

PH20105 Hand-In-Exercise 2022-23

1-The minimum of the Rosenbrock valley

Logic:

$$y = F(x_0, x_1) = 100(x_1 - x_0^2)^2 + (1 - x_0)^2$$

y is composed of two squares and therefore $y \geq 0$

Assuming the minimum occurs at $y = 0 \Rightarrow x_1 - x_0^2 = 0$ and $1 - x_0 = 0$

By substituting and solving for x_1 and x_0 we find that the minimum occurs at $F(1, 1)$

$$x_0 = 1 \Rightarrow x_1 - (1)^2 = 0 \Rightarrow x_1 = 1$$

Differentiating:

$$\frac{\partial y}{\partial x_0} = -400x_0(x_1 - x_0^2) - 2(1 - x_0)$$

$$\frac{\partial y}{\partial x_1} = 200(x_1 - x_0^2)$$

$$\frac{\partial y}{\partial x_0} = \frac{\partial y}{\partial x_1} = 0$$

From the second equation $\Rightarrow x_1 = x_0^2$

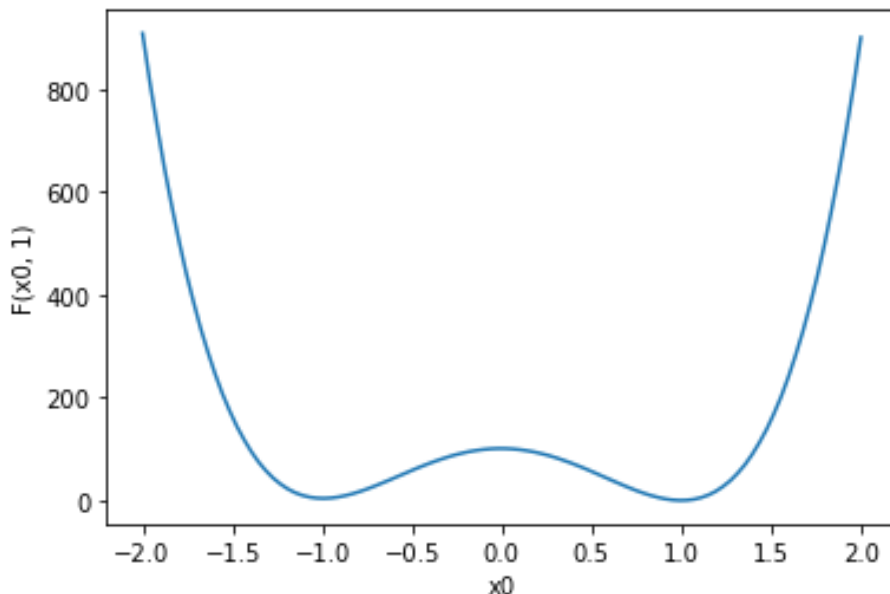
Subbing into the first equation $\Rightarrow x_0 = 1$ and therefore $x_1 = \pm 1$

Subbing $x_1 = -1$ into the original equation we get $y = 400$

Subbing $x_1 = 1$ into the original equation we get $y = 0$

Therefore we can conclude the minimum occurs at $F(1, 1)$, we know this is a minimum and not a saddle point since y cannot take any values lower than zero.

2-Rosenbrock's parabolic valley numerically



3-Downhill simplex**1st iteration:**

$$P_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_1 = \begin{pmatrix} 2 \\ 0 \end{pmatrix}, P_2 = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$y_0 = 1, y_1 = 1601, y_2 = 401 \Rightarrow y_0 = y_l, y_1 = y_h, y_2 = y_i \text{ and } P_0 = P_l, P_1 = P_h, P_2 = P_i$$

$$\bar{P} = \frac{P_l + P_h}{2} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$P^* = 2\bar{P} - P_h = \begin{pmatrix} -2 \\ 2 \end{pmatrix} \Rightarrow y^* = 409$$

$$y^* > y_i \Rightarrow y^* < y_h$$

$$P^{**} = \frac{P^* + \bar{P}}{2} = \begin{pmatrix} -1 \\ 1.5 \end{pmatrix} \Rightarrow y^{**} = 29$$

$$y^{**} < y^*$$

$$P_h = P^{**} = \begin{pmatrix} -1 \\ 1.5 \end{pmatrix} = P_1 \Rightarrow P_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_1 = \begin{pmatrix} -1 \\ 1.5 \end{pmatrix}, P_2 = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$n = 2, \sqrt{\sum_i \frac{(y_i - \bar{y})^2}{n}} \approx 832.7$$

$$832.7 > 10^{-8}$$

2nd iteration:

$$P_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_1 = \begin{pmatrix} -1 \\ 1.5 \end{pmatrix}, P_2 = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$y_0 = 1, y_1 = 29, y_2 = 401 \Rightarrow y_0 = y_l, y_1 = y_i, y_2 = y_h \text{ and } P_0 = P_l, P_1 = P_i, P_2 = P_h$$

$$\bar{P} = \frac{P_l + P_h}{2} = \begin{pmatrix} -0.5 \\ 0.75 \end{pmatrix}$$

$$P^* = 2\bar{P} - P_h = \begin{pmatrix} -1 \\ -0.5 \end{pmatrix} \Rightarrow y^* = 229$$

$$y^* > y_i \Rightarrow y^* < y_h$$

$$P^{**} = \frac{P^* + \bar{P}}{2} = \begin{pmatrix} -0.75 \\ 0.125 \end{pmatrix} \Rightarrow y^{**} = \frac{1421}{64} \approx 22.2$$

$$y^{**} < y^*$$

$$P_h = P^{**} = \begin{pmatrix} -0.75 \\ 0.125 \end{pmatrix} = P_2 \Rightarrow P_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_1 = \begin{pmatrix} -1 \\ 1.5 \end{pmatrix}, P_2 = \begin{pmatrix} -0.75 \\ 0.125 \end{pmatrix}$$

$$n = 2, \sqrt{\sum_i \frac{(y_i - \bar{y})^2}{n}} \approx 223.3$$

$$223.3 > 10^{-8}$$

Coordinates at the end of the 2nd iteration:

$$P_0 = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, P_1 = \begin{pmatrix} -1 \\ 1.5 \end{pmatrix}, P_2 = \begin{pmatrix} -0.75 \\ 0.125 \end{pmatrix}$$

$$y_0 = 1, y_1 = 29, y_2 \approx 22.2$$

Comparing to the code:

Final vertices:

(0.000000, 0.000000)

(-1.000000, 1.500000)

(-0.750000, 0.125000)

Evaluations:

1.000000

29.000000

22.203125

Iterations: 2

These coordinates match with those calculated previously.

The full code returns:

Final vertices:

(1.000108, 1.000217)

(0.999851, 0.999698)

(1.000017, 1.000041)

Evaluations:

0.000000

0.000000

0.000000

Iterations: 57

Appendix:

2-Rosenbrock's parabolic valley numerically

```
#include <stdio.h>
#include <math.h>

#define N 2 //number of dimensions

typedef struct {
    double x[N];          //struct containing the coordinates of the vertices
} Point;

double func(Point P) {
    return 100 * pow(P.x[1] - pow(P.x[0], 2), 2) + pow(1 - P.x[0], 2); //Rosenbrock function

void file_data(char *textfile, double xlow, double xhigh, int values) {

    double x0 = xlow;
    double step = (xhigh - xlow) / (values - 1);

    FILE *fp = fopen(textfile, "w");

    for (int i = 0; i < 100; i++, x0 += step) {
        Point P = {x0, 1};
        fprintf(fp, "%.3lf, %.3lf\n", x0, func(P));    //writing data into textfile
    }

    fclose(fp);
}

int main() {
    file_data("data.txt", -2., 2., 100);

    return 0;
}
```

Python:

```
import matplotlib.pyplot as plt
import numpy as np
data = np.loadtxt("data.txt", delimiter = ', ')
x = np.array(data[:,0])
F = np.array(data[:,1])
plt.plot(x, F)
plt.xlabel("x0")
plt.ylabel("F(x0, 1)")
plt.draw()
plt.show()
```

3-Downhill simplex

```

/*****
 *
 * Candidate number: 24563
 *
 * Downhill Simplex algorithm for finding the
 * minimum of the Rosenbrock function
 *
 * Starting vertices:
 * p0 = (0,0), p1 = (2,0), p2 = (0,2)
 *
 * This code can be amended for functions with more
 * variables by changing N to the number of
 * variables in the new function and the number of
 * initial vertices to N + 1
 *
 *****/

#include <stdio.h>
#include <math.h>

#define N 2      //number of dimensions

#define ALPHA 1.0
#define BETA 0.5
#define GAMMA 2.0
#define RHO 0.5   //coefficients for reflection, contraction, expansion and shrinking

#define TOL 1e-8
#define MAX_ITER 1000 //standard deviation tolerance and maximum iterations

typedef struct {
    double x[N];      //struct containing the coordinates of the vertices
} Point;

double func(Point P) {
    return 100 * pow(P.x[1] - pow(P.x[0], 2), 2) + pow(1 - P.x[0], 2); //Rosenbrock function
}

void sortPoints(double Y[], Point P[]) {
    double temp;
    Point pTemp;
    for (int i = 0; i < N; i++) {
        for (int j = i + 1; j < N + 1; j++) {
            if (Y[i] > Y[j]) {
                temp = Y[i];
                Y[i] = Y[j];    //reordering outputs from smallest to largest
                Y[j] = temp;
            }
        }
    }
}

```

```

        pTemp = P[i];
        P[i] = P[j];    //reordering the corresponding vertices
        P[j] = pTemp;
    }
}

}

void centroid(Point P[], Point* Pbar) {
    for (int i = 0; i < N; i++) {
        Pbar->x[i] = 0;
        for (int j = 0; j < N; j++) {
            Pbar->x[i] += P[j].x[i] / N;    //the centroid is the average of all vertices except
        }                                //Ph (worst vertex), denoted by Pbar
    }
}

void reflect(Point* Ps, Point* Pbar, Point P[]) {
    for (int i = 0; i < N; i++) {
        Ps->x[i] = Pbar->x[i] + ALPHA * (Pbar->x[i] - P[N].x[i]);    //expansion of Pbar away from
    }                                                                //Ph, denoted by P*
}

void insideContract(Point* Pss, Point P[], Point* Pbar) {
    for (int i = 0; i < N; i++) {
        Pss->x[i] = Pbar->x[i] + BETA * (P[N].x[i] - Pbar->x[i]);    //contraction of Ph towards
    }                                                                //Pbar, denoted by P**
}

void outsideContract(Point* Pss, Point* Ps, Point* Pbar) {
    for (int i = 0; i < N; i++) {
        Pss->x[i] = Pbar->x[i] + BETA * (Ps->x[i] - Pbar->x[i]);    //contraction of P* towards
    }                                                                //Pbar, denoted by P**
}

void expand(Point* Pss, Point* Ps, Point* Pbar) {
    for (int i = 0; i < N; i++) {
        Pss->x[i] = Pbar->x[i] + GAMMA * (Ps->x[i] - Pbar->x[i]);    //expansion of P* away from
    }                                                                //Pbar, denoted by P**
}

void shrink(Point P[]) {
    for (int i = 0; i < N + 1; i++) {
        for (int j = 0; j < N; j++) {
            P[i].x[j] = P[0].x[j] + RHO * (P[i].x[j] - P[0].x[j]);    //contraction of every point
        }                                                                //towards P1 (best vertex)
    }
}

void replacePoint(Point* new, Point* orig) {
    *new = *orig;    //replacing Ph with P* or P**
}

```

```

_Bool MinCon(double Y[]) {
    double Ybar = 0, sum = 0;
    for (int i = 0; i < N + 1; i++) {
        Ybar += Y[i] / (N + 1);
    }
    for (int i = 0; i < N + 1; i++) {
        sum += pow(Y[i] - Ybar, 2) / N;
    }
    return (sqrt(sum) < TOL);    //condition for breaking the loop containing the simplex method
}

```

```

void simplex(Point P[]) {
    Point Pbar, Ps, Pss;
    double Ys, Yss, Y[N + 1];

    int a; //iterations

    for (a = 0; a < MAX_ITER; a++) {

        for (int i = 0; i < N + 1; i++) {
            Y[i] = func(P[i]);                //initialising function outputs
        }

        sortPoints(Y, P);
        centroid(P, &Pbar);
        reflect(&Ps, &Pbar, P);

        Ys = func(Ps);

        if (Ys >= Y[0] && Ys < Y[N - 1]) {      //if y* >= yl and y* <= second worst vertex
            replacePoint(&P[N], &Ps);          //replacing Ph with P*
        }

        else if (Ys < Y[0]) {                  //if y* < yl
            expand(&Pss, &Ps, &Pbar);
            Yss = func(Pss);

            if (Yss < Ys) {                    //if y** < y*
                replacePoint(&P[N], &Pss);    //replacing Ph with P**
            }

            else {
                replacePoint(&P[N], &Ps);    //replacing Ph with P*
            }
        }

        else {                                //if y* >= second worst vertex

            if (Ys < Y[N]) {                  //if y* < yh
                outsideContract(&Pss, &Ps, &Pbar);
                Yss = func(Pss);

                if (Yss < Ys) {                //if y** < y*

```

```

        replacePoint(&P[N], &Pss);    //replacing Ph with P**
    }

    else {
        shrink(P);
    }
}

else {    //if y* >= yh
    insideContract(&Pss, P, &Pbar);
    Yss = func(Pss);

    if (Yss < Y[N]) {                //if y** < yh
        replacePoint(&P[N], &Pss);    //replacing Ph with P**
    }

    else {
        shrink(P);
    }
}

}

if (MinCon(Y)) {
    break;
}

}

printf("Final vertices:\n");
for (int i = 0; i < N + 1; i++) {
    printf("(%lf, %lf)\n", P[i].x[0], P[i].x[1]);
}

printf("\nEvaluations:\n");
for (int i = 0; i < N + 1; i++) {
    printf("%lf\n", func(P[i]));
}

printf("\nIterations: %d\n", a + 1);
}

int main() {
    Point P[N + 1] = { {0, 0}, {2, 0}, {0, 2} };    //initial vertices (each vertex has N coordinates)
    simplex(P);
    return 0;
}

```