Geometry¹ First Year, Computer science

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Lecture 7

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Applications of the vector products

The coplanarity condition o two straight lines

The equations of the projection parallel to a given direction

Conics

¹These notes are not in a final form. They are continuously being improved

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The Ellipse

Using the notations of the previous section, observe that the straight lines d_1 , d_2 are coplanar if and only if the vectors $\overrightarrow{A_1}, \overrightarrow{A_2}, d_1, d_2$ are linearly dependent (coplanar), or equivalently $(\overrightarrow{A_1}, \overrightarrow{A_2}, \overrightarrow{d_1}, \overrightarrow{d_2}) = 0$. Consequently the stright lines d_1 , d_2 are coplanar if and only if

$$\begin{vmatrix} x_2 - x_1 & y_2 - y_1 & z_2 - z_1 \\ p_1 & q_1 & r_1 \\ p_2 & q_2 & r_2 \end{vmatrix} = 0$$
 (1.1)

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Let π be a plan, let d be a straight line unparallel to π and let M be an arbitrary point in \mathcal{P} . Consider the straight line through M which is also parallel to d. This line punctures the plane π in a point denoted by $p_{\pi,d}(M)$. We call the map $\mathcal{P} \longrightarrow \pi, M \longrightarrow p_{\pi,d}(M)$ the *projection of the space* on the plane π parallel to the line d, or, the projection of the space on the plane π parallel to the direction \overrightarrow{d} , where \overrightarrow{d} stands for a direction vector of the line d. We shall fine here the equations of some projections. More precisely, we shall find the coordinates of the point $p_{\pi,d}(M)$ in terms of the coordinates of M.

$$\pi : F(x, y, z) = Ax + By + Cz + D = 0$$

$$d: \frac{x-x_0}{p} = \frac{y-y_0}{q} = \frac{z-z_0}{r}.$$

The unparallelism between the plane π and the straight line d is equivalent to $\overrightarrow{d} \cdot \overrightarrow{n}_{\pi} \neq 0$, where $\overrightarrow{d}(p,q,r)$ is the director vector of the line d, and $\overrightarrow{n}_{\pi}(A,B,C)$ is the normal vector of the plane π .

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$$\frac{\mathbf{x} - \alpha}{\mathbf{p}} = \frac{\mathbf{y} - \beta}{\mathbf{q}} = \frac{\mathbf{z} - \gamma}{\mathbf{r}},$$

and the parametric equations are:

$$\begin{cases} x = \alpha + pt \\ y = \beta + qt \\ z = \gamma + rt \end{cases}$$

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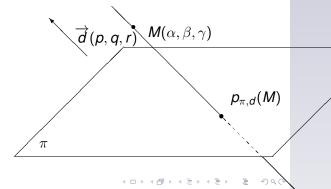
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In order to find the intersection point of this line with the plane π we shall solve the equation in t

$$A(\alpha + pt) + B(\beta + qt) + C(\gamma + rt) + D = 0.$$

This is equivalent to

$$A\alpha + B\beta + C\gamma + D + t(Ap + Bq + Cr) = 0$$

which shows that

$$t = -\frac{F(\alpha, \beta, \gamma)}{\overrightarrow{n}_{\pi} \cdot \overrightarrow{d}}.$$

$$\begin{cases} x = \alpha - \frac{F(\alpha, \beta, \gamma)}{\overrightarrow{n}_{\pi} \cdot \overrightarrow{d}} p \\ y = \beta - \frac{F(\alpha, \beta, \gamma)}{\overrightarrow{n}_{\pi} \cdot \overrightarrow{d}} q \\ z = \gamma - \frac{F(\alpha, \beta, \gamma)}{\overrightarrow{d}} r \end{cases}$$

Therefore, by identifying the point M with the triplet of its coordinates, we obtain:

$$p_{\pi,d}(\alpha,\beta,\gamma) = (\alpha,\beta,\gamma) - \frac{F(\alpha,\beta,\gamma)}{\overrightarrow{p}_{\pi} \cdot \overrightarrow{d}}(p,q,r).$$

If the vectors *d* and *n* are linearly dependent (collinear), then the projection is orhogonal and, in this case, its equations are:

$$p_{\pi,d}(\alpha,\beta,\gamma) = (\alpha,\beta,\gamma) - \frac{F(\alpha,\beta,\gamma)}{||\overrightarrow{n}_{\pi}||^2}(A,B,C).$$

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Consider the nonorthogonal planes

 $(\pi_1)P_1(x, y, z) = A_1x + B_1y + C_1z + D_1 = 0$ $(\pi_2)P_2(x,y,z) = A_2x + B_2y + C_2z + D_2 = 0$

such that

$$\operatorname{rang}\left(\begin{array}{ccc}A_1 & B_1 & C_1\\A_2 & B_2 & C_2\end{array}\right)=2$$

(The space is related to a cartesian orthogonal reference system). The planes π_1, π_2 devide the space into four regions, two of which, say \mathcal{R}_1 and \mathcal{R}_3 , correspond to the acute dihedral angle of the two planes.

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Proposition 1.1

The poin M(x,y,z) belong to these regions, that is to the union $\mathcal{R}_1 \cup \mathcal{R}_3$, if nad only if

$$P_1(x,y,z)\cdot P_2(x,y,z)(A_1A_2+B_1B_2+C_1C_2)<0.$$

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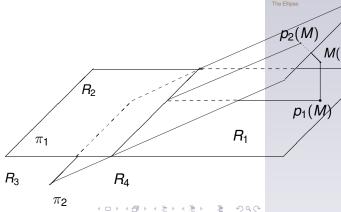
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Proof.

$$\begin{array}{ll} \textit{M}(\textit{x},\textit{y},\textit{z}) \in \mathcal{R}_1 \cup \mathcal{R}_3 & \Leftrightarrow \textit{m}(\textit{M}\overrightarrow{\textit{p}_1}(\textit{M}), \overrightarrow{\textit{M}}\overrightarrow{\textit{p}_2}(\textit{M})) > 90^\circ \\ & \Leftrightarrow \textit{M}\overrightarrow{\textit{p}_1}(\textit{M}) \cdot \textit{M}\overrightarrow{\textit{p}_2}(\textit{M}) < 0, \end{array}$$

where $p_1(M), p_2(M)$ are the projections of the point M on the planes π_1 and π_2 respectively. Thus, the equations are:

$$p_i(x, y, z) = (x, y, z) - \frac{P_i(x, y, z)}{||\overrightarrow{n}_{\pi_i}||^2} (A_i, B_i, C_i), i \in \{1, 2\},$$

which implies that

Therefore we have:

$$\begin{split} M(x,y,z) \in & \mathcal{R}_1 \cup \mathcal{R}_3 \Leftrightarrow \left(-\frac{P_i(x,y,z)}{||\overrightarrow{n}_{\pi_1}||^2} \overrightarrow{n}_{\pi_1} \right) \cdot \left(-\frac{P_i(x,y,z)}{||\overrightarrow{n}_{\pi_2}||^2} \overrightarrow{n}_{\pi_2} \right) < 0 \\ \Leftrightarrow & \frac{P_1(x,y,z) \cdot P_2(x,y,z)}{||\overrightarrow{n}_{\pi_1}||^2 \cdot ||\overrightarrow{n}_{\pi_2}||^2} (n_{\pi_1} \cdot \overrightarrow{n}_{\pi_2}) < 0 \\ \Leftrightarrow & P_1(x,y,z) \cdot P_2(x,y,z) (\overrightarrow{n}_{\pi_1} \cdot \overrightarrow{n}_{\pi_2}) < 0 \end{split}$$

$$\Leftrightarrow P_1(x, y, z) \cdot P_2(x, y, z) (A_1 A_2 + B_1 B_2 + C_1 C_2) < 0. \square$$

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Definition 2.1

An ellipse is the locus of points in a plane whose sum of distances to two fixed points F_1 and F_2 , called foci, is constant.

The distance between the two fixed points is called the *focal distance*

Let F and F' be the two foci of an ellipse and let |FF'|=2c be the focal distance. Suppose that the constant in the definition of the ellipse is 2a. If M is an arbitrary point of the ellipse, it must verify the condition

$$|MF| + |MF'| = 2a.$$

One may chose a Cartesian system of coordinates centered at the midpoint of the segment [F'F], so that F(c,0) and F'(-c,0).

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In $\triangle MFF'$ the following inequality |MF| + |MF'| > |FF'| holds. Hence 2a > 2c. Thus, the constants a and c must verify a > c.

Let us determine the equation of an ellipse. Starting with the definition, |MF| + |MF'| = 2a, or

$$\sqrt{(x-c)^2+y^2}+\sqrt{(x+c)^2+y^2}=2a.$$

This is equivalent to

$$\sqrt{(x-c)^2+y^2}=2a-\sqrt{(x+c)^2+y^2}$$

and thus

$$(x-c)^2 + y^2 = 4a^2 - 4a\sqrt{(x+c)^2 + y^2} + (x+c)^2 + y^2.$$

We therefore obtain

$$a\sqrt{(x+c)^2+y^2}=cx+a^2,$$

$$a^{2}(x^{2}+2xc+c^{2})+a^{2}y^{2}=c^{2}x^{2}+2a^{2}cx+a^{2},$$

and therefore to

$$(a^2-c^2)x^2+a^2y^2-a^2(a^2-c^2)=0.$$

Denoting $a^2 - c^2 = b^2$ (a > c), we deduce that

$$b^2x^2 + a^2y^2 - a^2b^2 = 0.$$

Dividing by a^2b^2 , we obtain the equation of the ellipse

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - 1 = 0. {(2.1)}$$

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[ROGV] Radó, F., Orban, B., Groze, V., Vasiu, A., Culegere de Probleme de Geometrie, Lit. Univ. "Babeş-Bolyai", Cluj-Napoca, 1979. Lecture 7

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