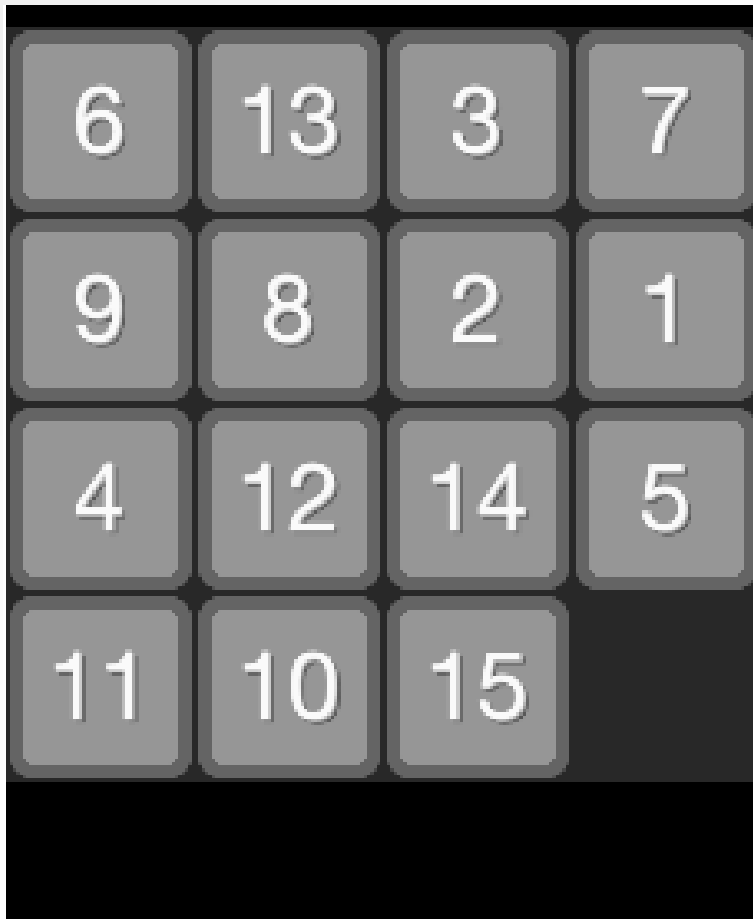


# Game 15

- Fifteen puzzle: 4x4 tiles



```

Subalg. searchSpace( initialConfig )
  reachedConfig  $\leftarrow$  { initialConfig }
  unExpandedConfig  $\leftarrow$  { initialConfig }

  while unExpandedConfig  $\neq \emptyset$  do
    config := extractOne (unExpandedConfig)
    @for any valid successor succ of config do
      if succ  $\notin$  reachedConfig then
        if isFinal(succ) then
          // ... !! process solution
        endif
        reachedConfig  $\leftarrow$  {succ}  $\cup$  reachedConfig
        unExpandedConfig  $\leftarrow$  {succ}  $\cup$  unExpandedConfig
      endif
    endfor
  endwhile
End_searchSpace

```

# Robot in a maze (1)

Consider a maze (rectangular shape) with occupied cells (X) and free cells (\*). Consider a robot (R) in this maze, and a goal position in this maze.

- (a) Verify if the robot can reach the goal position.
- (b) Determine a path (if exists).
- (c) Determine the shortest path (if exists).

X	*	X	X	*	*	*
*	X	*	*	X	*	*
G	*	*	*	*	*	*
*	X	*	S	*	*	X
*	X	*	*	*	*	X
*	X	*	*	X	*	*
*	X	*	X	*	*	*

# Robot in a maze (2)

Consider a maze (rectangular shape) with occupied cells (X) and free cells (\*). Consider a robot (R) in this maze

- (a) Verify if the robot can get out of the maze (can reach any of the margins).
- (b) Determine a path (if exists) to get out of the maze.
- (c) Determine the shortest path (if exists) to get out of the maze.

X	X	X	X	X	X	X
X	S	*	*	*	*	*
X	X	X	*	X	X	X
*	*	*	*	X	X	X
X	X	X	X	X	X	X
X	X	X	X	X	X	X
X	X	X	X	X	X	X