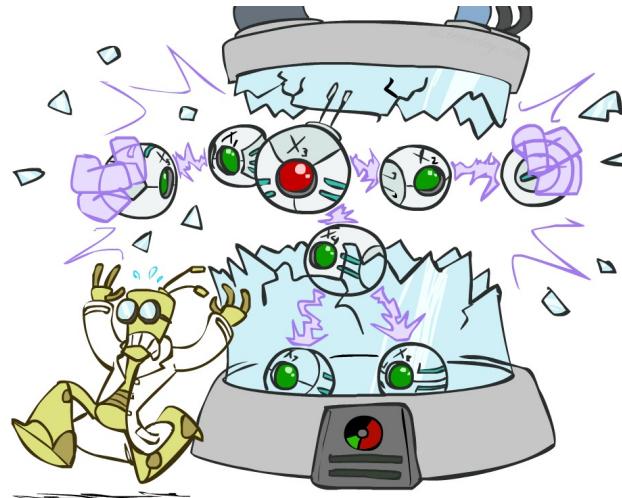


CS 3568: Intelligent Systems

Bayes' Nets (Part 3)



Instructor: Tara Salman

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[These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley (ai.berkeley.edu).]

Texas Tech University

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Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node

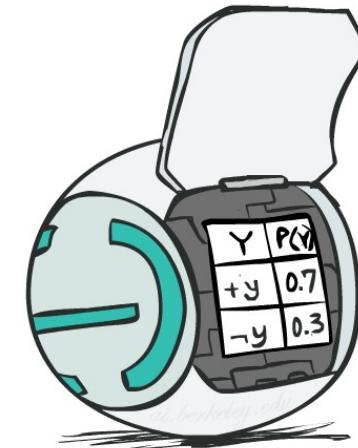
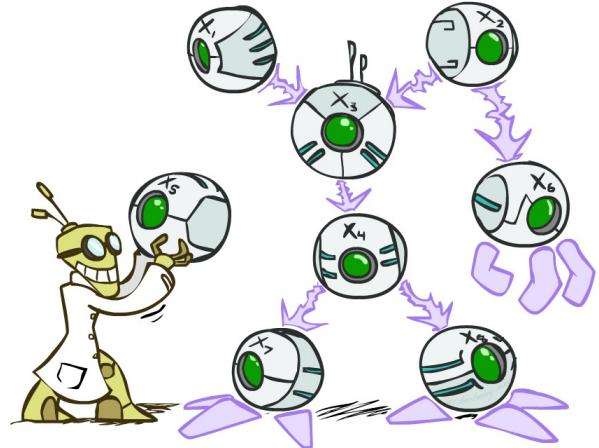
- A collection of distributions over X, one for each combination of parents' values

$$P(X|a_1 \dots a_n)$$

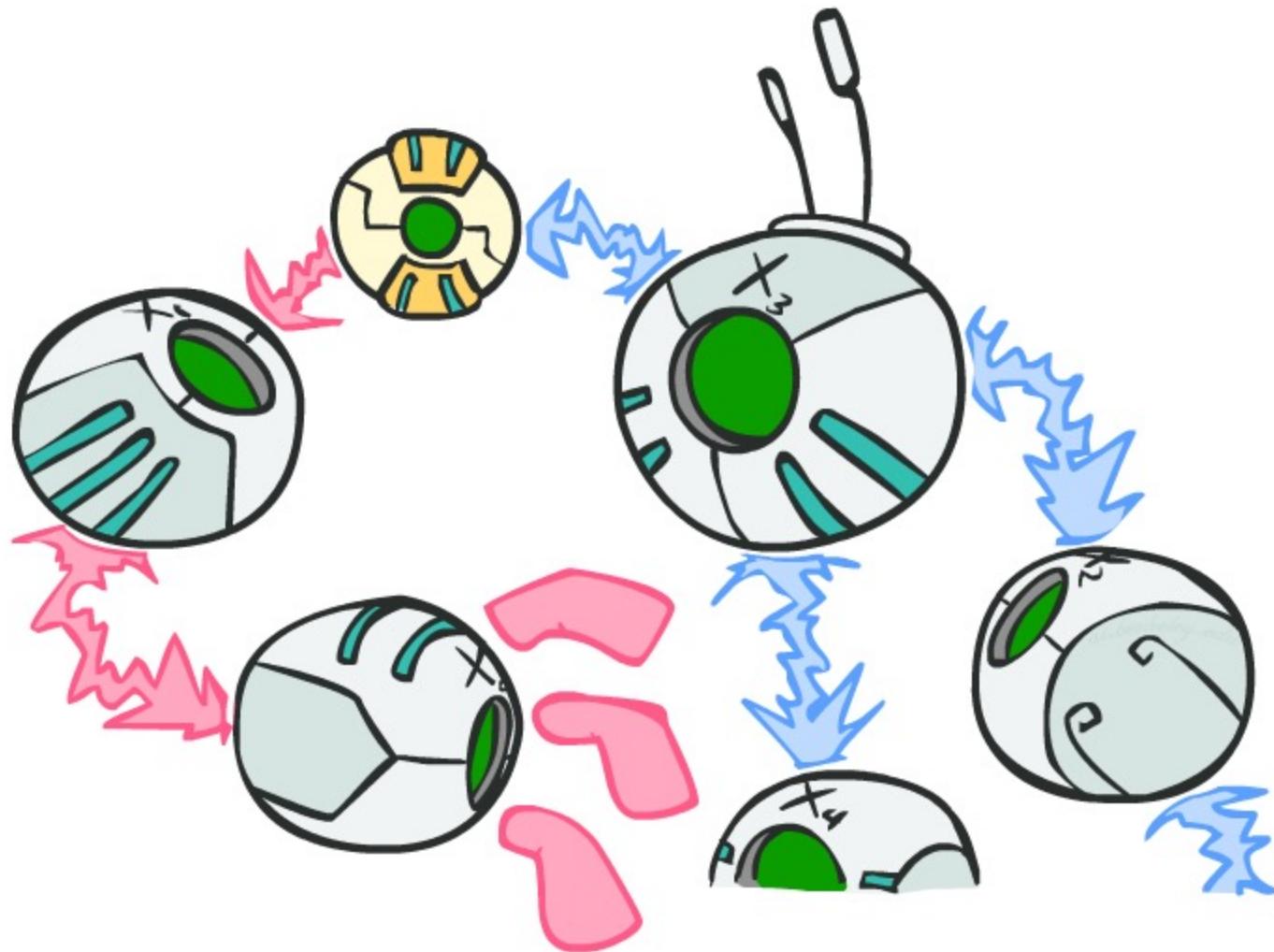
- Bayes' nets implicitly encode joint distributions

- As a product of local conditional distributions
- To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$



D-separation



Causal Chains

- This configuration is a “causal chain”



X: Low pressure

Y: Rain

Z: Traffic

$$\overrightarrow{P(x,y,z) = P(x)P(y|x)P(z|y)}$$

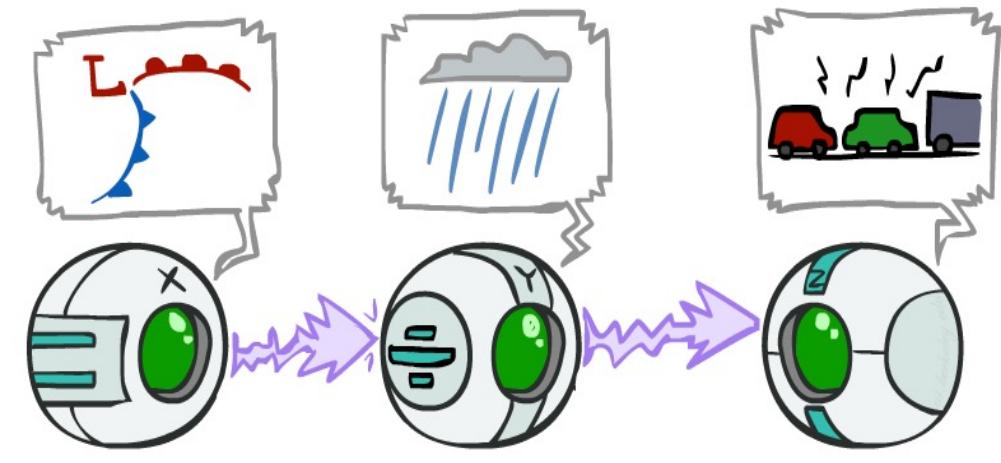
- Guaranteed X independent of Z? *No!*

- One example set of CPTs for which X is not independent of Z is sufficient to show this independence is not guaranteed.
- Example:
 - Low pressure causes rain causes traffic, high pressure causes no rain causes no traffic
- In numbers:

$$P(+y | +x) = 1, P(-y | -x) = 1,$$
$$P(+z | +y) = 1, P(-z | -y) = 1$$

Causal Chains

- This configuration is a “causal chain”



X: Low pressure

Y: Rain

Z: Traffic

$$P(x, y, z) = P(x)P(y|x)P(z|y)$$

- Guaranteed X independent of Z given Y?

$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} \\ &= \frac{P(x)P(y|x)P(z|y)}{P(x)P(y|x)} \\ &= P(z|y) \end{aligned}$$

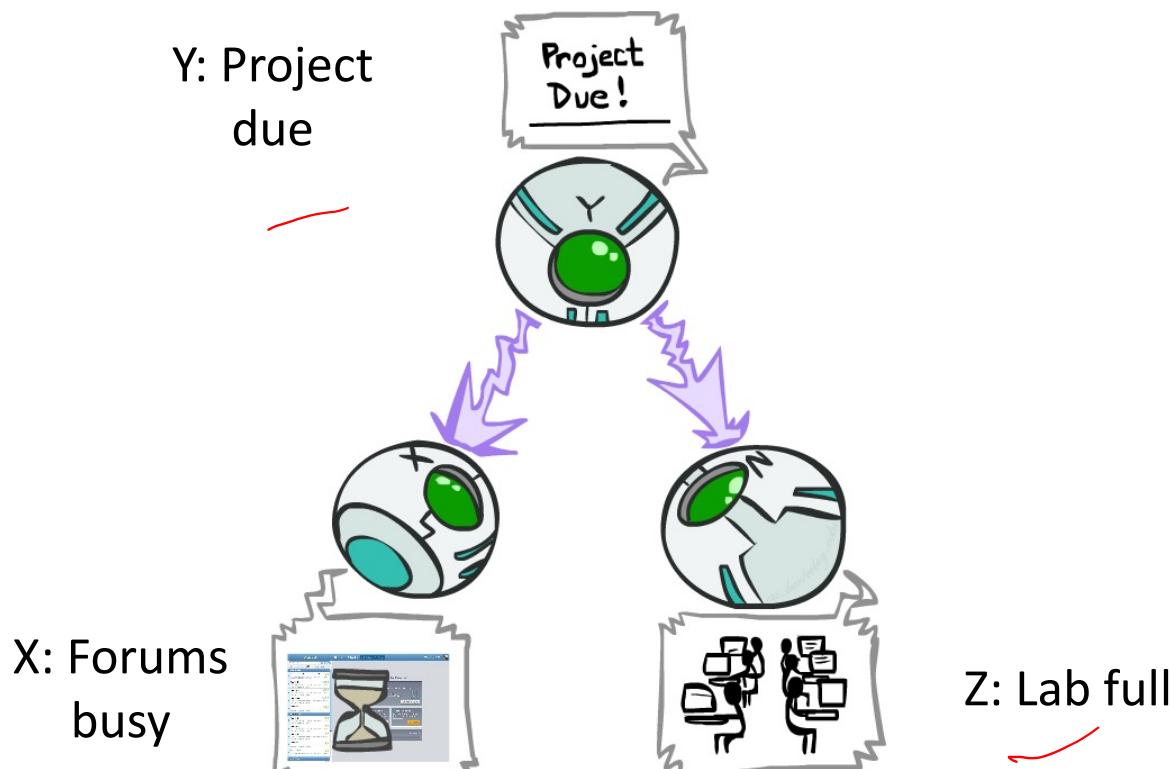
A red arrow points from the handwritten "Yes!" to the term $P(z|y)$.

Yes!

- Evidence along the chain “blocks” the influence

Common Cause

- This configuration is a “common cause”



$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

- Guaranteed X independent of Z ? *No!*

- One example set of CPTs for which X is not independent of Z is sufficient to show this independence is not guaranteed.

- Example:

- Project due causes both forums busy and lab full

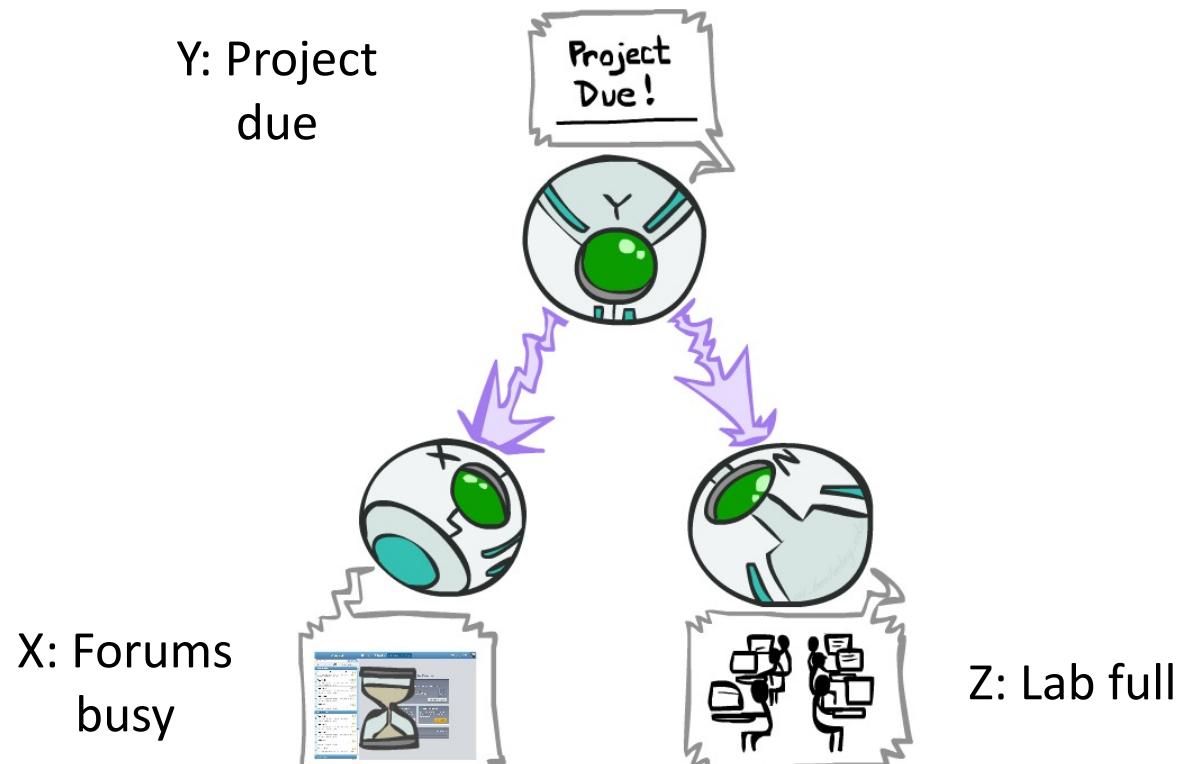
- In numbers:

$$\begin{aligned} P(+x | +y) &= 1, P(-x | -y) = 1, \\ P(+z | +y) &= 1, P(-z | -y) = 1 \end{aligned}$$

Common Cause

- This configuration is a “common cause”

- Guaranteed X and Z independent given Y?



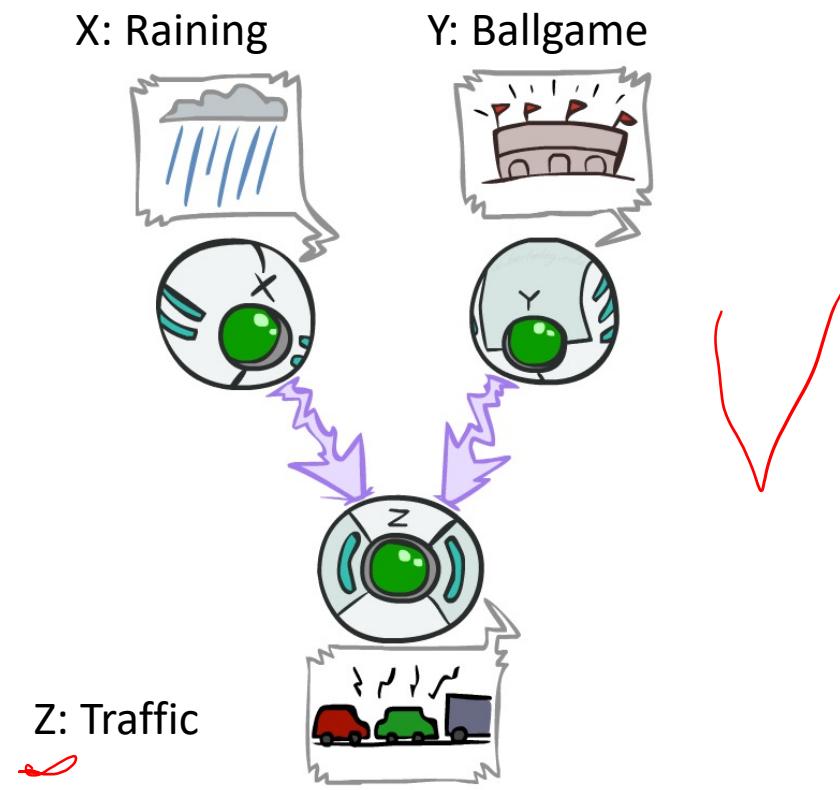
$$P(x, y, z) = P(y)P(x|y)P(z|y)$$

$$\begin{aligned} P(z|x, y) &= \frac{P(x, y, z)}{P(x, y)} \\ &= \frac{P(y)P(x|y)P(z|y)}{P(y)P(x|y)} \\ &= P(z|y) \end{aligned}$$

- Yes!
- Observing the cause blocks influence between effects.

Common Effect

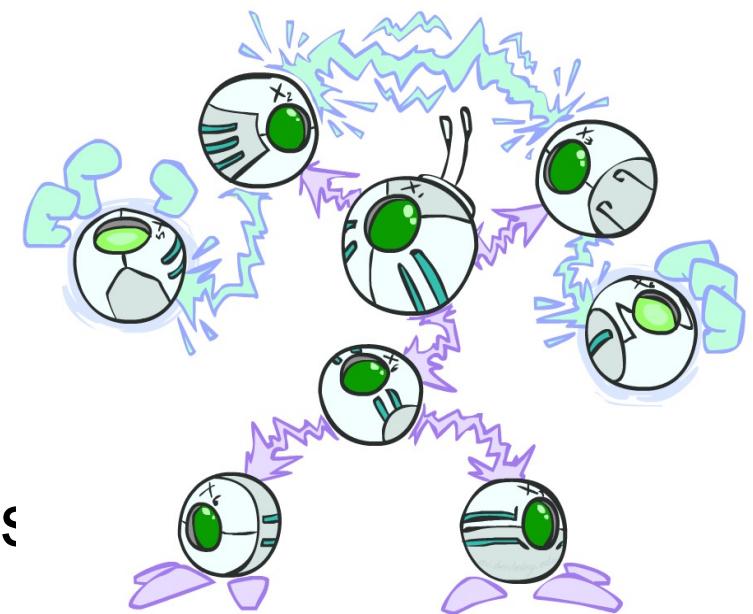
- Last configuration: two causes of one effect (v-structures)



- Are X and Y independent? ✓
 - Yes*: the ballgame and the rain cause traffic, but they are not correlated
 - Still need to prove they must be (try it!)
- Are X and Y independent given Z? ✓
 - No*: seeing traffic puts the rain and the ballgame in competition as explanation.
- This is backwards from the other cases
 - Observing an effect **activates** influence between possible causes.

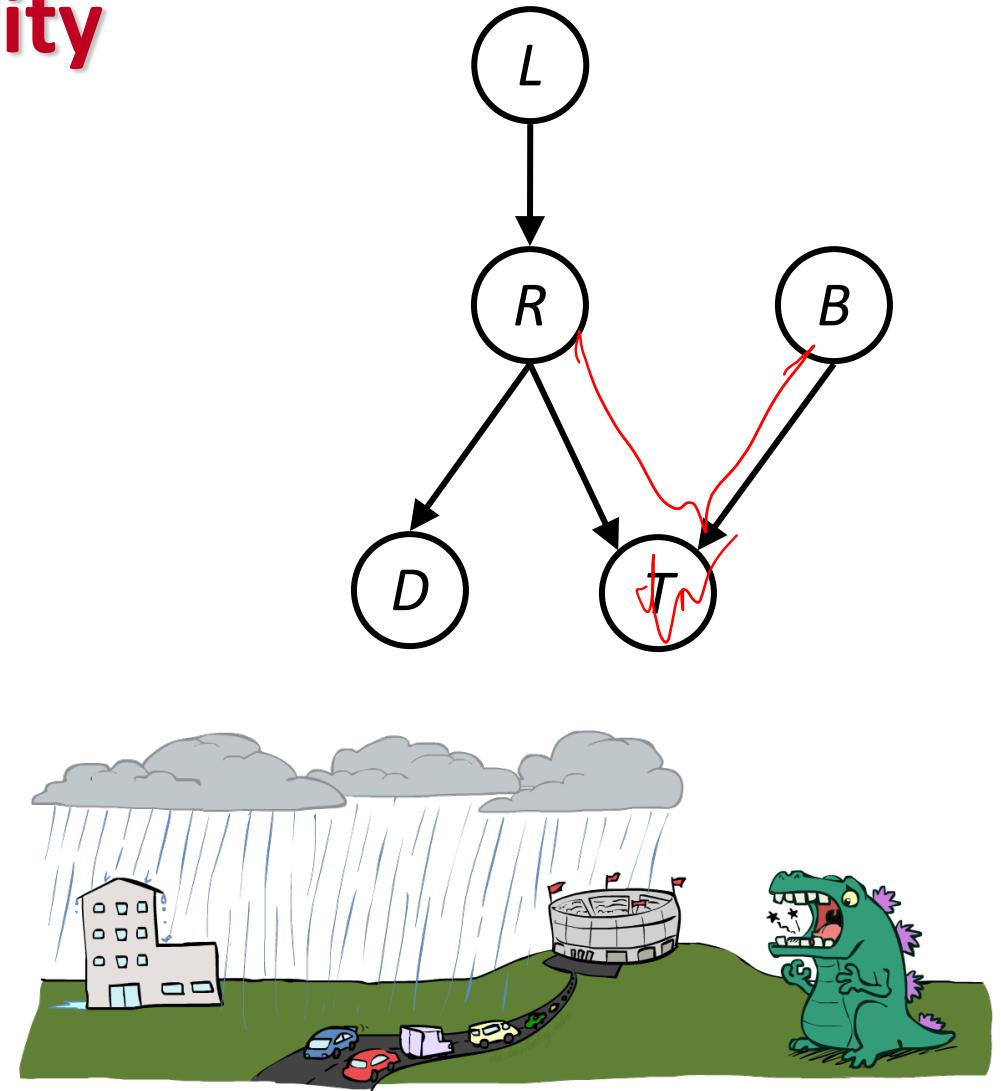
The General Case

- ❑ General question: in a given BN, are two variables independent (given evidence)?
- ❑ Solution: analyze the graph
- ❑ Any complex example can be broken into repetitions of the three canonical cas



Reachability

- ❑ Recipe: shade evidence nodes, look for paths in the resulting graph
- ❑ Attempt 1: if two nodes are connected by an undirected path not blocked by a shaded node, they are conditionally independent
- ❑ Almost works, but not quite
 - Where does it break?
 - Answer: the v-structure at T doesn't count as a link in a path unless "active"



Active / Inactive Paths

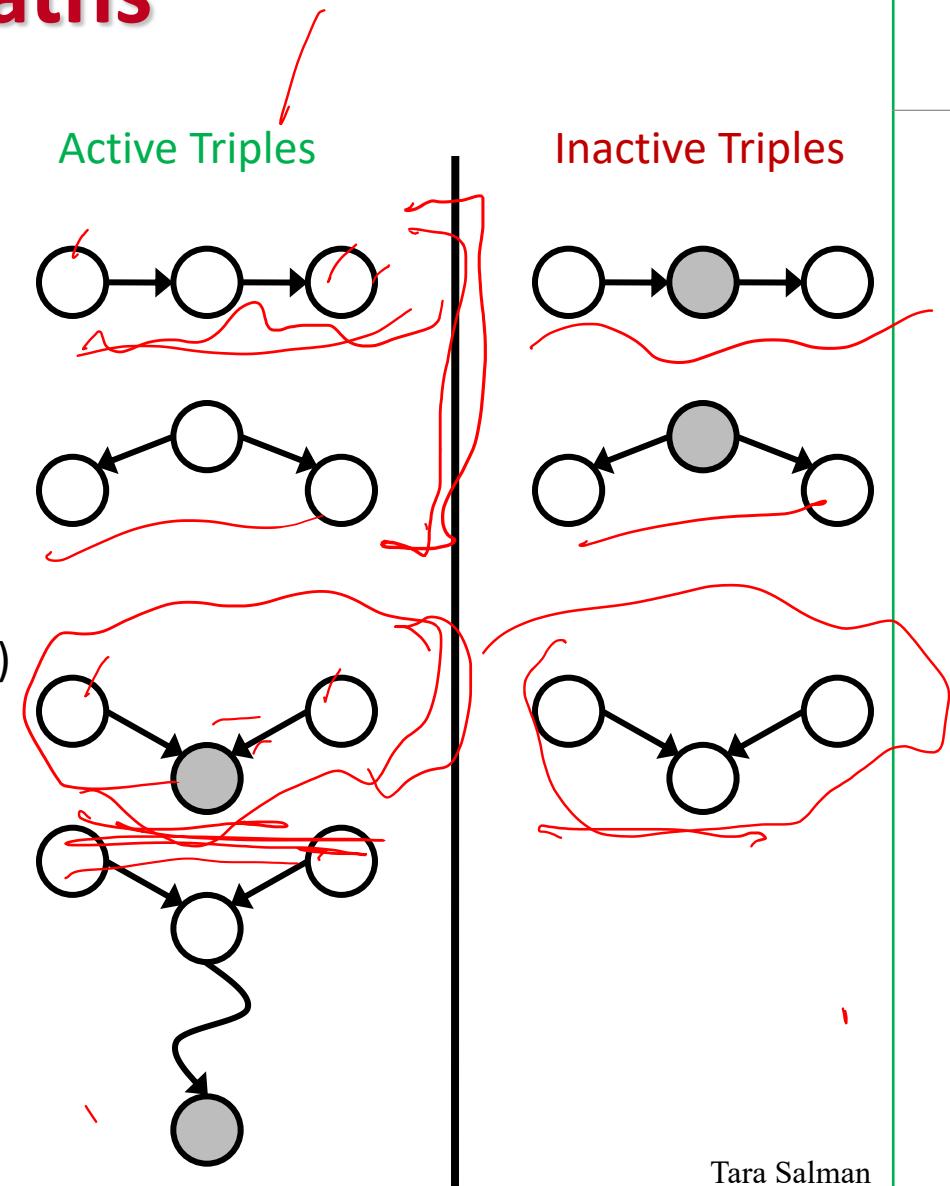
- ☐ Question: Are X and Y conditionally independent given evidence variables $\{Z\}$?

- Yes, if X and Y “d-separated” by Z
- Consider all (undirected) paths from X to Y
- No active paths = independence!

- ☐ A path is active if each triple is active:

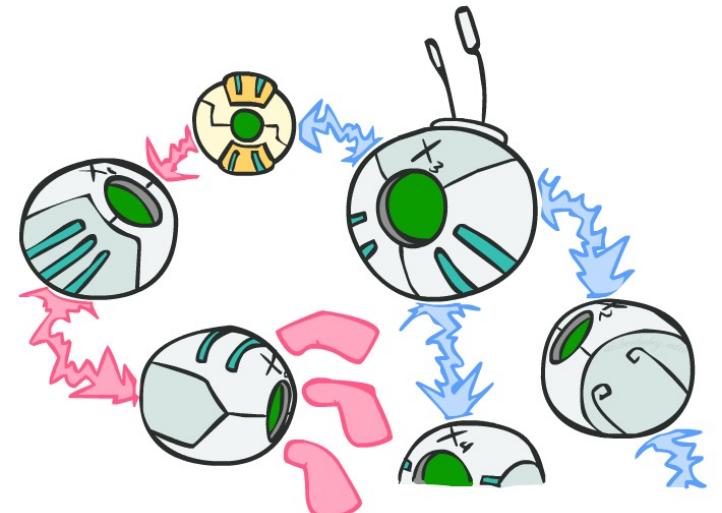
- Causal chain $A \rightarrow B \rightarrow C$ where B is unobserved (either direction)
- Common cause $A \leftarrow B \rightarrow C$ where B is unobserved
- Common effect (aka v-structure)
- $A \rightarrow B \leftarrow C$ where B or one of its descendants is observed

- ☐ All it takes to block a path is a single inactive segment



D-Separation

- Query: $X_i \perp\!\!\!\perp X_j | \{X_{k_1}, \dots, X_{k_n}\}$?
- Check all (undirected!) paths between $\underline{X_i}$ and $\underline{X_j}$
 - If one or more active, then independence not guaranteed
 - $X_i \not\perp\!\!\!\perp X_j | \{X_{k_1}, \dots, X_{k_n}\}$
 - Otherwise (i.e. if all paths are inactive), then independence is guaranteed
 - $X_i \perp\!\!\!\perp X_j | \{X_{k_1}, \dots, X_{k_n}\}$



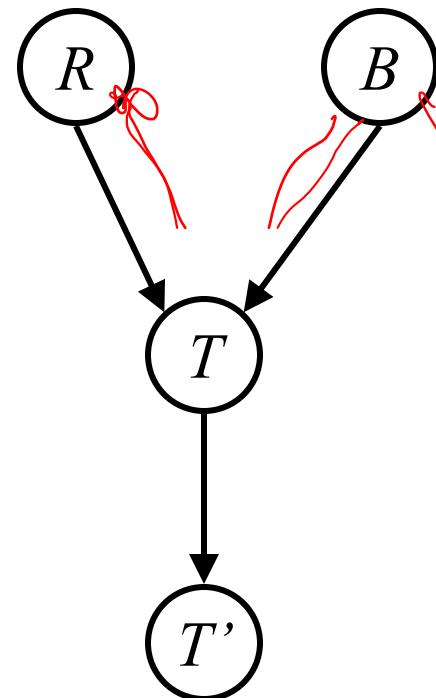
Example

$R \perp\!\!\!\perp B$

Yes

$R \perp\!\!\!\perp B | T$

$R \perp\!\!\!\perp B | T'$



Example

$L \perp\!\!\!\perp T' | T$

Yes

$L \perp\!\!\!\perp B$

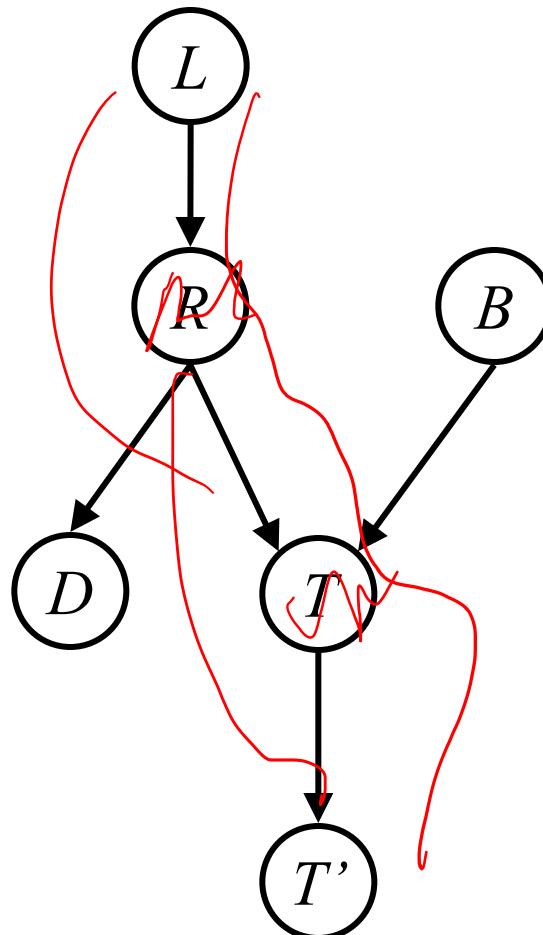
Yes

$L \perp\!\!\!\perp B | T$

$L \perp\!\!\!\perp B | T'$

$L \perp\!\!\!\perp B | T, R$

Yes



Example

- Variables:

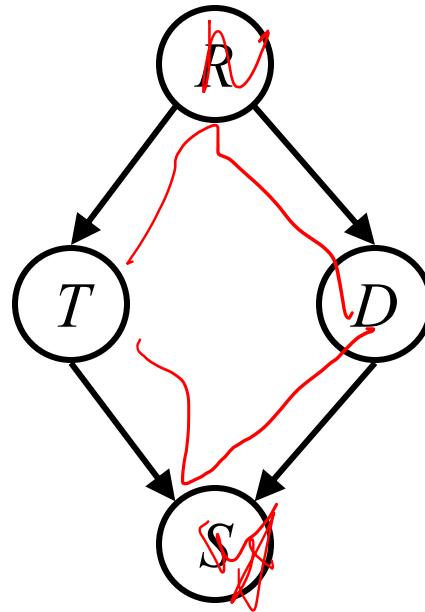
- R: Raining
- T: Traffic
- D: Roof drips
- S: I'm sad

- Questions:

$$T \perp\!\!\!\perp D$$

$$T \perp\!\!\!\perp D | R \quad \text{Yes}$$

$$T \perp\!\!\!\perp D | R, S$$



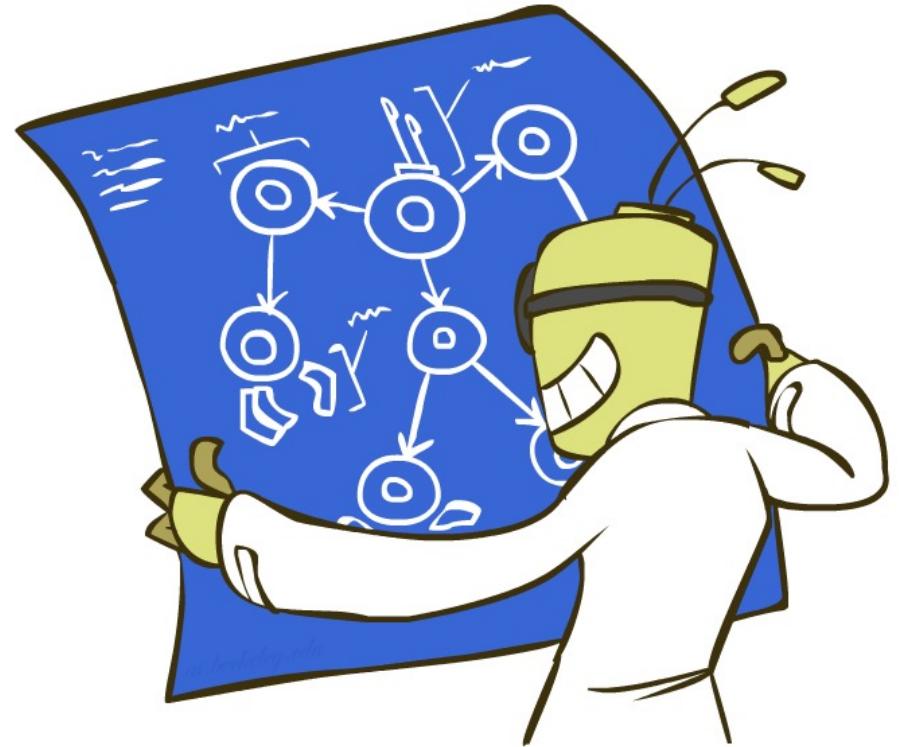
Structure Implications

- Given a Bayes net structure, can run d-separation algorithm to build a complete list of conditional independences that are necessarily true of the form

$$X_i \perp\!\!\!\perp X_j | \{X_{k_1}, \dots, X_{k_n}\}$$

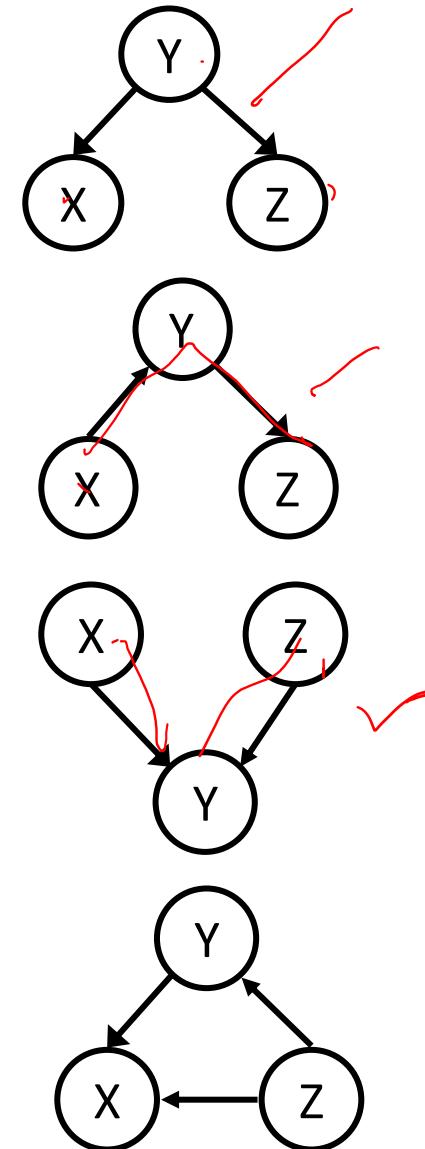


- This list determines the set of probability distributions that can be represented



Computing All Independences

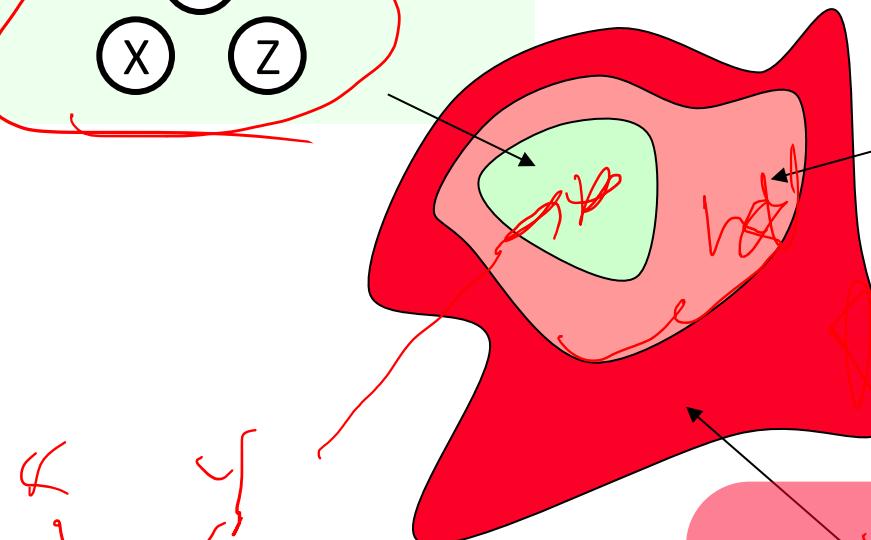
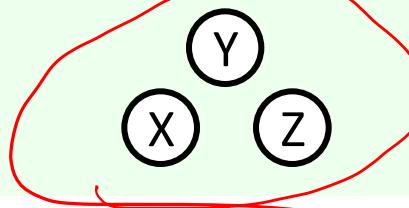
COMPUTE ALL THE INDEPENDENCES!



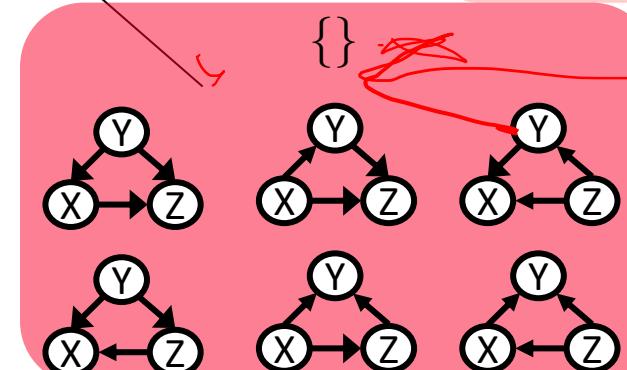
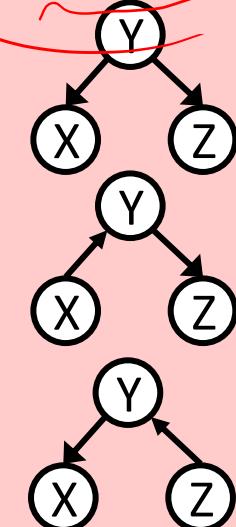
Topology Limits Distributions

- Given some graph topology G , only certain joint distributions can be encoded
- The graph structure guarantees certain (conditional) independences
- (There might be more independence)
- Adding arcs increases the set of distributions, but has several costs
- Full conditioning can encode any distribution

$$\{X \perp\!\!\!\perp Y, X \perp\!\!\!\perp Z, Y \perp\!\!\!\perp Z, X \perp\!\!\!\perp Z | Y, X \perp\!\!\!\perp Y | Z, Y \perp\!\!\!\perp Z | X\}$$



$$\{X \perp\!\!\!\perp Z | Y\}$$



Bayes' Nets

✓ Representation ✓

✓ Conditional Independences ✓

□ Probabilistic Inference

➤ Enumeration (exact, exponential complexity)

➤ Variable elimination (exact, worst-case)

exponential complexity, often better)

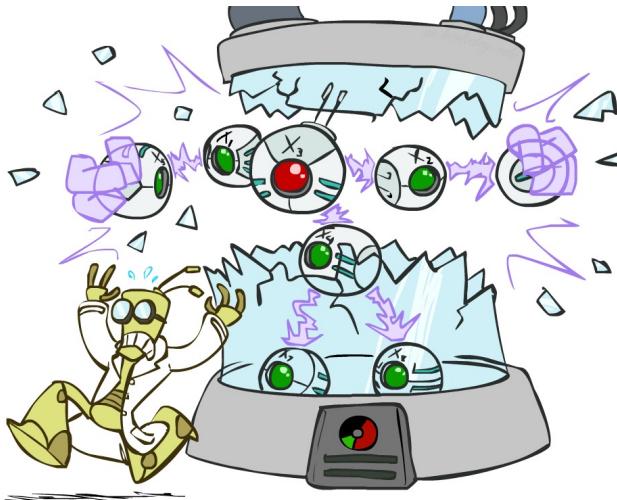
➤ Probabilistic inference is NP-complete

➤ Sampling (approximate)

□ Learning Bayes' Nets from Data

CS 3568: Intelligent Systems

Bayes' Nets: Inference (Part 3)



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Inference

- Inference: calculating some useful quantity from a joint probability distribution

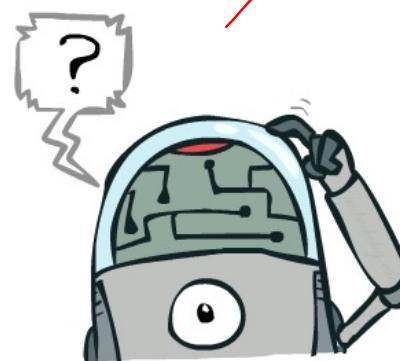
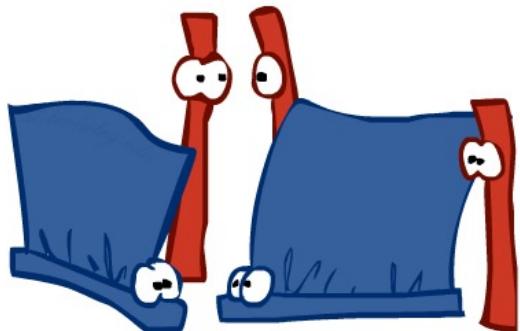
- Examples:

- Posterior probability

$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q | E_1 = e_1, \dots)$$



Inference by Enumeration

- General case:

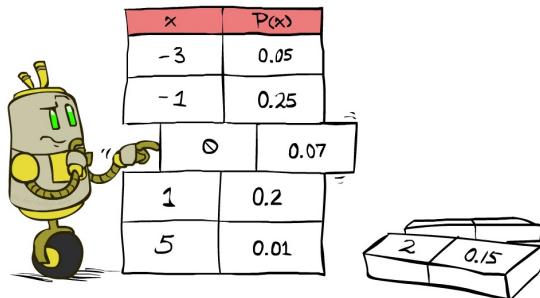
- Evidence variables $E_1 \dots E_k = e_1 \dots e_k$
 - Query* variable: Q
 - Hidden variables: $H_1 \dots H_r$
- All variables*

- We want:

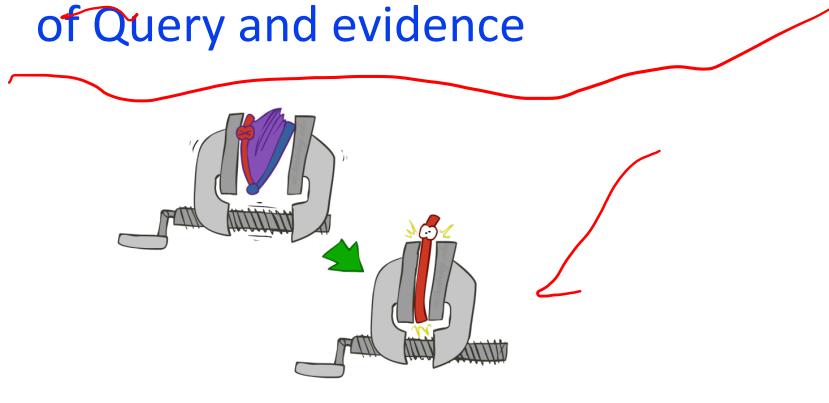
* Works fine with multiple query variables, too

$$P(Q|e_1 \dots e_k)$$

- Step 1: Select the entries consistent with the evidence



- Step 2: Sum out H to get joint of Query and evidence



$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} P(Q, h_1 \dots h_r, e_1 \dots e_k)$$

X₁, X₂, ..., X_n

- Step 3: Normalize

$$\times \frac{1}{Z}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

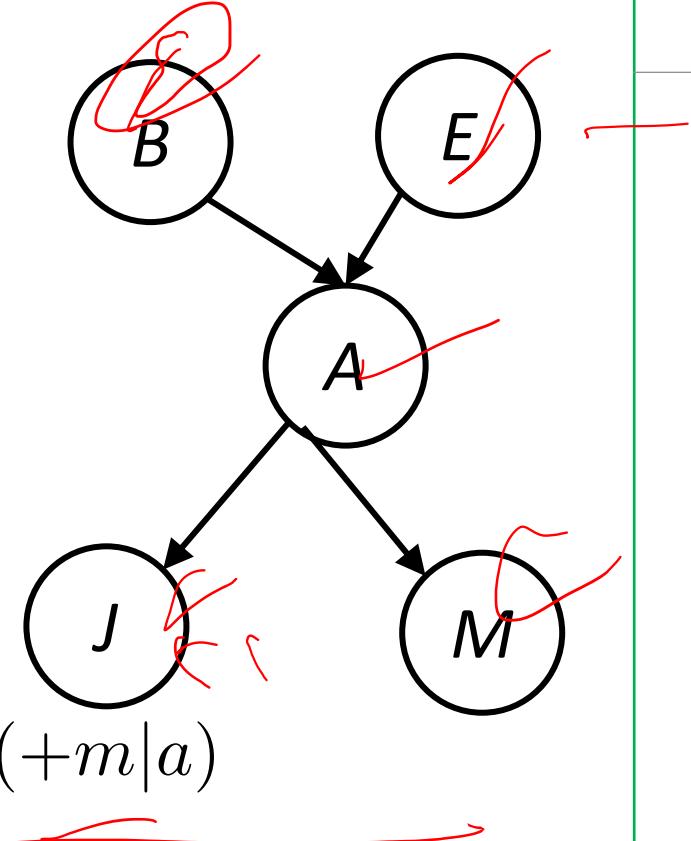
$$P(Q|e_1 \dots e_k) = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

Inference by Enumeration in Bayes' Net

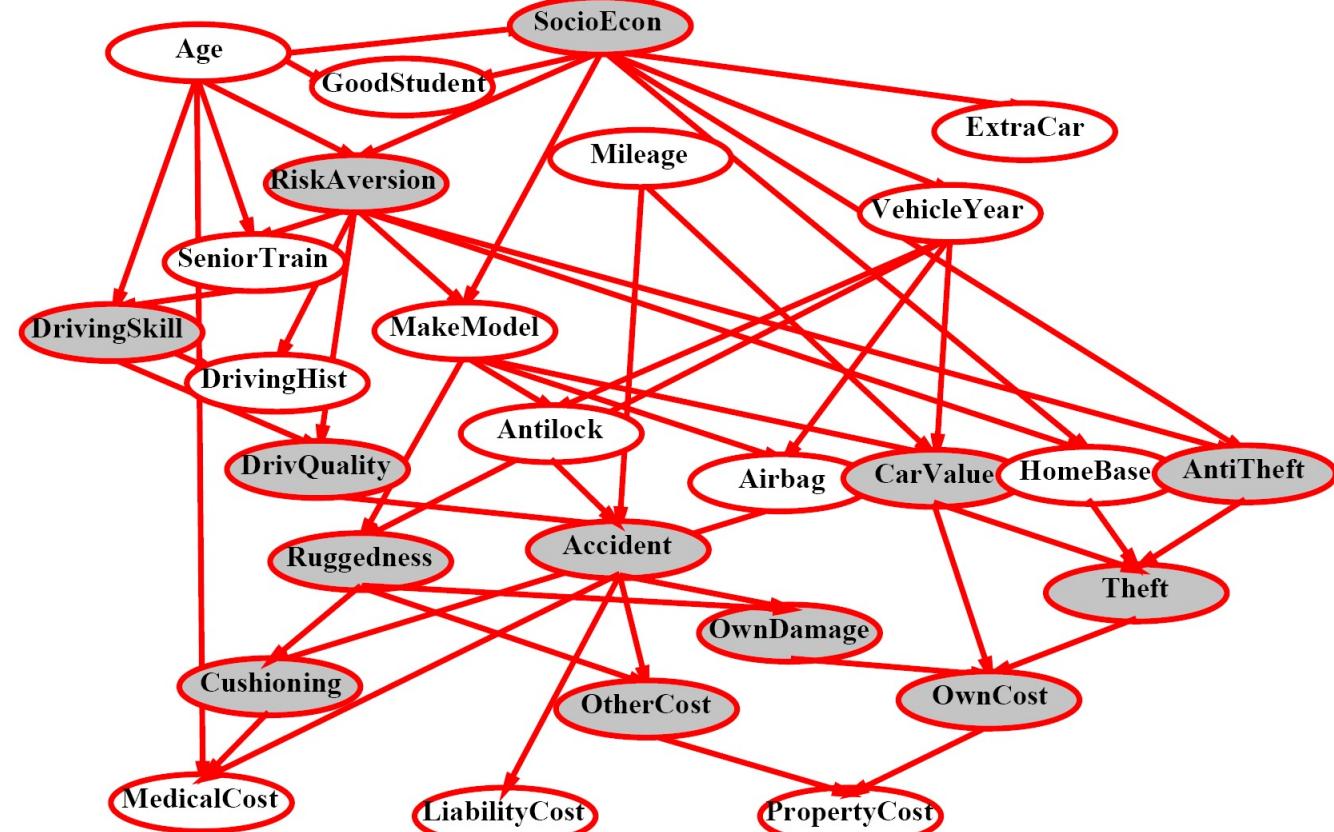
- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

$$\begin{aligned} P(B | +j, +m) &\propto_B P(B, +j, +m) \\ &= \sum_{e,a} P(B, e, a, +j, +m) \\ &= \sum_{e,a} P(B)P(e)P(a|B, e)P(+j|a)P(+m|a) \end{aligned}$$

$$\begin{aligned} &= P(B)P(+e)P(+a|B, +e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B, +e)P(+j|-a)P(+m|-a) \\ &\quad P(B)P(-e)P(+a|B, -e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B, -e)P(+j|-a)P(+m|-a) \end{aligned}$$

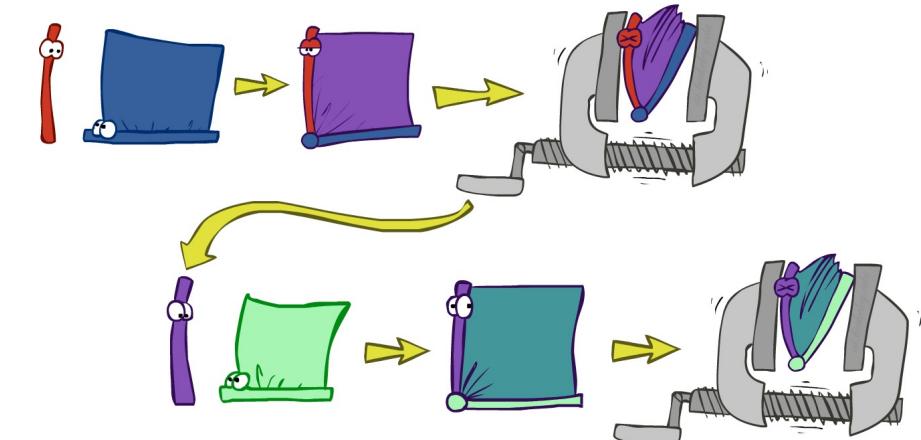
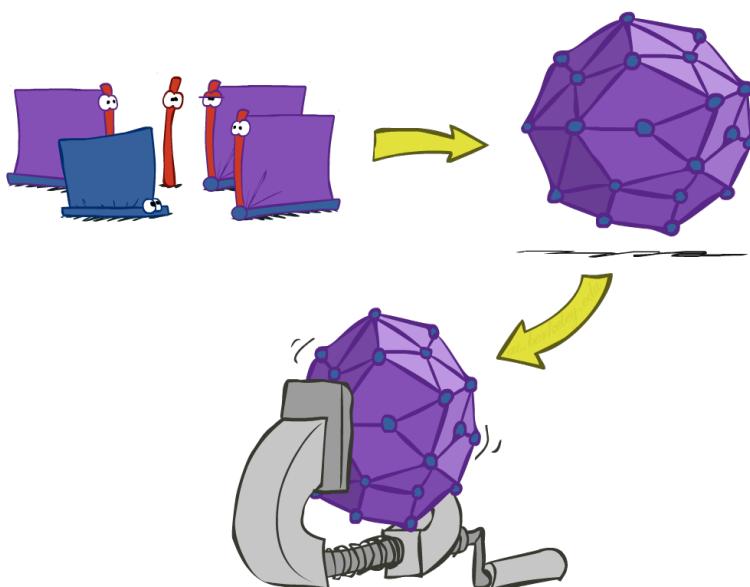


Inference by Enumeration?



Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables
- Idea: interleave joining and marginalizing!
 - Called “Variable Elimination”
 - Still NP-hard, but usually much faster than inference by enumeration



- First we'll need some new notation: factors

factors

Factor Zoo I

$P(T, W)$

❑ ~~Joint distribution: $P(X, Y)$~~

- Entries $P(x, y)$ for all x, y
- Sums to 1

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

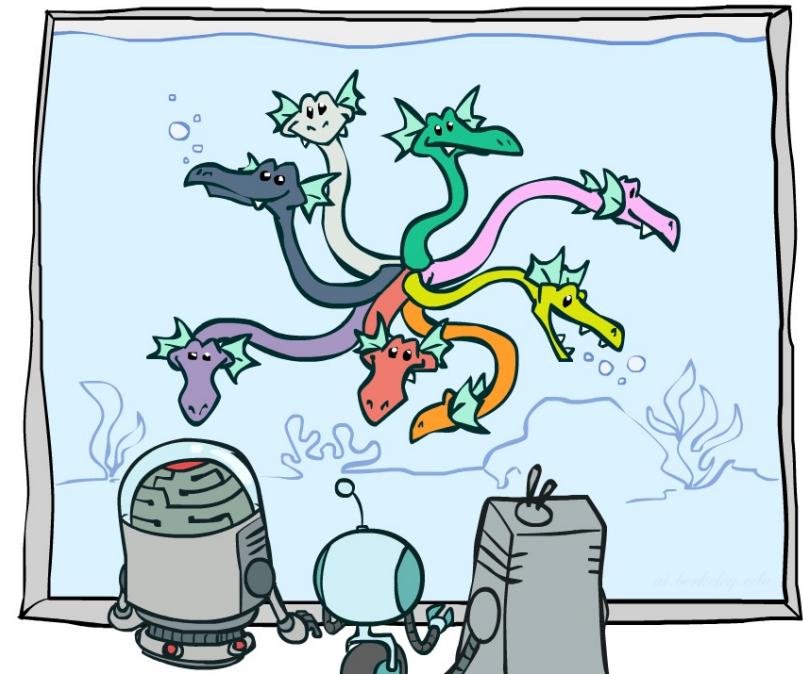
❑ Selected joint: $P(x, Y)$

- A slice of the joint distribution
- Entries $P(x, y)$ for fixed x , all y
- Sums to $P(x)$

$P(\text{cold}, W)$

T	W	P
cold	sun	0.2
cold	rain	0.3

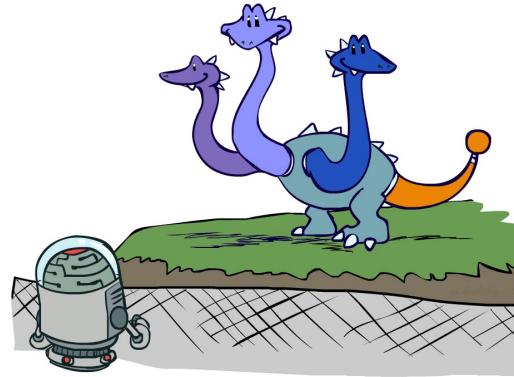
❑ Number of capitals = dimensionality of the table



Factor Zoo II

□ Single conditional: $P(Y | x)$

- Entries $P(y | x)$ for fixed x , all y
- Sums to 1



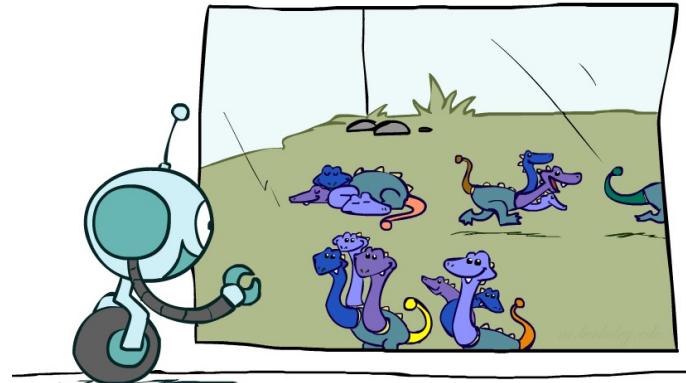
$$P(W|cold)$$

T	W	P
cold	sun	0.4
cold	rain	0.6

□ Family of conditionals:

$$P(Y | X)$$

- Multiple conditionals
- Entries $P(y | x)$ for all x, y
- Sums to $|X|$



$$P(W|T)$$

T	W	P
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

$$P(W|hot)$$

$$P(W|cold)$$

Factor Zoo III

□ Specified family: $P(\cancel{f} | X)$

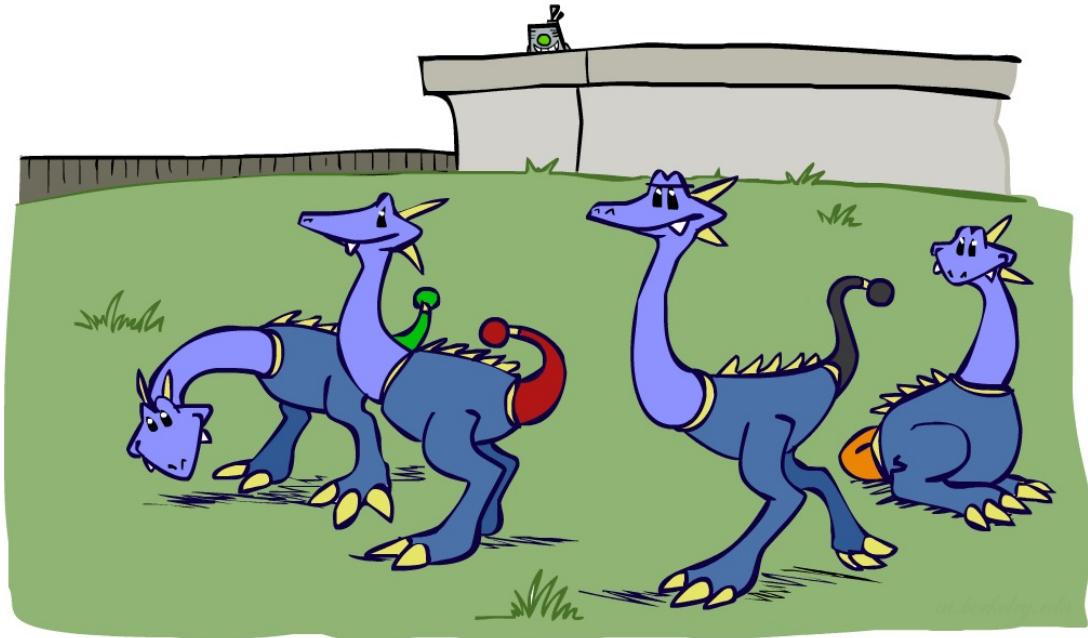
- Entries $P(y | x)$ for fixed y ,
but for all x
- Sums to ... who knows!

$P(rain | \cancel{T})$

T	W	P
hot	rain	0.2
cold	rain	0.6

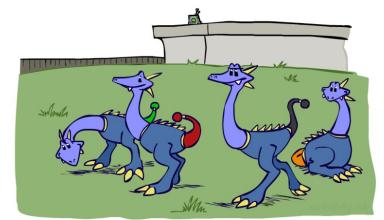
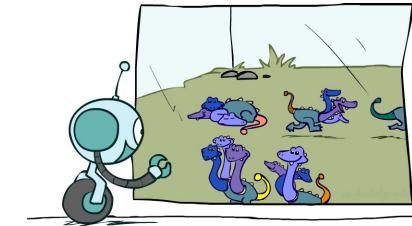
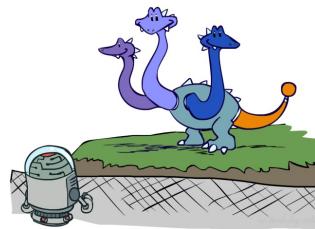
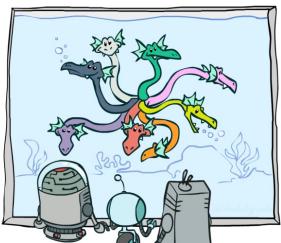
$$P(rain | hot)$$

$$P(rain | cold)$$



Factor Zoo Summary

- In general, when we write $P(Y_1 \dots Y_N | X_1 \dots X_M)$
 - It is a “factor,” a multi-dimensional array
 - Its values are $P(y_1 \dots y_N | x_1 \dots x_M)$
 - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array

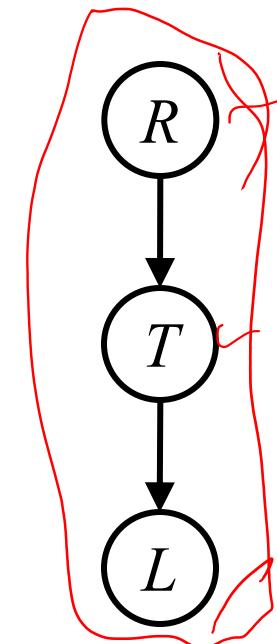


Example: Traffic Domain

- Random Variables
 - R: Raining
 - T: Traffic
 - L: Late for class!

$$P(L) = ? \\ = \sum P(r, t, L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$



$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9