

Chapter 8

Conservation Laws

Problem 8.1

Example 7.13.

$$\left. \begin{aligned} \mathbf{E} &= \frac{\lambda}{2\pi\epsilon_0} \frac{1}{s} \hat{\mathbf{s}} \\ \mathbf{B} &= \frac{\mu_0 I}{2\pi} \frac{1}{s} \hat{\phi} \end{aligned} \right\} \mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B}) = \frac{\lambda I}{4\pi^2 \epsilon_0} \frac{1}{s^2} \hat{\mathbf{z}};$$

$$P = \int \mathbf{S} \cdot d\mathbf{a} = \int_a^b S 2\pi s ds = \frac{\lambda I}{2\pi\epsilon_0} \int_a^b \frac{1}{s} ds = \frac{\lambda I}{2\pi\epsilon_0} \ln(b/a).$$

$$\text{But } V = \int_a^b \mathbf{E} \cdot d\mathbf{l} = \frac{\lambda}{2\pi\epsilon_0} \int_a^b \frac{1}{s} ds = \frac{\lambda}{2\pi\epsilon_0} \ln(b/a), \text{ so } \boxed{P = IV.}$$

Problem 7.58.

$$\left. \begin{aligned} \mathbf{E} &= \frac{\sigma}{\epsilon_0} \hat{\mathbf{z}} \\ \mathbf{B} &= \mu_0 K \hat{\mathbf{x}} = \frac{\mu_0 I}{w} \hat{\mathbf{x}} \end{aligned} \right\} \mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B}) = \frac{\sigma I}{\epsilon_0 w} \hat{\mathbf{y}};$$

$$P = \int \mathbf{S} \cdot d\mathbf{a} = Swh = \frac{\sigma I h}{\epsilon_0}, \text{ but } V = \int \mathbf{E} \cdot d\mathbf{l} = \frac{\sigma}{\epsilon_0} h, \text{ so } \boxed{P = IV.}$$

Problem 8.2

$$(a) \mathbf{E} = \frac{\sigma}{\epsilon_0} \hat{\mathbf{z}}; \sigma = \frac{Q}{\pi a^2}; Q(t) = It \Rightarrow \mathbf{E}(t) = \frac{It}{\pi \epsilon_0 a^2} \hat{\mathbf{z}}.$$

$$B 2\pi s = \mu_0 \epsilon_0 \frac{\partial E}{\partial t} \pi s^2 = \mu_0 \epsilon_0 \frac{I \pi s^2}{\pi \epsilon_0 a^2} \Rightarrow \mathbf{B}(s, t) = \frac{\mu_0 I s}{2\pi a^2} \hat{\phi}.$$

$$(b) u_{\text{em}} = \frac{1}{2} \left(\epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right) = \frac{1}{2} \left[\epsilon_0 \left(\frac{It}{\pi \epsilon_0 a^2} \right)^2 + \frac{1}{\mu_0} \left(\frac{\mu_0 I s}{2\pi a^2} \right)^2 \right] = \frac{\mu_0 I^2}{2\pi^2 a^4} [(ct)^2 + (s/2)^2].$$

$$\mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B}) = \frac{1}{\mu_0} \left(\frac{It}{\pi \epsilon_0 a^2} \right) \left(\frac{\mu_0 I s}{2\pi a^2} \right) (-\hat{\mathbf{s}}) = -\frac{I^2 t}{2\pi^2 \epsilon_0 a^4} s \hat{\mathbf{s}}.$$

$$\frac{\partial u_{\text{em}}}{\partial t} = \frac{\mu_0 I^2}{2\pi^2 a^4} 2c^2 t = \frac{I^2 t}{\pi^2 \epsilon_0 a^4}; \quad -\nabla \cdot \mathbf{S} = \frac{I^2 t}{2\pi^2 \epsilon_0 a^4} \nabla \cdot (s \hat{\mathbf{s}}) = \frac{I^2 t}{\pi^2 \epsilon_0 a^2} = \frac{\partial u_{\text{em}}}{\partial t}. \quad \checkmark$$

$$(c) U_{\text{em}} = \int u_{\text{em}} w 2\pi s ds = 2\pi w \frac{\mu_0 I^2}{2\pi^2 a^4} \int_0^b [(ct)^2 + (s/2)^2] s ds = \frac{\mu_0 w I^2}{\pi a^4} \left[(ct)^2 \frac{s^2}{2} + \frac{1}{4} \frac{s^4}{4} \right] \Big|_0^b$$

$$= \frac{\mu_0 w I^2 b^2}{2\pi a^4} \left[(ct)^2 + \frac{b^2}{16} \right]. \quad \text{Over a surface at radius } b: P_{\text{in}} = - \int \mathbf{S} \cdot d\mathbf{a} = \frac{I^2 t}{2\pi^2 \epsilon_0 a^4} [b \hat{\mathbf{s}} \cdot (2\pi b w \hat{\mathbf{s}})] = \frac{I^2 w t b^2}{\pi \epsilon_0 a^4}.$$

$$\frac{dU_{\text{em}}}{dt} = \frac{\mu_0 w I^2 b^2}{2\pi a^4} 2c^2 t = \frac{I^2 w t b^2}{\pi \epsilon_0 a^4} = P_{\text{in}}. \quad \checkmark \quad (\text{Set } b = a \text{ for total.})$$

Problem 8.3

$$\mathbf{F} = \oint \vec{\mathbf{T}} \cdot d\mathbf{a} - \mu_0 \epsilon_0 \frac{d}{dt} \int \mathbf{S} d\tau.$$

The fields are constant, so the second term is zero. The force is clearly in the z direction, so we need

$$\begin{aligned} (\vec{\mathbf{T}} \cdot d\mathbf{a})_z &= T_{zx} da_x + T_{zy} da_y + T_{zz} da_z = \frac{1}{\mu_0} \left(B_z B_x da_x + B_z B_y da_y + B_z B_z da_z - \frac{1}{2} B^2 da_z \right) \\ &= \frac{1}{\mu_0} \left[B_z (\mathbf{B} \cdot d\mathbf{a}) - \frac{1}{2} B^2 da_z \right]. \end{aligned}$$

Now $\mathbf{B} = \frac{2}{3} \mu_0 \sigma R \omega \hat{\mathbf{z}}$ (inside) and $\mathbf{B} = \frac{\mu_0 m}{4\pi r^3} (2 \cos \theta \hat{\mathbf{r}} + \sin \theta \hat{\boldsymbol{\theta}})$ (outside), where $m = \frac{4}{3} \pi R^3 (\sigma \omega R)$. (From Eq. 5.68, Prob. 5.36, and Eq. 5.86.) We want a surface that encloses the entire upper hemisphere—say a hemispherical cap just outside $r = R$ plus the equatorial circular disk.

Hemisphere:

$$B_z = \frac{\mu_0 m}{4\pi R^3} [2 \cos \theta (\hat{\mathbf{r}})_z + \sin \theta (\hat{\boldsymbol{\theta}})_z] = \frac{\mu_0 m}{4\pi R^3} [2 \cos^2 \theta - \sin^2 \theta] = \frac{\mu_0 m}{4\pi R^3} (3 \cos^2 \theta - 1).$$

$$d\mathbf{a} = R^2 \sin \theta d\theta d\phi \hat{\mathbf{r}}; \quad \mathbf{B} \cdot d\mathbf{a} = \frac{\mu_0 m}{4\pi R^3} (2 \cos \theta) R^2 \sin \theta d\theta d\phi; \quad da_z = R^2 \sin \theta d\theta d\phi \cos \theta;$$

$$B^2 = \left(\frac{\mu_0 m}{4\pi R^3} \right)^2 (4 \cos^2 \theta + \sin^2 \theta) = \left(\frac{\mu_0 m}{4\pi R^3} \right)^2 (3 \cos^2 \theta + 1).$$

$$(\vec{\mathbf{T}} \cdot d\mathbf{a})_z = \frac{1}{\mu_0} \left(\frac{\mu_0 m}{4\pi R^3} \right)^2 \left[(3 \cos^2 \theta - 1) 2 \cos \theta R^2 \sin \theta d\theta d\phi - \frac{1}{2} (3 \cos^2 \theta + 1) R^2 \sin \theta \cos \theta d\theta d\phi \right]$$

$$= \mu_0 \left(\frac{\sigma \omega R}{3} \right)^2 \left[\frac{1}{2} R^2 \sin \theta \cos \theta d\theta d\phi \right] (12 \cos^2 \theta - 4 - 3 \cos^2 \theta - 1)$$

$$= \frac{\mu_0}{2} \left(\frac{\sigma \omega R^2}{3} \right)^2 (9 \cos^2 \theta - 5) \sin \theta \cos \theta d\theta d\phi.$$

$$(F_{\text{hemi}})_z = \frac{\mu_0}{2} \left(\frac{\sigma \omega R^2}{3} \right)^2 2\pi \int_0^{\pi/2} (9 \cos^3 \theta - 5 \cos \theta) \sin \theta d\theta = \mu_0 \pi \left(\frac{\sigma \omega R^2}{3} \right)^2 \left[-\frac{9}{4} \cos^4 \theta + \frac{5}{2} \cos^2 \theta \right] \Big|_0^{\pi/2}$$

$$= \mu_0 \pi \left(\frac{\sigma \omega R^2}{3} \right)^2 \left(0 + \frac{9}{4} - \frac{5}{2} \right) = -\frac{\mu_0 \pi}{4} \left(\frac{\sigma \omega R^2}{3} \right)^2.$$

Disk:

$$\begin{aligned}
 B_z &= \frac{2}{3}\mu_0\sigma R\omega; \quad d\mathbf{a} = r \, dr \, d\phi \, \hat{\phi} = -r \, dr \, d\phi \, \hat{z}; \\
 \mathbf{B} \cdot d\mathbf{a} &= -\frac{2}{3}\mu_0\sigma R\omega r \, dr \, d\phi; \quad B^2 = \left(\frac{2}{3}\mu_0\sigma R\omega\right)^2; \quad da_z = -r \, dr \, d\phi. \\
 (\vec{\mathbf{T}} \cdot d\mathbf{a})_z &= \frac{1}{\mu_0} \left(\frac{2}{3}\mu_0\sigma R\omega\right)^2 \left[-r \, dr \, d\phi + \frac{1}{2}r \, dr \, d\phi\right] = -\frac{1}{2\mu_0} \left(\frac{2}{3}\mu_0\sigma R\omega\right)^2 r \, dr \, d\phi. \\
 (F_{\text{disk}})_z &= -2\mu_0 \left(\frac{\sigma\omega R}{3}\right)^2 2\pi \int_0^R r \, dr = -2\pi\mu_0 \left(\frac{\sigma\omega R^2}{3}\right)^2.
 \end{aligned}$$

Total:

$$\mathbf{F} = -\pi\mu_0 \left(\frac{\sigma\omega R^2}{3}\right)^2 \left(2 + \frac{1}{4}\right) \hat{z} = \boxed{-\pi\mu_0 \left(\frac{\sigma\omega R^2}{2}\right)^2 \hat{z}} \quad (\text{agrees with Prob. 5.42}).$$

Problem 8.4

(a) $(\vec{\mathbf{T}} \cdot d\mathbf{a})_z = T_{zx} da_x + T_{zy} da_y + T_{zz} da_z.$

But for the xy plane $da_x = da_y = 0$, and $da_z = -r \, dr \, d\phi$ (I'll calculate the force on the *upper* charge).

$$(\vec{\mathbf{T}} \cdot d\mathbf{a})_z = \epsilon_0 \left(E_z E_z - \frac{1}{2}E^2\right) (-r \, dr \, d\phi).$$

Now $\mathbf{E} = \frac{1}{4\pi\epsilon_0} 2\frac{q}{z^2} \cos\theta \, \hat{\mathbf{r}}$, and $\cos\theta = \frac{r}{z}$, so $E_z =$

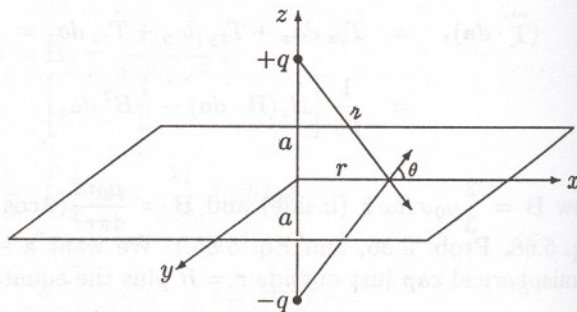
$$0, \quad E^2 = \left(\frac{q}{2\pi\epsilon_0}\right)^2 \frac{r^2}{(r^2 + a^2)^3}. \quad \text{Therefore}$$

$$\begin{aligned}
 F_z &= \frac{1}{2}\epsilon_0 \left(\frac{q}{2\pi\epsilon_0}\right)^2 2\pi \int_0^{fty} \frac{r^3 \, dr}{(r^2 + a^2)^3} = \frac{q^2}{4\pi\epsilon_0} \frac{1}{2} \int_0^{fty} \frac{u \, du}{(u + a^2)^3} \quad (\text{letting } u \equiv r^2) \\
 &= \frac{q^2}{4\pi\epsilon_0} \frac{1}{2} \left[-\frac{1}{(u + a^2)^2} + \frac{a^2}{2(u + a^2)^3} \right] \Big|_0^{fty} = \frac{q^2}{4\pi\epsilon_0} \frac{1}{2} \left[0 + \frac{1}{a^2} - \frac{a^2}{2a^4} \right] = \boxed{\frac{q^2}{4\pi\epsilon_0} \frac{1}{(2a)^2}} \checkmark
 \end{aligned}$$

(b) In this case $\mathbf{E} = -\frac{1}{4\pi\epsilon_0} 2\frac{q}{z^2} \sin\theta \, \hat{\mathbf{z}}$, and $\sin\theta = \frac{a}{z}$, so

$$E^2 = E_z^2 = \left(\frac{qa}{2\pi\epsilon_0}\right)^2 \frac{1}{(r^2 + a^2)^3}, \quad \text{and hence } (\vec{\mathbf{T}} \cdot d\mathbf{a})_z = -\frac{\epsilon_0}{2} \left(\frac{qa}{2\pi\epsilon_0}\right)^2 \frac{r \, dr \, d\phi}{(r^2 + a^2)^3}. \quad \text{Therefore}$$

$$F_z = -\frac{\epsilon_0}{2} \left(\frac{qa}{2\pi\epsilon_0}\right)^2 2\pi \int_0^{fty} \frac{r \, dr}{(r^2 + a^2)^3} = -\frac{q^2 a^2}{4\pi\epsilon_0} \left[-\frac{1}{4(r^2 + a^2)^2} \right]_0^{fty} = -\frac{q^2 a^2}{4\pi\epsilon_0} \left[0 + \frac{1}{4a^4} \right] = \boxed{-\frac{q^2}{4\pi\epsilon_0} \frac{1}{(2a)^2}} \checkmark$$



Problem 8.5

(a) $E_x = E_y = 0$, $E_z = -\sigma/\epsilon_0$. Therefore

$$T_{xy} = T_{xz} = T_{yz} = \cdots = 0; \quad T_{xx} = T_{yy} = -\frac{\epsilon_0}{2} E^2 = -\frac{\sigma^2}{2\epsilon_0}; \quad T_{zz} = \epsilon_0 \left(E_z^2 - \frac{1}{2} E^2 \right) = \frac{\epsilon_0}{2} E^2 = \frac{\sigma^2}{2\epsilon_0}.$$

$$\vec{T} = \frac{\sigma^2}{2\epsilon_0} \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & +1 \end{pmatrix}.$$

(b) $\mathbf{F} = \oint \vec{T} \cdot d\mathbf{a}$ ($\mathbf{S} = 0$, since $\mathbf{B} = 0$); integrate over the xy plane: $d\mathbf{a} = -dx dy \hat{\mathbf{z}}$ (negative because outward with respect to a surface enclosing the upper plate). Therefore

$$F_z = \int T_{zz} da_z = -\frac{\sigma^2}{2\epsilon_0} A, \text{ and the force per unit area is } \mathbf{f} = \frac{\mathbf{F}}{A} = \boxed{-\frac{\sigma^2}{2\epsilon_0} \hat{\mathbf{z}}}.$$

(c) $-T_{zz} = \boxed{\sigma^2/2\epsilon_0}$ is the momentum in the z direction crossing a surface perpendicular to z , per unit area, per unit time (Eq. 8.31).

(d) The recoil force is the momentum delivered per unit time, so the force per unit area on the top plate is

$$\mathbf{f} = \boxed{-\frac{\sigma^2}{2\epsilon_0} \hat{\mathbf{z}}} \quad (\text{same as (b)}).$$

Problem 8.6

(a) $\mathcal{P}_{em} = \epsilon_0 (\mathbf{E} \times \mathbf{B}) = \epsilon_0 EB \hat{\mathbf{y}}$; $\mathbf{p}_{em} = \boxed{\epsilon_0 EBA d \hat{\mathbf{y}}}$.

(b) $\mathbf{I} = \int_0^\infty \mathbf{F} dt = \int_0^\infty I(1 \times \mathbf{B}) dt = \int_0^\infty IB d(\hat{\mathbf{z}} \times \hat{\mathbf{x}}) dt = (Bd \hat{\mathbf{y}}) \int_0^\infty \left(-\frac{dQ}{dt} \right) dt = -(Bd \hat{\mathbf{y}})[Q(\infty) - Q(0)] = BQd \hat{\mathbf{y}}$. But the original field was $E = \sigma/\epsilon_0 = Q/\epsilon_0 A$, so $Q = \epsilon_0 EA$, and hence $\mathbf{I} = \boxed{\epsilon_0 EBA d \hat{\mathbf{y}}}$; as expected, the momentum originally stored in the fields (a) is delivered as a kick to the capacitor.

(c) $\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi}{dt} = -\frac{dB}{dt}ld$ (for a length l in the y direction). $-lE(d) + lE(0) = -ld\frac{dB}{dt} \Rightarrow E(d) - E(0) = d\frac{dB}{dt}$. $\mathbf{F} = -\sigma AE(d) \hat{\mathbf{y}} + \sigma AE(0) \hat{\mathbf{y}} = -\sigma A[E(d) - E(0)] \hat{\mathbf{y}} = -\sigma Ad\frac{dB}{dt} \hat{\mathbf{y}}$. $\mathbf{I} = \int_0^\infty \mathbf{F} dt = -(\sigma Ad \hat{\mathbf{y}}) \int_0^\infty \frac{dB}{dt} dt = -(\sigma Ad \hat{\mathbf{y}})[B(\infty) - B(0)] = \sigma AdB \hat{\mathbf{y}}$. But $E = \frac{\sigma}{\epsilon_0}$, so $\mathbf{I} = \boxed{\epsilon_0 EBA d \hat{\mathbf{y}}}$, as before.

Problem 8.7

$\mathbf{B} = \mu_0 n I \hat{\mathbf{z}}$ (for $a < r < R$; outside the solenoid $B = 0$). The force on a segment dr of spoke is

$$d\mathbf{F} = I' d\mathbf{l} \times \mathbf{B} = I' \mu_0 n I dr (\hat{\mathbf{r}} \times \hat{\mathbf{z}}) = -I' \mu_0 n I dr \hat{\phi}.$$

The torque on the spoke is

$$\mathbf{N} = \int \mathbf{r} \times d\mathbf{F} = I' \mu_0 n I \int_a^R r dr (-\hat{\mathbf{r}} \times \hat{\phi}) = I' \mu_0 n I \frac{1}{2} (R^2 - a^2) (-\hat{\mathbf{z}}).$$

Therefore the angular momentum of the cylinders is $\mathbf{L} = \int \mathbf{N} dt = -\frac{1}{2}\mu_0 n I Q (R^2 - a^2) \hat{\mathbf{z}} \int I' dt$. But $\int I' dt = Q$, so

$$\mathbf{L} = -\frac{1}{2}\mu_0 n I Q (R^2 - a^2) \hat{\mathbf{z}} \quad (\text{in agreement with Eq. 8.35}).$$

Problem 8.8

(a)

$$\mathbf{E} = \begin{cases} 0, & (r < R) \\ \frac{1}{4\pi\epsilon_0} \frac{Q}{r^2} \hat{\mathbf{r}}, & (r > R) \end{cases}; \quad \mathbf{B} = \begin{cases} \frac{2}{3}\mu_0 M \hat{\mathbf{z}}, & (r < R) \\ \frac{\mu_0 m}{4\pi r^3} [2 \cos \theta \hat{\mathbf{r}} + \sin \theta \hat{\boldsymbol{\theta}}], & (r > R) \end{cases} \quad (\text{Ex. 6.1})$$

(where $m = \frac{4}{3}\pi R^3 M$); $\boldsymbol{\wp} = \epsilon_0(\mathbf{E} \times \mathbf{B}) = \frac{\mu_0}{(4\pi)^2} \frac{Qm}{r^5} (\hat{\mathbf{r}} \times \hat{\boldsymbol{\theta}}) \sin \theta$, and $(\hat{\mathbf{r}} \times \hat{\boldsymbol{\theta}}) = \hat{\boldsymbol{\phi}}$, so

$$\boldsymbol{\ell} = \mathbf{r} \times \boldsymbol{\wp} = \frac{\mu_0}{(4\pi)^2} \frac{mQ}{r^4} \sin \theta (\hat{\mathbf{r}} \times \hat{\boldsymbol{\phi}}).$$

But $(\hat{\mathbf{r}} \times \hat{\boldsymbol{\phi}}) = -\hat{\boldsymbol{\theta}}$, and only the z component will survive integration, so (since $(\hat{\boldsymbol{\theta}})_z = -\sin \theta$):

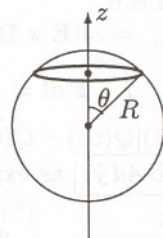
$$\mathbf{L} = \frac{\mu_0 m Q}{(4\pi)^2} \hat{\mathbf{z}} \int \frac{\sin^2 \theta}{r^4} (r^2 \sin \theta dr d\theta d\phi). \quad \int_0^{2\pi} d\phi = 2\pi; \quad \int_0^\pi \sin^3 \theta d\theta = \frac{4}{3}; \quad \int_R^\infty \frac{1}{r^2} dr = \left(-\frac{1}{r}\right)\Big|_R^\infty = \frac{1}{R}.$$

$$\mathbf{L} = \frac{\mu_0 m Q}{(4\pi)^2} \hat{\mathbf{z}} (2\pi) \left(\frac{4}{3}\right) \left(\frac{1}{R}\right) = \boxed{\frac{2}{9}\mu_0 M Q R^2 \hat{\mathbf{z}}}.$$

(b) Apply Faraday's law to the ring shown:

$$\oint \mathbf{E} \cdot d\mathbf{l} = E(2\pi r \sin \theta) = -\frac{d\Phi}{dt} = -\pi(r \sin \theta)^2 \left(\frac{2}{3}\mu_0 \frac{dM}{dt}\right)$$

$$\Rightarrow \boxed{\mathbf{E} = -\frac{\mu_0}{3} \frac{dM}{dt} (r \sin \theta) \hat{\boldsymbol{\phi}}}.$$



The force on a patch of surface (da) is $d\mathbf{F} = \sigma \mathbf{E} da = -\frac{\mu_0 \sigma}{3} \frac{dM}{dt} (r \sin \theta) da \hat{\boldsymbol{\phi}}$ ($\sigma = \frac{Q}{4\pi R^2}$).

The torque on the patch is $d\mathbf{N} = \mathbf{r} \times d\mathbf{F} = -\frac{\mu_0 \sigma}{3} \frac{dM}{dt} (r^2 \sin \theta) da (\hat{\mathbf{r}} \times \hat{\boldsymbol{\phi}})$. But $(\hat{\mathbf{r}} \times \hat{\boldsymbol{\phi}}) = -\hat{\boldsymbol{\theta}}$, and we want only the z component ($(\hat{\boldsymbol{\theta}})_z = -\sin \theta$):

$$\mathbf{N} = -\frac{\mu_0 \sigma}{3} \frac{dM}{dt} \hat{\mathbf{z}} \int r^2 \sin^2 \theta (r^2 \sin \theta d\theta d\phi).$$

Here $r = R$; $\int_0^\pi \sin^3 \theta d\theta = \frac{4}{3}$; $\int_0^{2\pi} d\phi = 2\pi$, so $\mathbf{N} = -\frac{\mu_0 \sigma}{3} \frac{dM}{dt} \hat{\mathbf{z}} R^4 \left(\frac{4}{3}\right) (2\pi) = \boxed{-\frac{2\mu_0}{9} Q R^2 \frac{dM}{dt} \hat{\mathbf{z}}}.$

$$\mathbf{L} = \int \mathbf{N} dt = -\frac{2\mu_0}{9} Q R^2 \hat{\mathbf{z}} \int_M^0 dM = \boxed{\frac{2\mu_0}{9} M Q R^2 \hat{\mathbf{z}}} \quad (\text{same as (a)}).$$

(c) Let the charge on the sphere at time t be $q(t)$; the charge density is $\sigma = \frac{q(t)}{4\pi R^2}$. The charge below (“south of”) the ring in the figure is

$$q_s = \sigma (2\pi R^2) \int_0^\pi \sin \theta' d\theta' = \frac{q}{2} (-\cos \theta') \Big|_0^\pi = \frac{q}{2} (1 + \cos \theta).$$

So the total current crossing the ring (flowing “north”) is $I(t) = -\frac{1}{2} \frac{dq}{dt} (1 + \cos \theta)$, and hence

$\mathbf{K}(t) = \frac{I}{2\pi R \sin \theta} (-\hat{\theta}) = \frac{1}{4\pi R} \frac{dq}{dt} \frac{(1 + \cos \theta)}{\sin \theta} \hat{\theta}$. The force on a patch of area da is $d\mathbf{F} = (\mathbf{K} \times \mathbf{B}) da$.

$$\mathbf{B}_{\text{ave}} = \left[\frac{2}{3} \mu_0 M \hat{\mathbf{z}} + \frac{\mu_0}{4\pi} \frac{\frac{4}{3} \pi R^3 M}{R^3} (2 \cos \theta \hat{\mathbf{r}} + \sin \theta \hat{\theta}) \right] \frac{1}{2} = \frac{\mu_0 M}{6} [2 \hat{\mathbf{z}} + 2 \cos \theta \hat{\mathbf{r}} + \sin \theta \hat{\theta}];$$

$$\mathbf{K} \times \mathbf{B} = \frac{1}{4\pi R} \frac{dq}{dt} \frac{\mu_0 M}{6} \frac{(1 + \cos \theta)}{\sin \theta} [2(\hat{\theta} \times \hat{\mathbf{z}}) + 2 \cos \theta \underbrace{(\hat{\theta} \times \hat{\mathbf{r}})}_{-\hat{\phi}}].$$

$$\begin{aligned} d\mathbf{N} &= R \hat{\mathbf{r}} \times d\mathbf{F} = \frac{\mu_0 M}{24\pi} \left(\frac{dq}{dt} \right) \frac{(1 + \cos \theta)}{\sin \theta} 2 \left[\underbrace{\hat{\mathbf{r}} \times (\hat{\theta} \times \hat{\mathbf{z}})}_{\hat{\theta}(\hat{\mathbf{r}} \cdot \hat{\mathbf{z}}) - \hat{\mathbf{z}}(\hat{\mathbf{r}} \cdot \hat{\theta})} - \cos \theta \underbrace{(\hat{\mathbf{r}} \times \hat{\phi})}_{-\hat{\theta}} \right] R^2 \sin \theta d\theta d\phi \\ &= \frac{\mu_0 M}{12\pi} \left(\frac{dq}{dt} \right) (1 + \cos \theta) R^2 [\cos \theta \hat{\theta} + \cos \theta \hat{\theta}] d\theta d\phi = \frac{\mu_0 M R^2}{6\pi} \left(\frac{dq}{dt} \right) (1 + \cos \theta) \cos \theta d\theta d\phi \hat{\theta}. \end{aligned}$$

The x and y components integrate to zero; $(\hat{\theta})_z = -\sin \theta$, so (using $\int_0^{2\pi} d\phi = 2\pi$):

$$\begin{aligned} N_z &= -\frac{\mu_0 M R^2}{6\pi} \left(\frac{dq}{dt} \right) (2\pi) \int_0^\pi (1 + \cos \theta) \cos \theta \sin \theta d\theta = -\frac{\mu_0 M R^2}{3} \left(\frac{dq}{dt} \right) \left(\frac{\sin^2 \theta}{2} - \frac{\cos^3 \theta}{3} \right) \Big|_0^\pi \\ &= -\frac{\mu_0 M R^2}{3} \left(\frac{dq}{dt} \right) \left(\frac{2}{3} \right) = -\frac{2\mu_0}{9} M R^2 \frac{dq}{dt}. \quad \boxed{\mathbf{N} = -\frac{2\mu_0}{9} M R^2 \frac{dq}{dt} \hat{\mathbf{z}}}. \end{aligned}$$

Therefore

$$\mathbf{L} = \int \mathbf{N} dt = -\frac{2\mu_0}{9} M R^2 \hat{\mathbf{z}} \int_Q^0 dq = \boxed{\frac{2\mu_0}{9} M R^2 Q \hat{\mathbf{z}}} \text{ (same as (a)).}$$

(I used the *average* field at the discontinuity—which is the correct thing to do—but in this case you’d get the same answer using either the inside field or the outside field.)

Problem 8.9

(a) $\mathcal{E} = -\frac{d\Phi}{dt}$; $\Phi = \pi a^2 B$; $B = \mu_0 n I_s$; $\mathcal{E} = I_r R$. So $\boxed{I_r = -\frac{1}{R} (\mu_0 \pi a^2 n) \frac{dI_s}{dt}}$.

(b) $\oint \mathbf{E} \cdot d\mathbf{l} = -\frac{d\Phi}{dt} \Rightarrow E(2\pi a) = -\mu_0 \pi a^2 n \frac{dI_s}{dt} \Rightarrow \mathbf{E} = -\frac{1}{2} \mu_0 a n \frac{dI_s}{dt} \hat{\phi}$. $\mathbf{B} = \frac{\mu_0 I_r}{2} \frac{b^2}{(b^2 + z^2)^{3/2}} \hat{\mathbf{z}}$ (Eq. 5.38).

$$\mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B}) = \frac{1}{\mu_0} \left(-\frac{\mu_0 a n}{2} \frac{dI_s}{dt} \right) \left(\frac{\mu_0 I_r}{2} \frac{b^2}{(b^2 + z^2)^{3/2}} \right) (\hat{\phi} \times \hat{\mathbf{z}}) = \boxed{-\frac{1}{4} \mu_0 I_r \frac{dI_s}{dt} \frac{a b^2 n}{(b^2 + z^2)^{3/2}} \hat{\mathbf{r}}}.$$

Power:

$$P = \int \mathbf{S} \cdot d\mathbf{a} = \int_{-\infty}^{\infty} (S)(2\pi a) dz = -\frac{1}{2}\pi\mu_0 a^2 b^2 n I_n \frac{dI_s}{dt} \int_{-\infty}^{\infty} \frac{1}{(b^2 + z^2)^{3/2}} dx$$

$$\text{The integral is } \frac{z}{b^2 \sqrt{z^2 + b^2}} \Big|_{-\infty}^{\infty} = \frac{1}{b^2} - \left(-\frac{1}{b^2}\right) = \frac{2}{b^2}.$$

$$= -\left(\pi\mu_0 a^2 n \frac{dI_s}{dt}\right) I_r = (RI_r) I_r = I_r^2 R. \quad \text{qed}$$

Problem 8.10

According to Eqs. 3.104, 4.14, 5.87, and 6.16, the fields are

$$\mathbf{E} = \begin{cases} -\frac{1}{3\epsilon_0} \mathbf{P}, & (r < R), \\ \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} [3(\mathbf{p} \cdot \hat{\mathbf{r}}) \hat{\mathbf{r}} - \mathbf{p}], & (r > R), \end{cases} \quad \mathbf{B} = \begin{cases} \frac{2}{3}\mu_0 \mathbf{M}, & (r < R), \\ \frac{\mu_0}{4\pi} \frac{m}{r^3} [3(\mathbf{m} \cdot \hat{\mathbf{r}}) \hat{\mathbf{r}} - \mathbf{m}], & (r > R), \end{cases}$$

where $\mathbf{p} = (4/3)\pi R^3 \mathbf{P}$, and $\mathbf{m} = (4/3)\pi R^3 \mathbf{M}$. Now $\mathbf{p} = \epsilon_0 \int (\mathbf{E} \times \mathbf{B}) d\tau$, and there are two contributions, one from inside the sphere and one from outside.

Inside:

$$\mathbf{p}_{\text{in}} = \epsilon_0 \int \left(-\frac{1}{3\epsilon_0} \mathbf{P}\right) \times \left(\frac{2}{3}\mu_0 \mathbf{M}\right) d\tau = -\frac{2}{9}\mu_0 (\mathbf{P} \times \mathbf{M}) \int d\tau = -\frac{2}{9}\mu_0 (\mathbf{P} \times \mathbf{M}) \frac{4}{3}\pi R^3 = \frac{8}{27}\mu_0 \pi R^3 (\mathbf{M} \times \mathbf{P}).$$

Outside:

$$\mathbf{p}_{\text{out}} = \epsilon_0 \frac{1}{4\pi\epsilon_0} \frac{\mu_0}{4\pi} \int \frac{1}{r^6} \{ [3(\mathbf{p} \cdot \hat{\mathbf{r}}) \hat{\mathbf{r}} - \mathbf{p}] \times [3(\mathbf{m} \cdot \hat{\mathbf{r}}) \hat{\mathbf{r}} - \mathbf{m}] \} d\tau.$$

Now $\hat{\mathbf{r}} \times (\mathbf{p} \times \mathbf{m}) = \mathbf{p}(\hat{\mathbf{r}} \cdot \mathbf{m}) - \mathbf{m}(\hat{\mathbf{r}} \cdot \mathbf{p})$, so $\hat{\mathbf{r}} \times [\hat{\mathbf{r}} \times (\mathbf{p} \times \mathbf{m})] = (\hat{\mathbf{r}} \cdot \mathbf{m})(\hat{\mathbf{r}} \times \mathbf{p}) - (\hat{\mathbf{r}} \cdot \mathbf{p})(\hat{\mathbf{r}} \times \mathbf{m})$, whereas using the BAC-CAB rule directly gives $\hat{\mathbf{r}} \times [\hat{\mathbf{r}} \times (\mathbf{p} \times \mathbf{m})] = \hat{\mathbf{r}}[\hat{\mathbf{r}} \cdot (\mathbf{p} \times \mathbf{m})] - (\mathbf{p} \times \mathbf{m})(\hat{\mathbf{r}} \cdot \hat{\mathbf{r}})$. So $\{ [3(\mathbf{p} \cdot \hat{\mathbf{r}}) \hat{\mathbf{r}} - \mathbf{p}] \times [3(\mathbf{m} \cdot \hat{\mathbf{r}}) \hat{\mathbf{r}} - \mathbf{m}] \} = -3(\mathbf{p} \cdot \hat{\mathbf{r}})(\hat{\mathbf{r}} \times \mathbf{m}) + 3(\mathbf{m} \cdot \hat{\mathbf{r}})(\hat{\mathbf{r}} \times \mathbf{p}) + (\mathbf{p} \times \mathbf{m}) = 3\{\hat{\mathbf{r}}[\hat{\mathbf{r}} \cdot (\mathbf{p} \times \mathbf{m})] - (\mathbf{p} \times \mathbf{m})\} + (\mathbf{p} \times \mathbf{m}) = -2(\mathbf{p} \times \mathbf{m}) + 3\hat{\mathbf{r}}[\hat{\mathbf{r}} \cdot (\mathbf{p} \times \mathbf{m})]$.

$$\mathbf{p}_{\text{out}} = \frac{\mu_0}{16\pi^2} \int \frac{1}{r^6} \{-2(\mathbf{p} \times \mathbf{m}) + 3\hat{\mathbf{r}}[\hat{\mathbf{r}} \cdot (\mathbf{p} \times \mathbf{m})]\} r^2 \sin \theta dr d\theta d\phi.$$

To evaluate the integral, set the z axis along $(\mathbf{p} \times \mathbf{m})$; then $\hat{\mathbf{r}} \cdot (\mathbf{p} \times \mathbf{m}) = |\mathbf{p} \times \mathbf{m}| \cos \theta$. Meanwhile, $\hat{\mathbf{r}} = \sin \theta \cos \phi \hat{\mathbf{x}} + \sin \theta \sin \phi \hat{\mathbf{y}} + \cos \theta \hat{\mathbf{z}}$. But $\sin \phi$ and $\cos \phi$ integrate to zero, so the $\hat{\mathbf{x}}$ and $\hat{\mathbf{y}}$ terms drop out, leaving

$$\begin{aligned} \mathbf{p}_{\text{out}} &= \frac{\mu_0}{16\pi^2} \left(\int_0^\infty \frac{1}{r^4} dr \right) \left\{ -2(\mathbf{p} \times \mathbf{m}) \int \sin \theta d\theta d\phi + 3|\mathbf{p} \times \mathbf{m}| \hat{\mathbf{z}} \int \cos^2 \theta \sin \theta d\theta d\phi \right\} \\ &= \frac{\mu_0}{16\pi^2} \left(-\frac{1}{3r^3} \right) \Big|_R^\infty \left[-2(\mathbf{p} \times \mathbf{m}) 4\pi + 3(\mathbf{p} \times \mathbf{m}) \frac{4\pi}{3} \right] = -\frac{\mu_0}{12\pi R^3} (\mathbf{p} \times \mathbf{m}) \\ &= -\frac{\mu_0}{12\pi R^3} \left(\frac{4}{3}\pi R^3 \mathbf{P} \right) \times \left(\frac{4}{3}\pi R^3 \mathbf{M} \right) = \frac{4\mu_0}{27} R^3 (\mathbf{M} \times \mathbf{P}). \\ \mathbf{p}_{\text{tot}} &= \left(\frac{8}{27} + \frac{4}{27} \right) \mu_0 R^3 (\mathbf{M} \times \mathbf{P}) = \boxed{\frac{4}{9} \mu_0 R^3 (\mathbf{M} \times \mathbf{P})}. \end{aligned}$$

Problem 8.11

(a) From Eq. 5.68 and Prob. 5.36,

$$\begin{cases} r < R: \mathbf{E} = 0, \mathbf{B} = \frac{2}{3}\mu_0\sigma R\omega \hat{\mathbf{z}}, \text{ with } \sigma = \frac{e}{4\pi R^2}; \\ r > R: \mathbf{E} = \frac{1}{4\pi\epsilon_0} \frac{e}{r^2} \hat{\mathbf{r}}, \mathbf{B} = \frac{\mu_0}{4\pi} \frac{m}{r^3} (2\cos\theta \hat{\mathbf{r}} + \sin\theta \hat{\boldsymbol{\theta}}), \text{ with } m = \frac{4}{3}\pi\sigma\omega R^4. \end{cases}$$

The energy stored in the electric field is (Ex. 2.8):

$$W_E = \frac{1}{8\pi\epsilon_0} \frac{e^2}{R}.$$

The energy density of the internal magnetic field is:

$$u_B = \frac{1}{2\mu_0} B^2 = \frac{1}{2\mu_0} \left(\frac{2}{3}\mu_0 R\omega \frac{e}{4\pi R^2} \right)^2 = \frac{\mu_0\omega^2 e^2}{72\pi^2 R^2}, \text{ so } W_{B_{in}} = \frac{\mu_0\omega^2 e^2}{72\pi^2 R^2} \frac{4}{3}\pi R^3 = \frac{\mu_0 e^2 \omega^2 R}{54\pi}.$$

The energy density in the external magnetic field is:

$$u_B = \frac{1}{2\mu_0} \frac{\mu_0^2}{16\pi^2} \frac{m^2}{r^6} (4\cos^2\theta + \sin^2\theta) = \frac{e^2\omega^2 R^4 \mu_0}{18(16\pi^2)} \frac{1}{r^6} (3\cos^2\theta + 1), \text{ so}$$

$$W_{B_{out}} = \frac{\mu_0 e^2 \omega^2 R^4}{(18)(16)\pi^2} \int_R^\infty \frac{1}{r^6} r^2 dr \int_0^\pi (3\cos^2\theta + 1) \sin\theta d\theta \int_0^{2\pi} d\phi = \frac{\mu_0 e^2 \omega^2 R^4}{(18)(16)\pi^2} \left(\frac{1}{3R^3} \right) (4)(2\pi) = \frac{\mu_0 e^2 \omega^2 R}{108\pi}.$$

$$W_B = W_{B_{in}} + W_{B_{out}} = \frac{\mu_0 e^2 \omega^2 R}{108\pi} (2 + 1) = \frac{\mu_0 e^2 \omega^2 R}{36\pi}; \quad W = W_E + W_B = \boxed{\frac{1}{8\pi\epsilon_0} \frac{e^2}{R} + \frac{\mu_0 e^2 \omega^2 R}{36\pi}}.$$

$$(b) \text{ Same as Prob. 8.8(a), with } Q \rightarrow e \text{ and } m \rightarrow \frac{1}{3}e\omega R^2: \quad \boxed{\mathbf{L} = \frac{\mu_0 e^2 \omega R}{18\pi} \hat{\mathbf{z}}}.$$

$$(c) \frac{\mu_0 e^2}{18\pi} \omega R = \frac{\hbar}{2} \Rightarrow \omega R = \frac{9\pi\hbar}{\mu_0 e^2} = \frac{(9)(\pi)(1.05 \times 10^{-34})}{(4\pi \times 10^{-7})(1.60 \times 10^{-19})^2} = \boxed{9.23 \times 10^{10} \text{ m/s}}.$$

$$\frac{1}{8\pi\epsilon_0} \frac{e^2}{R} \left[1 + \frac{2}{9} \left(\frac{\omega R}{c} \right)^2 \right] = mc^2; \quad \left[1 + \frac{2}{9} \left(\frac{\omega R}{c} \right)^2 \right] = 1 + \frac{2}{9} \left(\frac{9.23 \times 10^{10}}{3 \times 10^8} \right)^2 = 2.10 \times 10^4;$$

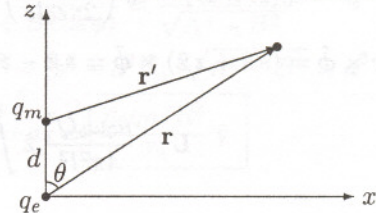
$$R = \frac{(2.01 \times 10^4)(1.6 \times 10^{-19})^2}{8\pi(8.85 \times 10^{-12})(9.11 \times 10^{-31})(3 \times 10^8)^2} = \boxed{2.95 \times 10^{-11} \text{ m}}; \quad \omega = \frac{9.23 \times 10^{10}}{2.95 \times 10^{-11}} = \boxed{3.13 \times 10^{21} \text{ rad/s}}.$$

Since ωR , the speed of a point on the equator, is 300 times the speed of light, this "classical" model is clearly unrealistic.

Problem 8.12

$$\mathbf{E} = \frac{q_e}{4\pi\epsilon_0} \frac{\mathbf{r}}{r^3};$$

$$\mathbf{B} = \frac{\mu_0 q_m}{4\pi} \frac{\mathbf{r}'}{r'^3} = \frac{\mu_0 q_m}{4\pi} \frac{(\mathbf{r} - d\hat{\mathbf{z}})}{(r^2 + d^2 - 2rd\cos\theta)^{3/2}}.$$



Momentum density (Eq. 8.33):

$$\wp = \epsilon_0(\mathbf{E} \times \mathbf{B}) = \frac{\mu_0 q_e q_m}{(4\pi)^2} \frac{(-d)(\mathbf{r} \times \hat{\mathbf{z}})}{r^3 (r^2 + d^2 - 2rd \cos \theta)^{3/2}}.$$

Angular momentum density (Eq. 8.34):

$$\ell = (\mathbf{r} \times \wp) = -\frac{\mu_0 q_e q_m d}{(4\pi)^2} \frac{\mathbf{r} \times (\mathbf{r} \times \hat{\mathbf{z}})}{r^3 (r^2 + d^2 - 2rd \cos \theta)^{3/2}}. \quad \text{But } \mathbf{r} \times (\mathbf{r} \times \hat{\mathbf{z}}) = \mathbf{r}(\mathbf{r} \cdot \hat{\mathbf{z}}) - r^2 \hat{\mathbf{z}} = r^2 \cos \theta \hat{\mathbf{r}} - r^2 \hat{\mathbf{z}}.$$

The x and y components will integrate to zero; using $(\hat{\mathbf{r}})_z = \cos \theta$, we have:

$$\begin{aligned} \mathbf{L} &= -\frac{\mu_0 q_e q_m d}{(4\pi)^2} \hat{\mathbf{z}} \int \frac{r^2 (\cos^2 \theta - 1)}{r^3 (r^2 + d^2 - 2rd \cos \theta)^{3/2}} r^2 \sin \theta dr d\theta d\phi. \quad \text{Let } u \equiv \cos \theta : \\ &= \frac{\mu_0 q_e q_m d}{(4\pi)^2} \hat{\mathbf{z}} (2\pi) \int_{-1}^1 \int_0^\infty \frac{r (1 - u^2)}{(r^2 + d^2 - 2rd u)^{3/2}} du dr. \end{aligned}$$

Do the r integral first:

$$\int_0^\infty \frac{r dr}{(r^2 + d^2 - 2rd u)^{3/2}} = \frac{(ru - d)}{d(1 - u^2)\sqrt{r^2 + d^2 - 2rd u}} \Big|_0^\infty = \frac{u}{d(1 - u^2)} + \frac{d}{d(1 - u^2)d} = \frac{u + 1}{d(1 - u^2)} = \frac{1}{d(1 - u)}.$$

Then

$$\mathbf{L} = \frac{\mu_0 q_e q_m d}{8\pi} \hat{\mathbf{z}} \frac{1}{d} \int_{-1}^1 \frac{(1 - u^2)}{(1 - u)} du = \frac{\mu_0 q_e q_m}{8\pi} \hat{\mathbf{z}} \int_{-1}^1 (1 + u) du = \frac{\mu_0 q_e q_m}{8\pi} \hat{\mathbf{z}} \left(u + \frac{u^2}{2} \right) \Big|_{-1}^1 = \boxed{\frac{\mu_0 q_e q_m}{4\pi} \hat{\mathbf{z}}}.$$

Problem 8.13

(a) The rotating shell at radius b produces a solenoidal magnetic field:

$$\mathbf{B} = \mu_0 K \hat{\mathbf{z}}, \quad \text{where } K = \sigma_b \omega_b b, \quad \text{and } \sigma_b = -\frac{Q}{2\pi b l}. \quad \text{So } \mathbf{B} = -\frac{\mu_0 \omega_b Q}{2\pi l} \hat{\mathbf{z}} \quad (a < s < b).$$

The shell at a also produces a magnetic field $(\mu_0 \omega_a Q / 2\pi l) \hat{\mathbf{z}}$, in the region $s < a$, so the total field inside the inner shell is

$$\mathbf{B} = \frac{\mu_0 Q}{2\pi l} (\omega_a - \omega_b) \hat{\mathbf{z}}, \quad (s < a).$$

Meanwhile, the electric field is

$$\mathbf{E} = \frac{1}{2\pi\epsilon_0} \frac{\lambda}{s} \hat{\mathbf{s}} = \frac{Q}{2\pi\epsilon_0 l s} \hat{\mathbf{s}}, \quad (a < s < b).$$

$$\wp = \epsilon_0(\mathbf{E} \times \mathbf{B}) = \epsilon_0 \left(\frac{Q}{2\pi\epsilon_0 l s} \right) \left(-\frac{\mu_0 \omega_b Q}{2\pi l} \right) (\hat{\mathbf{s}} \times \hat{\mathbf{z}}) = \frac{\mu_0 \omega_b Q^2}{4\pi^2 l^2 s} \hat{\phi}; \quad \ell = \mathbf{r} \times \wp = \frac{\mu_0 \omega_b Q^2}{4\pi^2 l^2 s} (\mathbf{r} \times \hat{\phi}).$$

Now $\mathbf{r} \times \hat{\phi} = (s \hat{\mathbf{s}} + z \hat{\mathbf{z}}) \times \hat{\phi} = s \hat{\mathbf{z}} - z \hat{\mathbf{s}}$, and the $\hat{\mathbf{s}}$ term integrates to zero, so

$$\mathbf{L} = \frac{\mu_0 \omega_b Q^2}{4\pi^2 l^2} \hat{\mathbf{z}} \int d\tau = \frac{\mu_0 \omega_b Q^2}{4\pi^2 l^2} \pi (b^2 - a^2) l \hat{\mathbf{z}} = \boxed{\frac{\mu_0 \omega_b Q^2 (b^2 - a^2)}{4\pi l} \hat{\mathbf{z}}}.$$

(b) The extra electric field induced by the changing magnetic field due to the rotating shells is given by

$$E 2\pi s = -\frac{d\Phi}{dt} \Rightarrow \mathbf{E} = -\frac{1}{2\pi s} \frac{d\Phi}{dt} \hat{\phi}, \text{ and in the region } a < s < b$$

$$\Phi = \frac{\mu_0 Q}{2\pi l} (\omega_a - \omega_b) \pi a^2 - \frac{\mu_0 Q \omega_b}{2\pi l} \pi (s^2 - a^2) = \frac{\mu_0 Q}{2l} (\omega_a a^2 - \omega_b s^2); \quad \mathbf{E}(s) = -\frac{1}{2\pi s} \frac{\mu_0 Q}{2l} \left(a^2 \frac{d\omega_a}{dt} - s^2 \frac{d\omega_b}{dt} \right) \hat{\phi}.$$

In particular,

$$\mathbf{E}(a) = -\frac{\mu_0 Q a}{4\pi l} \left(\frac{d\omega_a}{dt} - \frac{d\omega_b}{dt} \right) \hat{\phi}, \quad \text{and } \mathbf{E}(b) = -\frac{\mu_0 Q}{4\pi l b} \left(a^2 \frac{d\omega_a}{dt} - b^2 \frac{d\omega_b}{dt} \right) \hat{\phi}.$$

The torque on a shell is $\mathbf{N} = \mathbf{r} \times q\mathbf{E} = qsE \hat{\mathbf{z}}$, so

$$\mathbf{N}_a = Qa \left(-\frac{\mu_0 Q a}{4\pi l} \right) \left(\frac{d\omega_a}{dt} - \frac{d\omega_b}{dt} \right) \hat{\mathbf{z}}; \quad \mathbf{L}_a = \int_0^\infty \mathbf{N}_a dt = -\frac{\mu_0 Q^2 a^2}{4\pi l} (\omega_a - \omega_b) \hat{\mathbf{z}}.$$

$$\mathbf{N}_b = -Qb \left(-\frac{\mu_0 Q}{4\pi l b} \right) \left(a^2 \frac{d\omega_a}{dt} - b^2 \frac{d\omega_b}{dt} \right) \hat{\mathbf{z}}; \quad \mathbf{L}_b = \int_0^\infty \mathbf{N}_b dt = \frac{\mu_0 Q^2}{4\pi l} (a^2 \omega_a - b^2 \omega_b) \hat{\mathbf{z}}.$$

$$\mathbf{L}_{\text{tot}} = \mathbf{L}_a + \mathbf{L}_b = \frac{\mu_0 Q^2}{4\pi l} (a^2 \omega_a - b^2 \omega_b - a^2 \omega_a + a^2 \omega_b) \hat{\mathbf{z}} = \boxed{-\frac{\mu_0 Q^2 \omega_b}{4\pi l} (b^2 - a^2) \hat{\mathbf{z}}}.$$

Thus the reduction in the final mechanical angular momentum (b) is equal to the residual angular momentum in the fields (a). ✓

Problem 8.14

$$\mathbf{B} = \mu_0 n I \hat{\mathbf{z}}, \quad (s < R); \quad \mathbf{E} = \frac{q}{4\pi\epsilon_0} \frac{\mathbf{r}}{r^3}, \text{ where } \mathbf{r} = (x - a, y, z).$$

$$\wp = \epsilon_0 (\mathbf{E} \times \mathbf{B}) = \epsilon_0 (\mu_0 n I) \left(\frac{q}{4\pi\epsilon_0} \right) \frac{1}{r^3} (\mathbf{r} \times \hat{\mathbf{z}}) = \frac{\mu_0 q n I}{4\pi r^3} [y \hat{\mathbf{x}} - (x - a) \hat{\mathbf{y}}].$$

Linear Momentum.

$$\mathbf{p} = \int \wp d\tau = \frac{\mu_0 q n I}{4\pi} \int \frac{y \hat{\mathbf{x}} - (x - a) \hat{\mathbf{y}}}{[(x - a)^2 + y^2 + z^2]^{3/2}} dx dy dz. \text{ The } \hat{\mathbf{x}} \text{ term is odd in } y; \text{ it integrates to zero.}$$

$$= -\frac{\mu_0 q n I}{4\pi} \hat{\mathbf{y}} \int \frac{(x - a)}{[(x - a)^2 + y^2 + z^2]^{3/2}} dx dy dz. \text{ Do the } z \text{ integral first:}$$

$$\frac{z}{[(x - a)^2 + y^2] \sqrt{(x - a)^2 + y^2 + z^2}} \Big|_{-\infty}^{\infty} = \frac{2}{[(x - a)^2 + y^2]}.$$

$$= -\frac{\mu_0 q n I}{2\pi} \hat{\mathbf{y}} \int \frac{(x - a)}{[(x - a)^2 + y^2]} dx dy. \text{ Switch to polar coordinates:}$$

$$x = s \cos \phi, \quad y = s \sin \phi, \quad dx dy \Rightarrow s ds d\phi; \quad [(x - a)^2 + y^2] = s^2 + a^2 - 2sa \cos \phi.$$

$$= -\frac{\mu_0 q n I}{2\pi} \hat{\mathbf{y}} \int \frac{(s \cos \phi - a)}{(s^2 + a^2 - 2sa \cos \phi)} s ds d\phi$$

$$\text{Now } \int_0^{2\pi} \frac{\cos \phi d\phi}{(A + B \cos \phi)} = \frac{2\pi}{B} \left(1 - \frac{A}{\sqrt{A^2 - B^2}} \right); \quad \int_0^{2\pi} \frac{d\phi}{(A + B \cos \phi)} = \frac{2\pi}{\sqrt{A^2 - B^2}}.$$

$$\text{Here } A^2 - B^2 = (s^2 + a^2)^2 - 4s^2 a^2 = s^4 + 2s^2 a^2 + a^4 - 4s^2 a^2 = (s^2 - a^2)^2; \quad \sqrt{A^2 - B^2} = a^2 - s^2.$$

$$= \frac{\mu_0 q n I}{2a} \hat{\mathbf{y}} \int \left[1 - \left(\frac{a^2 + s^2}{a^2 - s^2} \right) + \frac{2a^2}{(a^2 - s^2)} \right] s ds = \frac{\mu_0 q n I}{a} \hat{\mathbf{y}} \int_0^R s ds = \boxed{\frac{\mu_0 q n I R^2}{2a} \hat{\mathbf{y}}}.$$

Angular Momentum.

$$\ell = \mathbf{r} \times \wp = \frac{\mu_0 q n I}{4\pi z^3} \mathbf{r} \times [y \hat{\mathbf{x}} - (x - a) \hat{\mathbf{y}}] = \frac{\mu_0 q n I}{4\pi z^3} \{z(x - a) \hat{\mathbf{x}} + zy \hat{\mathbf{y}} - [x(x - a) + y^2] \hat{\mathbf{z}}\}.$$

The $\hat{\mathbf{x}}$ and $\hat{\mathbf{y}}$ terms are odd in z , and integrate to zero, so

$$\begin{aligned} \mathbf{L} &= -\frac{\mu_0 q n I}{4\pi} \hat{\mathbf{z}} \int \frac{x^2 + y^2 - xa}{[(x - a)^2 + y^2 + z^2]^{3/2}} dx dy dz. \text{ The } z \text{ integral is the same as before.} \\ &= -\frac{\mu_0 q n I}{2\pi} \hat{\mathbf{z}} \int \frac{x^2 + y^2 - xa}{[(x - a)^2 + y^2]} dx dy = -\frac{\mu_0 q n I}{2\pi} \hat{\mathbf{z}} \int \frac{s - a \cos \phi}{(s^2 + a^2 - 2sa \cos \phi)} s^2 ds d\phi \\ &= -\mu_0 q n I \hat{\mathbf{z}} \int \left[\frac{s^2}{a^2 - s^2} + \left(1 - \frac{a^2 + s^2}{a^2 - s^2}\right) \right] s ds = -\mu_0 q n I \hat{\mathbf{z}} \int_0^R \frac{s^2 - s^2}{a^2 - s^2} s ds = \boxed{\text{zero.}} \end{aligned}$$

Problem 8.15

(a) If we're only interested in the work done on *free* charges and currents, Eq. 8.6 becomes $\frac{dW}{dt} = \int_V (\mathbf{E} \cdot \mathbf{J}_f) d\tau$. But $\mathbf{J}_f = \nabla \times \mathbf{H} - \frac{\partial \mathbf{D}}{\partial t}$ (Eq. 7.55), so $\mathbf{E} \cdot \mathbf{J}_f = \mathbf{E} \cdot (\nabla \times \mathbf{H}) - \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t}$. From product rule #6, $\nabla \cdot (\mathbf{E} \times \mathbf{H}) = \mathbf{H}(\nabla \times \mathbf{E}) - \mathbf{E} \cdot (\nabla \times \mathbf{H})$, while $\nabla \times \mathbf{E} = -\frac{\partial \mathbf{B}}{\partial t}$, so $\mathbf{E} \cdot (\nabla \times \mathbf{H}) = -\mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t} - \nabla \cdot (\mathbf{E} \times \mathbf{H})$. Therefore $\mathbf{E} \cdot \mathbf{J}_f = -\mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t} - \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} - \nabla \cdot (\mathbf{E} \times \mathbf{H})$, and hence

$$\frac{dW}{dt} = - \int_V \left(\mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} + \mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t} \right) d\tau - \oint_S (\mathbf{E} \times \mathbf{H}) \cdot d\mathbf{a}.$$

This is Poynting's theorem for the fields in matter. Evidently the Poynting vector, representing the power per unit area transported by the fields, is $\mathbf{S} = \mathbf{E} \times \mathbf{H}$, and the rate of change of the electromagnetic energy density is $\frac{\partial u_{em}}{\partial t} = \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} + \mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t}$.

For *linear* media, $\mathbf{D} = \epsilon \mathbf{E}$ and $\mathbf{H} = \frac{1}{\mu} \mathbf{B}$, with ϵ and μ constant (in time); then

$$\frac{\partial u_{em}}{\partial t} = \epsilon \mathbf{E} \cdot \frac{\partial \mathbf{E}}{\partial t} + \frac{1}{\mu} \mathbf{B} \cdot \frac{\partial \mathbf{B}}{\partial t} = \frac{1}{2} \epsilon \frac{\partial}{\partial t} (\mathbf{E} \cdot \mathbf{E}) + \frac{1}{2\mu} \frac{\partial}{\partial t} (\mathbf{B} \cdot \mathbf{B}) = \frac{1}{2} \frac{\partial}{\partial t} (\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H}),$$

so $u_{em} = \frac{1}{2} (\mathbf{E} \cdot \mathbf{D} + \mathbf{B} \cdot \mathbf{H})$. *qed*

(b) If we're only interested in the force on *free* charges and currents, Eq. 8.15 becomes $\mathbf{f} = \rho_f \mathbf{E} + \mathbf{J}_f \times \mathbf{B}$. But $\rho_f = \nabla \cdot \mathbf{D}$, and $\mathbf{J}_f = \nabla \times \mathbf{H} - \frac{\partial \mathbf{D}}{\partial t}$, so $\mathbf{f} = \mathbf{E}(\nabla \cdot \mathbf{D}) + (\nabla \times \mathbf{H}) \times \mathbf{B} - \left(\frac{\partial \mathbf{D}}{\partial t} \right) \times \mathbf{B}$. Now $\frac{\partial}{\partial t} (\mathbf{D} \times \mathbf{B}) = \frac{\partial \mathbf{D}}{\partial t} \times \mathbf{B} + \mathbf{D} \times \left(\frac{\partial \mathbf{B}}{\partial t} \right)$, and $\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$, so $\frac{\partial \mathbf{D}}{\partial t} \times \mathbf{B} = \frac{\partial}{\partial t} (\mathbf{D} \times \mathbf{B}) + \mathbf{D} \times (\nabla \times \mathbf{E})$, and hence $\mathbf{f} = \mathbf{E}(\nabla \cdot \mathbf{D}) - \mathbf{D} \times (\nabla \times \mathbf{E}) - \mathbf{B} \times (\nabla \times \mathbf{H}) - \frac{\partial}{\partial t} (\mathbf{D} \times \mathbf{B})$. As before, we can with impunity add the term $\mathbf{H}(\nabla \cdot \mathbf{B})$, so

$$\mathbf{f} = \{[\mathbf{E}(\nabla \cdot \mathbf{D}) - \mathbf{D} \times (\nabla \times \mathbf{E})] + [\mathbf{H}(\nabla \cdot \mathbf{B}) - \mathbf{B} \times (\nabla \times \mathbf{H})]\} - \frac{\partial}{\partial t} (\mathbf{D} \times \mathbf{B}).$$

The term in curly brackets can be written as the divergence of a stress tensor (as in Eq. 8.21), and the last term is (minus) the rate of change of the momentum density, $\wp = \mathbf{D} \times \mathbf{B}$.