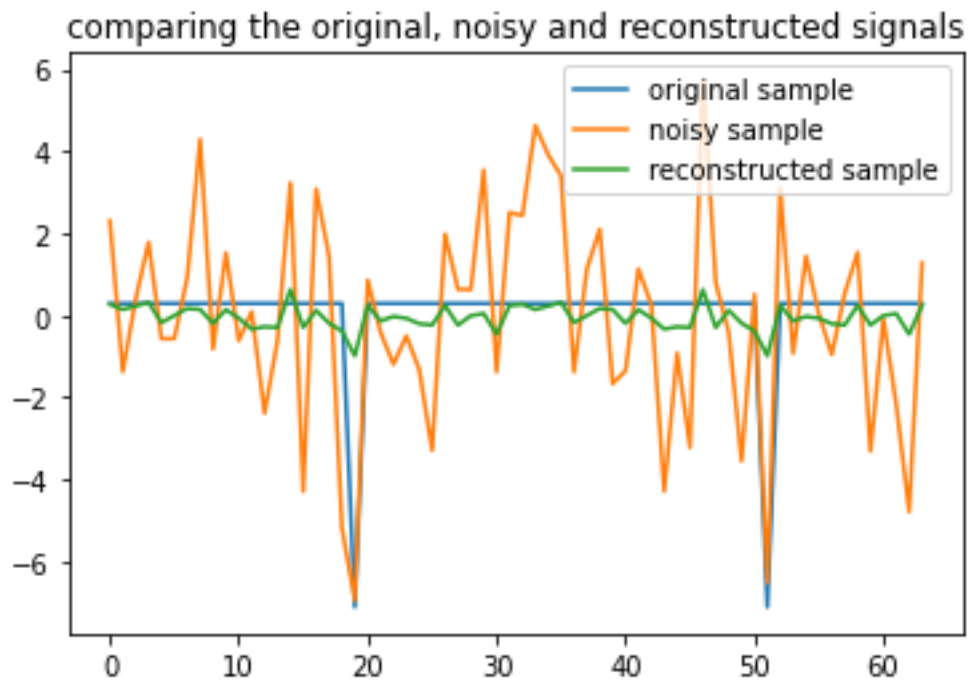
And the Samples are:



the mse for sample: 71 is: 0.1046399966323058



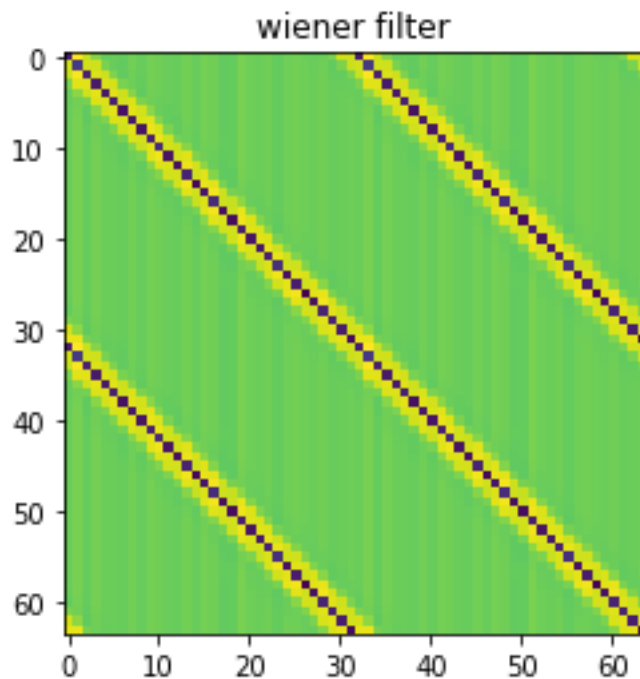
the mse for sample: 308 is: 0.32144790488100305



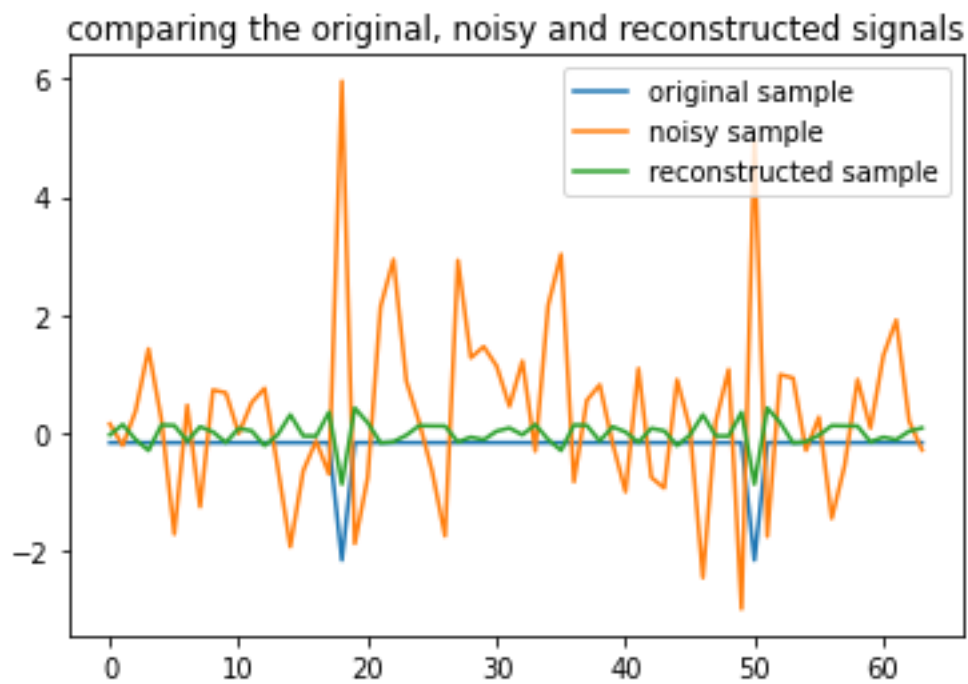
the mse for sample: 4007 is: 1.3252289208856771

And all the samples give the average MSE : 0.43

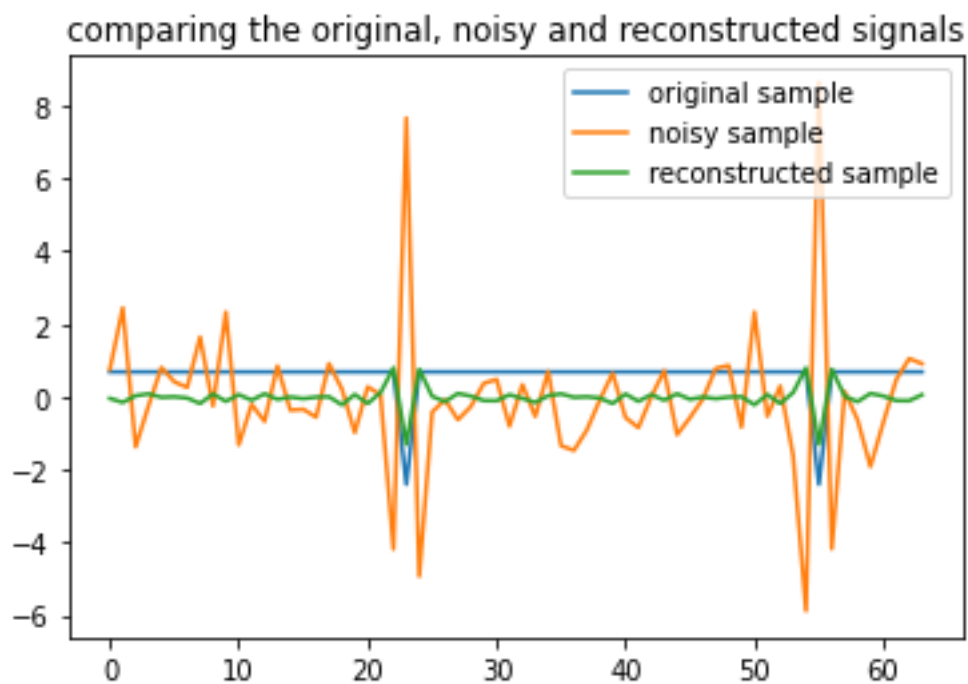
For transformation using H matrix: The Wiener Filter differs again because we use a different σ_n in our calculations of W .



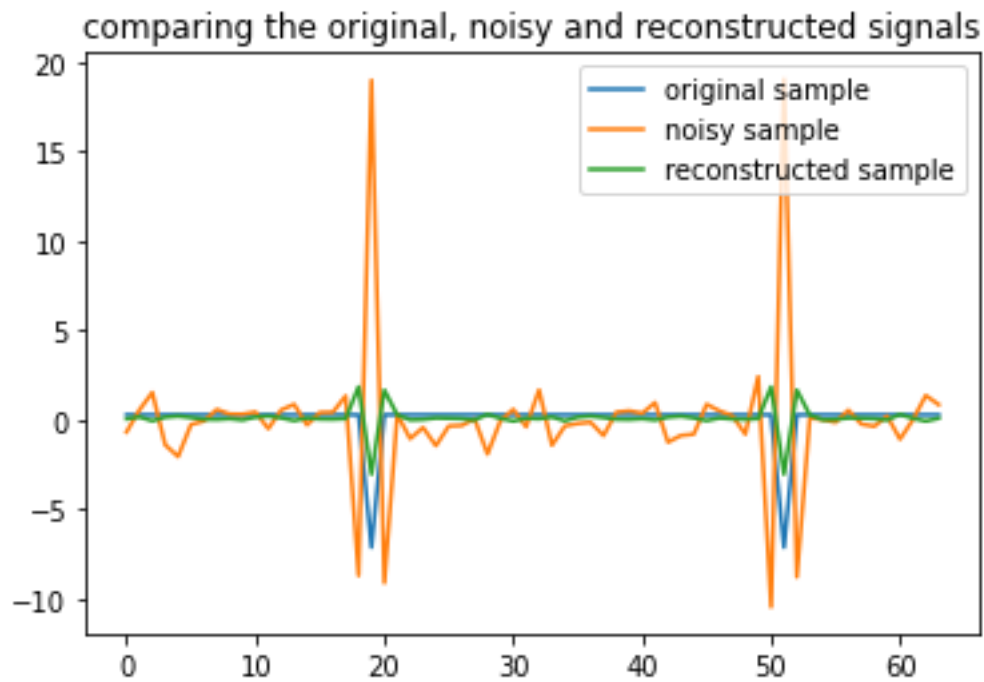
And the samples are:



the mse for sample: 71 is: 0.11073238137886912



the mse for sample: 308 is: 0.50711260487628



the mse for sample: 4007 is: 0.6982612877178969

We can see that we are actually able to approximate our signal well.

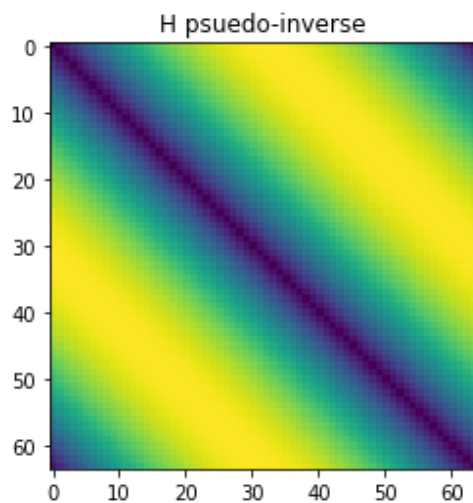
And all the samples give the average MSE : 0.7992770905892264.

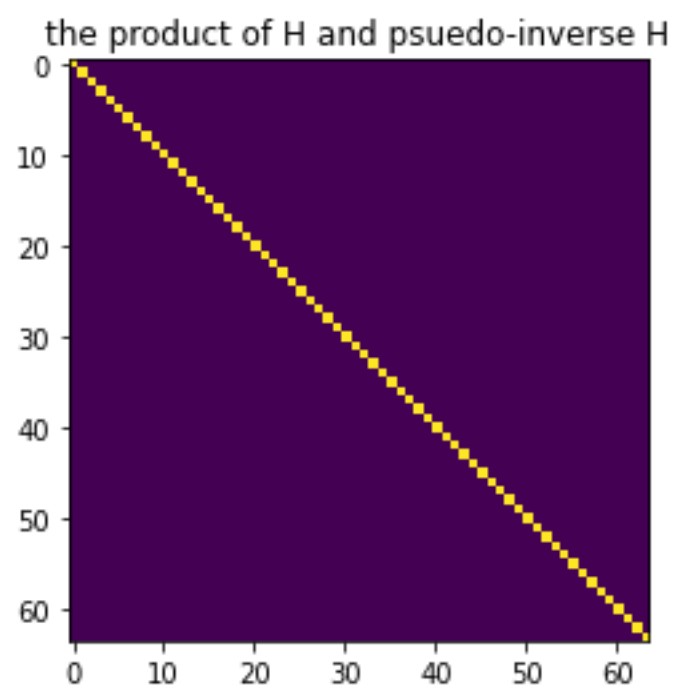
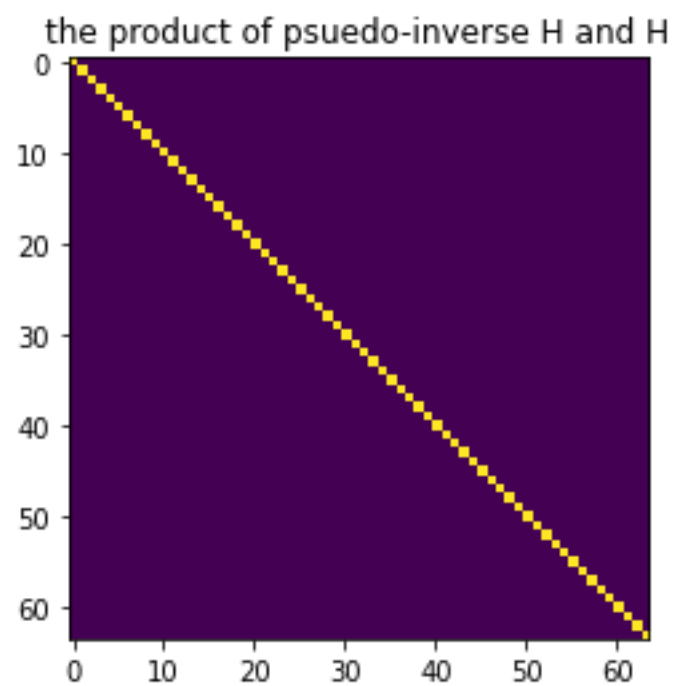
Overall we can see that increasing the std we will have a harder time to approximate our original signal, because the error margin now is bigger.

.e

Yes.

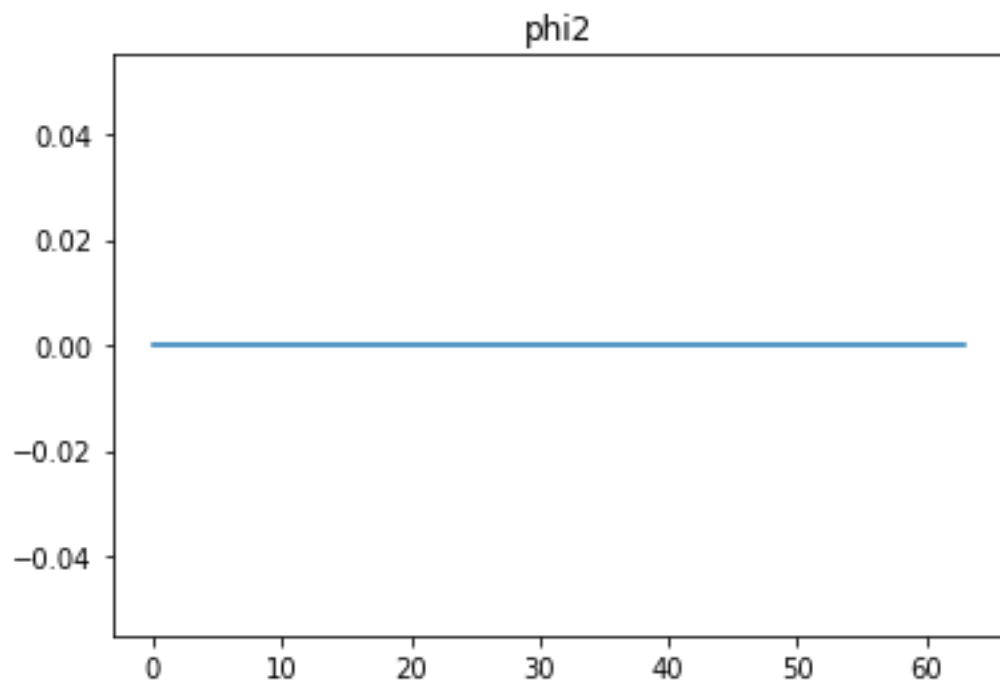
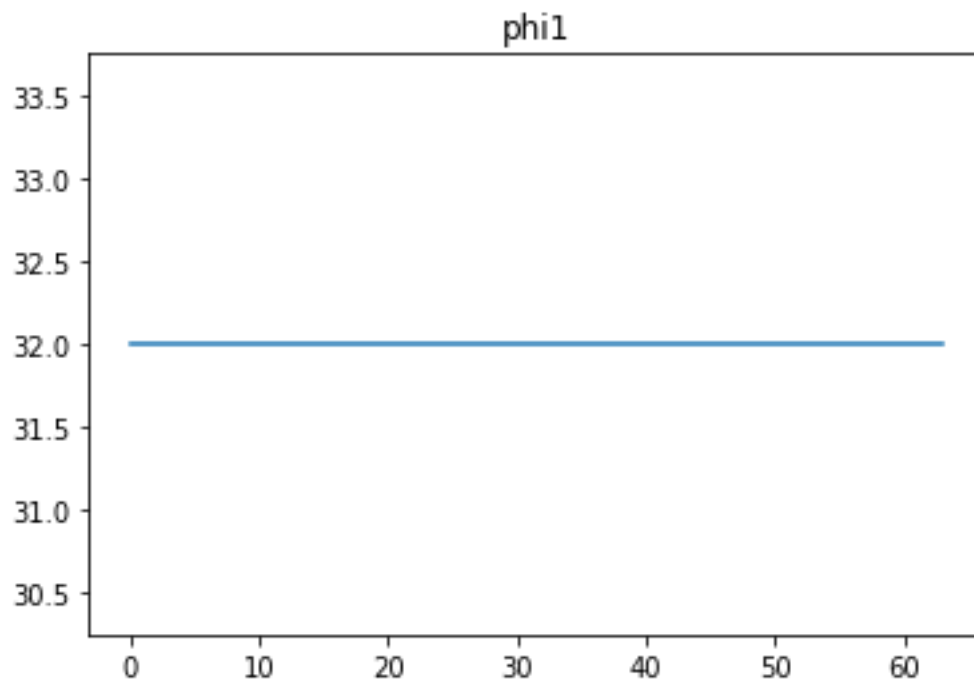
The selection of values and calculations are detailed in the code.

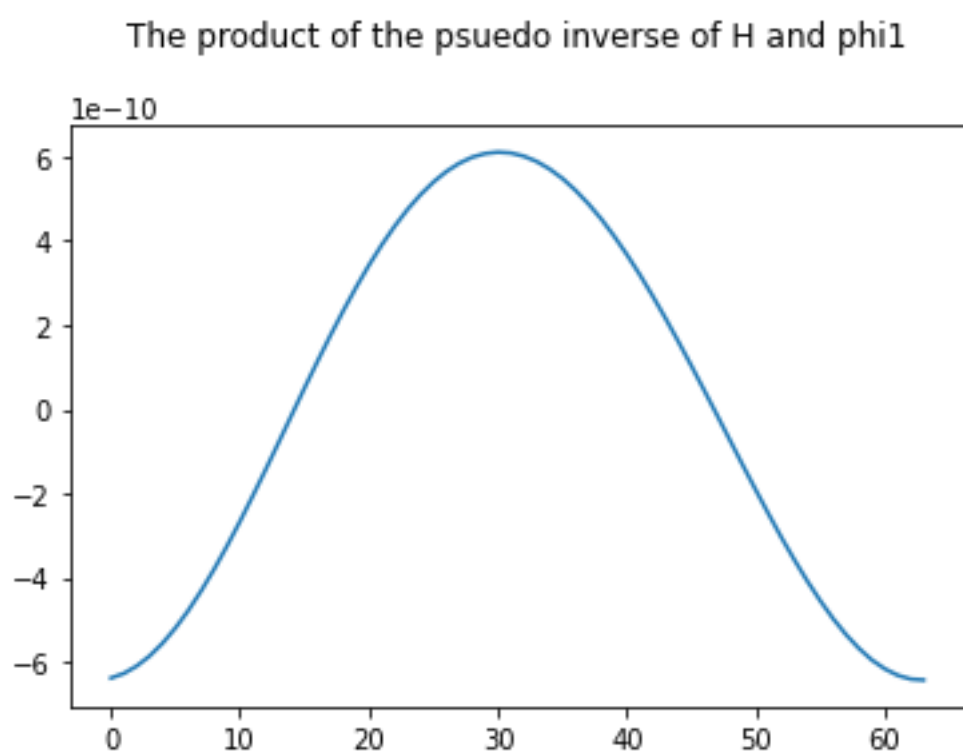
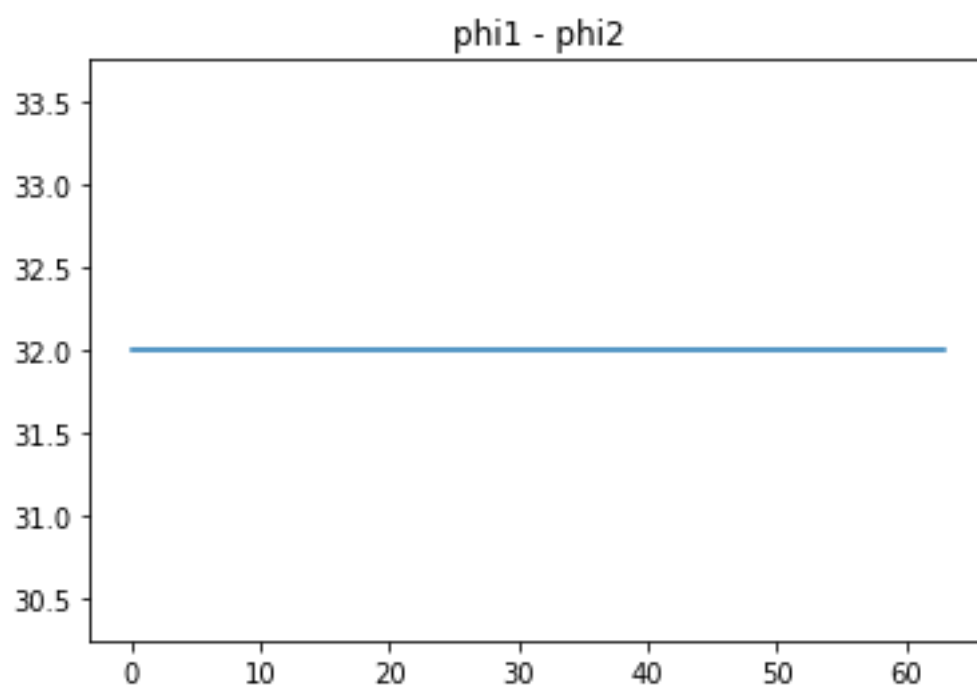


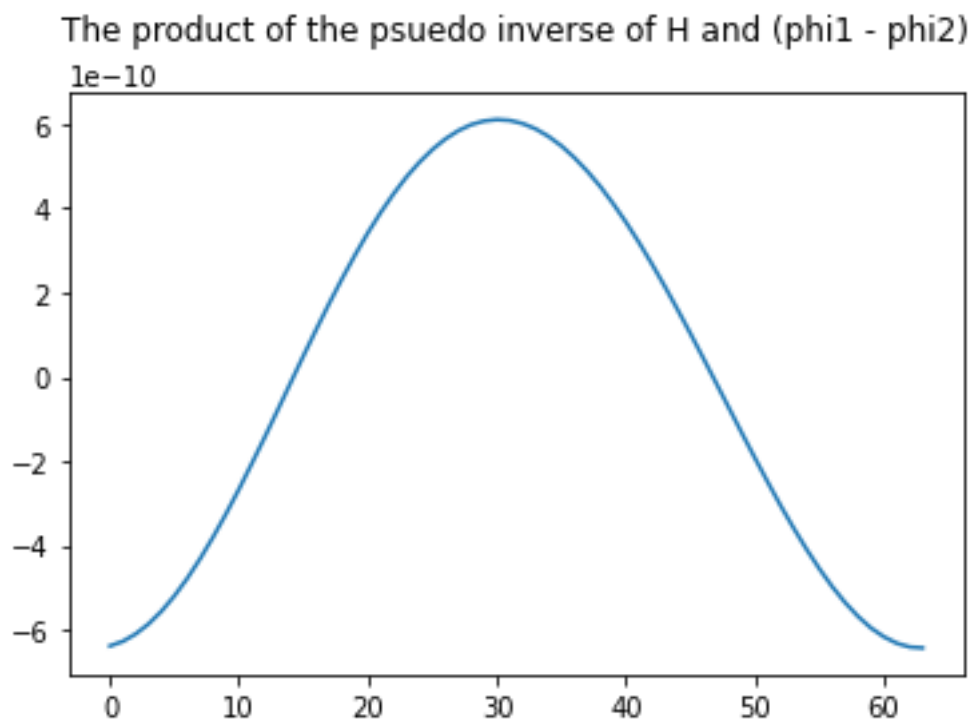
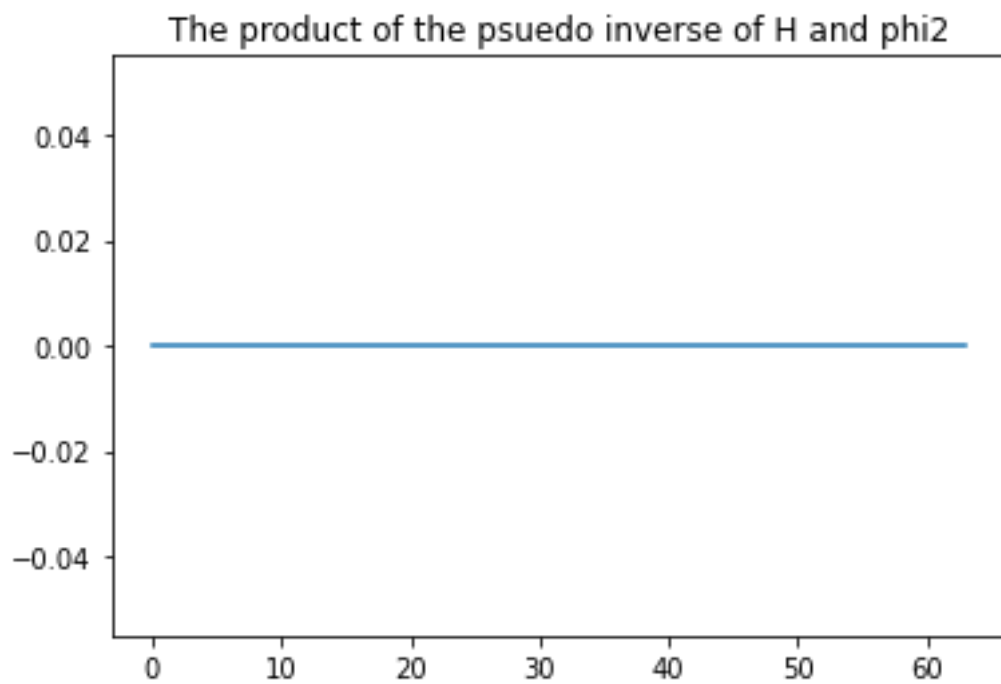


As we can see $H^\dagger H = HH^\dagger$ Because those are symmetric matrices.

We will plot rest of the signals :







Which fits the theory because the multiplications are almost zero (due to numerical errors) and the norms equal to zero too.