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目录

1 代数

1.1 FFT-gwx

```cpp
#include <complex>

int n, m;
int rev[maxn];  //maxn > 2 ^ k

void fft(Complex *a, int f)
{
    for(int i = 0; i < m; i++)
        if(i < r[i]) swap(a[i], a[r[i]]);
    for(int l = 2; l <= m; l <<= 1)
    {
        int h = l >> 1;
        Complex ur = (Complex){cos(pi / h), f * sin(pi / h)};
        for(int i = 0; i < m; i += l)
        {
            Complex w = (Complex){1, 0};
            for(int k = 0; k < h; k++, w = w * ur)
            {
                Complex x = a[i + k], y = a[i + k + h] * w;
                a[i + k] = x + y; a[i + k + h] = x - y;
            }
        }
    }
    if(f == -1)
        for(int i = 0; i < m; i++)
            a[i] = a[i] / m;
}

void multi(Complex *a, Complex *b)
{
    fft(a, 1); fft(b, 1);
    for(int i = 0; i < m; i++)
        a[i] *= b[i];
    fft(a, -1);
}

void init()
{
    for(m = 1; m <= 2 * n; m <<= 1);
    for(int i = 0, j = 0; i < m; i++)
    {
        rev[i] = j;
        for(int x = m >> 1; (j ^= x) < x; x >>= 1);
    }
}
```

1.2 FFT-wrz

```cpp
int len;
struct comp
{
    double r, i;
    comp operator + (const comp &that) {return (comp){r+that.r, i+that.i};}
    comp operator - (const comp &that) {return (comp){r-that.r, i-that.i};}
    comp operator * (const comp &that) {return (comp){r*that.r-i*that.i, r*that.i+i*that.r};}
}w[N<<1], a[N<<1], b[N<<1], c[N<<1]; // 数组记得至少开两倍
void init()
{
    double pi = acos(-1.0);
    for(int i = 0; i < len; i++) w[i] = (comp){cos(2*pi*i/len), sin(2*pi*i/len)};
}
void FFT(comp *a, comp *w)
{
    for(int i = 0, j = 0; i < len; i++)
    {
        if(i<j) swap(a[i], a[j]);
        for(int l = len>>1; (j^=l)<l; l >>= 1);
    }
    for(int i = 2; i <= len; i <<= 1)
    {
        int m = i >> 1;
        for(int j = 0; j < len; j += i)
        {
            for(int k = 0; k < m; k++)
            {
                comp tmp = w[len/i*k] * a[j+k+m];
                a[j+k+m] = a[j+k] - tmp;
                a[j+k] = a[j+k] + tmp;
            }
        }
    }
}
void mul(comp *a, comp *b, comp *c, int l) // 多项式乘法, c = a * b , c的长度为l
{
    for(len = 1; len <= l; len <<= 1);
    init(); FFT(a, w); FFT(b, w);
    for(int i = 0; i < len; i++) c[i] = a[i] * b[i];
    reverse(c+1, c+len); FFT(c, w);
    for(int i = 0; i < len; i++) c[i].r /= len; // 转化为int等时应加0.5, 如int(c[i].r+0.5)
}
```

1.3 高精度-wrz

```cpp
#include<cmath>
#include<cstdio>
#include<cstring>
```

```
#include<algorithm>
#define BASE 10000
#define L 20005
using namespace std;
int p;
char s[10*L];
struct bigint
{
    int num[L], len;
    bigint(int x = 0)
    {
        memset(num,0,sizeof(num));
        len = 1;
        num[0] = x;
    }
    bigint operator + (bigint b)
    {
        bigint c;
        c.len = max(b.len, len);
        for(int i = 0; i < c.len; i++)
        {
            c.num[i] += num[i] + b.num[i];
            c.num[i+1] = c.num[i] / BASE;
            c.num[i] %= BASE;
        }
        if(c.num[c.len])c.len++;
        return c;
    }
    bigint operator - (bigint b)
    {
        bigint c;
        c.len = max(len, b.len);
        for(int i = 0; i < c.len; i++)
        {
            c.num[i] += num[i] - b.num[i];
            if(c.num[i] < 0)
            {
                c.num[i] += BASE;
                c.num[i+1]--;
            }
        }
        while(!c.num[c.len-1] && c.len > 1)c.len--;
        return c;
    }
    void operator -= (int b)
    {
        num[0] -= b;
        for(int i = 0; i < len; i++)
        {
            num[i+1] += num[i] / BASE;
            num[i] %= BASE;
            if(num[i] < 0)num[i] += BASE, num[i+1]--;
        }
        while(!num[len-1] && len > 1) len--;
    }
    bigint operator * (bigint b)
    {
        bigint c;
        c.len = len + b.len;
        for(int i = 0; i < len; i++)
        {
            for(int j = 0; j < b.len; j++)
            {
                c.num[i+j] += num[i] * b.num[j];
                c.num[i+j+1] += c.num[i+j] / BASE;
                c.num[i+j] %= BASE;
            }
        }
        if(!c.num[c.len-1] && c.len > 1)c.len--;
        return c;
    }
    bigint operator * (int b)
    {
        bigint c;
        for(int i = 0; i < len; i++)
            c.num[i] = num[i] * b; // long long
        for(int i = 0; i < len; i++)
        {
            c.num[i+1] += c.num[i] / BASE;
            c.num[i] %= BASE;
        }
        c.len = len;
        while(c.num[c.len])c.len++;
        return c;
    }
    bool substract(bigint b, int pos)
    {
        if(len < b.len - pos)return false;
        else if(len == b.len-pos)
            for(int i = len-1; i>=0; i--)
                if(num[i] < b.num[i+pos])return false;
                else if(num[i] > b.num[i+pos])break;
        for(int i = 0; i < len; i++)
        {
            num[i] -= b.num[i+pos];
            if(num[i] < 0)
            {
                num[i] += BASE;
                num[i+1] --;
            }
        }
        while(!num[len-1] && len > 1)len--;
```

```
        return true;
    }

    // remember to change [BASE] to 10 !!!
    // [this] is the remainder
    bigint operator / (bigint b)
    {
        bigint c;
        if(len < b.len)return c;
        int k = len - b.len;
        c.len = k + 1;
        for(int i = len-1; i>=0; i--)
        {
            if(i>=k)b.num[i] = b.num[i-k];
            else b.num[i] = 0;
        }
        b.len = len;
        for(int i = 0; i <= k; i++)
            while(this->substract(b,i)) c.num[k-i]++;
        for(int i = 0; i < c.len; i++)
        {
            c.num[i+1] += c.num[i] / BASE;
            c.num[i] %= BASE;
        }
        while(!c.num[c.len-1] && c.len > 0) c.len--;
        return c;
    }

    // [this] is not the remainder
    bigint operator / (int b)
    {
        bigint c;
        int tmp = 0;
        for(int i = len-1; i>=0; i--)
        {
            tmp = tmp * BASE + num[i];
            c.num[i] = tmp / b;
            tmp %= b;
        }
        for(c.len = len; !c.num[c.len-1] && c.len > 1; c.len--);
        return c;
    }
    bool scan()
    {
        int n = -1;
        char ch = getchar();
        while(ch < '0' || ch > '9') if(ch == EOF)return false; else ch = getchar();
        while(ch >= '0' && ch <= '9') s[++n] = ch - '0', ch = getchar();
        len = 0;
        for(int i = n; i >= 0; i-=4)
        {
            num[len] += s[i];
            if(i>=1)num[len] += s[i-1] * 10;
            if(i>=2)num[len] += s[i-2] * 100;
            if(i>=3)num[len] += s[i-3] * 1000;
            ++len;
        }
        return true;
    }
    void clr()
    {
        memset(num,0,sizeof(num));
    }
    void print()
    {
        printf("%d",num[len-1]);
        for(int i = len-2; i>=0; i--)
            printf("%04d",num[i]);
        printf("\n");
    }
};
```

1.4 线性基-gwx

```
ll solve()
{
    ll res = 0;
    memset(b, 0, sizeof(b));
    for(int i = 1; i <= tot; i++)
        for(int j = 60; j >= 0; j--)
            if((a[i] >> j) & 1)
            {
                if(!b[j])
                {
                    b[j] = a[i];
                    break;
                }
                a[i] ^= b[j];
            }
    for(int i = 60; i >= 0; i--)
        res = max(res, res ^ b[i]);
    return res;
}
```

1.5 单纯形

```
// max{c * x | Ax <= b, x >= 0}的解, 无解返回空的vector, 否则就是解. 答案在an中
template <int MAXN = 100, int MAXM = 100>
struct simplex {
    int n, m; double a[MAXM][MAXN], b[MAXM], c[MAXN];
```

```
    bool infeasible, unbounded;
    double v, an[MAXN + MAXM]; int q[MAXN + MAXM];
    void pivot (int l, int e) {
        std::swap (q[e], q[l + n]);
        double t = a[l][e]; a[l][e] = 1; b[l] /= t;
        for (int i = 0; i < n; ++i) a[l][i] /= t;
        for (int i = 0; i < m; ++i) if (i != l && std::abs (a[i][e]) > EPS) {
            t = a[i][e]; a[i][e] = 0; b[i] -= t * b[l];
            for (int j = 0; j < n; ++j) a[i][j] -= t * a[l][j]; }
        if (std::abs (c[e]) > EPS) {
            t = c[e]; c[e] = 0; v += t * b[l];
            for (int j = 0; j < n; ++j) c[j] -= t * a[l][j]; } }
    bool pre () {
        for (int l, e; ; ) {
            l = e = -1;
            for (int i = 0; i < m; ++i) if (b[i] < -EPS && (!~l || rand () & 1)) l = i;
            if (!~l) return false;
            for (int i = 0; i < n; ++i) if (a[l][i] < -EPS && (!~e || rand () & 1)) e = i;
            if (!~e) return infeasible = true;
            pivot (l, e); } }
    double solve () {
        double p; std::fill (q, q + n + m, -1);
        for (int i = 0; i < n; ++i) q[i] = i;
        v = 0; infeasible = unbounded = false;
        if (pre ()) return 0;
        for (int l, e; ; pivot (l, e)) {
            l = e = -1; for (int i = 0; i < n; ++i) if (c[i] > EPS) { e = i; break; }
            if (!~e) break; p = INF;
            for (int i = 0; i < m; ++i) if (a[i][e] > EPS && p > b[i] / a[i][e])
                p = b[i] / a[i][e], l = i;
            if (!~l) return unbounded = true, 0; }
        for (int i = n; i < n + m; ++i) if (~q[i]) an[q[i]] = b[i - n];
        return v; } };
```

1.6 NTT-gwx

```
const int G;
int n, m, inm;
int rev[maxn], a[maxn], b[maxn];    //maxn > 2 ^ k

ll power(ll b, int k)
{
    ll res = 1;
    for(; k; k >>= 1, b = b * b % mod)
        if(k & 1)
            res = res * b % mod;
    return res;
}

void ntt(ll*a, int f)
{
    for(int i = 0; i < m; i++)
        if(rev[i] < i)
            swap(a[i], a[rev[i]]);
    for(int l = 2, h = 1; l <= m; h = l, l <<= 1)
    {
        int ur;
        if(f == 1)
            ur = power(G, (mod - 1) / l);
        else
            ur = power(G, mod - 1 - (mod - 1) / l);
        for(int i = 0; i < m; i += l)
        {
            ll w = 1;
            for(int k = i; k < i + h; k++, w = w * ur % mod)
            {
                int x = a[k], y = a[k + h] * w % mod;
                a[k] = (x + y) % mod;
                a[k + h] = (x - y + mod) % mod;
            }
        }
    }
    if(f == -1)
        for(int i = 0; i < m; i++)
            a[i] = a[i] * inm % mod;
}

void multi()
{
    ntt(a, 1); ntt(b, 1);
    for(int i = 0; i < m; i++)
        a[i] = a[i] * b[i] % mod;
    ntt(a, -1);
}

void init()
{
    for(m = 1; m <= 2 * n; m <<= 1) ;
    for(int i = 1; i < m; i++)
    {
        rev[i] = rev[i - 1];
        for(int j = m >> 1; (rev[i] ^= j) < j; j >>= 1) ;
    }
}
```

2 计算几何

2.1 二维计算几何-wrz

```
// c++11
```

```cpp

#include<bits/stdc++.h>
using namespace std;

const double inf = 1e9;
const double eps = 1e-9;
const double pi = acos(-1.0);

/*精度误差下的各种运算*/
bool le(double x, double y){return x < y - eps;} // x严格小于y
bool leq(double x, double y){return x < y + eps;} // x小于等于y
bool equ(double x, double y){return fabs(x - y) < eps;} // x等于y
double mysqrt(double x) {return x < eps ? 0 : sqrt(x);} // 开根号
double sqr(double x) {return x * x;} // 平方

struct point // 点或向量
{
    double x, y;
    double operator * (point that){return x*that.x + y*that.y;}
    double operator ^ (point that){return x*that.y - y*that.x;}
    point operator * (double t){return (point){x*t, y*t};}
    point operator / (double t){return (point){x/t, y/t};}
    point operator + (point that) {return (point){x + that.x, y + that.y};}
    point operator - (point that) {return (point){x - that.x, y - that.y};}
    double len(){return mysqrt(x*x+y*y);} // 到原点距离/向量长度
    point reset_len(double t) // 改变向量长度为t, t为正则方向不变, t为负则方向相反
    {
        double p = len();
        return (point){x*t/p, y*t/p};
    }
    point rot90() {return (point){-y, x};} // 逆时针旋转90度
    point rotate(double angle) // 使向量逆时针旋转angle弧度
    {
        double c = cos(angle), s = sin(angle);
        return (point){c * x  - s * y, s * x + c * y};
    }
};

struct line // 参数方程表示, p为线上一点, v为方向向量
{
    point p, v; // p为线上一点, v为方向向量

    double angle; // 半平面交用, 用atan2计算, 此时v的左侧为表示的半平面。注意有的函数声明一个新的line时没有初始化这个值!
    bool operator < (const line &that) const {return angle < that.angle;} // 半平面交用, 按与x轴夹角排序
};

struct circle
{
    point c; double r;
};


double distance(point a, point b) // a, b两点距离
{
    return mysqrt(sqr(a.x - b.x) + sqr(a.y - b.y));
}

circle make_circle(point a, point b) // 以a, b两点为直径作圆
{
    double d = distance(a, b);
    return (circle){(a+b)/2, d/2};
}

double point_to_line(point a, line b) // 点a到直线b距离
{
    return fabs((b.v ^ (a - b.p)) / b.v.len());
}

point project_to_line(point a, line b) // 点a到直线b的垂足/投影
{
    return b.v.reset_len((a - b.p) * b.v / b.v.len()) + b.p;
}

vector<point> circle_inter(circle a, circle b) // 圆a和圆b的交点, 需保证两圆不重合, 圆的半径必须大于0
{
    double d = distance(a.c, b.c);
    vector<point> ret;
    if(le(a.r + b.r, d) || le(a.r + d, b.r) || le(b.r + d, a.r)) return vector<point>(); // 相离或内含
    point r = (b.c - a.c).reset_len(1);
    double x = ((sqr(a.r) - sqr(b.r)) / d + d) / 2;
    double h = mysqrt(sqr(a.r) - sqr(x));
    if(equ(h, 0)) return vector<point>({a.c + r * x}); // 内切或外切
    else return vector<point>({a.c + r*x + r.rot90()*h, a.c + r*x - r.rot90()*h}); // 相交两点
}

vector<point> line_circle_inter(line a, circle b) // 直线a和圆b的交点
{
    double d = point_to_line(b.c, a);
    if(le(b.r, d)) return vector<point>(); // 不交
    double x = mysqrt(sqr(b.r) - sqr(d));
    point p = project_to_line(b.c, a);
    if(equ(x, 0)) return vector<point> ({p}); // 相切
    else return vector<point> ({p + a.v.reset_len(x), p - a.v.reset_len(x)}); // 相交两点
}

point line_inter(line a, line b) // 直线a和直线b的交点, 需保证两直线不平行
{
    double s1 = a.v ^ (b.p - a.p);
```

```
    double s2 = a.v ^ (b.p + b.v - a.p);
    return (b.p * s2 - (b.p + b.v) * s1) / (s2 - s1);
}

vector<point> tangent(point p, circle a) // 过点p的圆a的切线的切点, 圆的半径必须大于0
{
    circle c = make_circle(p, a.c);
    return circle_inter(a, c);
}

vector<line> intangent(circle a, circle b) // 圆a和圆b的内公切线
{
    point p = (b.c * a.r + a.c * b.r) / (a.r + b.r);
    vector<point> va = tangent(p, a), vb = tangent(p, b);
    vector<line> ret;
    if(va.size() == 2 && vb.size() == 2)
    {
        ret.push_back((line){va[0], vb[0] - va[0]});
        ret.push_back((line){va[1], vb[1] - va[1]});
    }
    else if(va.size() == 1 && vb.size() == 1)
    {
        ret.push_back((line){p, (a.c - b.c).rot90()});
    }
    return ret;
}

// 判断半平面交是否有解, 若有解需保证半平面交必须有界, 可以通过外加四个大半平面解决
// lcnt为半平面数量, l为需要做的所有半平面的数组, p为存交点的临时数组, h为时刻更新的合法的半平面数组, 下标均从1开始
bool HP(int lcnt, line *l, line *h, point *p)
{
    sort(l+1, l+1+lcnt);
    int head = 1, tail = 1;
    h[1] = l[1];
    for(int i = 2; i <= lcnt; i++)
    {
        line cur = l[i];
        for(; head < tail && le(cur.v ^ (p[tail-1]-cur.p), 0); tail--); // 先删队尾再删队头, 顺序不能换
        for(; head < tail && le(cur.v ^ (p[head]-cur.p), 0); head++);
        h[++tail] = cur;
        if(equ(h[tail].v ^ h[tail-1].v, 0)) // 平行
        {
            if(le(h[tail].v * h[tail-1].v, 0)) return false; // 方向相反的平行直线, 显然已经不可能围出有界半平面了
            tail--;
            if(le(h[tail+1].v ^ (h[tail].p - h[tail+1].p), 0)) h[tail] = h[tail+1];
        }
        if(head < tail) p[tail-1] = line_inter(h[tail-1], h[tail]);
    }
    for(; head < tail && le(h[head].v ^ (p[tail-1]-h[head].p), 0); tail--);
    return tail - head > 1;
}

double calc(double X){return 0;} // 计算给定X坐标上的覆盖的长度, 配合辛普森积分使用
// 自适应辛普森积分, 参数分别为(左端点x坐标, 中点x坐标, 右端点x坐标, 左端点答案, 中点答案, 右端点答案)
// 改变计算深度应调整eps
double simpson(double l, double mid, double r, double fl, double fm, double fr)
{
    double lmid = (l+mid)/2, rmid = (r+mid)/2, flm = calc(lmid), frm = calc(rmid);
    double ans = (r-l) * (fl + 4*fm + fr), ansl = (mid-l) * (fl + 4*flm + fm), ansr = (r-mid) * (fm + 4*frm + fr);
    if(fabs(ansl + ansr - ans) < eps) return ans / 6;
    else return simpson(l,lmid,mid,fl,flm,fm) + simpson(mid,rmid,r,fm,frm,fr);
}


int main(){}
```

2.2 basis

```
int sign(DB x) {
    return (x > eps) - (x < -eps);
}
DB msqrt(DB x) {
    return sign(x) > 0 ? sqrt(x) : 0;
}

struct Point {
    DB x, y;
    Point rotate(DB ang) const {  // 逆时针旋转 ang 弧度
        return Point(cos(ang) * x - sin(ang) * y,
                cos(ang) * y + sin(ang) * x);
    }
    Point turn90() const {  // 逆时针旋转 90 度
        return Point(-y, x);
    }
    Point unit() const {
        return *this / len();
    }
};
DB dot(const Point& a, const Point& b) {
    return a.x * b.x + a.y * b.y;
}
DB det(const Point& a, const Point& b) {
    return a.x * b.y - a.y * b.x;
}
#define cross(p1,p2,p3) ((p2.x-p1.x)*(p3.y-p1.y)-(p3.x-p1.x)*(p2.y-p1.y))
#define crossOp(p1,p2,p3) sign(cross(p1,p2,p3))
bool isLL(const Line& l1, const Line& l2, Point& p) {  // 直线与直线交点
```

```
    DB s1 = det(l2.b - l2.a, l1.a - l2.a),
       s2 = -det(l2.b - l2.a, l1.b - l2.a);
    if (!sign(s1 + s2)) return false;
    p = (l1.a * s2 + l1.b * s1) / (s1 + s2);
    return true;
}
bool onSeg(const Line& l, const Point& p) {  // 点在线段上
    return sign(det(p - l.a, l.b - l.a)) == 0 && sign(dot(p - l.a, p - l.b)) <= 0;
}
Point projection(const Line & l, const Point& p) {
    return l.a + (l.b - l.a) * (dot(p - l.a, l.b - l.a) / (l.b - l.a).len2());
}
DB disToLine(const Line& l, const Point& p) {  // 点到*直线*距离
    return fabs(det(p - l.a, l.b - l.a) / (l.b - l.a).len());
}
DB disToSeg(const Line& l, const Point& p) {  // 点到线段距离
    return sign(dot(p - l.a, l.b - l.a)) * sign(dot(p - l.b, l.a - l.b)) == 1 ? disToLine(l, p) : std::min((p - l
        .a).len(), (p - l.b).len());
}
// 圆与直线交点
bool isCL(Circle a, Line l, Point& p1, Point& p2) {
    DB x = dot(l.a - a.o, l.b - l.a),
       y = (l.b - l.a).len2(),
       d = x * x - y * ((l.a - a.o).len2() - a.r * a.r);
    if (sign(d) < 0) return false;
    Point p = l.a - ((l.b - l.a) * (x / y)), delta = (l.b - l.a) * (msqrt(d) / y);
    p1 = p + delta; p2 = p - delta;
    return true;
}
//圆与圆的交面积
DB areaCC(const Circle& c1, const Circle& c2) {
    DB d = (c1.o - c2.o).len();
    if (sign(d - (c1.r + c2.r)) >= 0) return 0;
    if (sign(d - std::abs(c1.r - c2.r)) <= 0) {
        DB r = std::min(c1.r, c2.r);
        return r * r * PI;
    }
    DB x = (d * d + c1.r * c1.r - c2.r * c2.r) / (2 * d),
        t1 = acos(x / c1.r), t2 = acos((d - x) / c2.r);
    return c1.r * c1.r * t1 + c2.r * c2.r * t2 - d * c1.r * sin(t1);
}
// 圆与圆交点
bool isCC(Circle a, Circle b, P& p1, P& p2) {
    DB s1 = (a.o - b.o).len();
    if (sign(s1 - a.r - b.r) > 0 || sign(s1 - std::abs(a.r - b.r)) < 0) return false;
    DB s2 = (a.r * a.r - b.r * b.r) / s1;
    DB aa = (s1 + s2) * 0.5, bb = (s1 - s2) * 0.5;
    P o = (b.o - a.o) * (aa / (aa + bb)) + a.o;
    P delta = (b.o - a.o).unit().turn90() * msqrt(a.r * a.r - aa * aa);
    p1 = o + delta, p2 = o - delta;
    return true;
}
// 求点到圆的切点，按关于点的顺时针方向返回两个点
bool tanCP(const Circle &c, const Point &p0, Point &p1, Point &p2) {
    double x = (p0 - c.o).len2(), d = x - c.r * c.r;
    if (d < eps) return false; // 点在圆上认为没有切点
    Point p = (p0 - c.o) * (c.r * c.r / x);
    Point delta = ((p0 - c.o) * (-c.r * sqrt(d) / x)).turn90();
    p1 = c.o + p + delta;
    p2 = c.o + p - delta;
    return true;
}
// 求圆到圆的外共切线，按关于 c1.o 的顺时针方向返回两条线
vector<Line> extanCC(const Circle &c1, const Circle &c2) {
    vector<Line> ret;
    if (sign(c1.r - c2.r) == 0) {
        Point dir = c2.o - c1.o;
        dir = (dir * (c1.r / dir.len())).turn90();
        ret.push_back(Line(c1.o + dir, c2.o + dir));
        ret.push_back(Line(c1.o - dir, c2.o - dir));
    } else {
        Point p = (c1.o * -c2.r + c2.o * c1.r) / (c1.r - c2.r);
        Point p1, p2, q1, q2;
        if (tanCP(c1, p, p1, p2) && tanCP(c2, p, q1, q2)) {
            if (c1.r < c2.r) swap(p1, p2), swap(q1, q2);
            ret.push_back(Line(p1, q1));
            ret.push_back(Line(p2, q2));
        }
    }
    return ret;
}
// 求圆到圆的内共切线，按关于 c1.o 的顺时针方向返回两条线
std::vector<Line> intanCC(const Circle &c1, const Circle &c2) {
    std::vector<Line> ret;
    Point p = (c1.o * c2.r + c2.o * c1.r) / (c1.r + c2.r);
    Point p1, p2, q1, q2;
    if (tanCP(c1, p, p1, p2) && tanCP(c2, p, q1, q2)) { // 两圆相切认为没有切线
        ret.push_back(Line(p1, q1));
        ret.push_back(Line(p2, q2));
    }
    return ret;
}
bool contain(vector<Point> polygon, Point p) { // 判断点 p 是否被多边形包含，包括落在边界上
    int ret = 0, n = polygon.size();
    for(int i = 0; i < n; ++ i) {
        Point u = polygon[i], v = polygon[(i + 1) % n];
        if (onSeg(Line(u, v), p)) return true;  // Here I guess.
        if (sign(u.y - v.y) <= 0) swap(u, v);
        if (sign(p.y - u.y) > 0 || sign(p.y - v.y) <= 0) continue;
        ret += sign(det(p, v, u)) > 0;
```

```
    }
    return ret & 1;
}
// 用半平面 (q1,q2) 的逆时针方向去切凸多边形
std::vector<Point> convexCut(const std::vector<Point>&ps, Point q1, Point q2) {
    std::vector<Point> qs; int n = ps.size();
    for (int i = 0; i < n; ++i) {
        Point p1 = ps[i], p2 = ps[(i + 1) % n];
        int d1 = crossOp(q1,q2,p1), d2 = crossOp(q1,q2,p2);
        if (d1 >= 0) qs.push_back(p1);
        if (d1 * d2 < 0) qs.push_back(isSS(p1, p2, q1, q2));
    }
    return qs;
}
// 求凸包
std::vector<Point> convexHull(std::vector<Point> ps) {
    int n = ps.size(); if (n <= 1) return ps;
    std::sort(ps.begin(), ps.end());
    std::vector<Point> qs;
    for (int i = 0; i < n; qs.push_back(ps[i ++]))
        while (qs.size() > 1 && sign(det(qs[qs.size() - 2], qs.back(), ps[i])) <= 0)
            qs.pop_back();
    for (int i = n - 2, t = qs.size(); i >= 0; qs.push_back(ps[i --]))
        while ((int)qs.size() > t && sign(det(qs[qs.size() - 2], qs.back(), ps[i])) <= 0)
            qs.pop_back();
    return qs;
```

2.3 circle-arc-struct

```
struct circle {
    point o;
    double r;
    circle(point o, double r) : o(o), r(r) {}
};
struct arcs { // 点l顺时针到点r
    point o, l, r;
    arcs() {}
    arcs(point o, point l, point r) : o(o), l(l), r(r) {}
};
bool isCL(circle a, line l, point &p1, point &p2) { // 圆与直线的交点
    double x = dot(l.a - a.o, l.b - l.a);
    double y = (l.b - l.a).len2();
    double d = x * x - y * ((l.a - a.o).len2() - a.r * a.r);
    if(sign(d) < 0) return false;
    d = max(d, 0.0);
    point p = l.a - ((l.b - l.a) * (x / y)), delta = (l.b - l.a) * (sqrt(d) / y);
    p1 = p + delta, p2 = p - delta;
    return true;
}
double ang(const point &d1, const point &d2) { // 向量d1顺时针转到向量d2的角度
    if (sign(det(d1, d2)) == 0)
        return (sign(dot(d1, d2)) > 0) ? 0 : pi;
    if (sign(det(d1, d2)) < 0)
        return acos(dot(d1, d2) / d1.len() / d2.len());
    else return 2 * pi - acos(dot(d1, d2) / d1.len() / d2.len());
}
bool onArcs(const point &p, const arcs &a) { // 点在圆弧上
    return sign(ang(a.l - a.o, a.r - a.o) - ang(a.l - a.o, p - a.o)) > 0;
}

/*struct circle {
    point o;
    double r;
    circle(point o, double r) : o(o), r(r) {}
};

struct arcs {
    //l -> r clockwise
    point o, l, r;
    arcs() {}
    arcs(point o, point l, point r) : o(o), l(l), r(r) {}
};

//Circle intersect with Line
bool isCL(circle a, line l, point &p1, point &p2) {
    double x = dot(l.a - a.o, l.b - l.a);
    double y = (l.b - l.a).len2();
    double d = x * x - y * ((l.a - a.o).len2() - a.r * a.r);
    if(sign(d) < 0) return false;
    d = max(d, 0.0);
    point p = l.a - ((l.b - l.a) * (x / y)), delta = (l.b - l.a) * (sqrt(d) / y);
    p1 = p + delta, p2 = p - delta;
    return true;
}

//use acos !precision

//angle (d1, d2) clockwise
double ang(const point &d1, const point &d2) {
    if (sign(det(d1, d2)) == 0)
        return (sign(dot(d1, d2)) > 0) ? 0 : pi;
    if (sign(det(d1, d2)) < 0)
        return acos(dot(d1, d2) / d1.len() / d2.len());
    else return 2 * pi - acos(dot(d1, d2) / d1.len() / d2.len());
}
//
bool onArcs(const point &p, const arcs &a) {
    return sign(ang(a.l - a.o, a.r - a.o) - ang(a.l - a.o, p - a.o)) > 0;
}*/
```

2.4 circles-intersections

```cpp
struct Event {
    Point p;
    double ang;
    int delta;
    Event (Point p = Point(0, 0), double ang = 0, double delta = 0) : p(p), ang(ang), delta(delta) {}
};
bool operator < (const Event &a, const Event &b) {
    return a.ang < b.ang;
}
void addEvent(const Circle &a, const Circle &b, vector<Event> &evt, int &cnt) {
    double d2 = (a.o - b.o).len2(),
           dRatio = ((a.r - b.r) * (a.r + b.r) / d2 + 1) / 2,
           pRatio = sqrt(-(d2 - sqr(a.r - b.r)) * (d2 - sqr(a.r + b.r)) / (d2 * d2 * 4));
    Point d = b.o - a.o, p = d.rotate(PI / 2),
          q0 = a.o + d * dRatio + p * pRatio,
          q1 = a.o + d * dRatio - p * pRatio;
    double ang0 = (q0 - a.o).ang(),
           ang1 = (q1 - a.o).ang();
    evt.push_back(Event(q1, ang1, 1));
    evt.push_back(Event(q0, ang0, -1));
    cnt += ang1 > ang0;
}
bool issame(const Circle &a, const Circle &b) { return sign((a.o - b.o).len()) == 0 && sign(a.r - b.r) == 0; }
bool overlap(const Circle &a, const Circle &b) { return sign(a.r - b.r - (a.o - b.o).len()) >= 0; }
bool intersect(const Circle &a, const Circle &b) { return sign((a.o - b.o).len() - a.r - b.r) < 0; }
Circle c[N];
double area[N];  // area[k] -> area of intersections >= k.
Point centroid[N];
bool keep[N];
void add(int cnt, DB a, Point c) {
    area[cnt] += a;
    centroid[cnt] = centroid[cnt] + c * a;
}
void solve(int C) {
    for (int i = 1; i <= C; ++ i) {
        area[i] = 0;
        centroid[i] = Point(0, 0);
    }
    for (int i = 0; i < C; ++i) {
        int cnt = 1;
        vector<Event> evt;
        for (int j = 0; j < i; ++j) if (issame(c[i], c[j])) ++cnt;
        for (int j = 0; j < C; ++j) {
            if (j != i && !issame(c[i], c[j]) && overlap(c[j], c[i])) {
                ++cnt;
            }
        }
        for (int j = 0; j < C; ++j) {
            if (j != i && !overlap(c[j], c[i]) && !overlap(c[i], c[j]) && intersect(c[i], c[j])) {
                addEvent(c[i], c[j], evt, cnt);
            }
        }
        if (evt.size() == 0u) {
            add(cnt, PI * c[i].r * c[i].r, c[i].o);
        } else {
            sort(evt.begin(), evt.end());
            evt.push_back(evt.front());
            for (int j = 0; j + 1 < (int)evt.size(); ++j) {
                cnt += evt[j].delta;
                add(cnt, det(evt[j].p, evt[j + 1].p) / 2, (evt[j].p + evt[j + 1].p) / 3);
                double ang = evt[j + 1].ang - evt[j].ang;
                if (ang < 0) {
                    ang += PI * 2;
                }
                if (sign(ang) == 0) continue;
                add(cnt, ang * c[i].r * c[i].r / 2, c[i].o +
                    Point(sin(ang1) - sin(ang0), -cos(ang1) + cos(ang0)) * (2 / (3 * ang) * c[i].r));
                add(cnt, -sin(ang) * c[i].r * c[i].r / 2, (c[i].o + evt[j].p + evt[j + 1].p) / 3);
            }
        }
    }
    for (int i = 1; i <= C; ++ i)
        if (sign(area[i])) {
            centroid[i] = centroid[i] / area[i];
        }
}
```

2.5 cirque-area-merge

```cpp
//n^2*logn
struct point {
    point rotate(const double &ang) {
        return point(cos(ang) * x - sin(ang) * y, cos(ang) * y + sin(ang) * x);
    }
    double ang() {
        return atan2(y, x);
    }
};
struct Circle {
    point o;
    double r;
    int tp; // 正圆为1 反向圆为-1
    Circle (point o = point(0, 0), double r = 0, int tp = 0) : o(o), r(r), tp(tp) {}
};
struct Event {
    point p;
    double ang;
    int delta;
    Event (point p = point(0, 0), double ang = 0, double delta = 0) : p(p), ang(ang), delta(delta) {}
```

```
};
bool operator < (const Event &a, const Event &b) {
    return a.ang < b.ang;
}
void addEvent(const Circle &a, const Circle &b, vector<Event> &evt, int &cnt) {
    double d2 = (a.o - b.o).len2(),
        dRatio = ((a.r - b.r) * (a.r + b.r) / d2 + 1) / 2,
        pRatio = sqrt(-(d2 - sqr(a.r - b.r)) * (d2 - sqr(a.r + b.r))) / d2 / 2;
    point d = b.o - a.o, p = d.rotate(PI / 2),
        q0 = a.o + d * dRatio + p * pRatio,
        q1 = a.o + d * dRatio - p * pRatio;
    double ang0 = (q0 - a.o).ang(),
        ang1 = (q1 - a.o).ang();
    evt.push_back(Event(q1, ang1, b.tp));
    evt.push_back(Event(q0, ang0, -b.tp));
    cnt += (ang1 > ang0) * b.tp;
}
bool issame(const Circle &a, const Circle &b) {
    return sign((a.o - b.o).len()) == 0 && sign(a.r - b.r) == 0;
}
bool overlap(const Circle &a, const Circle &b) {
    return sign(a.r - b.r - (a.o - b.o).len()) >= 0;
}
bool intersect(const Circle &a, const Circle &b) {
    return sign((a.o - b.o).len() - a.r - b.r) < 0;
}

int C;
Circle c[N];
double area[N];
void solve() { // area[1]..area[C]
    memset(area, 0, sizeof(double) * (C + 1));
    for (int i = 0; i < C; ++i) {
        int cnt = (c[i].tp > 0);
        vector<Event> evt;
        for (int j = 0; j < i; ++j) if (issame(c[i], c[j])) cnt += c[j].tp;
        for (int j = 0; j < C; ++j)
            if (j != i && !issame(c[i], c[j]) && overlap(c[j], c[i])) cnt += c[j].tp;
        for (int j = 0; j < C; ++j)
            if (j != i && !overlap(c[j], c[i]) && !overlap(c[i], c[j]) && intersect(c[i], c[j]))
                addEvent(c[i], c[j], evt, cnt);
        if (evt.size() == 0) area[cnt] += c[i].tp * PI * c[i].r * c[i].r;
        else {
            sort(evt.begin(), evt.end());
            evt.push_back(evt.front());
            for (int j = 0; j + 1 < (int)evt.size(); ++j) {
                cnt += evt[j].delta;
                area[cnt] += c[i].tp * det(evt[j].p, evt[j + 1].p) / 2;
                double ang = evt[j + 1].ang - evt[j].ang;
                if (ang < 0) ang += PI * 2;
                area[cnt] += c[i].tp * (ang * c[i].r * c[i].r / 2 - sin(ang) * c[i].r * c[i].r / 2);
            }
        }
    }
}
```

2.6 凸包

```
// 凸包中的点按逆时针方向
struct Convex {
    int n;
    std::vector<Point> a, upper, lower;
    void make_shell(const std::vector<Point>& p,
            std::vector<Point>& shell) {  // p needs to be sorted.
        clear(shell); int n = p.size();
        for (int i = 0, j = 0; i < n; i++, j++) {
            for (; j >= 2 && sign(det(shell[j-1] - shell[j-2],
                                      p[i] - shell[j-2])) <= 0; --j) shell.pop_back();
            shell.push_back(p[i]);
        }
    }
    void make_convex() {
        std::sort(a.begin(), a.end());
        make_shell(a, lower);
        std::reverse(a.begin(), a.end());
        make_shell(a, upper);
        a = lower; a.pop_back();
        a.insert(a.end(), upper.begin(), upper.end());
        if ((int)a.size() >= 2) a.pop_back();
        n = a.size();
    }
    void init(const std::vector<Point>& _a) {
        clear(a); a = _a; n = a.size();
        make_convex();
    }
    void read(int _n) {  // Won't make convex.
        clear(a); n = _n; a.resize(n);
        for (int i = 0; i < n; i++)
            a[i].read();
    }
    std::pair<DB, int> get_tangent(
            const std::vector<Point>& convex, const Point& vec) {
        int l = 0, r = (int)convex.size() - 2;
        assert(r >= 0);
        for (; l + 1 < r; ) {
            int mid = (l + r) / 2;
            if (sign(det(convex[mid + 1] - convex[mid], vec)) > 0)
                r = mid;
            else l = mid;
        }
        return std::max(std::make_pair(det(vec, convex[r]), r),
```

```
                std::make_pair(det(vec, convex[0]), 0));
    }
    int binary_search(Point u, Point v, int l, int r) {
        int s1 = sign(det(v - u, a[l % n] - u));
        for (; l + 1 < r; ) {
            int mid = (l + r) / 2;
            int smid = sign(det(v - u, a[mid % n] - u));
            if (smid == s1) l = mid;
            else r = mid;
        }
        return l % n;
    }
    // 求凸包上和向量 vec 叉积最大的点，返回编号，共线的多个切点返回任意一个
    int get_tangent(Point vec) {
        std::pair<DB, int> ret = get_tangent(upper, vec);
        ret.second = (ret.second + (int)lower.size() - 1) % n;
        ret = std::max(ret, get_tangent(lower, vec));
        return ret.second;
    }
    // 求凸包和直线 u, v 的交点，如果不相交返回 false，如果有则是和 (i, next(i)) 的交点，交在点上不确定返回前后两条边其中之一
    bool get_intersection(Point u, Point v, int &i0, int &i1) {
        int p0 = get_tangent(u - v), p1 = get_tangent(v - u);
        if (sign(det(v - u, a[p0] - u)) * sign(det(v - u, a[p1] - u)) <= 0) {
            if (p0 > p1) std::swap(p0, p1);
            i0 = binary_search(u, v, p0, p1);
            i1 = binary_search(u, v, p1, p0 + n);
            return true;
        }
        else return false;
    }
};
```

2.7 point-in-polygon

```
bool pit_in_polygon(pit q){ // p
    int cnt = 0;
    for(int i = 1; i <= n; ++i){
        pit p1 = p[i];
        pit p2 = p[suc[i]];
        if(pit_on_seg(q, p1, p2)) return true;
        int k = dcmp(det(p2 - p1, q - p1));
        int d1 = dcmp(p1.y - q.y);
        int d2 = dcmp(p2.y - q.y);
        if(k > 0 && d1 <= 0 && d2 > 0) ++cnt;
        if(k < 0 && d2 <= 0 && d1 > 0) --cnt;
    }
    if(cnt != 0) return true;
    else return false;
}
bool seg_in_polygon(pit a, pit b){ //
    vec v = b - a;
    for(int t = 1; t <= 1000; ++t){
        pit c = a + v * (1.00 * (rand() % 10000) / 10000);
        if(pit_in_polygon(c)) continue;
        else return false;
    }
    return true;
}
```

2.8 point-struct

```
const double eps = 1e-8;
const double PI = acos(-1.0);

int sign(double x) {
    return (x < -eps) ? -1 : (x > eps);
}
double sqr(double x) {
    return x * x;
}

struct point {
    double x, y;
    point(double x = 0, double y = 0) : x(x), y(y) {}
    point operator + (const point &rhs) const {
        return point(x + rhs.x, y + rhs.y);
    }
    point operator - (const point &rhs) const {
        return point(x - rhs.x, y - rhs.y);
    }
    point operator * (const double &k) const {
        return point(x * k, y * k);
    }
    point operator / (const double &k) const {
        return point(x / k, y / k);
    }
    double len2() {
        return x * x + y * y;
    }
    double len() {
        return sqrt(len2());
    }
    point rotate(const double &ang) { // 逆时针旋转 ang 弧度
        return point(cos(ang) * x - sin(ang) * y, cos(ang) * y + sin(ang) * x);
    }
    point turn90() { // 逆时针旋转 90 度
        return point(-y, x);
    }
    double ang() {
```

```
        return atan2(y, x);
    }
    point operator < (const point &rhs) {
        return (x < rhs.x || x == rhs.x && y < rhs.y);
    }
};
double dot(const point &a, const point &b) {
    return a.x * b.x + a.y * b.y;
}
double det(const point &a, const point &b) {
    return a.x * b.y - a.y * b.x;
}

struct line {
    point a, b;
    line(point a, point b) : a(a), b(b) {}
};
bool onSeg(const point &p, const line &l) { // 点在线段上 包含端点
    return sign(det(p - l.a, l.b - l.a)) == 0 && sign(dot(p - l.a, p - l.b)) <= 0;
}
double disToLine(const point &p, const line &l) { // 点到直线距离
    return fabs(det(p - l.a, l.b - l.a) / (l.b - l.a).len());
}
double disToSeg(const point &p, const line &l) { // 点到线段距离
    return sign(dot(p - l.a, l.b - l.a)) * sign(dot(p - l.b, l.a - l.b)) != 1 ?
    disToLine(l, p) : min((p - l.a).len(), (p - l.b).len());
}
point projection(const point &p, const line &l) { // 点到直线投影
    return l.a + (l.b - l.a) * (dot(p - l.a, l.b - l.a) / (l.b - l.a).len2());
}
point symmetry(const point &a, const point &b) { // 点a关于点b的对称点
    return b + b - a;
}
point reflection(const point &p, const line &l) { // 点关于直线的对称点
    return symmetry(p, projection(p, l));
}
bool isLL(const line &l1, const line &l2, point &p) { // 直线求交
    long long s1 = det(l2.b - l2.a, l1.a - l2.a);
    long long s2 = -det(l2.b - l2.a, l1.b - l2.a);
    if(!sign(s1 + s2)) return false;
    p = (l1.a * s2 + l1.b * s1) / (s1 + s2);
    return true;
}
bool p_in_tri(const point &p, const point &a, const point &b, const point &c) { //点在三角形内(包含边界)
    return sign(abs(det(a - p, b - p)) + abs(det(b - p, c - p))
        + abs(det(c - p, a - p)) - abs(det(b - a, c - a))) == 0;
}
bool Check(const point &p, const point &d, const point &a, const point &b) {
    return sign(det(d, a - p)) * sign(det(b - p, d)) >= 0;
}
bool isll(const point &p, const point &q, const point &a, const point &b) { // 跨立实验
    return Check(p, q - p, a, b) && Check(a, b - a, p, q);
}
```

2.9 三角形内心，外心，垂心

```
Point inCenter(const Point &A, const Point &B, const Point &C) { // 内心
    double a = (B - C).len(), b = (C - A).len(), c = (A - B).len(),
        s = fabs(det(B - A, C - A)),
        r = s / p;
    return (A * a + B * b + C * c) / (a + b + c);
}
Point circumCenter(const Point &a, const Point &b, const Point &c) { // 外心
    Point bb = b - a, cc = c - a;
    double db = bb.len2(), dc = cc.len2(), d = 2 * det(bb, cc);
    return a - Point(bb.y * dc - cc.y * db, cc.x * db - bb.x * dc) / d;
}
Point othroCenter(const Point &a, const Point &b, const Point &c) { // 垂心
    Point ba = b - a, ca = c - a, bc = b - c;
    double Y = ba.y * ca.y * bc.y,
           A = ca.x * ba.y - ba.x * ca.y,
           x0 = (Y + ca.x * ba.y * b.x - ba.x * ca.y * c.x) / A,
           y0 = -ba.x * (x0 - c.x) / ba.y + ca.y;
    return Point(x0, y0);
}
```

2.10 三维计算几何

```
// 三维绕轴旋转, 大拇指指向 axis 向量方向, 四指弯曲方向转 w 弧度
Point rotate(const Point& s, const Point& axis, DB w) {
    DB x = axis.x, y = axis.y, z = axis.z;
    DB s1 = x * x + y * y + z * z, ss1 = msqrt(s1),
       cosw = cos(w), sinw = sin(w);
    DB a[4][4];
    memset(a, 0, sizeof a);
    a[3][3] = 1;
    a[0][0] = ((y * y + z * z) * cosw + x * x) / s1;
    a[0][1] = x * y * (1 - cosw) / s1 + z * sinw / ss1;
    a[0][2] = x * z * (1 - cosw) / s1 - y * sinw / ss1;
    a[1][0] = x * y * (1 - cosw) / s1 - z * sinw / ss1;
    a[1][1] = ((x * x + z * z) * cosw + y * y) / s1;
    a[1][2] = y * z * (1 - cosw) / s1 + x * sinw / ss1;
    a[2][0] = x * z * (1 - cosw) / s1 + y * sinw / ss1;
    a[2][1] = y * z * (1 - cosw) / s1 - x * sinw / ss1;
    a[2][2] = ((x * x + y * y) * cos(w) + z * z) / s1;
    DB ans[4] = {0, 0, 0, 0}, c[4] = {s.x, s.y, s.z, 1};
    for (int i = 0; i < 4; ++ i)
        for (int j = 0; j < 4; ++ j)
            ans[i] += a[j][i] * c[j];
```

```
    return Point(ans[0], ans[1], ans[2]);
}
```

2.11 三维凸包

```
__inline P cross(const P& a, const P& b) {
    return P(
            a.y * b.z - a.z * b.y,
            a.z * b.x - a.x * b.z,
            a.x * b.y - a.y * b.x
        );
}

__inline DB mix(const P& a, const P& b, const P& c) {
    return dot(cross(a, b), c);
}

__inline DB volume(const P& a, const P& b, const P& c, const P& d) {
    return mix(b - a, c - a, d - a);
}

struct Face {
    int a, b, c;
    __inline Face() {}
    __inline Face(int _a, int _b, int _c):
        a(_a), b(_b), c(_c) {}
    __inline DB area() const {
        return 0.5 * cross(p[b] - p[a], p[c] - p[a]).len();
    }
    __inline P normal() const {
        return cross(p[b] - p[a], p[c] - p[a]).unit();
    }
    __inline DB dis(const P& p0) const {
        return dot(normal(), p0 - p[a]);
    }
};

std::vector<Face> face, tmp;  // Should be O(n).
int mark[N][N], Time, n;

__inline void add(int v) {
    ++ Time;
    clear(tmp);
    for (int i = 0; i < (int)face.size(); ++ i) {
        int a = face[i].a, b = face[i].b, c = face[i].c;
        if (sign(volume(p[v], p[a], p[b], p[c])) > 0) {
            mark[a][b] = mark[b][a] = mark[a][c] =
                mark[c][a] = mark[b][c] = mark[c][b] = Time;
        }
        else {
            tmp.push_back(face[i]);
        }
    }
    clear(face); face = tmp;
    for (int i = 0; i < (int)tmp.size(); ++ i) {
        int a = face[i].a, b = face[i].b, c = face[i].c;
        if (mark[a][b] == Time) face.emplace_back(v, b, a);
        if (mark[b][c] == Time) face.emplace_back(v, c, b);
        if (mark[c][a] == Time) face.emplace_back(v, a, c);
        assert(face.size() < 500u);
    }
}

void reorder() {
    for (int i = 2; i < n; ++ i) {
        P tmp = cross(p[i] - p[0], p[i] - p[1]);
        if (sign(tmp.len())) {
            std::swap(p[i], p[2]);
            for (int j = 3; j < n; ++ j)
                if (sign(volume(p[0], p[1], p[2], p[j]))) {
                    std::swap(p[j], p[3]);
                    return;
                }
        }
    }
}

void build_convex() {
    reorder();
    clear(face);
    face.emplace_back(0, 1, 2);
    face.emplace_back(0, 2, 1);
    for (int i = 3; i < n; ++ i)
        add(i);
}
```

3 数据结构

3.1 KD 树

```
long long norm(const long long &x) {
    //    For manhattan distance
    return std::abs(x);
    //    For euclid distance
    return x * x;
}

struct Point {
    int x, y, id;

```

```
    const int& operator [] (int index) const {
        if (index == 0) {
            return x;
        } else {
            return y;
        }
    }

    friend long long dist(const Point &a, const Point &b) {
        long long result = 0;
        for (int i = 0; i < 2; ++i) {
            result += norm(a[i] - b[i]);
        }
        return result;
    }
} point[N];

struct Rectangle {
    int min[2], max[2];

    Rectangle() {
        min[0] = min[1] = INT_MAX;  // sometimes int is not enough
        max[0] = max[1] = INT_MIN;
    }

    void add(const Point &p) {
        for (int i = 0; i < 2; ++i) {
            min[i] = std::min(min[i], p[i]);
            max[i] = std::max(max[i], p[i]);
        }
    }

    long long dist(const Point &p) {
        long long result = 0;
        for (int i = 0; i < 2; ++i) {
            //    For minimum distance
            result += norm(std::min(std::max(p[i], min[i]), max[i]) - p[i]);
            //    For maximum distance
            result += std::max(norm(max[i] - p[i]), norm(min[i] - p[i]));
        }
        return result;
    }
};

struct Node {
    Point seperator;
    Rectangle rectangle;
    int child[2];

    void reset(const Point &p) {
        seperator = p;
        rectangle = Rectangle();
        rectangle.add(p);
        child[0] = child[1] = 0;
    }
} tree[N << 1];

int size, pivot;

bool compare(const Point &a, const Point &b) {
    if (a[pivot] != b[pivot]) {
        return a[pivot] < b[pivot];
    }
    return a.id < b.id;
}

// 左閉右開: build(1, n + 1)
int build(int l, int r, int type = 1) {
    pivot = type;
    if (l >= r) {
        return 0;
    }
    int x = ++size;
    int mid = l + r >> 1;
    std::nth_element(point + l, point + mid, point + r, compare);
    tree[x].reset(point[mid]);
    for (int i = l; i < r; ++i) {
        tree[x].rectangle.add(point[i]);
    }
    tree[x].child[0] = build(l, mid, type ^ 1);
    tree[x].child[1] = build(mid + 1, r, type ^ 1);
    return x;
}

int insert(int x, const Point &p, int type = 1) {
    pivot = type;
    if (x == 0) {
        tree[++size].reset(p);
        return size;
    }
    tree[x].rectangle.add(p);
    if (compare(p, tree[x].seperator)) {
        tree[x].child[0] = insert(tree[x].child[0], p, type ^ 1);
    } else {
        tree[x].child[1] = insert(tree[x].child[1], p, type ^ 1);
    }
    return x;
}

// For minimum distance
// For maximum:下面递归query时0, 1 换顺序;< and >;min and max
void query(int x, const Point &p, std::pair<long long, int> &answer, int type = 1) {
```

```
    pivot = type;
    if (x == 0 || tree[x].rectangle.dist(p) > answer.first) {
        return;
    }
    answer = std::min(answer,
             std::make_pair(dist(tree[x].seperator, p), tree[x].seperator.id));
    if (compare(p, tree[x].seperator)) {
        query(tree[x].child[0], p, answer, type ^ 1);
        query(tree[x].child[1], p, answer, type ^ 1);
    } else {
        query(tree[x].child[1], p, answer, type ^ 1);
        query(tree[x].child[0], p, answer, type ^ 1);
    }
}

std::priority_queue<std::pair<long long, int> > answer;

void query(int x, const Point &p, int k, int type = 1) {
    pivot = type;
    if (x == 0 || (int)answer.size() == k && tree[x].rectangle.dist(p) > answer.top().first) {
        return;
    }
    answer.push(std::make_pair(dist(tree[x].seperator, p), tree[x].seperator.id));
    if ((int)answer.size() > k) {
        answer.pop();
    }
    if (compare(p, tree[x].seperator)) {
        query(tree[x].child[0], p, k, type ^ 1);
        query(tree[x].child[1], p, k, type ^ 1);
    } else {
        query(tree[x].child[1], p, k, type ^ 1);
        query(tree[x].child[0], p, k, type ^ 1);
    }
}
```

3.2 KD 树-gwx

```
struct Point
{
    double x, y;
    int id;
    Point operator - (const Point &a) const {
        return (Point){x - a.x, y - a.y, id};
    }
} b[maxn], c[maxn];
struct node
{
    Point p;
    int ch[2];
} a[maxn];
struct rev
{
    int id;
    double dis;
    bool operator < (const rev &a) const{
        int tmp = sign(dis - a.dis);
        if(tmp)
            return tmp < 0;
        return id < a.id;
    }
};
typedef pr priority_queue <rev>;
pr p0;

int build(int l, int r, int f)
{
    if(l > r)
        return 0;
    int x = (l + r) >> 1;
    if(f == 0)
        nth_element(a + l, a + x, a + r + 1, cmp0); //按x排序
    else
        nth_element(a + l, a + x, a + r + 1, Cmp1); //按y排序
    a[x].ch[0] = build(l, x - 1, f ^ 1);
    a[x].ch[1] = build(x + 1, r, f ^ 1);
    return x;
}

void update(pr &a, rev x)
{
    if(a.size() < K)
        a.push(x);
    else if(x < a.top())
    {
        a.pop();
        a.push(x);
    }
}

pr merge(pr a, pr b)
{
    int s1 = a.size(), s2 = b.size();
    if(s1 < s2)
    {
        while(!a.empty())
        {
            update(b, a.top());
            a.pop();
        }
        return b;
    }
```

```
    else
    {
        while(!b.empty())
        {
            update(a, b.top());
            b.pop();
        }
        return a;
    }
}

pr query(int u, Point x, int f)
{
    if(!u)
        return p0;//empty priority_queue
    int d = (dis(a[a[u].ch[0]].p, x) > dis(a[a[u].ch[1]].p, x));
    double dx;
    pr res = query(a[u].ch[d], x, f ^ 1);
    update(res, (rev){a[u].p.id, dis(a[u].p, x)});
    if(f == 0)
        dx = abs(x.x - a[u].p.x);
    else
        dx = abs(x.y - a[u].p.y);
    if(dx > res.top().dis)
        return res;
    res = merge(res, query(a[u].ch[d ^ 1], x, f ^ 1));
    return res;
}

pr solve(Point p)   //离p最近的K个点
{
    int root = build(1, tot, 0);
    return query(root, p, 0);
}
```

3.3 lct-gwx

```
int pa[maxn], st[maxn];
struct node
{
    int ch[2], pa;
    ll s, w, sw;    //s: size of subtree; w: value; sw: sum of value
    ll m, p;    //tags of addition and multiplication
    bool f; //tag of flip
} a[maxn];

void flip(int u)
{
    if(!u) return;
    swap(a[u].ch[0], a[u].ch[1]);
    a[u].f ^= 1;
}

void add(int u, int c)
{
    if(!u) return;
    (a[u].p += c) %= mod;
    (a[u].w += c) %= mod;
    (a[u].sw += a[u].s * c % mod) % mod;
}

void mult(int u, int c)
{
    if(!u) return;
    if(a[u].m == -1) a[u].m = c;
    else (a[u].m *= c) %= mod;
    (a[u].p *= c) %= mod;
    (a[u].w *= c) %= mod;
    (a[u].sw *= c) %= mod;
}

void pushdown(int u)
{
    if(!u) return;
    int l = a[u].ch[0], r = a[u].ch[1];
    if(a[u].m != -1)
    {
        mult(l, a[u].m); mult(r, a[u].m);
        a[u].m = -1;
    }
    if(a[u].p)
    {
        add(l, a[u].p); add(r, a[u].p);
        a[u].p = 0;
    }
    if(a[u].f)
    {
        flip(l); flip(r);
        a[u].f ^= 1;
    }
}

void maintain(int u)
{
    pushdown(u);
    int l = a[u].ch[0], r = a[u].ch[1];
    a[u].s = a[l].s + a[r].s + 1;
    a[u].sw = (a[l].sw + a[r].sw + a[u].w) % mod;
}

void rotate(int u)
```

```
{
    int x = a[u].pa, y = a[x].pa, d = (a[x].ch[1] == u);
    if(!y) pa[u] = pa[x], pa[x] = 0;
    else a[y].ch[a[y].ch[1] == x] = u;
    a[x].ch[d] = a[u].ch[d ^ 1], a[a[u].ch[d ^ 1]].pa = x;
    a[u].ch[d ^ 1] = x; a[x].pa = u; a[u].pa = y;
    maintain(x); maintain(u);
}

void splay(int u)
{
    int t = u;
    while(a[t].pa) st[++top] = t, t = a[t].pa;
    pushdown(t);
    while(top) pushdown(st[top]), top--;
    while(a[u].pa)
    {
        int x = a[u].pa, y = a[x].pa;
        if(!y)  {rotate(u); return;}
        if(a[x].ch[1] == u ^ a[y].ch[1] == x) rotate(u);
        else rotate(x);
        rotate(u);
    }
}

void access(int u)
{
    splay(u);
    if(a[u].ch[1])
        a[a[u].ch[1]].pa = 0, pa[a[u].ch[1]] = u, a[u].ch[1] = 0, maintain(u);
    while(pa[u])
    {
        int v = pa[u];
        splay(v);
        if(a[v].ch[1])
            a[a[v].ch[1]].pa = 0, pa[a[v].ch[1]] = v, a[v].ch[1] = 0;
        a[v].ch[1] = u; a[u].pa = v; pa[u] = 0;
        maintain(v); splay(u);
    }
}

void sroot(int u)
{
    access(u); flip(u);
}

void get(int u, int v)
{
    sroot(u); access(v);
}

void cut(int u, int v)
{
    get(u, v); a[v].ch[0] = a[u].pa = 0;
    maintain(v);
}

void join(int u, int v)
{
    access(u); sroot(v);
    a[u].ch[1] = v; a[v].pa = u;
    maintain(u);
}
```

3.4 LCT-wrz

```
struct node
{
    node *ch[2], *fa;
    uint v, sum, k, b; int rev, siz;
}mem[N], *tot, *null, *pos[N];
void init()
{
    null = tot = mem;
    null->ch[0] = null->ch[1] = null->fa = null;
    null->v = null->sum = null->b = null->rev = null->siz = 0; null->k = 1;
    for(int i = 1; i <= n; i++) pos[i] = ++tot, *pos[i] = *null, pos[i]->v = pos[i]->sum = 1;
}
int type(node *x){return x->fa->ch[1]==x?1:0;}
int isroot(node *x){return x->fa->ch[type(x)] != x;}
void mswap(node *&x, node *&y){node *t = x; x = y; y = t;}
void pushup(node *x)
{
    x->sum = (x->v + x->ch[0]->sum + x->ch[1]->sum) % MOD;
    x->siz = (x->ch[0]->siz + x->ch[1]->siz + 1) % MOD;
}
void pushdown(node *x)
{
    if(x->rev)
    {
        x->rev = 0, x->ch[0]->rev ^= 1, x->ch[1]->rev ^= 1;
        mswap(x->ch[0]->ch[0], x->ch[0]->ch[1]);
        mswap(x->ch[1]->ch[0], x->ch[1]->ch[1]);
    }
    for(int i = 0; i <= 1; i++)
    {
        x->ch[i]->v = (x->k * x->ch[i]->v % MOD + x->b) % MOD;
        x->ch[i]->sum = (x->ch[i]->sum * x->k % MOD + x->b * x->ch[i]->siz % MOD) % MOD;
        (x->ch[i]->k *= x->k) %= MOD;
        (x->ch[i]->b *= x->k) %= MOD, (x->ch[i]->b += x->b) %= MOD;
    }
```

```
    x->k = 1;  x->b = 0;
}
void update(node *x){if(!isroot(x))update(x->fa); pushdown(x);}
void rotate(node *x)
{
    node *f = x->fa; int d = type(x);
    x->fa = f->fa, !isroot(f) ? x->fa->ch[type(f)] = x : 0;
    (f->ch[d] = x->ch[d^1]) != null ? f->ch[d]->fa = f : 0;
    f->fa = x, x->ch[d^1] = f; pushup(f);
}
void splay(node *x)
{
    update(x);
    for(; !isroot(x); )
    {
        if(isroot(x->fa)) rotate(x);
        else if(type(x) == type(x->fa)) rotate(x->fa), rotate(x);
        else rotate(x),rotate(x);
    }
    pushup(x);
}
void access(node *x)
{
    node *tmp = null;
    for(; x != null; )
    {
        splay(x);
        x->ch[1] = tmp;
        pushup(x);
        tmp = x;
        x = x->fa;
    }
}
void makeroot(node *x)
{
    access(x);
    splay(x);
    x->rev ^= 1;
    swap(x->ch[0], x->ch[1]);
}
void link(node *x, node *y)
{
    makeroot(x);
    x->fa = y;
}
void cut(node *x, node *y)
{
    makeroot(x); access(y);
    splay(y); y->ch[0] = x->fa = null;
    pushup(y);
}
```

3.5 左偏树-wrz

```
struct heap
{
    heap *ch[2];
    int dis, siz, v;
}mem[N*2], *h[N], *null, *tot;
heap* newheap()
{
    heap *p = ++tot;
    *p = *null;
    return p;
}
void init()
{
    null = tot = mem;
    null->ch[0] = null->ch[1] = null;
    null->v = null->dis = null->siz = 0;
    for(int i = 1; i <= n; i++) h[i] = null;
}
heap *merge(heap *x, heap *y) // big
{
    if(x == null) return y;
    if(y == null) return x;
    if(x->v < y->v) swap(x, y);
    x->ch[1] = merge(x->ch[1], y);
    if(x->ch[0]->dis < x->ch[1]->dis) swap(x->ch[0], x->ch[1]);
    x->dis = x->ch[1]->dis + 1;
    x->siz = x->ch[0]->siz + x->ch[1]->siz + 1;
    return x;
}
heap *pop(heap *x){return merge(x->ch[0], x->ch[1]);}
int main()
{
    init();
    heap *a = newheap(); a->siz = 1; a->v = 233;
    heap *b = newheap(); b->siz = 1; b->v = 233;
    heap *c = merge(a, b);
}
```

3.6 splay-gwx

```
struct node
{
    int pa, ch[2], s, f;
}a[maxn];

void flip(int u)
```

```
{
    a[u].f ^= 1;
    swap(a[u].ch[0], a[u].ch[1]);
}

void pushdown(int k)
{
    if(!k)  return;
    int l = a[k].ch[0], r = a[k].ch[1];
    if(a[k].flip)
    {
    flip(l);
    flip(r);
    a[k].flip ^= 1;
    }
}

int pre(int u)
{
    u = a[u].ch[0];
    while(a[u].ch[1])
    u = a[u].ch[1];
    return u;
}

int post(int u)
{
    u = a[u].ch[1];
    while(a[u].ch[0])
    u = a[u].ch[0];
    return u;
}

void maintain(int u)
{
    int l = a[u].ch[0], r = a[u].ch[1];
    a[u].s = a[l].s + a[r].s + 1;
}

void rotate(int u)
{
    int x = a[u].pa, y = a[x].pa, d = (a[x].ch[1] == u);
    if(!y)
    root = u;
    else
    a[y].ch[a[y].ch[1] == x] = u;
    a[x].ch[d] = a[u].ch[d ^ 1];
    a[a[u].ch[d ^ 1]].pa = x;
    a[u].ch[d ^ 1] = x;
    a[x].pa = u;
    a[u].pa = y;
    maintain(x);
    maintain(u);
}

void splay(int u, int pa)  //u的父亲为pa
{
    int t;
    for(t = u; a[t].pa != pa; t = a[t].pa)
    st[++top] = t;
    pushdown(t);
    for(; top; top--)
        pushdown(st[top]);   //pushdown the tags

    while(a[u].pa != pa)
    {
    int x = a[u].pa, y = a[x].pa;
    if(y == pa)
    {
        rotate(u);
        return;
    }
    if((a[x].ch[0] == u) ^ (a[y].ch[0] == x))
        rotate(u);
    else
        rotate(x);
    rotate(u);
    }
}

void splay2(int u, int &g)  //将u旋转到g
{
    while(u != g)
    {
    int x = a[u].pa, y = a[x].pa;
    if(x == g)
    {
        rotate(u);
        return;
    }
    if((a[x].ch[0] == u) ^ (a[y].ch[0] == x))
        rotate(u);
    else
        rotate(x);
    rotate(u);
    }
}

int find_kth(int u, int k)
{
    pushdown(u);
```

```
    int size = a[a[u].ch[0]].s;
    if(k <= size)
    return find_kth(a[u].ch[0], k);
    if(k > size + 1)
    return find_kth(a[u].ch[1], k - size - 1);
    return u;
}

int get(int l, int r)
{
    int L = find_kth(root, l), R = find_kth(root, r + 2);  //L = pre(l), R = post(r)
    splay(L, 0);  //splay2(L, root)
    splay(R, L);  //splay2(R, a[root].ch[1])
    return a[R].ch[0];
}

int new_node() //recycle
{
    int res = q.front();
    q.pop();
    a[res].init();
    return res;
}

int build(int l, int r, int pa)
{
    if(l > r)
    return 0;
    int mid = (l + r) >> 1, u = new_node();
    a[u].pa = pa;
    a[u].s = 1;
    a[u].ch[0] = build(l, mid - 1, u);
    a[u].ch[1] = build(mid + 1, r, u);
    maintain(u);
    return u;
}

void recycle(int u)
{
    q.push(u);
    if(a[u].ch[0])
    recycle(a[u].ch[0]);
    if(a[u].ch[1])
    recycle(a[u].ch[1]);
}

void del(int l, int r)
{
    int r = get(l, r);
    recycle(a[r].ch[0]);
    a[a[r].pa].ch[0] = 0;
    maintain(a[r].pa);
    maintain(root);
}
```

3.7 splay-wrz

```
struct node
{
    node *ch[2], *fa;
    ll key; int siz, tag;
}mem[N*20], *tot, *null, *root;
void init()
{
    root = null = tot = mem;
    null->ch[0] = null->ch[1] = null->fa = null;
    null->key = null->siz = null->tag = 0;
}
int type(node *x){return x->fa->ch[1]==x;}
node *newnode(ll key)
{
    node *p = ++tot; *p = *null;
    p->key = key; p->siz = 1;
    return p;
}
void pushup(node *x)
{
    x->siz = x->ch[0]->siz + x->ch[1]->siz + 1;
}
void rotate(node *x)
{
    node *f =  x->fa; int d = type(x);
    (x->fa = f->fa) != null ? x->fa->ch[type(f)] = x : 0;
    (f->ch[d] = x->ch[!d]) != null ? f->ch[d]->fa = f : 0;
    x->ch[!d] = f, f->fa = x, pushup(f);
}
void pushdown(node *x)
{
    if(x->tag)
    {
        int &tag = x->tag;
        if(x->ch[0] != null) x->ch[0]->key += tag, x->ch[0]->tag += tag;
        if(x->ch[1] != null) x->ch[1]->key += tag, x->ch[1]->tag += tag;
        tag = 0;
    }
}
void update(node *x)
{
    if(x==null) return;
    update(x->fa);
    pushdown(x);
```

```
}
void splay(node *x, node *top)
{
    update(x);
    for(;x->fa!=top;)
    {
        if(x->fa->fa == top) rotate(x);
        else if(type(x) == type(x->fa)) rotate(x->fa), rotate(x);
        else rotate(x), rotate(x);
    }
    if(top == null) root = x;
    pushup(x);
}
void insert(node *x, node *f, node *p, int d)
{
    if(x == null)
    {
        p->fa = f, f->ch[d] = p;
        return;
    }
    pushdown(x);
    if(p->key < x->key) insert(x->ch[0], x, p ,0);
    else insert(x->ch[1], x, p, 1);
    pushup(x);
}

void insert(node *p)
{
    if(root == null) root = p, p->fa = p->ch[0] = p->ch[1] = null;
    else insert(root, null, p, 0), splay(p, null);
}
node *findl(node *x){return x->ch[0]==null?x:findl(x->ch[0]);}
node *findr(node *x){return x->ch[1]==null?x:findr(x->ch[1]);}
void insertlr()
{
    insert(newnode(-INF));
    insert(newnode(INF));
}
void delet(node *p)
{
    splay(p, null);
    node *lp = findr(p->ch[0]), *rp = findl(p->ch[1]);
    if(lp == null && rp != null) root = p->ch[1], root->fa = null;
    else if(lp != null && rp == null) root = p->ch[0], root->fa = null;
    else if(lp == null && rp == null)root = null;
    else
    {
        splay(rp, null); splay(lp,rp);
        lp->ch[1] = null; splay(lp,null);
    }
}
node* findk(node *p, int k)
{
    for(; ; )
    {
        pushdown(p);
        if(p->ch[0]->siz >= k) p = p->ch[0];
        else if(p->ch[0]->siz + 1 == k) {splay(p, null); return p;}
        else k -= p->ch[0]->siz + 1, p = p->ch[1];
    }
}
node* findv(node *p, int v)
{
    node* ret = null;
    for(; p!=null; )
    {
        pushdown(p);
        if(p->key >= v) ret = p, p = p->ch[0];
        else p = p->ch[1];
    }
    splay(ret, null);
    return ret;
}
void addv(node *p, int v)
{
    if(p == null) return;
    p->key += v;
    p->tag += v;
}
```

3.8 treap-gwx

```
struct node
{
    int pri, val, c, s;    //pri: random value; c: times of showing; s: size of subtree
    int ch[2];
    int cmp(int x) const {
        if(x == val) return -1;
        return x < val ? 0 : 1;
    }
} a[maxn];

void maintain(int u)  {
    a[u].s = a[u].c + a[a[u].ch[0]].s + a[a[u].ch[1]].s;
}

void rotate(int &u, int d)
{
    int tmp = a[u].ch[d ^ 1];
    a[u].ch[d ^ 1] = a[tmp].ch[d];
    a[tmp].ch[d] = u;
```

```
    maintain(u); maintain(tmp);
    u = tmp;
}

void insert(int &u, int val)
{
    if(!u)
    {
        u = ++cnt;
        a[cnt] = (node){rand(), val, 1, 1};
        return;
    }
    a[u].s++;
    int d = a[u].cmp(val);
    if(d == -1)  {a[u].c++; return;}
    insert(a[u].ch[d], val);
    if(a[a[u].ch[d]].pri > a[u].pri) rotate(u, d ^ 1);
}

int find(int u, int val, int comp, int &res)
{
    int d = a[u].cmp(val);
    if(!u) return -1;
    if(d == -1) return u;
    if(d == comp)
    {
        if(d) res = max(res, a[u].val);
        else res = min(res, a[u].val);
    }
    return find(a[u].ch[d], val, comp, res);
}

void remove(int &u)
{
    if(!a[u].ch[0]) u = a[u].ch[1];
    else if(!a[u].ch[1]) u = a[u].ch[0];
    else
    {
        int d = a[a[u].ch[0]].pri < a[a[u].ch[1]].pri ? 0 : 1;
        rotate(u, d); remove(a[u].ch[d]);
    }
}

void del(int &u, int val)
{
    if(find(root, val, -2, val) == -1) return;
    a[u].s--;
    int d = a[u].cmp(val);
    if(d == -1)
    {
        a[u].c--;
        if(!a[u].c) remove(u);
    }
    else del(a[u].ch[d], val);
}

int find_rank(int u, int val)
{
    int d = a[u].cmp(val);
    if(d == -1) return 1 + a[a[u].ch[0]].s;
    if(d == 0) return find_rank(a[u].ch[0], val);
    return a[u].s - a[a[u].ch[1]].s + find_rank(a[u].ch[1], val);
}

int find_kth(int u, int k)
{
    if(k <= a[a[u].ch[0]].s) return find_kth(a[u].ch[0], k);
    if(k > a[a[u].ch[0]].s + a[u].c) return find_kth(a[u].ch[1], k - a[a[u].ch[0]].s - a[u].c);
    return a[u].val;
}

int pre(int val)
{
    int ans = -inf;
    int pos = find(root, val, 1, ans);
    if(pos != -1 && a[pos].ch[0])
    {
        pos = a[pos].ch[0];
        while(a[pos].ch[1]) pos = a[pos].ch[1];
        ans = max(ans, a[pos].val);
    }
    return ans;
}

int post(int val)
{
    int ans = inf;
    int pos = find(root, val, 0, ans);
    if(pos != -1 && a[pos].ch[1])
    {
        pos = a[pos].ch[1];
        while(a[pos].ch[0]) pos = a[pos].ch[0];
        ans = min(ans, a[pos].val);
    }
    return ans;
}
//srand()
```

3.9 zkw 线段树

```
//zkw-segment-tree
```

```
int n, M, q;
int d[N << 1];
inline void build(int n) {
    for(M = 1; M < n; M <<= 1);
    for(int i = M + 1; i <= M + n; i++) t[i] = in();
    //sum
    for(int i = M - 1; i; --i) d[i] = d[i << 1] + d[i << 1 | 1];
    //max
    for(int i = M - 1; i; --i) d[i] = max(d[i << 1], d[i << 1 | 1]);
    //min
    for(int i = M - 1; i; --i) d[i] = min(d[i << 1], d[i << 1 | 1]);
}

//单点修改
void change(int x, int v) {
    t[x = M + x] += v;
    while(x) d[x >>= 1] = d[x << 1] + d[x << 1 | 1];
}

//区间查询
int Sum(int s,int t,int Ans=0){
    for (s = s + M - 1, t = t + M + 1; s ^ t ^ 1; s >>= 1, t >>= 1) {
        if(~ s & 1) Ans += d[s ^ 1];
        if(t & 1) Ans += d[t ^ 1];
    }
    return Ans;
}
    void Sum(int s,int t,int L=0,int R=0){
        for(s=s+M-1,t=t+M+1;s^t^1;s>>=1,t>>=1){
            L+=d[s],R+=d[t];
            if(~s&1) L=min(L,d[s^1]);
            if(t&1) R=min(R,d[t^1]);
        }
        int res=min(L,R);while(s) res+=d[s>>=1];
    }
//单点查询
//差分，当前点的值为该点和其父节点的差值
void build(int n) {
    for(M = 1; M <= n + 1; M <<= 1);
    for(int i = M + 1; i <= M + n; i++) d[i] = in();
    for(int i = M - 1; i; --i) {
        d[i] = min(d[i << 1], d[i << 1 | 1]),
        d[i << 1] -= d[i],
        d[i << 1 | 1] -= d[i];
    }
}

void Sum(int x, int res = 0) {
    while(x) res += d[x], x >>= 1;
    return res;
}
//区间最小(差分)
void Sum(int s, int t, int L = 0, int R = 0) {
    for(s = s + M - 1, t = t + M + 1; s ^ t ^ 1; s >>= 1, t >>= 1) {
        L += d[s], R += d[t];
        if(~ s & 1) L = min(L, d[s ^ 1]);
        if(t & 1) R = min(R, d[t ^ 1]);
    }
    int res = min(L, R);
    while(s) res += d[s >>= 1];
}
//区间加法，维护最小值(差分)
void Add(int s, int t, int v, int A = 0) {
    for(s = s + M - 1, t = t + M + 1; s ^ t ^ 1;s >>= 1, t >>= 1) {
        if(~ s & 1) d[s ^ 1] += v;
        if(t & 1) d[t ^ 1] += v;
        A = min(d[s], d[s ^ 1]);
        d[s] -= A, d[s ^ 1] -= A, d[s >> 1] += A;
        A = min(d[t], d[t^1]);
        d[t] -= A, d[t ^ 1] -=A, d[t >> 1] += A;
    }
    while(s) {
        A = min(d[s], d[s ^ 1]),
        d[s] -= A,
        d[s ^ 1] -= A,
        d[s >>= 1] += A;
    }
}
```

4 图论

4.1 2-SAT

```
2-SAT的tarjan做法适用于一类如果A->B，则一定有B' ->A' 的对称的图。
一个强联通分量里的所有点，要么一起选要么一起不选，那就缩起来。
一个重要的结论是如果一个强联通分量里同时有A和A'，则此图无解，否则一定有解。
无解的情况显然正确。
有解的情况考虑构造。每次随便从点集里抓一个点A出来，选中A的所有可达点，删去所有可达A' 的点。显然这是可以做到的。
那这样会不会把图弄成无解？考虑如果一个B->A，那么选了A及其可达点，那B选不选是不影响的。对于不可达A的显然也不影响，
    因此可以这样构造。
一个特例是存在A->A' 的边，那这样选A就挂了，因此逆拓扑序 来构造才是更一般的做法。
因此构造方案只需对于任意一对点A,A'，取dfs序大的即可。
```

4.2 上下界网络流

```
有源汇上下界费用流：
    转换为求无源汇上下界最小费用可行循环流，通过T→S连边，流量上下界为(原总流量，INF)。

```

```
无源汇上下界最小费用可行循环流:
    在原基础上再新增一个超级源点 supS, supT, 构造只有上界的网络。
    对于原图的每一条边 (u, v) , 再新图中添加一条 supS→v 流量为 u, v 流量下界的边, 一条 u→supT 流量为 u, v 流量下
        界的边, 一条 u→v 流量为 u, v 流量上界-流量下界的边。
    做从 supS→supT 的最小费用流, 限定到达 supT 的流量为满流 (即 supS 所有出边的流量和) 。此即为答案。
    HINT: 原图中所有未提及的边费用都应记为 0 。新图中的重新构造的边的费用等同原图中对应边的费用。


4.7 上下界网络流
B(u, v) 表示边 (u, v) 流量的下界,C(u, v) 表示边 (u, v) 流量的上界,F (u, v) 表示边 (u, v)
的流量。设 G(u, v) = F (u, v) - B(u, v),显然有
0   G(u, v)   C(u, v) - B(u, v)
4.7.1 无源汇的上下界可行流
建立超级源点 S * 和超级汇点 T * ,对于原图每条边 (u, v) 在新网络中连如下三条边: S * → v,
容量为 B(u, v);u → T * ,容量为 B(u, v);u → v,容量为 C(u, v) - B(u, v)。最后求新网络
的最大流,判断从超级源点 S * 出发的边是否都满流即可,边 (u, v) 的最终解中的实际流量为
G(u, v) + B(u, v)。
4.7.2 有源汇的上下界可行流
从汇点 T 到源点 S 连一条上界为 ∞,下界为 0 的边。按照无源汇的上下界可行流一样做
即可,流量即为 T → S 边上的流量。
4.7.3 有源汇的上下界最大流
1. 在有源汇的上下界可行流中,从汇点 T 到源点 S 的边改为连一条上界为 ∞,下届为 x 的
边。x 满足二分性质,找到最大的 x 使得新网络存在无源汇的上下界可行流即为原图的最大
流。
2. 从汇点 T 到源点 S 连一条上界为 ∞,下界为 0 的边,变成无源汇的网络。按照无源汇的
上下界可行流的方法,建立超级源点 S * 和超级汇点 T * ,求一遍 S * → T * 的最大流,再将
从汇点 T 到源点 S 的这条边拆掉,求一次 S → T 的最大流即可。
4.7.4 有源汇的上下界最小流
1. 在有源汇的上下界可行流中,从汇点 T 到源点 S 的边改为连一条上界为 x,下界为 0 的
边。x 满足二分性质,找到最小的 x 使得新网络存在无源汇的上下界可行流即为原图的最小
流。
712. 按照无源汇的上下界可行流的方法,建立超级源点 S * 与超级汇点 T * ,求一遍 S * → T * 的
最大流,但是注意这一次不加上汇点 T 到源点 S 的这条边,即不使之改为无源汇的网络去
求解。求完后,再加上那条汇点 T 到源点 S 上界 ∞ 的边。因为这条边下界为 0,所以
S * ,T * 无影响,再直接求一次 S * → T * 的最大流。若超级源点 S * 出发的边全部满流,则
T → S 边上的流量即为原图的最小流,否则无解。
```

4.3 矩阵树定理

```
C = 度数矩阵-领接矩阵
无向图G的生成树个数 = C的任意n - 1阶主子式(对角线的乘积)
```

4.4 边双联通-gwx

```
//G[i]: 第i个边双联通分量中有哪些点
void tarjan(int u, int pa)
{
    d[u] = l[u] = ++timer;
    for(int i = tail[u]; i; i = e[i].next)
    {
        if(!d[e[i].v])
        {
            st[++top] = i;
            tarjan(e[i].v, u);
            l[u] = min(l[u], l[e[i].v]);
            if(l[e[i].v] >= d[u])
            {
                bcc++;
                while(true)
                {
                    int now = st[top--];
                    if(vst[e[now].u] != bcc)
                    {
                        vst[e[now].u] = bcc;
                        G[bcc].push_back(e[now].u);
                    }
                    if(vst[e[now].v] != bcc)
                    {
                        vst[e[now].v] = bcc;
                        G[bcc].push_back(e[now].v);
                    }
                    if(now == i) break;
                }
            }
        }
        else if(e[i].v != pa)
            l[u] = min(l[u], d[e[i].v]);
    }
}
```

4.5 带花树

```
vector<int> link[maxn];
int n,match[maxn],Queue[maxn],head,tail;
int pred[maxn],base[maxn],start,finish,newbase;
bool InQueue[maxn],InBlossom[maxn];
void push(int u){ Queue[tail++]=u;InQueue[u]=true; }
int pop(){ return Queue[head++]; }
int FindCommonAncestor(int u,int v){
    bool InPath[maxn];
    for(int i=0;i<n;i++) InPath[i]=0;
    while(true){ u=base[u];InPath[u]=true;if(u==start) break;u=pred[match[u]]; }
    while(true){ v=base[v];if(InPath[v]) break;v=pred[match[v]]; }
    return v;
}
void ResetTrace(int u){
```

```
    int v;
    while(base[u]!=newbase){
        v=match[u];
        InBlossom[base[u]]=InBlossom[base[v]]=true;
        u=pred[v];
        if(base[u]!=newbase) pred[u]=v;
    }
}
void BlossomContract(int u,int v){
    newbase=FindCommonAncestor(u,v);
    for (int i=0;i<n;i++)
    InBlossom[i]=0;
    ResetTrace(u);ResetTrace(v);
    if(base[u]!=newbase) pred[u]=v;
    if(base[v]!=newbase) pred[v]=u;
    for(int i=0;i<n;++i)
    if(InBlossom[base[i]]){
        base[i]=newbase;
        if(!InQueue[i]) push(i);
    }
}
bool FindAugmentingPath(int u){
    bool found=false;
    for(int i=0;i<n;++i) pred[i]=-1,base[i]=i;
    for (int i=0;i<n;i++) InQueue[i]=0;
    start=u;finish=-1; head=tail=0; push(start);
    while(head<tail){
        int u=pop();
        for(int i=link[u].size()-1;i>=0;i--){
            int v=link[u][i];
            if(base[u]!=base[v]&&match[u]!=v)
                if(v==start||(match[v]>=0&&pred[match[v]]>=0))
                    BlossomContract(u,v);
                else if(pred[v]==-1){
                    pred[v]=u;
                    if(match[v]>=0) push(match[v]);
                    else{ finish=v; return true; }
                }
        }
    }
    return found;
}
void AugmentPath(){
    int u=finish,v,w;
    while(u>=0){ v=pred[u];w=match[v];match[v]=u;match[u]=v;u=w; }
}
void FindMaxMatching(){
    for(int i=0;i<n;++i) match[i]=-1;
    for(int i=0;i<n;++i) if(match[i]==-1) if(FindAugmentingPath(i)) AugmentPath();
}
```

4.6 支配树-gwx

```
/*
    用ins()加边
    build前设置n为点数，s为源点
    树中的i号点对应原图的id[i]号点
*/
struct Dominator_Tree {
    int n, s, cnt;
    int dfn[N], id[N], pa[N], semi[N], idom[N], p[N], mn[N];
    vector<int>e[N], dom[N], be[N];
    void ins(int x, int y) {e[x].push_back(y);}
    void dfs(int x) {
        dfn[x] = ++cnt; id[cnt] = x;
        for (int i : e[x]) {
            if (!dfn[i])dfs(i), pa[dfn[i]] = dfn[x];
            be[dfn[i]].push_back(dfn[x]);
        }
    }
    int get(int x) {
        if (p[x] != p[p[x]]) {
            if (semi[mn[x]] > semi[get(p[x])])mn[x] = get(p[x]);
            p[x] = p[p[x]];
        }
        return mn[x];
    }
    void LT() {
        for (int i = cnt; i > 1; i--) {
            for (int j : be[i])semi[i] = min(semi[i], semi[get(j)]);
            dom[semi[i]].push_back(i);
            int x = p[i] = pa[i];
            for (int j : dom[x])idom[j] = (semi[get(j)] < x ? get(j) : x);
            dom[x].clear();
        }
        for (int i = 2; i <= cnt; i++) {
            if (idom[i] != semi[i])idom[i] = idom[idom[i]];
            dom[id[idom[i]]].push_back(id[i]);
        }
    }
    void build() {
        for(int i = 1; i <= n; ++i)
            dfn[i] = 0, dom[i].clear(), be[i].clear(), p[i] = mn[i] = semi[i] = i;
        cnt = 0; dfs(s); LT();
    }
};
```

4.7 支配树-wrz

```
int dfn[N],redfn[N],fa[N],sdom[N],idom[N],fo[N],vo[N],dtimer;
```

```
vector<int> pre[N],bkt[N];
int dom_find(int x)
{
    if(fo[x]==x) return x;
    int r = dom_find(fo[x]);
    if(sdom[vo[fo[x]]]<sdom[vo[x]]) vo[x] = vo[fo[x]];
    return fo[x] = r;
}
int dom_eval(int x){dom_find(x); return vo[x];}
void dom_dfs(int x)
{
    redfn[dfn[x]=++dtimer] = x, sdom[x] = dfn[x];
    for(int i=last[x];i;i=e[i].next) if(!dfn[e[i].to])
        dom_dfs(e[i].to), fa[e[i].to] = x;
}
void dom_build(int S)
{
    int i,x;
    dom_dfs(S);
    for(i = dtimer; i >=2; i--)
    {
        x = redfn[i];
        for(int i = 0, ii = pre[x].size(); i < ii; i++)
        {
            int k = pre[x][i];
            if(dfn[k]) sdom[x] = min(sdom[x],sdom[dom_eval(k)]);
        }
        bkt[redfn[sdom[x]]].push_back(x);
        int fp = fa[x]; fo[x] = fa[x];
        for(int i = 0, ii = bkt[fp].size(); i < ii; i++)
        {
            int v = bkt[fp][i];
            int u = dom_eval(v);
            idom[v] = sdom[u]==sdom[v]?fp:u;
        }
        bkt[fp].clear();
    }
    for(int i = 2;i <= dtimer; i++) x = redfn[i], idom[x] = idom[x]==redfn[sdom[x]]?idom[x]:idom[idom[x]];
    for(int i = 2;i <= dtimer; i++) x = redfn[i], sdom[x] = redfn[sdom[x]];
}
void dom_init()
{
    dtimer = 0;
    for(int i = 1; i <= n; i++)
    {
        dfn[i] = 0;
        fo[i] = vo[i] = i;
        pre[i].clear(), bkt[i].clear();
    }
    for(int x = 1; x <= n; x++) for(int i = last[x]; i; i = e[i].next) pre[e[i].to].push_back(x);
}
/*
    步骤:
    1.建好原图
    2.dom_init() // 必须保证原图上所有的边已经连好
    3.dom_build(S) // S为支配树的根结点标号
    4.得到idom数组 // idom[x]表示x在支配树上的父结点, 别的数组用处不大
*/
```

4.8 欧拉回路-wrz

```
#include<cstdio>
#define N 100005
#define M 200005
using namespace std;
int last[N], ecnt = 1, cnt, ans[M], in_deg[N], out_deg[N];
bool vis[M];
struct edge{int next,to;}e[M<<1];
void addedge(int a, int b)
{
    e[++ecnt] = (edge){last[a], b};
    last[a] = ecnt;
}
void dfs(int x)
{
    for(int &i = last[x]; i; i = e[i].next)
    {
        int y = e[i].to, j = i;
        if(!vis[j>>1])
        {
            vis[j>>1] = 1;
            dfs(y);
            ans[++cnt] = j;
        }
    }
}
int main()
{
    int t, n, m, a, b;
    scanf("%d%d%d",&t,&n,&m);
    for(int i = 1; i <= m; i++)
    {
        scanf("%d%d",&a,&b);
        addedge(a,b);
        if(t == 1)addedge(b,a), in_deg[a]++, in_deg[b]++;
        else ecnt++, in_deg[b]++, out_deg[a]++;
    }

    if(t == 1) // 无向
    {
```

```
        for(int i = 1; i <= n; i++)
            if((in_deg[i]+out_deg[i]) & 1)
                return !printf("NO\n");
    }
    else // 有向
    {
        for(int i = 1; i <= n; i++)
            if(in_deg[i] != out_deg[i])
                return !printf("NO\n");
    }
    dfs(a);
    if(cnt != m)
    {
        puts("NO");
    }
    else
    {
        puts("YES");
        for(int i = cnt; i; i--)
        {
            printf("%d␣",ans[i]&1?-(ans[i]>>1):(ans[i]>>1));
        }
    }
}
```

4.9 Hopcoft-Karp

```
// O(sqrt(n)m)
template <int MAXN = 100000, int MAXM = 100000>
struct hopcoft_karp {
    int mx[MAXN], my[MAXM], lv[MAXN];
    bool dfs (edge_list <MAXN, MAXM> &e, int x) {
        for (int i = e.begin[x]; ~i; i = e.next[i]) {
            int y = e.dest[i], w = my[y];
            if (!~w || (lv[x] + 1 == lv[w] && dfs (e, w))) {
                mx[x] = y; my[y] = x; return true; } }
        lv[x] = -1; return false; }
    int solve (edge_list <MAXN, MAXM> &e, int n, int m) {
        std::fill (mx, mx + n, -1); std::fill (my, my + m, -1);
        for (int ans = 0; ; ) {
            std::vector <int> q;
            for (int i = 0; i < n; ++i)
                if (mx[i] == -1) {
                    lv[i] = 0; q.push_back (i);
                } else lv[i] = -1;
            for (int head = 0; head < (int) q.size(); ++head) {
                int x = q[head];
                for (int i = e.begin[x]; ~i; i = e.next[i]) {
                    int y = e.dest[i], w = my[y];
                    if (~w && lv[w] < 0) { lv[w] = lv[x] + 1; q.push_back (w); } } }
            int d = 0; for (int i = 0; i < n; ++i) if (!~mx[i] && dfs (e, i)) ++d;
            if (d == 0) return ans; else ans += d; } } };
```

4.10 KM-truly-n3

```
struct KM {
    // Truly O(n^3)
    // 邻接矩阵，不能连的边设为 -INF，求最小权匹配时边权取负，但不能连的还是 -INF，使用时先对 1 -> n 调用 hungary
        () ，再 get_ans() 求值
    int w[N][N];
    int lx[N], ly[N], match[N], way[N], slack[N];
    bool used[N];
    void init() {
        for (int i = 1; i <= n; i++) {
            match[i] = 0;
            lx[i] = 0;
            ly[i] = 0;
            way[i] = 0;
        }
    }
    void hungary(int x) {
        match[0] = x;
        int j0 = 0;
        for (int j = 0; j <= n; j++) {
            slack[j] = INF;
            used[j] = false;
        }

        do {
            used[j0] = true;
            int i0 = match[j0], delta = INF, j1 = 0;
            for (int j = 1; j <= n; j++) {
                if (used[j] == false) {
                    int cur = -w[i0][j] - lx[i0] - ly[j];
                    if (cur < slack[j]) {
                        slack[j] = cur;
                        way[j] = j0;
                    }
                    if (slack[j] < delta) {
                        delta = slack[j];
                        j1 = j;
                    }
                }
            }
            for (int j = 0; j <= n; j++) {
                if (used[j]) {
                    lx[match[j]] += delta;
                    ly[j] -= delta;
                }
                else slack[j] -= delta;
```

```
            }
            j0 = j1;
        } while (match[j0] != 0);

        do {
            int j1 = way[j0];
            match[j0] = match[j1];
            j0 = j1;
        } while (j0);
    }

    int get_ans() {
        int sum = 0;
        for(int i = 1; i <= n; i++) {
            if (w[match[i]][i] == -INF) ; // 无解
            if (match[i] > 0) sum += w[match[i]][i];
        }
        return sum;
    }
} km;
```

4.11 k 短路 a 星-gwx

```
const int maxn = 1005;
int n, m;
int S, T, K;
int dist[maxn], cnt[maxn];
bool vst[maxn];
vector<pair<int, int>> G[maxn], H[maxn];    //正图&反图
struct node
{
    ll d;
    int id;
    node(){}
    node(ll d, int id): d(d), id(id) {}
    bool operator< (const node &other) const{
        return d + dist[id] > other.d + dist[other.id];
    }
};

priority_queue <pair<ll, int>> q;
priority_queue <node> Q;

void init()
{
    for(int i = 1; i <= n; ++i)
        G[i].clear(), H[i].clear(), cnt[i] = 0;
}

void dijkstra(int S)
{
    memset(dist, 127, sizeof(dist));
    memset(vst, 0, sizeof(vst));
    while(!q.empty()) q.pop();
    dist[S] = 0;
    q.push(make_pair(0, S));
    for(int i = 1; i <= n; ++i)
    {
        if(q.empty()) break;
        while(vst[q.top().second]) q.pop();
        int u = q.top().second; q.pop();
        vst[u] = 1;
        for(auto i: H[u])
        {
            if(dist[i.first] > dist[u] + i.second)
            {
                dist[i.first] = dist[u] + i.second;
                q.push(make_pair(-dist[i.first], i.first));
            }
        }
    }
}

int solve()
{
    while(!Q.empty()) Q.pop();
    Q.push(node(0, S));
    while(!Q.empty())
    {
        auto u = Q.top(); Q.pop();
        if(++cnt[u.id] > K) continue;
        if(u.d + dist[u.id] > ti) continue;
        if(u.id == T && cnt[T] == K)
            return u.d;
        for(auto i: G[u.id])
            Q.push(node(u.d + i.second, i.first));
    }
    return -1;
}
```

4.12 K 短路可并堆

```
//Kth Shortest Path via Persistable Mergeable Heap
//可持久化可并堆求k短路 O(SSSP+(m+k)\log n)
//By ysf
//通过题目：USACO Mar08 牛跑步（板子题）

//注意这是个多项式算法，在k比较大时很有优势，但k比较小时最好还是用A*
//DAG和有环的情况都可以，有重边或自环也无所谓，但不能有零环
//以下代码以Dijkstra+可持久化左偏树为例
```

```

const int maxn=1005,maxe=10005,maxm=maxe*30;//点数，边数，左偏树结点数

//需要用到的结构体定义
struct A{//用来求最短路
    int x,d;
    A(int x,int d):x(x),d(d){}
    bool operator<(const A &a)const{return d>a.d;}
};

struct node{//左偏树结点
    int w,i,d;//i: 最后一条边的编号 d: 左偏树附加信息
    node *lc,*rc;
    node(){}
    node(int w,int i):w(w),i(i),d(0){}
    void refresh(){d=rc->d+1;}
}null[maxm],*ptr=null,*root[maxn];

struct B{//维护答案用
    int x,w;//x是结点编号，w表示之前已经产生的权值
    node *rt;//这个答案对应的堆顶，注意可能不等于任何一个结点的堆
    B(int x,node *rt,int w):x(x),w(w),rt(rt){}
    bool operator<(const B &a)const{return w+rt->w>a.w+a.rt->w;}
};

//全局变量和数组定义
vector<int>G[maxn],W[maxn],id[maxn];//最开始要存反向图，然后把G清空作为儿子列表
bool vis[maxn],used[maxe];//used表示边是否在最短路树上
int u[maxe],v[maxe],w[maxe];//存下每条边，注意是有向边
int d[maxn],p[maxn];//p表示最短路树上每个点的父边
int n,m,k,s,t;//s,t分别表示起点和终点

//以下是主函数中较关键的部分
for(int i=0;i<=n;i++)root[i]=null;//一定要加上！！！
//(读入&建反向图)
Dijkstra();
//(清空G,W,id)
for(int i=1;i<=n;i++)
    if(p[i]){
        used[p[i]]=true;//在最短路树上
        G[v[p[i]]].push_back(i);
    }
for(int i=1;i<=m;i++){
    w[i]-=d[u[i]]-d[v[i]];//现在的w[i]表示这条边能使路径长度增加多少
    if(!used[i])
        root[u[i]]=merge(root[u[i]],newnode(w[i],i));
}
dfs(t);
priority_queue<B>heap;
heap.push(B(s,root[s],0));//初始状态是找贡献最小的边加进去
printf("%d\n",d[s]);//第1短路需要特判
while(--k){//其余k-1短路径用二叉堆维护
    if(heap.empty())printf("-1\n");
    else{
        int x=heap.top().x,w=heap.top().w;
        node *rt=heap.top().rt;
        heap.pop();
        printf("%d\n",d[s]+w+rt->w);
        if(rt->lc!=null||rt->rc!=null)
            heap.push(B(x,merge(rt->lc,rt->rc),w));//pop掉当前边，换成另一条贡献大一点的边
        if(root[v[rt->i]]!=null)
            heap.push(B(v[rt->i],root[v[rt->i]],w+rt->w));//保留当前边，往后面再接上另一条边
    }
}
//主函数到此结束

//Dijkstra预处理最短路 O(m\log n)
void Dijkstra(){
    memset(d,63,sizeof(d));
    d[t]=0;
    priority_queue<A>heap;
    heap.push(A(t,0));
    while(!heap.empty()){
        int x=heap.top().x;
        heap.pop();
        if(vis[x])continue;
        vis[x]=true;
        for(int i=0;i<(int)G[x].size();i++)
            if(!vis[G[x][i]]&&d[G[x][i]]>d[x]+W[x][i]){
                d[G[x][i]]=d[x]+W[x][i];
                p[G[x][i]]=id[x][i];
                heap.push(A(G[x][i],d[G[x][i]]));
            }
    }
}

//dfs求出每个点的堆 总计O(m\log n)
//需要调用merge，同时递归调用自身
void dfs(int x){
    root[x]=merge(root[x],root[v[p[x]]]);
    for(int i=0;i<(int)G[x].size();i++)
        dfs(G[x][i]);
}

//包装过的new node() O(1)
node *newnode(int w,int i){
    *++ptr=node(w,i);
    ptr->lc=ptr->rc=null;
```

```
    return ptr;
}

//带可持久化的左偏树合并 总计O(\log n)
//递归调用自身
node *merge(node *x,node *y){
    if(x==null)return y;
    if(y==null)return x;
    if(x->w>y->w)swap(x,y);
    node *z=newnode(x->w,x->i);
    z->lc=x->lc;
    z->rc=merge(x->rc,y);
    if(z->lc->d>z->rc->d)swap(z->lc,z->rc);
    z->refresh();
    return z;
}
```

4.13 最大团

```
/*
Int g[][]为图的邻接矩阵。
    MC(V)表示点集V的最大团
    令Si={vi, vi+1, ..., vn}, mc[i]表示MC(Si)
    倒着算mc[i], 那么显然MC(V)=mc[1]
    此外有mc[i]=mc[i+1] or mc[i]=mc[i+1]+1
*/
void init(){
    int i, j;
    for (i=1; i<=n; ++i) for (j=1; j<=n; ++j) scanf("%d", &g[i][j]);
}
void dfs(int size){
    int i, j, k;
    if (len[size]==0) {
        if (size>ans) {
            ans=size; found=true;
        }
        return;
    }
    for (k=0; k<len[size] && !found; ++k) {
        if (size+len[size]-k<=ans) break;
        i=list[size][k];
        if (size+mc[i]<=ans) break;
        for (j=k+1, len[size+1]=0; j<len[size]; ++j)
        if (g[i][list[size][j]]) list[size+1][len[size+1]++]=list[size][j];
        dfs(size+1);
    }
}
void work(){
    int i, j;
    mc[n]=ans=1;
    for (i=n-1; i; --i) {
        found=false;
        len[1]=0;
        for (j=i+1; j<=n; ++j) if (g[i][j]) list[1][len[1]++]=j;
        dfs(1);
        mc[i]=ans;
    }
}
```

4.14 SAP 网络流

```
#include<bits/stdc++.h>
typedef long long ll;
using std::min;

void read(int &digit)
{
    digit=0;
    char c;
    for (c=getchar();(c<'0' || c>'9') && c!='-';c=getchar());
    bool type=false;
    if (c=='-')
        type=true,c=getchar();
    for (;c>='0' && c<='9';digit=digit*10+c-'0',c=getchar());
    if (type==true)
        digit=-digit;
}

#define maxn 1010
const int INF=1<<30;
int n,m;
int S,T;
struct Edge
{
    int v,flow,next;
}   e[510010];
int g[maxn],tot=1;//tot初值必须赋为1
void addedge(int x,int y,int flow)
{
    e[++tot].v=y;e[tot].flow=flow;e[tot].next=g[x];g[x]=tot;
    e[++tot].v=x;e[tot].flow=0;e[tot].next=g[y];g[y]=tot;
}
int w[maxn],hash[maxn],d[maxn];
int que[maxn],pre1[maxn],pre2[maxn],p[maxn];
bool vis[maxn];
int maxflow()
{
    for (int i=1;i<=n;i++)  hash[i]=0,d[i]=0,vis[i]=false;
    for (int i=1;i<=n;i++)  p[i]=g[i];
    //hash[0]=n;
```

```
    int l,r;
    l=r=1;
    que[1]=T;hash[0]=1;vis[T]=true;
    while (l<=r)
    {
        int u=que[l++];
        for (int i=g[u];i;i=e[i].next)
        if ((i&1) && !vis[e[i].v])
        {
            que[++r]=e[i].v;
            vis[e[i].v]=true;
            d[e[i].v]=d[u]+1;
            hash[d[e[i].v]]++;
        }
    }
    for (int i=1;i<=n;i++)
    if (!vis[i])    d[i]=n,hash[n]++;
    int flow=INF;
    int ans=0;
    int u=S;
    while (d[S]<n)
    {
        w[u]=flow;
        bool bo=true;
        for (int i=p[u];i;i=e[i].next)
        if (e[i].flow && d[e[i].v]==d[u]-1)
        {
            flow=min(flow,e[i].flow);
            p[u]=i;
            pre1[e[i].v]=u;
            pre2[e[i].v]=i;
            u=e[i].v;
            bo=false;
            if (u==T)
            {
                ans+=flow;
                while (u!=S)
                {
                    e[pre2[u]].flow-=flow;
                    e[pre2[u]^1].flow+=flow;
                    u=pre1[u];
                }
                flow=INF;
            }
            break;
        }
        if (!bo)    continue;
        int minx=n,pos=0;
        for (int i=g[u];i;i=e[i].next)
        if (e[i].flow && d[e[i].v]<minx)    minx=d[e[i].v],pos=i;
        p[u]=pos;
        hash[d[u]]--;
        if (hash[d[u]]==0)  break;
        d[u]=minx+1;
        hash[d[u]]++;
        if (u!=S)   u=pre1[u],flow=w[u];
    }
    return ans;
}
int main()
{
    int n1,n2;
    read(n1),read(n2),read(m);
    n=n1+n2+2;
    S=n1+n2+1,T=n1+n2+2;
    tot=1;
    for (int i=1;i<=n1;i++) addedge(S,i,1);
    for (int i=1;i<=n2;i++) addedge(i+n1,T,1);
    while (m--)
    {
        int x,y;
        read(x),read(y);
        addedge(x,y+n1,1);
    }
    int mjy=maxflow();
    printf("%d\n",mjy);
    for (int i=1;i<=n1;i++)
    {
        bool bo=true;
        for (int j=g[i];j;j=e[j].next)
            if (!(j&1) && e[j].flow==0) {bo=false;printf("%d␣",e[j].v-n1);break;}
        if (bo) printf("0␣");
    }
    printf("\n");
    return 0;
}

//求割的方案：从S开始，沿着非满流边bfs，能遍历到的地方为集合SS，其余为集合TT，横跨两个集合的边为割边
```

4.15 SPFA 判负环-wrz

```
int inq[N], inqt[N], dis[N];
bool SPFA()
{
    queue<int> q;
    for(int i = 1; i <= n; i++) dis[i] = 0, q.push(i), inq[i] = 1; // 全部入队
    for(; !q.empty(); )
    {
        int x = q.front(); q.pop(); inq[x] = 0;
        for(int i = last[x]; i; i = e[i].next)
        {
```

```
            int y = e[i].to;
            if(dis[x] + e[i].val < dis[y])
            {
                dis[y] = dis[x] + e[i].val;
                if(!inq[y])
                {
                    if(++inqt[y] > n) return false; // 入队n次即有负环
                    inq[y] = 1;
                    q.push(y);
                }
            }
        }
    }
    return true;
}
/*
    步骤:
    1.建好原图
    2.SPFA() // 若返回为true表示无负环, false表示有负环

    多次调用时记得清空inqt等数组
    有负环时理论复杂度是O(n^2)的
*/
```

4.16 斯坦纳树

```
//Nμ   , M±   , P¹  μ
const int inf = 0x3f3f3f3f;
int n, m, p, status, idx[P], f[1 << P][N];
priority_queue<pair<int, int> > q; //int top, h[N];
void dijkstra(int dis[]) {}
void Steiner_Tree() {
    for (int i = 1; i < status; i++) {
        while (!q.empty()) q.pop(); //top = 0;
        memset(vis, 0, sizeof(vis));
        for (int j = 1; j <= n; j++) {
            for (int k = i & (i - 1); k; (--k) &= i)
                f[i][j] = min(f[i][j], f[k][j] + f[i ^ k][j]);
            if (f[i][j] != inf)
                q.push(make_pair(-f[i][j], j)); //h[++top] = j, vis[j] = 1;
        }
        dijkstra(f[i]); //SPFA(f[i]);
    }
}
int main() {
    scanf("%d%d%d", &n, &m, &p);
    status = 1 << p;
    tot = 0; memset(lst, 0, sizeof(lst));
    /*      ³
      ÿ¿   ³             ¸ Fμ  I´ ¼
       ¿ª ¸      μ 0  I
      Add(0, i, val[i]); Add(i, 0, val[i]);*/
    for (int i = 1; i <= p; i++) scanf("%d", &idx[i]);
    memset(f, 0x3f, sizeof(f));
    for (int i = 1; i <= n; i++) f[0][i] = 0;
    for (int i = 1; i <= p; i++) f[1 << (i - 1)][idx[i]] = 0;
    Steiner_Tree();
    int ans = inf;
    for (int i = 1; i <= n; i++) ans = min(ans, f[status - 1][i]);
}
```

4.17 stoer-wagner 无向图最小割树

```
int cost[maxn][maxn],seq[maxn],len[maxn],n,m,pop,ans;
bool used[maxn];
void Init(){
    int i,j,a,b,c;
    for(i=0;i<n;i++) for(j=0;j<n;j++) cost[i][j]=0;
    for(i=0;i<m;i++){
        scanf("%d␣%d␣%d",&a,&b,&c); cost[a][b]+=c; cost[b][a]+=c;
    }
    pop=n; for(i=0;i<n;i++) seq[i]=i;
}
void Work(){
    ans=inf; int i,j,k,l,mm,sum,pk;
    while(pop > 1){
        for(i=1;i<pop;i++) used[seq[i]]=0; used[seq[0]]=1;
        for(i=1;i<pop;i++) len[seq[i]]=cost[seq[0]][seq[i]];
        pk=0; mm=-inf; k=-1;
        for(i=1;i<pop;i++) if(len[seq[i]] > mm){ mm=len[seq[i]]; k=i; }
        for(i=1;i<pop;i++){
            used[seq[l=k]]=1;
            if(i==pop-2) pk=k;
            if(i==pop-1) break;
            mm=-inf;
            for(j=1;j<pop;j++) if(!used[seq[j]])
                if((len[seq[j]]+=cost[seq[l]][seq[j]]) > mm)
                    mm=len[seq[j]], k=j;
        }
        sum=0;
        for(i=0;i<pop;i++) if(i != k) sum+=cost[seq[k]][seq[i]];
        ans=min(ans,sum);
        for(i=0;i<pop;i++)
            cost[seq[k]][seq[i]]=cost[seq[i]][seq[k]]+=cost[seq[pk]][seq[i]];
        seq[pk]=seq[--pop];
    }
    printf("%d\n",ans);
}
```

4.18 tarjan-gwx

```cpp
//cut[i]: i是否为割点
//bridge[i]: e[i]是否为桥
void dfs(int u, int pa)
{
    d[u] = l[u] = ++timer;
    st.push(u); vst[u] = 1;
    int child = 0;
    for(int i = tail[u]; i; i = e[i].next)
        if(!d[e[i].v])
        {
            child++;
            dfs(e[i].v, u);
            l[u] = min(l[u], l[e[i].v]);
            if(l[e[i].v] >= d[u])
            {
                cut[u] = 1;
                if(l[e[i].v] > d[u])
                    bridge[i] = 1;
            }
        }
        else if(vst[e[i].v]) l[u] = min(l[u], d[e[i].v]);
    if(!pa && child < 2) cut[u] = 0;
    if(l[u] == d[u])
    {
        int v; scc++;
        while(true)
        {
            v = st.top(); st.pop();
            id[v] = scc; vst[v] = 0; size[scc]++;
            if(u == v) break;
        }
    }
}
```

4.19 tarjan-wrz

```cpp
void tarjan(int x) // 找割点
{
    low[x] = dfn[x] = ++timer;
    int siz = 0;
    for(int i = last[x]; i; i = e[i].next)
    {
        int y = e[i].to;
        if(!dfn[y])
        {
            tarjan(y); siz++;
            cmin(low[x], low[y]);
            if(x != 1 && low[y] >= dfn[x]) cut[x] = 1;
        }
        else cmin(low[x], dfn[y]);
    }
    if(x == 1 && siz > 1) cut[1] = 1;
}

void tarjan(int x) // 有向图 缩
{
    dfn[x] = low[x] = ++timer; sta[++stacnt] = x; insta[x] = 1;
    for(int i = last[x]; i; i = e[i].next)
    {
        int y = e[i].to;
        if(!dfn[y]) tarjan(y), low[x] = min(low[x], low[y]); // 根据不同需求适当修改
        else if(insta[y])low[x] = min(low[x], dfn[y]);
    }
    if(low[x] == dfn[x])
    {
        bel[x] = ++bcnt; insta[x] = 0;
        for(; sta[stacnt] != x; stacnt--)
            bel[sta[stacnt]] = bcnt, insta[sta[stacnt]] = 0;
        stacnt--;
    }
}
```

4.20 朱刘算法-gwx

```cpp
//时间复杂度: O(nm)
int N, m;
int pre[maxn], in[maxn], f[maxn], id[maxn];
struct node {int u, v, w;} a[maxm * 2]; //边表

int find(int x)
{
    return f[x] == x ? x : f[x] = find(f[x]);
}

int mst()
{
    long long res = 0;
    int root = 1;
    int n = N;
    while(true)
    {
        for(int i = 1; i <= n; i++) in[i] = INT_MAX, pre[i] = 0;
        for(int i = 1; i <= m; i++)
            if(a[i].u != a[i].v  && in[a[i].v] > a[i].w)
                in[a[i].v] = a[i].w, pre[a[i].v] = a[i].u;
        for(int i = 1; i <= n; i++)
            if(in[i] == INT_MAX && i != root) return 0;
        int cnt = 0;
```

```
        for(int i = 1; i <= n; i++) f[i] = i, id[i] = 0;
        for(int i = 1; i <= n; i++)
        {
            if(i == root) continue;
            res += in[i];
            if(find(i) != find(pre[i])) f[f[i]] = f[pre[i]];
            else
            {
                cnt++;
                for(int j = i; j && !id[j]; j = pre[j])
                    id[j] = cnt;
            }
        }
        if(!cnt) break;
        for(int i = 1; i <= n; i++)
            if(!id[i]) id[i] = ++cnt;
        for(int i = 1; i <= m; i++)
        {
            if(id[a[i].u] != id[a[i].v]) a[i].w -= in[a[i].v];
            a[i].u = id[a[i].u];
            a[i].v = id[a[i].v];
        }
        n = cnt;
        root = id[root];
    }
    return res;
}
```

4.21 zkw 费用流

```
//稠密图、二分图中较快，稀疏图中不如SPFA
int flow, cost, price;

int dfs(int u, int f)
{
    if(u == t)
    {
        flow += f;
        cost += price * f;
        return f;
    }
    vst[u] = 1;
    int used = 0;
    for(int i = tail[u]; i; i = e[i].next)
        if(!vst[e[i].v] && e[i].c > 0 && e[i].w == 0)
        {
            int w = dfs(e[i].v, min(e[i].c, f - used));
            e[i].c -= w; e[i ^ 1].c += w; used += w;
            if(used == f) return f;
        }
    return used;
}
bool modlabel()
{
    int d = inf;
    for(int u = s; u <= t; u++)
        if(vst[u])
            for(int i = tail[u]; i; i = e[i].next)
                if(e[i].c > 0 && !vst[e[i].v]) d = min(d, e[i].w);
    if(d == inf) return 0;
    for(int u = s; u <= t; u++)
        if(vst[u])
            for(int i = tail[u]; i; i = e[i].next)
                e[i].w -= d, e[i ^ 1].w += d;
    price += d;
    return 1;
}
void zkw()
{
    do
        do memset(vst, 0, sizeof(vst));
        while(dfs(s, inf) > 0);
    while(modlabel());
}
```

5 数论

5.1 杜教筛

```
#define N 1000005 // (10^9)^(2/3)
#define M 3333331 // hash siz
int prime[N], notprime[N], pcnt, mu[N], pre[N];
int hash[M], nocnt; struct node{int id, f, next;}no[1000000];
int F(int n) // calculate mu[1]+mu[2]+...+mu[n]
{
    if(n<N) return pre[n];
    int h = n%M; for(int i = hash[h]; i; i = no[i].next) if(no[i].id == n) return no[i].f;
    int ret = 1;
    for(int i = 2, j; i <= n; i = j + 1)
    {
        j = n/(n/i);
        ret -= F(n/i) * (j-i+1);
    }
    no[++nocnt] = (node){n, ret, hash[h]};
    hash[h] = nocnt;
    return ret;
}
void init()
{
    mu[1] = 1;
```

```
    for(int i = 2; i < N; i++)
    {
        if(!notprime[i]) prime[++pcnt] = i, mu[i] = -1;
        for(int j = 1; j <= pcnt && prime[j] * i < N; j++)
        {
            notprime[prime[j] * i] = 1;
            if(i % prime[j]) mu[prime[j] * i] = -mu[i];
            else {mu[prime[j] * i] = 0; break;}
        }
    }
    for(int i = 1; i < N; i++) pre[i] = pre[i-1] + mu[i];
}

/*
    用之前必须先init()
    如果n很大，求和记得开long long
    如果有取模，求和记得改取模
*/
```

5.2 求逆元

```
void ex_gcd(long long a, long long b, long long &x, long long &y) {
    if (b == 0) {
        x = 1;
        y = 0;
        return;
    }
    long long xx, yy;
    ex_gcd(b, a % b, xx, yy);
    y = xx - a / b * yy;
    x = yy;
}

long long inv(long long x, long long MODN) {
    long long inv_x, y;
    ex_gcd(x, MODN, inv_x, y);
    return (inv_x % MODN + MODN) % MODN;
}
```

5.3 直线下整点

```
// $\sum_{i=0}^{n-1} \lfloor \frac{a+bi}{m}\rfloor$, $n,m,a,b>0$
LL solve(LL n,LL a,LL b,LL m){
    if(b==0) return n*(a/m);
    if(a>=m) return n*(a/m)+solve(n,a%m,b,m);
    if(b>=m) return (n-1)*n/2*(b/m)+solve(n,a,b%m,m);
    return solve((a+b*n)/m,(a+b*n)%m,m,b);
}
```

5.4 拉格朗日插值

```
#define MOD 1000000007
int inv[N], invf[N], f[N];
int fpow(int a, int b)
{
    int r = 1;
    for(; b; b >>= 1)
    {
        if(b & 1) r = 1ll*r*a%MOD;
        a = 1ll*a*a%MOD;
    }
    return r;
}
int la(int x, int k) // k次，求f(x)
{
    int lim = k+2, ff = 1;
    for(int i = 1; i <= lim; i++)
        ff = 1ll * ff * (x-i) % MOD;
    for(int i = 1; i <= lim; i++)
        f[i] = (f[i-1] + fpow(i, k)) % MOD; // 预处理 f(1),f(2),...,f(lim)，注意修改
    if(x <= lim) return f[x];
    int ret = 0;
    for(int i = 1; i <= lim; i++)
    {
        (ret += 1ll * f[i]
                * ff % MOD * (x-i < N ? inv[x-i] : fpow(x-i, MOD-2)) % MOD // 复杂度
                * invf[i-1] % MOD * invf[lim-i] % MOD * ((lim-i) % 2 ? MOD-1 : 1) % MOD
        ) %= MOD;
    }
    return ret;
}
void init()
{
    inv[1] = 1;
    for(int i = 2; i < N; i++) inv[i] = 1ll * (MOD - MOD / i) * inv[MOD % i] % MOD;
    invf[0] = 1;
    for(int i = 1; i < N; i++) invf[i] = 1ll * invf[i-1] * inv[i] % MOD;
}
/*
    用之前必须先init()
    如果所有的逆元都能预处理就是O(n)的，否则是O(nlogn)的
*/
```

5.5 线性回归

```
// O(m^2logn)
// Given a[0], a[1], ..., a[m - 1]
// a[n] = c[0] * a[n - m] + ... + c[m - 1] * a[n - 1]
```

```
// Solve for a[n] = v[0] * a[0] + v[1] * a[1] + ... + v[m - 1] * a[m - 1]

void linear_recurrence(long long n, int m, int a[], int c[], int p) {
    long long v[M] = {1 % p}, u[M << 1], msk = !!n;
    for(long long i(n); i > 1; i >>= 1) {
        msk <<= 1;
    }
    for(long long x(0); msk; msk >>= 1, x <<= 1) {
        fill_n(u, m << 1, 0);
        int b(!!(n & msk));
        x |= b;
        if(x < m) {
            u[x] = 1 % p;
        }else {
            for(int i(0); i < m; i++) {
                for(int j(0), t(i + b); j < m; j++, t++) {
                    u[t] = (u[t] + v[i] * v[j]) % p;
                }
            }
            for(int i((m << 1) - 1); i >= m; i--) {
                for(int j(0), t(i - m); j < m; j++, t++) {
                    u[t] = (u[t] + c[j] * u[i]) % p;
                }
            }
        }
        copy(u, u + m, v);
    }
    //a[n] = v[0] * a[0] + v[1] * a[1] + ... + v[m - 1] * a[m - 1].
    for(int i(m); i < 2 * m; i++) {
        a[i] = 0;
        for(int j(0); j < m; j++) {
            a[i] = (a[i] + (long long)c[j] * a[i + j - m]) % p;
        }
    }
    for(int j(0); j < m; j++) {
        b[j] = 0;
        for(int i(0); i < m; i++) {
            b[j] = (b[j] + v[i] * a[i + j]) % p;
        }
    }
    for(int j(0); j < m; j++) {
        a[j] = b[j];
    }
}
```

5.6 素数测试-gwx

```
ll multi(ll x, ll y, ll M) {
    ll res = 0;
    for(; y; y >>= 1, x = (x + x) % M)
        if(y & 1) res = (res + x) % M;
    return res;
}
ll power(ll x, ll y, ll p)
{
    ll res = 1;
    for(; y; y >>= 1, x = multi(x, x, p))
        if(y & 1) res = multi(res, x, p);
    return res;
}
int primetest(ll n, int base)
{
    ll n2 = n - 1, res;
    int s = 0;
    while(!(n2 & 1)) n2 >>= 1, s++;
    res = power(base, n2, n);
    if(res == 1 || res == n - 1) return 1;
    s--;
    while(s >= 0)
    {
        res = multi(res, res, n);
        if(res == n - 1) return 1;
        s--;
    }
    return 0;   // n is not a strong pseudo prime
}
int isprime(ll n)
{
    static ll testNum[] = {2, 3, 5, 7, 11, 13, 17, 19, 23, 29, 31, 37};
    static ll lim[] = {4, 0, 137363511, 2532600111, 250000000001l, 215230289874711, 347474966038311,
        3415500717283211l, 0, 0, 0, 0};
    if(n < 2 || n == 32150317511l) return 0;
    for(int i = 0; i < 12; i++)
    {
        if(n < lim[i]) return 1;
        if(!primetest(n, testNum[i])) return 0;
    }
    return 1;
}
ll pollard(ll n)
{
    ll i, x, y, p;
    if(isprime(n)) return n;
    if(!(n & 1)) return 2;
    for(i = 1; i < 20; i++)
    {
        x = i, y = func(x, n), p = gcd(y - x, n);
        while(p == 1)
        {
            x = func(x, n);
            y = func(func(y, n), n);
```

```
            p = gcd((y - x + n) % n, n) % n;
        }
        if(p == 0 || p == n) continue;
        return p;
    }
}
```

5.7 原根-gwx

```
bool check_force(int g, int p)
{
    int cnt = 0, prod = g;
    for(int i = 1; i <= p - 1; ++i, prod = prod * g % p)
        if(prod == 1)
            if(++cnt > 1) return 0;
    return 1;
}

//d[]: prime divisor of (p - 1)
bool check_fast(int g, int p)
{
    for(int i = 1; i <= m; ++i)
        if(power(g, (p - 1) / d[i], p) == 1)
            return 0;
    return 1;
}

int primitive_root(int p)
{
    for(int i = 2; i < p; ++i)
        if(check(i, p)) return i;
}
```

5.8 勾股数

```
a=m^2-n^2, b=2mn, c=m^2+n^2
其中m和n中有一个是偶数, 则(a, b, c)是素勾股数
```

6 字符串

6.1 AC 自动机-gwx

```
void add(int now)
{
    int k = 0;
    for(int i = 1; i <= n; i++)
    {
        int c = s[i] - 'A';
        if(!ch[k][c])
            ch[k][c] = ++cnt;
        k = ch[k][c];
    }
    ed[k] = 1;      //或vector全部记录
    id[now] = k;
}

void build()
{
    q.push(0);
    while(!q.empty())
    {
        int u = q.front(), v;
        q.pop();
        for(int i = 0; i < m; i++)
            if(v = ch[u][i])
            {
                int k = pa[u];
                while(k && !ch[k][i])
                    k = pa[k];
                if(u)
                    pa[v] = ch[k][i];
                q.push(v);
            }
            else
                ch[u][i] = ch[pa[u]][i];
    }
}
```

6.2 AC 自动机-wrz

```
struct ACAM
{
    ACAM *next[S], *fail;
    int ban;
}mem[N], *tot, *null, *root, *q[N];
ACAM *newACAM()
{
    ACAM *p = ++tot;
    *p = *null; return p;
}
void init()
{
    null = tot = mem;
    for(int i = 0; i < alpha; i++) null->next[i] = null;
    null->fail = null; null->ban = 0;
    root = newACAM();
}
void inser(char *s)
{
```

```
    ACAM *p = root;
    for(int i = 0; s[i]; i++)
    {
        int w = s[i] - 'a';
        if(p->next[w] == null) p->next[w] = newACAM();
        p = p->next[w];
    }
    p->ban = 1;
}
void build()
{
    root->fail = root; int head = 0, tail = 0;
    for(int i = 0; i < alpha; i++)
    {
        if(root->next[i] == null) root->next[i] = root;
        else root->next[i]->fail = root, q[tail++] = root->next[i];
    }
    for(; head < tail; head++)
    {
        ACAM *p = q[head];
        p->ban |= p->fail->ban;
        for(int i = 0; i < alpha; i++)
        {
            if(p->next[i] == null) p->next[i] = p->fail->next[i];
            else p->next[i]->fail = p->fail->next[i], q[tail++] = p->next[i];
        }
    }
}
```

6.3 exKMP-gwx

```
void get_next()
{
    int a = 0, p = 0;
    nxt[0] = m;
    for(int i = 1; i < m; i++)
    {
        if(i >= p || i + nxt[i - a] >= p)
        {
            if(i >= p)  p = i;
            while(p < m && t[p] == t[p - i]) p++;
            nxt[i] = p - i;
            a = i;
        }
        else nxt[i] = nxt[i - a];
    }
}

void exkmp()
{
    int a = 0, p = 0;
    get_next();
    for(int i = 0; i < n; i++)
    {
        if(i >= p || i + nxt[i - a] >= p) // i >= p 的作用：举个典型例子，s 和 t 无一字符相同
        {
            if(i >= p) p = i;
            while(p < n && p - i < m && s[p] == t[p - i]) p++;
            ext[i] = p - i;
            a = i;
        }
        else ext[i] = nxt[i - a];
    }
}
```

6.4 最小表示-wrz

```
int min_represent(char *s, int len) // 当s不是字符串时应该将char改成int等，len是s的长度，下标从0开始到n-1结束
{
    int i = 0, j = 1;
    for(; i < len && j < len; )
    {
        int k = 0;
        for(; s[(i+k)%len] == s[(j+k)%len] && k < len; k++);
        if(k == len) break;
        if(s[(i+k)%len] > s[(j+k)%len])
        {
            i += k+1;
            if(i <= j) i = j + 1;
        }
        else
        {
            j += k+1;
            if(j <= i) j = i + 1;
        }
    }
    return i < j ? i : j;
}
```

6.5 最小表示-gwx

```
//不保证起始位置最靠前(?)
string find(int N, string s) {
    int i, j, k, l;
    for (i = 0, j = 1; j < N; ) {
        for (k = 0; k < N && s[i + k] == s[j + k]; k++);
        if (k >= N) break;
        if (s[i + k] > s[j + k]) j += k + 1;
        else l = i + k, i = j, j = max(l, j) + 1;
```

```
    }
    return s.substr(i, N);
}
```

6.6 马拉车-gwx

```
//maxn = 2 * n
void manacher(int n)
{
    int p = 0, r = 0;
    for(int i = 1; i <= n; i++)
    {
        if(i <= r) len[i] = min(len[2 * p - i], r - i + 1);
        else len[i] = 1;
        while(b[i + len[i]] == b[i - len[i]]) len[i]++;
        if(i + len[i] - 1 >= r)
            r = i + len[i] - 1, p = i;
    }
}

int main()
{
    scanf("%d\n%s", &n, a + 1);
    b[++tot] = '@'; b[++tot] = '#';
    for(int i = 1; i < n; i++)
        b[++tot] = a[i], b[++tot] = '#';
    b[++tot] = a[n];
    b[++tot] = '#'; b[++tot] = '$';
    manacher(tot);
}
```

6.7 回文树-wrz

```
char s[N], out[N];
struct PT
{
    PT *fail, *next[A];
    int len;
}mem[N], *tot, *null, *root1, *root0, *last;
PT *newPT()
{
    PT *p = ++tot;
    *p = *null; return p;
}
void init()
{
    null = tot = mem;
    null->fail = null;
    for(int i = 0; i < A; i++) null->next[i] = null;
    null->len = 0;
    root1 = newPT(); root1->fail = root1; root1->len = -1;
    root0 = newPT(); root0->fail = root1; last = root1;
}
int extend(int c, int i) // 返回这一次是否多了一个回文子串
{
    PT *p = last;
    for(; s[i-p->len-1] != c+'a'; p = p->fail);
    if(p->next[c] != null) {last = p->next[c]; return 0;}
    PT *np = p->next[c] = last = newPT(); np->len = p->len + 2;
    if(p->len == -1) np->fail = root0;
    else
    {
        for(p=p->fail; s[i-p->len-1] != c+'a'; p = p->fail);
        np->fail = p->next[c];
    }
    return 1;
}
void main()
{
    scanf("%s",s+1); init();
    for(int i = 1, ii = strlen(s+1); i <= ii; i++)
        out[i] = extend(s[i]-'a', i)?'1':'0';
    puts(out+1);
}
```

6.8 后缀数组-gwx

```
//sa[i]: 排第i的串的开头位置  rank[i]:开头位置为i的串的排名
//maxn = 2 ^ k

void trans(int*s1, int*s2, int*r1, int*r2)
{
    for(int i = 1; i <= n; i++)
        v[r1[s1[i]]] = i;
    for(int i = n; i >= 1; i--)
        if(s1[i] > k)
            s2[v[r1[s1[i] - k]]--] = s1[i] - k;
    for(int i = n - k + 1; i <= n; i++)
        s2[v[r1[i]]--] = i;
    for(int i = 1; i <= n; i++)
        r2[s2[i]] = r2[s2[i - 1]] + (r1[s2[i]] != r1[s2[i - 1]] || r1[s2[i] + k] != r1[s2[i - 1] + k]);
}

int lcp(int s, int t)
{
    s = rank[p][s], t = rank[p][t];
    if(s > t) swap(s, t);
    s++;
    int k = Log[t - s + 1];
```

```
    return min(f[s][k], f[t + 1 - (1 << k)][k]);
}

void work()
{
    for(int k = 0; k <= maxk; k++)
        for(int i = 1 << k; i < (1 << k + 1) && i <= n; i++)
            Log[i] = k;
    int p = 0, q = 1;
    for(int i = 1; i <= n; i++)
        v[a[i]]++;
    for(int i = 1; i <= S; i++)  //S:alphabet_size
        v[i] += v[i - 1];
    for(int i = 1; i <= n; i++)
        sa[p][v[a[i]]--] = i;
    for(int i = 1; i <= n; i++)
        rank[p][sa[p][i]] = rank[p][sa[p][i - 1]] + (a[sa[p][i]] != a[sa[p][i - 1]]);
    k = 1;
    while(k < n)
    {
        trans(sa[p], sa[q], rank[p], rank[q]);
        p ^= 1, q ^= 1;
        k <<= 1;
    }
    for(int i = 1; i <= n; i++)
    {
        h[i] = max(h[i - 1] - 1, 0);
        int j = sa[p][rank[p][i] - 1];
        while(a[i + h[i]] == a[j + h[i]])
            h[i]++;
    }
    for(int i = 2; i <= n; i++)
        f[i][0] = h[i];
    for(int k = 1; k <= maxk; i++)
        for(int i = 2; i + (1 << k) - 1 <= n; i++)
            f[i][k] = min(f[i][k - 1], f[i + (1 << k - 1)][k - 1]);
}
```

6.9 后缀数组-wrz

```
// 对都是数字的数组做SA时要保证数组中没有0，否则height等可能由于s[0]=s[n+1]=0出问题
// 多次使用要保证s[0]=s[n+1]=0
char s[N];
int n, t1[N], t2[N], sa[N], rank[N], sum[N], height[N], lef, rig; // 数组开两倍
void SA_build()
{
    int *x = t1, *y = t2, m = 30;
    for(int i = 1; i <= n; i++) sum[x[i] = s[i] - 'a' + 1]++;
    for(int i = 1; i <= m; i++) sum[i] += sum[i-1];
    for(int i = n; i >= 1; i--) sa[sum[x[i]]--] = i;
    for(int k = 1; k <= n; k <<= 1)
    {
        int p = 0;
        for(int i = n-k+1; i <= n; i++) y[++p] = i;
        for(int i = 1; i <= n; i++) if(sa[i] - k > 0) y[++p] = sa[i] - k;

        for(int i = 1; i <= m; i++) sum[i] = 0;
        for(int i = 1; i <= n; i++) sum[x[i]]++;
        for(int i = 1; i <= m; i++) sum[i] += sum[i-1];
        for(int i = n; i >= 1; i--) sa[sum[x[y[i]]]--] = y[i];

        swap(x, y);
        for(int i = 1; i <= n; i++)
            x[sa[i]] = x[sa[i-1]] + (y[sa[i]] == y[sa[i-1]] && y[sa[i]+k] == y[sa[i-1]+k] ? 0 : 1);
        m = x[sa[n]];
        if(m == n) break;
    }
    for(int i = 1; i <= n; i++) rank[sa[i]] = i;
    for(int i = 1, k = 0; i <= n; height[rank[i++]] = k?k--:k)
        for(; s[i+k] == s[sa[ran[i]-1]+k] && i+k <= n && sa[ran[i]-1]+k <= n; k++);
}
```

6.10 后缀数组 SAIS

```
// string is 0-based
// sa[] is 1-based
// s[n] < s[i] i = 0...n-1
namespace SA {
    int sa[MAXN], rk[MAXN], ht[MAXN], s[MAXN << 1], t[MAX << 1], p[MAXN], cnt[MAXN], cur[MAXN];
#define pushS(x) sa[cur[s[x]]--] = x
#define pushL(x) sa[cur[s[x]]++] = x
#define inducedSort(v) std::fill_n(sa, n, -1); std::fill_n(cnt, m, 0);\
    for (int i = 0; i < n; i++) cnt[s[i]]++;\
    for (int i = 1; i < m; i++) cnt[i] += cnt[i-1];\
    for (int i = 0; i < m; i++) cur[i] = cnt[i]-1;\
    for (int i = n1-1; ~i; i--) pushS(v[i]);\
    for (int i = 1; i < m; i++) cur[i] = cnt[i-1];\
    for (int i = 0; i < n; i++) if (sa[i] > 0 &&  t[sa[i]-1]) pushL(sa[i]-1);\
    for (int i = 0; i < m; i++) cur[i] = cnt[i]-1;\
    for (int i = n-1;  ~i; i--) if (sa[i] > 0 && !t[sa[i]-1]) pushS(sa[i]-1)
    void sais(int n, int m, int *s, int *t, int *p) {
        int n1 = t[n-1] = 0, ch = rk[0] = -1, *s1 = s+n;
        for (int i = n-2; ~i; i--) t[i] = s[i] == s[i+1] ? t[i+1] : s[i] > s[i+1];
        for (int i = 1; i < n; i++) rk[i] = t[i-1] && !t[i] ? (p[n1] = i, n1++) : -1;
        inducedSort(p);
        for (int i = 0, x, y; i < n; i++) if (~(x = rk[sa[i]])) {
            if (ch < 1 || p[x+1] - p[x] != p[y+1] - p[y]) ch++;
            else for (int j = p[x], k = p[y]; j <= p[x+1]; j++, k++)
                if ((s[j]<<1|t[j]) != (s[k]<<1|t[k])) {ch++; break;}
            s1[y = x] = ch; }
```

```
        if (ch+1 < n1) sais(n1, ch+1, s1, t+n, p+n1);
        else for (int i = 0; i < n1; i++) sa[s1[i]] = i;
        for (int i = 0; i < n1; i++) s1[i] = p[sa[i]];
        inducedSort(s1); }
    int mapCharToInt(int n, const T *str) {
        int m = *std::max_element(str, str+n);
        std::fill_n(rk, m+1, 0);
        for (int i = 0; i < n; i++) rk[str[i]] = 1;
        for (int i = 0; i < m; i++) rk[i+1] += rk[i];
        for (int i = 0; i < n; i++) s[i] = rk[str[i]] - 1;
        return rk[m]; }
    void suffixArray(int n, const T *str) {
        int m = mapCharToInt(++n, str);
        sais(n, m, s, t, p);
        for (int i = 0; i < n; i++) rk[sa[i]] = i;
        for (int i = 0, h = ht[0] = 0; i < n-1; i++) {
            int j = sa[rk[i]-1];
            while (i+h < n && j+h < n && s[i+h] == s[j+h]) h++;
            if (ht[rk[i]] = h) h--; } } };
```

6.11 后缀自动机-gwx

```
int root = 1, cnt = 1, last = 1;
int pa[maxn], l[maxn], ch[maxn][maxs];

void add(int c) //c : 0 ~ alpha_size
{
    int np = ++cnt, p = last; last = cnt;
    l[np] = x; r[np] = 1;
    while(p && !ch[p][c])
        ch[p][c] = np, p = pa[p];
    if(!p)
    {
        pa[np] = root;
        return;
    }
    int q = ch[p][c];
    if(l[q] == l[p] + 1)
        pa[np] = q;
    else
    {
        int nq = ++cnt;
        l[nq] = l[p] + 1;
        pa[nq] = pa[q];
        pa[q] = pa[np] = nq;
        memcpy(ch[nq], ch[q], sizeof(ch[q]));
        while(p && ch[p][c] == q)
            ch[p][c] = nq, p = pa[p];
    }
}

void get_right()
{
    for(int i = 1; i <= n; i++) add(i);
    for(int i = 1; i <= cnt; i++) v[l[i]]++;
    for(int i = 1; i <= n; i++) v[i] += v[i - 1];
    for(int i = cnt; i; i--) t[v[l[i]]--] = i;
    for(int i = cnt; i; i--) if(pa[t[i]]) r[pa[t[i]]] += r[t[i]];
    r[1] = 0;
}
```

6.12 后缀自动机-wrz

```
struct SAM
{
    SAM *next[A], *fail;
    int len, mi, mx;
}mem[N], *tot, *null, *root, *last, *q[N];
SAM *newSAM(int len)
{
    SAM *p = ++tot;
    *p = *null;
    p->len = p->mi = len;
    p->mx = 0;
    return p;
}
void init()
{
    null = tot = mem;
    for(int i = 0; i < A; i++) null->next[i] = null;
    null->fail = null;
    null->len = null->mi = null->mx = 0;
    root = last = newSAM(0);
}
void extend(int v)
{
    SAM *p = last, *np = newSAM(p->len + 1); last = np;
    for(; p->next[v] == null && p != null; p = p->fail) p->next[v] = np;
    if(p==null) np->fail = root;
    else
    {
        SAM *q = p->next[v];
        if(q->len == p->len+1) np->fail = q;
        else
        {
            SAM *nq = newSAM(p->len+1);
            memcpy(nq->next, q->next, sizeof(nq->next));
            nq->fail = q->fail;
            q->fail = np->fail = nq;
            for(; p->next[v] == q && p != null; p = p->fail) p->next[v] = nq;
        }
```

```
    }
}
```

6.13 ex 后缀自动机-wrz

```
struct sam
{
    sam *fail, *next[A];
    int len;
}mem[N<<1], *tot, *null, *root;
sam* newsam()
{
    *++tot = *null;
    return tot;
}
void init()
{
    null = tot = mem; null->fail = null; null->len = 0;
    for(int i = 0; i < A; i++) null->next[i] = null;
    root = newsam();
}
sam* extend(sam *p, int v)
{
    if(p->next[v] != null)
    {
        sam *q = p->next[v];
        if(p->len + 1 == q->len) return q;
        else
        {
            sam *nq = newsam(); *nq = *q; nq->len = p->len + 1;
            q->fail = nq;
            for(; p->next[v] == q && p != null; p = p->fail) p->next[v] = nq;
            return nq;
        }
    }
    else
    {
        sam *np = newsam(); np->len = p->len + 1;
        for(; p->next[v] == null && p != null; p = p->fail) p->next[v] = np;
        if(p == null) np->fail = root;
        else
        {
            sam *q = p->next[v];
            if(p->len + 1 == q->len) np->fail = q;
            else
            {
                sam *nq = newsam(); *nq = *q; nq->len = p->len + 1;
                np->fail = q->fail = nq;
                for(; p->next[v] == q && p != null; p = p->fail) p->next[v] = nq;
            }
        }
        return np;
    }
}
void build_tree()
{
    for(sam *i = tot; i != mem; i--)
        addedge(i->fail - mem, i - mem);
}
```

7 其他

7.1 蔡勒公式

```
int zeller(int y,int m,int d) {
    if (m<=2) y--,m+=12; int c=y/100; y%=100;
    int w=((c>>2)-(c<<1)+y+(y>>2)+(13*(m+1)/5)+d-1)%7;
    if (w<0) w+=7; return(w);
}
```

7.2 dancing-links

```
struct Node {
    Node *l, *r, *u, *d, *col;
    int size, line_no;
    Node() {
        size = 0; line_no = -1;
        l = r = u = d = col = NULL;
    }
} *root;

void cover(Node *c) {
    c->l->r = c->r; c->r->l = c->l;
    for (Node *u = c->d; u != c; u = u->d)
        for (Node *v = u->r; v != u; v = v->r) {
            v->d->u = v->u;
            v->u->d = v->d;
            -- v->col->size;
        }
}

void uncover(Node *c) {
    for (Node *u = c->u; u != c; u = u->u) {
        for (Node *v = u->l; v != u; v = v->l) {
            ++ v->col->size;
            v->u->d = v;
            v->d->u = v;
        }
    }
    c->l->r = c; c->r->l = c;
```

```
}

std::vector<int> answer;
bool search(int k) {
    if (root->r == root) return true;
    Node *r = NULL;
    for (Node *u = root->r; u != root; u = u->r)
        if (r == NULL || u->size < r->size)
            r = u;
    if (r == NULL || r->size == 0) return false;
    else {
        cover(r);
        bool succ = false;
        for (Node *u = r->d; u != r && !succ; u = u->d) {
            answer.push_back(u->line_no);
            for (Node *v = u->r; v != u; v = v->r)  // Cover row
                cover(v->col);
            succ |= search(k + 1);
            for (Node *v = u->l; v != u; v = v->l)
                uncover(v->col);
            if (!succ) answer.pop_back();
        }
        uncover(r);
        return succ;
    }
}

bool entry[CR][CC];
Node *who[CR][CC];
int cr, cc;

void construct() {
    root = new Node();
    Node *last = root;
    for (int i = 0; i < cc; ++ i) {
        Node *u = new Node();
        last->r = u; u->l = last;
        Node *v = u; u->line_no = i;
        last = u;
        for (int j = 0; j < cr; ++ j)
            if (entry[j][i]) {
                ++ u->size;
                Node *cur = new Node();
                who[j][i] = cur;
                cur->line_no = j;
                cur->col = u;
                cur->u = v; v->d = cur;
                v = cur;
            }
        v->d = u; u->u = v;
    }
    last->r = root; root->l = last;
    for (int j = 0; j < cr; ++ j) {
        Node *last = NULL;
        for (int i = cc - 1; i >= 0; -- i)
            if (entry[j][i]) {
                last = who[j][i];
                break;
            }
        for (int i = 0; i < cc; ++ i)
            if (entry[j][i]) {
                last->r = who[j][i];
                who[j][i]->l = last;
                last = who[j][i];
            }
    }
}

void destruct() {
    for (Node *u = root->r; u != root; ) {
        for (Node *v = u->d; v != u; ) {
            Node *nxt = v->d;
            delete(v);
            v = nxt;
        }
        Node *nxt = u->r;
        delete(u); u = nxt;
    }
    delete root;
}
```

7.3 枚举子集

```
for (int x = 1; x <= n; x++)
    for (int y  = x & (x - 1); y; (--y) &= x) {
        //y is a subset of x
    }
```

7.4 梅森旋转

```
#include <random>

int main() {
    std::mt19937 g(seed);  // std::mt19937_64
    std::cout << g() << std::endl;
}
```

7.5 乘法取模

```
// 需要保证 x 和 y 非负
```

```cpp
long long mult(long long x, long long y, long long MODN) {
    long long t = (x * y - (long long)((long double)x / MODN * y + 1e-3) * MODN) % MODN;
    return t < 0 ? t + MODN : t;
}
```

8 提示

8.1 make 支持 c++11

```
export CXXFLAGS='-std=c++11 -Wall'
source .bashrc
```

8.2 Java

```
import java.util.*;
import java.math.*;
public class javaNote
{
    static BigInteger q[] = new BigInteger[5000000]; // 定义数组的正确姿势，记得分配内存

    public static void main(String[] args)
    {

        long currentTime = System.currentTimeMillis(); // 获取时间，单位是ms

        Scanner sc = new Scanner(System.in); // 定义输入
        int a = sc.nextInt(), b;
        System.out.println("integer = " + a); // 输出

        BigInteger x = new BigInteger("233"), y = new BigInteger("666");
        BigInteger.valueOf(1); // 将指定的表达式转化成BigInteger类型
        x.add(y); //x+y
        x.subtract(y); //x-y
        x.multiply(y); //x*y
        x.divide(y);

        x.pow(233); // x**233
        x.compareTo(y); // 比较x和y，x < y : -1，x = y : 0，x > y : 1

        BigDecimal n = new BigDecimal("233"), m = new BigDecimal("666");
        n.divide(m,a,RoundingMode.DOWN); //n/m并精确到小数点后第a位，a=0表示精确到个位，a为负数表示精确到小数点前-a+1位，可能变成科学计数法
        /*
            取整方式
            RoundingMode.CEILING：取右边最近的整数，即向正无穷取整
            RoundingMode.FLOOR：取左边最近的整数，即向负无穷取整
            RoundingMode.DOWN：向0取整
            RoundingMode.UP：远离0取整
            RoundingMode.HALF_UP:上取整的四舍五入，>=0.5会进位，<0.5会舍去，负数会先取绝对值再四舍五入再变回负数
            RoundingMode.HALF_DOWN:下取整的四舍五入，>0.5会进位，<=0.5会舍去，负数原理同上
            RoundingMode.HALF_EVEN:分奇偶的四舍五入，>0.5会进位，<0.5会舍去，=0.5会向最近的偶数取整，如2.5->2，(-2.5)->(-2)
        */

        Math.max(a, b);//取大
        Math.min(a, b);//取小
        Math.PI;//pi

        HashSet<BigInteger> hash = new HashSet<BigInteger>(); // hash table
        hash.contains(x); // hash table中是否有a，有则返回true，反之返回false
        hash.add(x); // 把x加进hash table
        hash.remove(x); // 从hash table中删去x

        Arrays.sort(arr, 1, n+1); // arr 是需要排序的数组，后两个参数分别是排序的起始位置和结束位置+1，还可以有第四个参数是比较函数
        // Arrays.sort(arr, a, b, cmp) = sort(arr+a, arr+b, cmp)

    }
}
```

8.3 cout 输出小数

```
std::cout << std::fixed << std::setprecision(5);
```

8.4 释放容器内存

```
template <typename T>
__inline void clear(T& container) {
    container.clear();  // 或者删除了一堆元素
    T(container).swap(container);
}
```

8.5 tuple

```
mytuple = std::make_tuple (10, 2.6, 'a');           // packing values into tuple
std::tie (myint, std::ignore, mychar) = mytuple;    // unpacking tuple into variables
std::get<I>(mytuple) = 20;
std::cout << std::get<I>(mytuple) << std::endl;     // get the Ith(const) element
```

8.6 读入优化

```
// getchar()读入优化 << 关同步cin << 此优化
// 用isdigit()会小幅变慢
// 返回 false 表示读到文件尾
namespace Reader {
```

```
    const int L = (1 << 15) + 5;
    char buffer[L], *S, *T;
    __inline bool getchar(char &ch) {
        if (S == T) {
            T = (S = buffer) + fread(buffer, 1, L, stdin);
            if (S == T) {
                ch = EOF;
                return false;
            }
        }
        ch = *S++;
        return true;
    }
    __inline bool getint(int &x) {
        char ch; bool neg = 0;
        for (; getchar(ch) && (ch < '0' || ch > '9'); ) neg ^= ch == '-';
        if (ch == EOF) return false;
        x = ch - '0';
        for (; getchar(ch), ch >= '0' && ch <= '9'; )
            x = x * 10 + ch - '0';
        if (neg) x = -x;
        return true;
    }
}
```

9 附录-数学公式