Statistical Rethinking Notes - Chapter 2

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library(rethinking)

Chapter 2

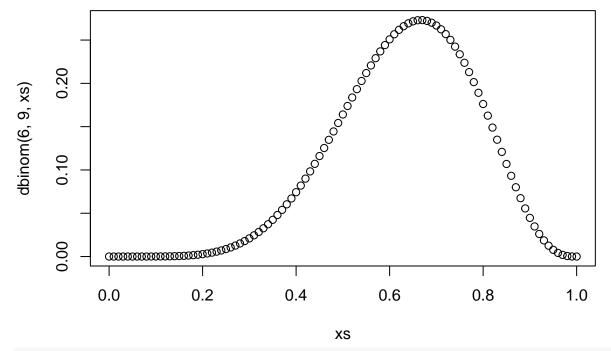
Notes on chapter 2.

Bayesian data analysis: For each possible explanation of the data, Count all the ways the data can happen. Explanations with more ways to produce the data are more plausible.

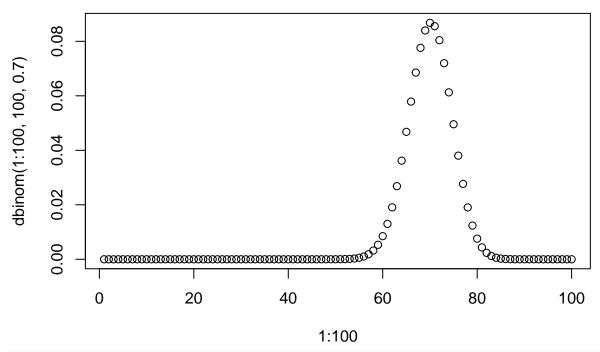
 $\Pr(W, L|p) = \frac{(W+L)!}{W!L!} p^W (1-p)^L$ where W is the number of water hits and L is the number of land hits. dbinom(6, 9, 0.7)

```
## [1] 0.2668279
```

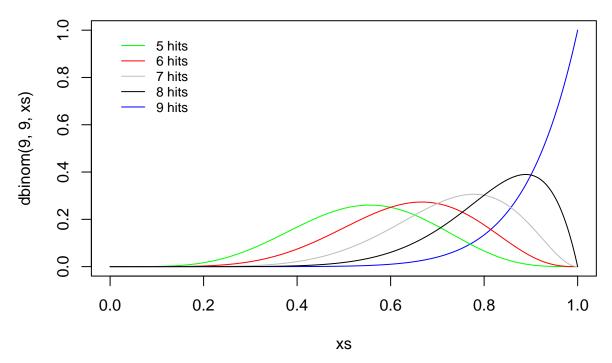
```
xs <- seq(0, 1, 0.01)
plot(xs, dbinom(6, 9, xs))
```



plot(1:100, dbinom(1:100, 100, 0.7))



Binomial density plot for different number of hits (of 9 total)



Question 1: why is it okay to set the prior to 1 (rather than 1 / sum(prior))? (in the code example given in the lecture) (answer: because we will normalize after anyway, so it doesn't matter.)

Question 2: why is the evidence of a single W or L a line (and not some other shape)? (answer: garden of forking data; we assume a model where the number of ways that the true proportion is some value p is determined by the number of "paths" that end up at that proportion given the observed data.)

Question 3: can we choose a different likelihood function? More specifically: say there is some down-stream variable causally associated with the true probability of observing p. e.g. planetoids are either "land-likely" or "water-likely", where "water-likely" planets have a true distribution that is linearly decreasing from p(water) = 1 to p(water) = 0, while "land-likely" planets have the opposite. These planets occur at the same rate, so a flat prior is appropriate (i.e., absent data on whether a planetoid is land- or water-likely, there is a uniform probability of any proportion of water on that planet). In this case, it seems like maybe we want a different likelihood function! (Or should we? I think this is a false example, since land-likeliness needs to assign some probability mass to p(water), otherwise we shouldn't hold a uniform distribution.)

- "For each possible value of the unobserved variables, we need to define the relative number of ways—the probability—that the values of each observed variable could arise."
- "So that we don't have to literally count, we can use a mathematical function that tells us the right plausibility. In conventional statistics, a distribution function assigned to an observed variable is usually called a *likelihood*."
- "The probability of the data, often called the likelihood, provides the plausibility of an observation (data), given a fixed value for the parameters."

Book code

```
len <- 30
# define grid
p_grid <- seq(from=0, to=1, length.out=len )
# define prior
#prior <- rep(1 , len) # rep = repeat</pre>
```

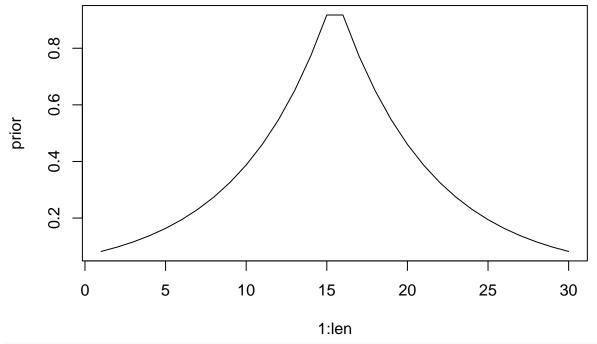
```
prior <- exp( -5*abs( p_grid - 0.5 ) )

# compute likelihood at each value in grid
likelihood <- dbinom(6 , size=9, prob=p_grid)

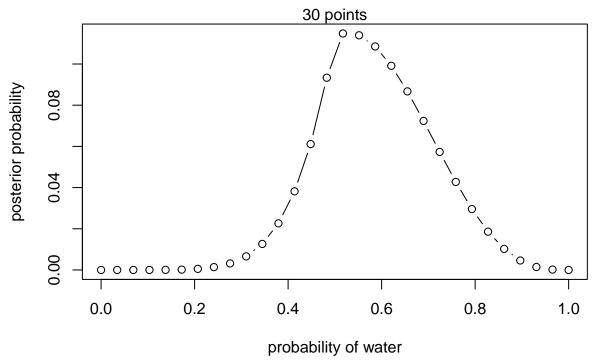
# compute product of likelihood and prior
unstd.posterior <- likelihood * prior

# standardize the posterior, so it sums to 1
posterior <- unstd.posterior / sum(unstd.posterior)

# plot the prior
plot(1:len, prior, type='1')</pre>
```



```
plot( p_grid, posterior, type="b",
xlab="probability of water" , ylab="posterior probability" )
mtext(sprintf("%d points", len))
```



```
globe.qa <- quap(
   alist(
    W ~ dbinom( W+L ,p) , # binomial likelihood
    p ~ dunif(0,1) # uniform prior
   ) ,
   data=list(W=6,L=3)
)
# display summary of quadratic approximation
precis( globe.qa )</pre>
```

mean sd 5.5% 94.5% ## p 0.666667 0.1571337 0.415537 0.917797

Homework

2M1.

```
plot_posterior <- function(obs, len=1000) {
  W <- length(which(obs == "W"))
  L <- length(obs) - W

# define grid
  p_grid <- seq(from=0, to=1, length.out=len)
  # define prior
  prior <- rep(1, len) # rep = repeat

# compute likelihood at each value in grid
  likelihood <- dbinom(W, size=W+L, prob=p_grid)
  # compute product of likelihood and prior
  unstd.posterior <- likelihood * prior
  # standardize the posterior, so it sums to 1
  posterior <- unstd.posterior / sum(unstd.posterior)</pre>
```

