Games

Outline



- Games as search
- Optimal decisions in games
 - minimax decisions
 - α - β pruning
- Real-time decisions

Why study games?



- Examples: chess, checkers, Go, backgammon, bridge
- Why study games?
 - · Fun; historically entertaining
 - Interesting subject of study because they are hard
 - Easy to represent and agents restricted to small number of actions
- Games are to AI as grand prix racing is to automobile design.

3

Games vs. Search



- Games are a form of *multi-agent environment*
 - What other agents do affect our success
- Competitive multi-agent environments give rise to adversarial search
- Solution is strategy (specifying a move for every possible opponent reply)

Types of Games



- Games of deterministic, perfect information: chess, checkers
- Stochastic games: backgammon
- Partially observable games: bridge, poker

5

Game setup



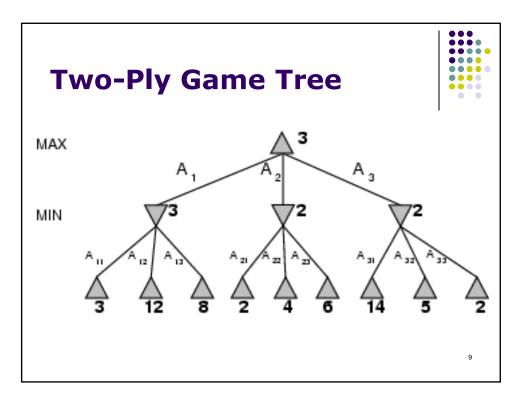
- Two players: MAX and MIN
- MAX moves first and they take turns until the game is over.
- Winner is awarded points (payoff), loser gets penalties.
- Zero-sum game: payoff values at the end of the game are equal and opposite (or the total payoff to all players is the same for every instance of the game)

Game setup



- Games as search:
 - Initial state: e.g. board configuration of chess
 - PLAYER(s): which player has the move in a state
 - Actions and transition model (or successor function): list of (move, state) pairs specifying legal moves.
 - Terminal test: Is the game finished (in terminal states)?
 - Utility function or payoff function UTILITY(s,p): Gives numerical value for terminal states. E.g. win (+1), loss (-1), and draw (0) in tic-tac-toe
- The initial state and the legal moves define the game tree

7



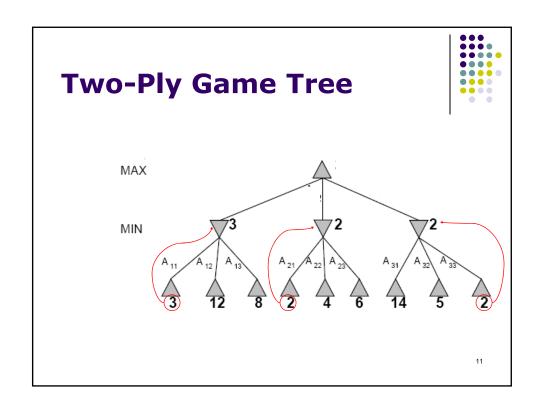
Optimal strategies

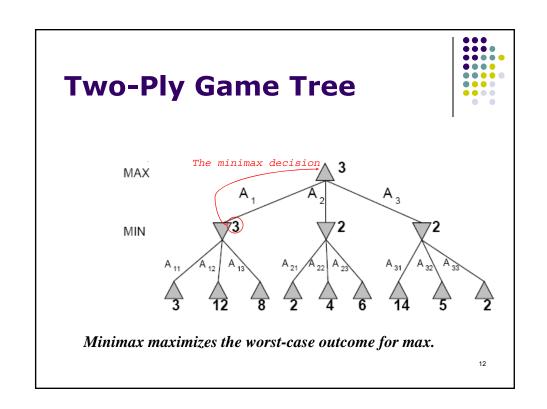


- Find the contingent strategy for MAX assuming an infallible MIN opponent.
- Assumption: Both players play optimally !!
- Given a game tree, the optimal strategy can be determined by using the minimax value of each node:

```
\begin{array}{ll} {\sf MINIMAX-VALUE}(n) = & \\ {\sf UTILITY}(n) & {\sf If} \ n \ {\sf is} \ {\sf a} \ {\sf terminal} \\ {\sf max}_{s \ \in \ successors(n)} \ {\sf MINIMAX-VALUE}(s) & {\sf If} \ n \ {\sf is} \ {\sf a} \ {\sf max} \ {\sf node} \\ {\sf min}_{s \ \in \ successors(n)} \ {\sf MINIMAX-VALUE}(s) & {\sf If} \ n \ {\sf is} \ {\sf a} \ {\sf min} \ {\sf node} \end{array}
```

Idea: choose move to position with highest minimax value
 best achievable payoff against best play





Minimax Algorithm



function MINIMAX-DECISION(state) returns an action inputs: state, current state in game return argmax ain ACTIONS(state) MIN-VALUE(RESULT(state,a))

function MAX-VALUE(state) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) $v \leftarrow -\infty$ for each a in ACTIONS(state) do $v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{RESULT}(state, a)))$

function MIN-VALUE(state) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) $v \leftarrow \infty$ for each a in ACTIONS(state) do

for each a in ACTIONS(state) do $v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{RESULT}(state, a)))$ return v

13

Properties of minimax



- Complete? Yes (if tree is finite)
- Optimal? Yes, against an optimal opponent, otherwise?
- <u>Time complexity?</u> O(b^m)

return v

- Space complexity? O(bm) (depth-first exploration)
- For chess, b ≈ 35, m ≈100 for "reasonable" games
 → exact solution completely infeasible

What if MIN does not play optimally?



- Definition of optimal play for MAX assumes MIN plays optimally: maximizes worst-case outcome for MAX.
- But if MIN does not play optimally, MAX will do even better.
- There may be better strategies against suboptimal opponents, but they do worse against optimal opponents

15

Improving minimax search



- Number of states is exponential to the number of moves.
 - Solution: Do not examine every node
 - ==> Alpha-beta pruning
 - Remove branches that do not influence final decision
 - (Related algorithm: DFBnB)

Diversion: Depth-First Branch & Bound (DFBnB)



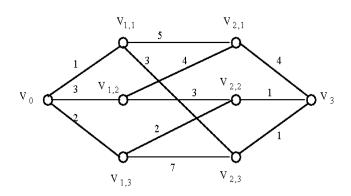
- Want to find the optimal solution among many solutions (or solving an optimization problem)
- DF search
- Keep track of best solution so far
- If f(n) = g(n)+h(n) ≥ cost(best-soln)
 - Then prune n

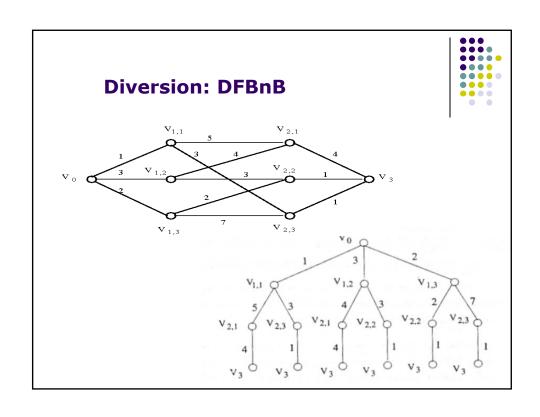
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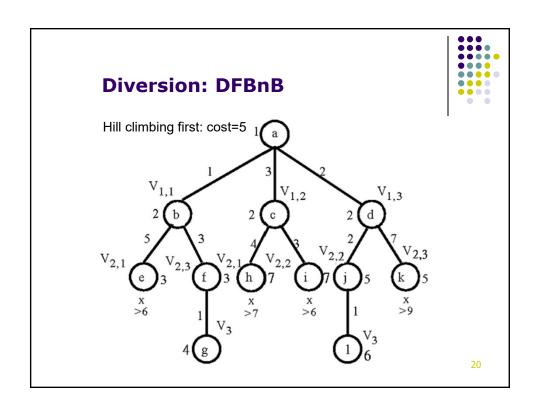
Diversion: DFBnB

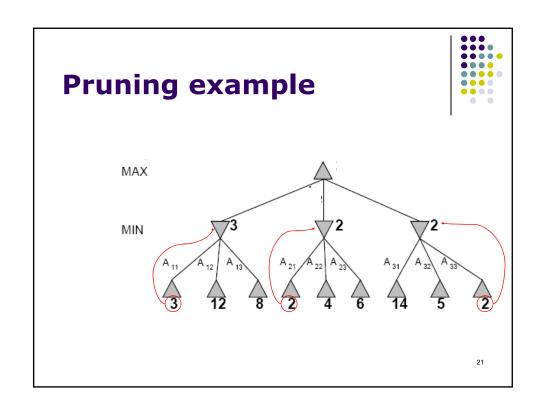


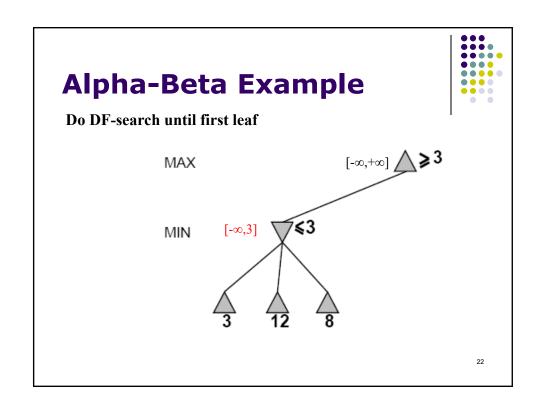
Find the shortest path from V_0 to V_3

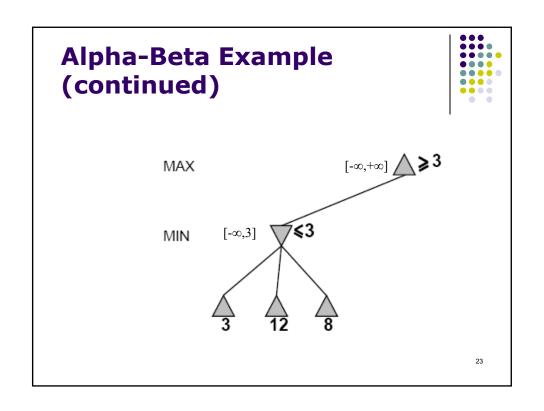


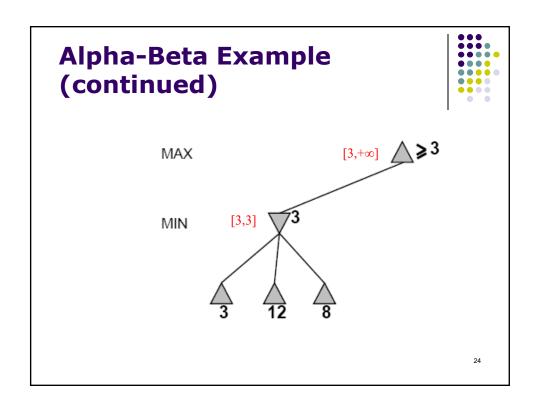


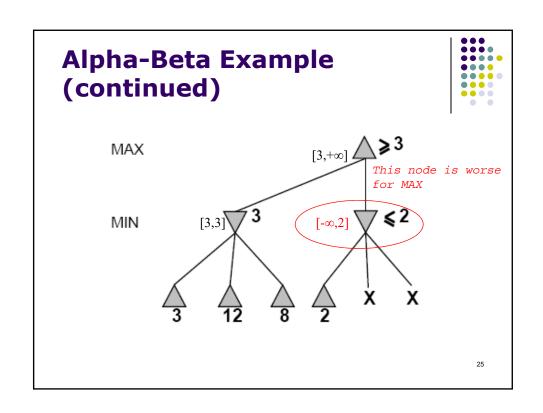


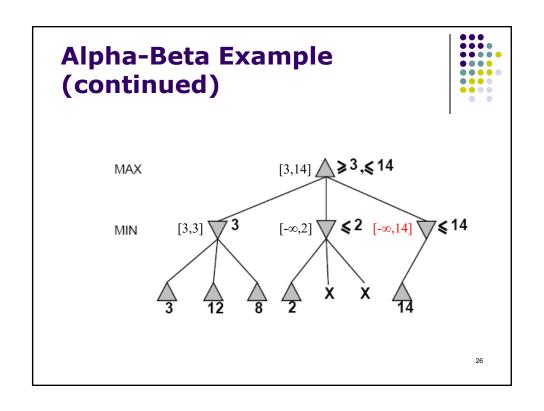


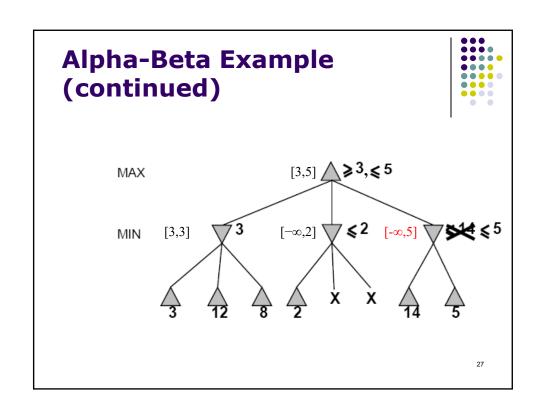


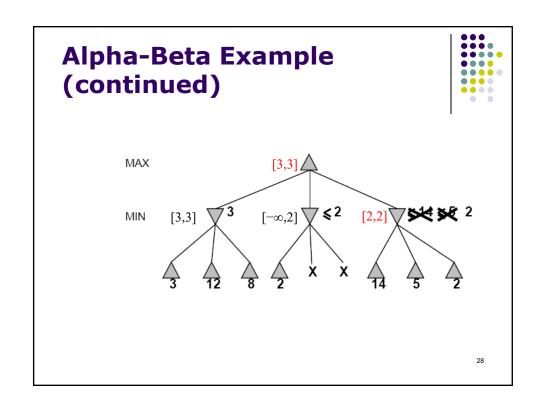












Why is it called α-β?



- Similar for MIN nodes
- a is the value of the best (i.e., highestvalue) choice found so far at any choice point along the path for max
- β is the value of the best (i.e., lowestvalue) choice found so far at any choice point along the path for min

29

The α-β algorithm



```
function ALPHA-BETA-SEARCH(state) returns an action inputs: state, current state in game v \leftarrow MAX-VALUE(state, -\infty, +\infty) return the action in ACTIONS(state) with value v
```

```
function MAX-VALUE(state, \alpha, \beta) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) v \leftarrow -\infty for each a in ACTIONS(state) do v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(\text{Result}(s,a), \alpha, \beta)) if v \geq \beta then return v \alpha \leftarrow \text{MAX}(\alpha, v) return v
```

The α-β algorithm



```
function MIN-VALUE(state, \alpha, \beta) returns a utility value if TERMINAL-TEST(state) then return UTILITY(state) v \leftarrow + \infty for each a in ACTIONS(state) do v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(\text{Result}(s,a), \alpha, \beta)) if v \leq \alpha then return v \in \text{MIN}(\beta, v) return v \in \text{MIN}(\beta, v)
```

31

Properties of Alpha-Beta Pruning



- Pruning does not affect final results
- The effectiveness of pruning is highly dependent on the order in which the successors are checked
 - Try to examine first the successors that are likely to be best
 - ordering heuristics
- With "perfect ordering," time complexity is $O(b^{m/2})$
 - Branching factor of sqrt(b) !!
 - Alpha-beta pruning can look twice as far as minimax in the same amount of time

Real-time Decisions



- Minimax and alpha-beta pruning require leaf-node evaluations.
- May be impractical within a reasonable amount of time.
- Suppose we have 100 secs, explore 10⁶ nodes/sec $\rightarrow 10^8$ nodes per move $\sim 35^5$

 - → Alpha-beta pruning reaches depth 10

33

Real-time Decisions



Standard approach

- Cut off search earlier (replace TERMINAL-TEST by CUTOFF-TEST)
 - E.g., introduce a fixed depth limit (selected so that the amount of time will not exceed what the rules of the game allow), or iterative deepening
- Apply heuristic *evaluation function* EVAL (replacing utility function of alpha-beta)
- - **if** TERMINAL-TEST(*state*) **then return** UTILITY(*state*)
 - if CUTOFF-TEST(state,depth) then return EVAL(state)

Heuristic evaluation function



- Idea: produce an estimate of the expected utility of the game from a given position.
- Performance depends strongly on quality of evaluation function
- Requirements:
 - EVAL should order terminal-nodes in the same way as UTILITY.
 - · Computation may not take too long.
 - For non-terminal states the EVAL should be strongly correlated with the actual chance of winning.
- Exact values don't matter, only the order matters

35

Evaluation functions



- Most evaluation functions work by calculating various features of the state
 - Compute numerical contributions from each feature and combine them to find the total value
- For chess, material value for each piece: pawn=1, knight=bishop=3, rook=5, queen=9
- Linear weighted sum of features

$$Eval(s) = W_1 f_1(s) + W_2 f_2(s) + ... + W_n f_n(s)$$

• e.g., $w_1 = 9$ with

 $f_1(s) = (number of white queens) - (number of black queens)$

Real-time Decisions



- Minimax with alpha-beta pruning
- An evaluation function
- More sophisticated cutoff test: e.g., wild swings in value in near future
- A large *transposition table* (closed list): repeated states problem

37

Real-time Decisions



- Extensively tuned evaluation function
- Pruning heuristics
- A large database of optimal opening and endgame moves: table lookup instead of search
 - Chess endgames with up to 7 pieces solved

Go







39

Monte Carlo tree search



- Find the most promising moves by playing out many random moves to the end, using techniques in Markov Decision Processes
- Doesn't necessarily require game-specific knowledge -> no need for evaluation function; simply implementing the game's mechanics is sufficient
- Does well in games with a high branching factor
- Used in Go, real-time video games
- AlphaGo: uses a Monte Carlo tree search guided by deep neural networks extensively trained from games played by human experts and games against itself
- AlphaGo Zero (2017) learns to play using Reinforcement Learning simply by playing games against itself, starting from completely random play

State-of-the-Art Deterministic games



- Checkers: Chinook ended 40-year-reign of human world champion Marion Tinsley in 1994. In July 2007, Chinook's developers announced that the program has been improved to the point where it cannot lose a game. Used a precomputed endgame database defining perfect play for all positions involving 8 or fewer pieces on the board, a total of 444 billion positions.
- Chess: Deep Blue defeated human world champion Garry Kasparov in a six-game match in 1997. Deep Blue searches 200 million positions per second, uses very sophisticated evaluation.
- Othello/Reversi: humans are no match for computers
- Go: AlphaGo beat a professional player without handicaps on a full-sized 19×19 board in 2015, beat a top Go player in 2016.

41

Types of Games



- We covered games of deterministic, perfect information: chess, checkers
- Stochastic Games: backgammon (Chapter 5.5)
- Partially observable games: bridge, poker (Chapter 5.6)