

# stgam: An R package for GAM-based varying coefficient models

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## Summary

We are often interested in understanding how and where statistical relationships vary over space, and how they change over time. Quantifying such *process heterogeneity* (spatial and or temporal) can be done using *varying coefficient* models. The opportunity to undertake such space-time analyses are greater due to the increased generation and availability of data that include both spatial and temporal attributes (e.g. GPS coordinates and time-stamps). The **stgam** package provides a framework for creating regression models using Generalized Additive Models (GAMs) (Hastie & Tibshirani, 1990) in which the relationships between the response (dependent) variable and individual predictor (independent) variables are allowed to vary over space, time or both. It addresses a key question of the form space-time interaction to be specified in models. Frequently randomly guessed have to be made about the form of predictor-to-response relationships until an effective model form and associated model fits are found. To address this the **stgam** package includes functions to create multiple models, each specifying different relationships between the response variable  $y$  and the predictor variables  $x_1 \dots x_n$ . Each model is evaluated using the Bayesian Information Criterion (BIC) (Schwarz, 1978) which approximates the likelihood (probability) of the model being the correct model, given the data used in the analysis. Where multiple models are highly probable, then these can be combined using a Bayesian Model Averaging approach (Brunsdon et al., 2023; Fragoso et al., 2018). Finally the **stgam** package contains functions for creating spatially and / or temporally varying regression coefficient estimates. These can be mapped in the usual way to show how where and when the relationships between the response and the predictor variables vary over space and time.

## Statement of need

A number approaches have been established to quantify process spatial non-stationarity or heterogeneity (Brunsdon et al., 1996; Casetti, 1972; Fotheringham et al., 2002; Gelfand et al., 2003; Griffith, 2008; Jones, 1991; McMillen, 1996) and tools also exist to quantify the temporal dynamics of these (Crespo et al., 2007; Di Giacinto, 2006; Elhorst, 2003; Gelfand et al., 2004; Huang et al., 2010; Pace et al., 1998, 2000). All existing models require the user to make decisions about the nature of the space-time relationships in the data and thus the model and assume the presence of latent spatial and temporal autocorrelation in variables. The most commonly used approach in geographical analyses of space-time problems is geographically and temporally weighted regression (GTWR) (Huang et al., 2010) which seeks to optimises a single space-time kernel to define the space-time relationships of all covariates with the target variable. Some recent steps in the right direction have been taken in this regard: Liu et al. (2017) developed a semi-parametric temporal extension to mixed geographically weighted regression, in which some relationships and coefficients are assumed to be globally constant and others vary locally over time; Hong et al. (2021) used a bootstrap approach to identify

43 global coefficients in such models, but still define the same space-time relationship for each  
44 varying covariate.

45 To address this gap, the **stgam** package draws from the **mgcv** GAM package (S. N. Wood,  
46 2017). GAMs are able to handle many kinds of responses (Fahrmeir et al., 2021) and provide  
47 an intuitive approach to fit relatively complex relationships in data with complex interactions  
48 and non-linearities (S. N. Wood, 2017). The outputs of GAMs provide readily understood  
49 summaries of the relationship between predictor and response variables, and how the outcome  
50 is modelled. They are able to predict well from complex systems, quantify relationships,  
51 and support inferences about these relationships, such as which variables are important and  
52 at what range of values they are most influential (Hastie & Tibshirani, 1990; S. N. Wood,  
53 2017). GAMs can perform as well as or better than most machine learning models and  
54 they are relatively fast (Friedman, 2001; S. N. Wood, 2017). Importantly, in the context of  
55 varying coefficient modelling, GAMs combine predictive power, model accuracy and model  
56 transparency. GAMs model non-linear relationships using smooths, also referred to as splines.  
57 These can be of different forms depending on the problem and data (Hastie & Tibshirani,  
58 1990) and, as they can be represented as linear combinations of basis functions, they are  
59 sometimes referred to as Gaussian Process (GP) splines. A GP is a random process over  
60 functions, and its terms can be modelled using GP-splines within a GAM. Thus GP splines  
61 are represented as a linear combination of non-linear *basis functions* of predictor variables,  
62 which can generate predictions of the outcome variable. Basis functions can be either single or  
63 multi-dimensional in terms of predictor variables. As a result, a GAM consists of linear sums  
64 of multi-dimensional basis functions that allow complex relationships to be modelled. The  
65 appropriate degree of “wiggleness” in each spline is determined by the smoothing parameters,  
66 which balances over-fitting versus capturing the complexity in the relationship. GAMs with  
67 GP smooths parameterised with location and / or time can be used to construct regression  
68 models that allow coefficient estimates to vary and capture process spatial and / or temporal  
69 heterogeneity: a varying coefficient approach. While spline-based varying coefficient models  
70 have been proposed, for example using a generalized linear model with reduced-rank thin-plate  
71 splines (Fan & Huang, 2022), here the predictor-to-response relationship is considered over  
72 space and time as a GP.

73 A final consideration is the need to determine model form. Standard approaches for constructing  
74 spatially and temporally varying coefficient models, which in the absence of a theoretical model,  
75 commonly assume that some degree of spatial and temporal dependence *is* present in the data  
76 and in the relationship of each covariate with the target variable. In the GAM GP smooth  
77 approach, each covariate would be specified in a SP smooth parameterised with location and  
78 with time under the assumption that any temporal trends in coefficient estimates *will* vary  
79 with location. However, each covariate can be specified in six different ways: it can be omitted,  
80 included as a parametric (global) term, in a smooth with location, in a smooth with time, in  
81 a smooth with location *and* time, or in two separate space and time smooths. The last five  
82 options similarly apply to the intercept.

## 83 Package overview

84 The **stgam** package contains functions to support varying coefficient modelling using GAMs  
85 with GP smooths, that provide a wrapper for the GAM implementation in the **mgcv** package  
86 (S. Wood, 2015), that create, evaluate, and aggregate multiple models. It also contains two  
87 datasets that are used to illustrate the functions. These are described in Table 1.

Name	Type	Description
calculate_vcs	function	Extracts varying coefficient estimates (for SVC, TVC and STVC)
do_bma	function	Undertake undertake coefficient averaging using Bayesian Model Averaging
evaluate_models	function	Creates evaluates multiple varying coefficient GAM GP smooth models
gam_model_probs	function	Calculates the model probabilities of the different GAM models generated
plot_1d_smooth	function	Plots a 1-Dimensional GAM smooth
plot_2d_smooth	function	Plots a 2-Dimensional GAM smooth
productivity	data	US States Economic Productivity Data (1970-1985)
us_data	data	US States boundaries

The package includes two vignettes. The first, *space-time-gam-intro*, provides a gentle introduction to undertaking varying coefficient regression analyses with GAMs via the **mgcv** package. The second vignette, *space-time-gam-model-probs-BMA*, describes a standard **stgam** workflow to create and evaluate multiple models, and then to either select the best one or to combine competing models using Bayesian Model Averaging.

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